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# Basic of Industrial IOT

I IOT  
↓ subset  
IOT

I IOT → Integration of Sensors in the field.

I IOT → Industrial Internet of thing.

ICT → customer based service.

IIOT → complex & expensive.

→ I IOT Transforms many Industries :-

- \* agriculture
- \* companies
- \* automotive Industry.

1) Engineering Industry

2) Mining

3) Manufacturing

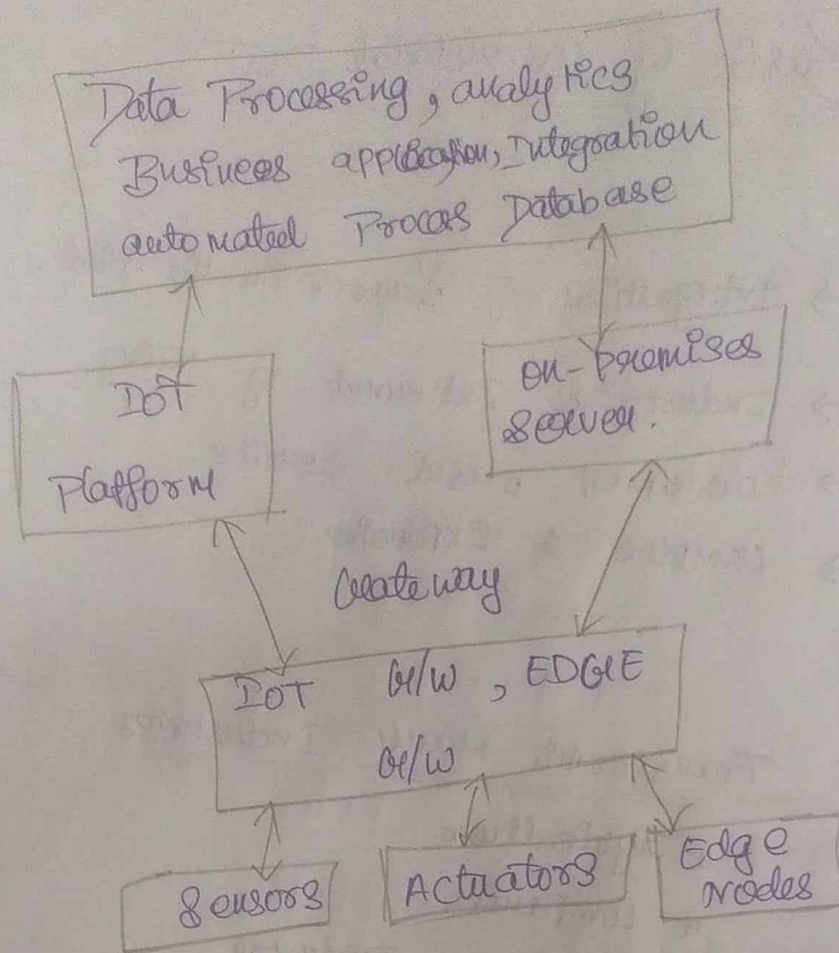
4) Logistics.

5) Healthcare

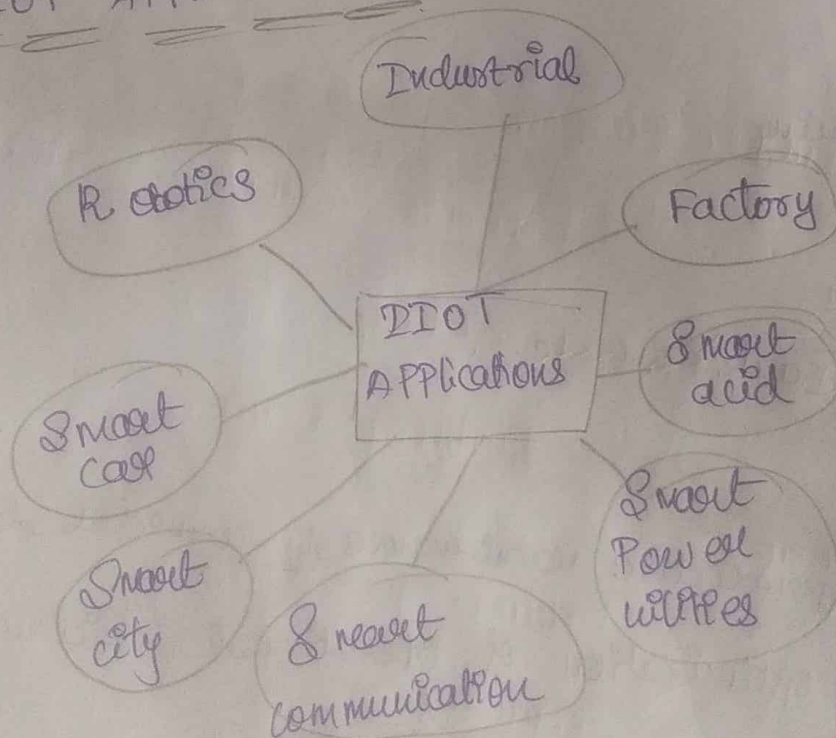
6) Others - Bank ATM etc...

→ Benefits :-

- 1) Predictive maintenance of connected devices.
- 2) optimization of Operational Efficiency.
- 3) optimization of Process.



### → IIOT Applications :-





↳

\* IIOT  $\Rightarrow$  connect physical as well as virtual  
Interposable Infra common.

\* IOT  $\Rightarrow$  conceptual model, use of new technology  
which enable device to communicate each  
other using internet.

$\rightarrow$  A take intelligent decisions on available data:-

\* IIOT  $\rightarrow$  subset of IOT.

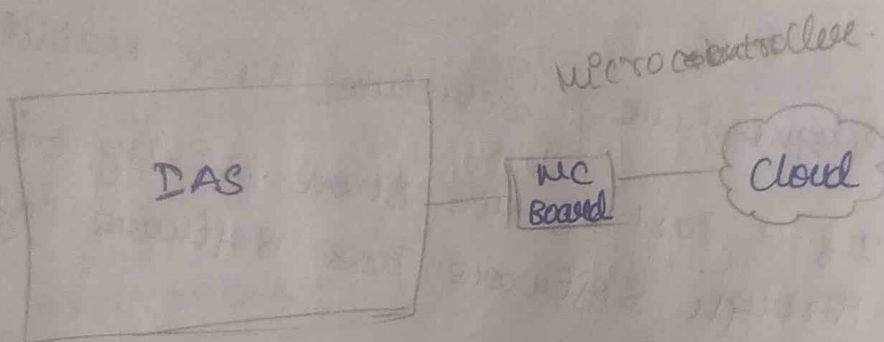
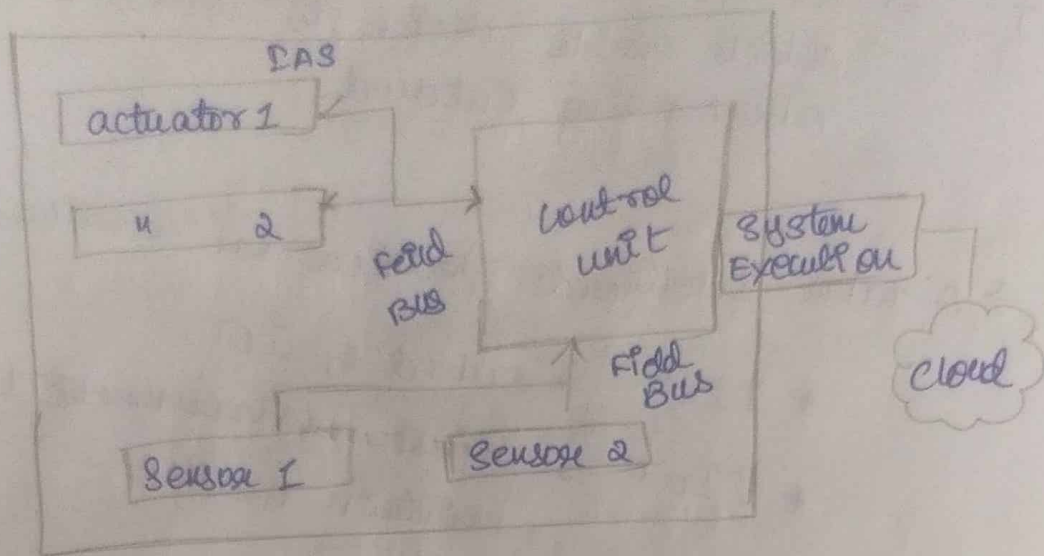
\* DIIOT  $\rightarrow$  adjust environment to  
maintain health.

$\rightarrow$  Diagnose mic + schedule their maintenance.

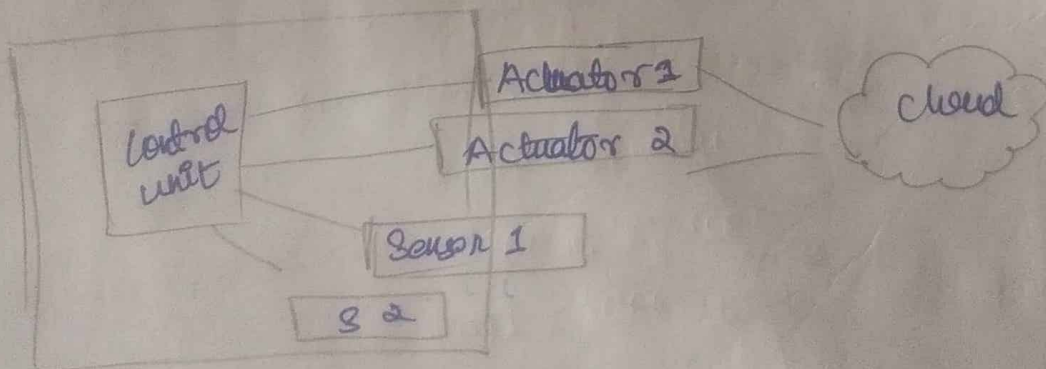
$\rightarrow$  If a part of mic start giving trouble  
through software pass software information  
to other mic.

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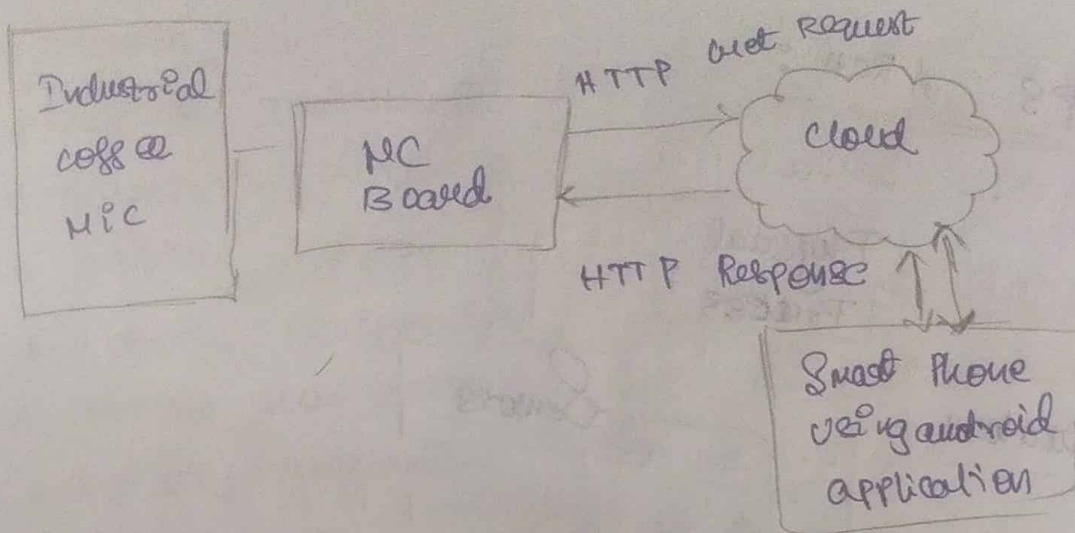
## → Industrial Automation System (IAS) :-



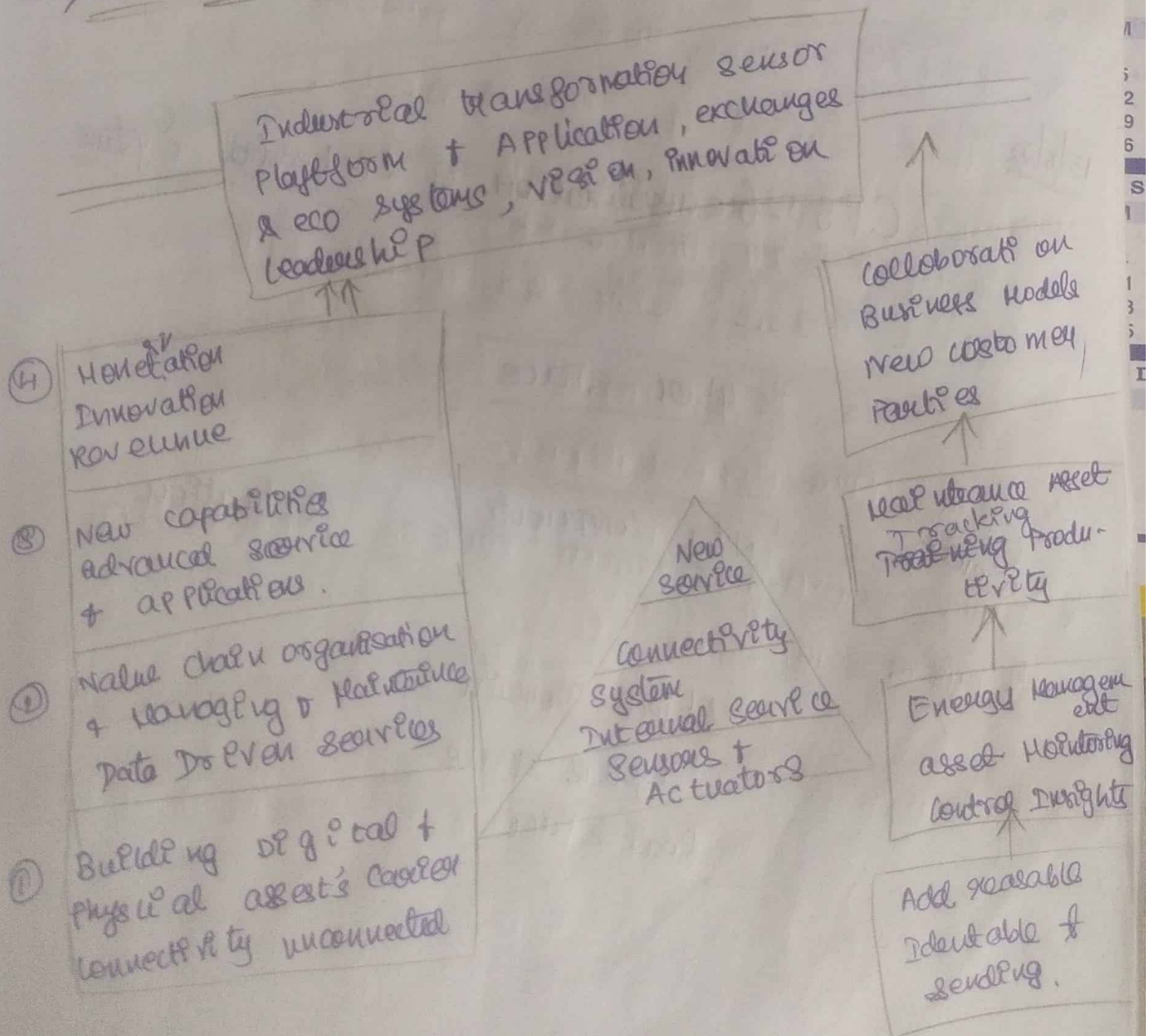
## → Usage of Intelligent actuator + sensors



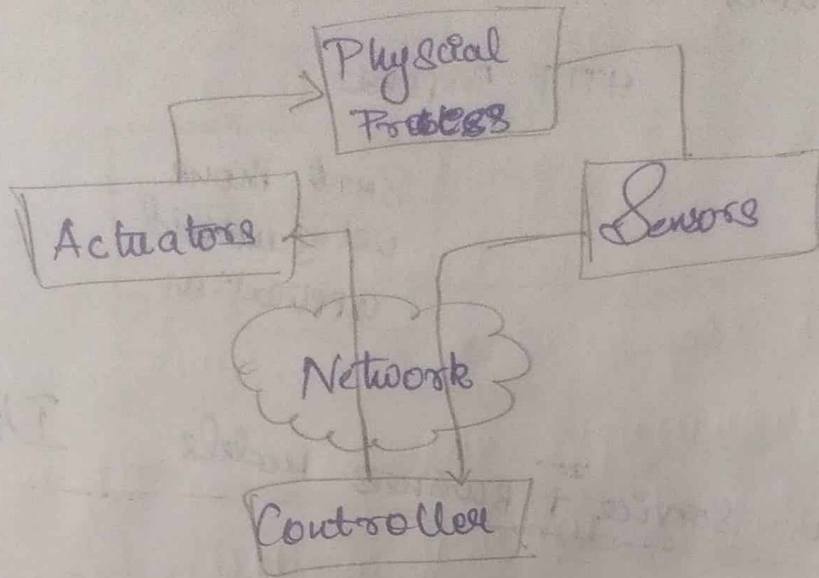




→ Sensors to New Service + Business models I4.0

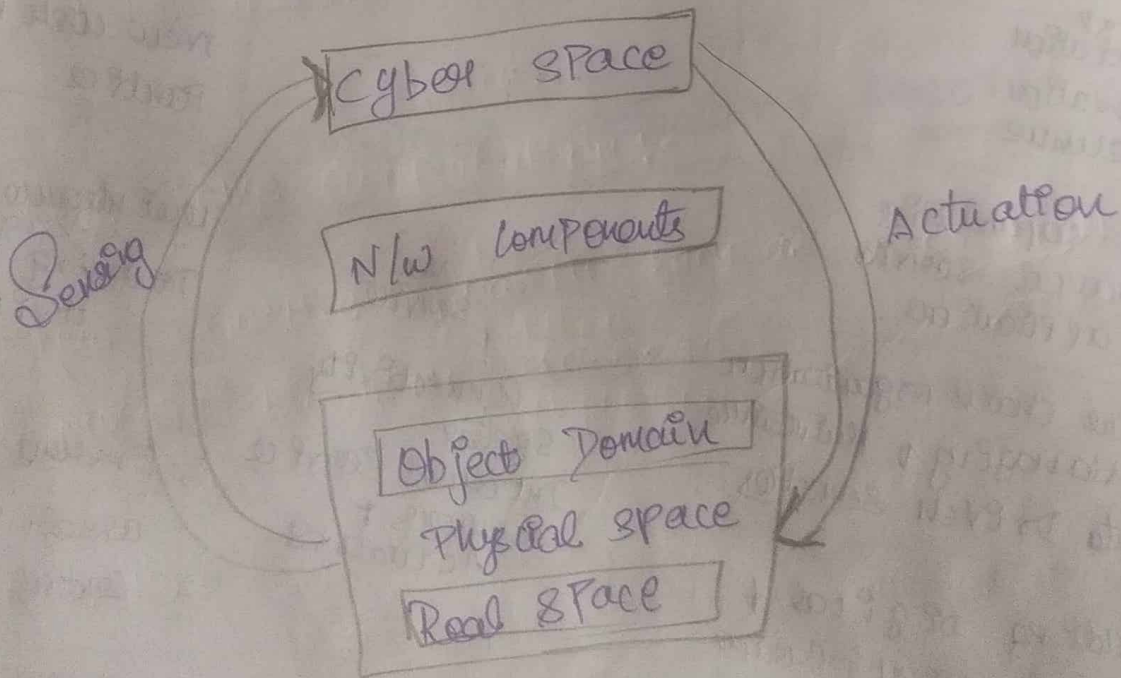


→ CPS A RCH :-



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CPS - Generalization of Embedded System





→ Examples:-

- \* Medical Instruments
- \* Transportation vehicle
- \* Defense Systems.
- \* Robotic Equipment
- \* Process Monitoring
- \* Factory Automation System.

→ Difference b/w ES & CPS

ES	CPS
* Device has Information Processing System Embedded into them.	Complete system has physical component & s/w
* Typically, confined to a single device	Networked set of Embedded system
* Limited Resources, Limited NO. of task	Not Resource constrained.
* Main issue - Real time Response + Reliability	Timing + Concurrency

## → Features of CPS

- \* Reactive Computation.
- \* Interact with Environment
- \* Sequence of observed I/O.

## → Concurrency :-

- \* Multiple Process run concurrently.
- \* Process <sup>exchange</sup> XCHG Information to get desired result.
- \* <sup>synchronization</sup> SYNC or <sup>asynchronization</sup> ASYNC Modes of operation.
- \* Feedback control of Physical world.
- ↳ \* Sensors - sense Environment.
- ↳ \* actuators - influence P.E.
- \* Hybrid control system for complex task.

## → Real Time Computation :-

- \* Time sensitive operation such as co-ordination Resource allocation etc...



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## → APPLICATIONS OF CPS:-

### ① Health Care:-

- \* Highly accurate medical services system.
- \* Image guided surgery + therapy.
- \* Control of fluid flow for medical purpose.
- \* Biological Analysis of Intelligent operation theatres + hospitals.
- \* Engineering systems based on cognition + neuroscience

### ② Transportation + Infrastructure (IS) based transportation CTS:-

- \* Real time monitoring of traffic IS + traffic control (traffic signal, camera etc)

### ③ Vehicle IS coordinated Transportation CTS:-

- \* Proximity detection for safety.
- \* Vehicle health monitoring.

### ④ Smart grid:-

- \* smart meters
- \* Demand management with distributed generation
- \* Automated distributed with intelligent substations
- \* Wides area control of smart grid.
- \* Phasor measurement unit (PMU)
- \* Data aggregation unit.

## ⑤ Industry :-

\* Manufacturing systems with logistics.

\* Integrated with communication abilities, sensors + actuators.

→ Smart control.

→ optimal resource utilization.

→ smart diagnostics + maintenance.

\* Flexibility of development system.

\* End products customized specific to needs of customer.

→ CPS arch for IIoT :- ✓ ④ question  
↳ 5C architecture ⇒ 5 levels.

① connection

② conversion

③ cyber

④ cognition

⑤ configuration.

## ① Connection :-

\* Smart connection to ensure accurate

data obtained from IIoT.

→ seamless data

→ selection of sensors.



## ② Conversion :-

\* Convert Machine data to meaning & use  
Information Machine  $\rightarrow$  self aware

## ③ Cyber

- \* Central Information Hub
- \* Gather Information
- \* Obtain status of individual machine
- \* Rate  $\rightarrow$  Performance of machine
- \* Predict future behaviour
- \* Cluster for data mining
- \* Machine  $\rightarrow$  self comparison ability

## ④ Cognition :-

\* Purpose presentation of info to the user for generation through to knowledge of the system.

\* Collaborative diagnosis

\* Design making

$\downarrow$   $\downarrow$   
prioritization optimization

## ⑤ Configuration :-

\* supervisory control to determine actions to be taken by machine

\* self configuration of hardware

\* " adjustment for variation

\* " optimisation for disturbance

## → Challenges - CPS :-

- \* Safety, Security, Robustness.
- \* Hybrid control systems.
- \* Computation & Real time Embedded system.
- \* Sensor & Mobile network.
- \* Architecture & Modelling
- \* Verification, validation & certification.
- \* Education & Training.

## → Next Generation Sensors :-

### ↳ Smart Sensors :-

- \* Integration of sensors & actuation with processor & communication module.
- \* Defined in IEEE 1451 standard as sensor has small memory & standardized connection to enable communication with processor & data network.

### → Functionality :-

- \* self calibration, communication, multi sensing, cost improvement.



## → Limitation of Smart Sensors:-

- \* Predefined Embedded function, customization not possible.
- \* Narrow application
- \* Sensors data aggregation not possible.
- \* External processor → sensor calibration
- \* Basic communication protocols.

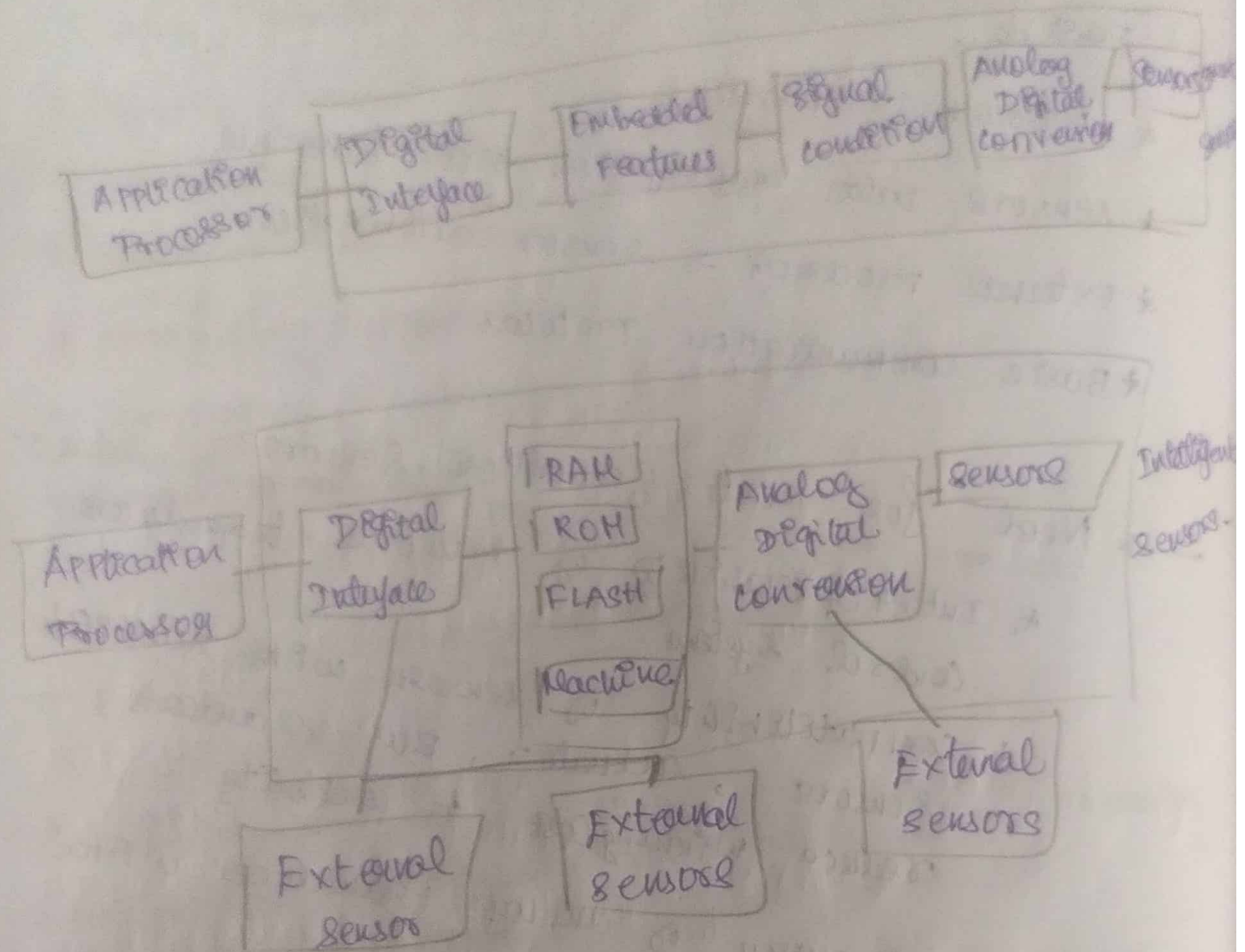
## → Need for Next Generation Sensors:-

- \* Interoperability of Networks, transducers, control systems.
- \* Compatibility of sensors with multiple sensors, actuators, bus standards, reduce wiring cost & complexity
- \* Integration of analog transducer with digital network.
- \* Increase usage of existing network → Instead of proposing new state.

## → Intelligent Sensors:-

- \* Capable of processing
- \* Capable of customize
- \* Capable of managing controlling external sensors.
- \* sensor, Machine memory  
→ RAM, ROM, FLASH

## → Block Diagram of Smart Sensors :



## → Advantages :-

- \* Reduce Data communication
- \* Reduce Power communication
- \* Application specific customization of sensors <sup>needs</sup> ~~order~~
- \* Continuous observation + monitoring of sensors
- \* Adaptive samples rate & sleep wake cycles
- \* Shorter software network development time
- Improved compatibility of sensors



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# Augment Reality & Virtual Reality

- \* AR & VR in ITO.
- \* AR & VR used in Manufacturing Industry.
- \* Data warehouse efficiency Improved.
- \* safety training - safety hazards.

## → AR & VR in IIOT :-

- \* Machining & Production.
- \* Education & Collaboration.
- \* Assembly.
- \* safety & Security.
- \* Digital Factory Eng.
- \* Factory Planning.
- \* Maintenance & Inspection.

## → Augment Reality :-

- \* Enhanced version of reality.
- \* Direct / Indirect views of physical world are augmented with computer generated superimposed images.
- \* Adds digital Element to actual.
- \* Amplifies present perception of Reality.

## → Key Features of AR:-

\* Lies in middle of real reality spectrum.

\* Multiple sensor

Module → audio, video, haptic (touch)

\* Use existing Environment & overlays new information on top of it.

## → Application of AR:-

\* Retail + Industrial Design.

\* Medical.

\* Education.

\* Flight training.

\* Military

\* Tourism

\* Entertainment.

## → Key Components of Devices:-

\* Sensors

\* Projection screen.

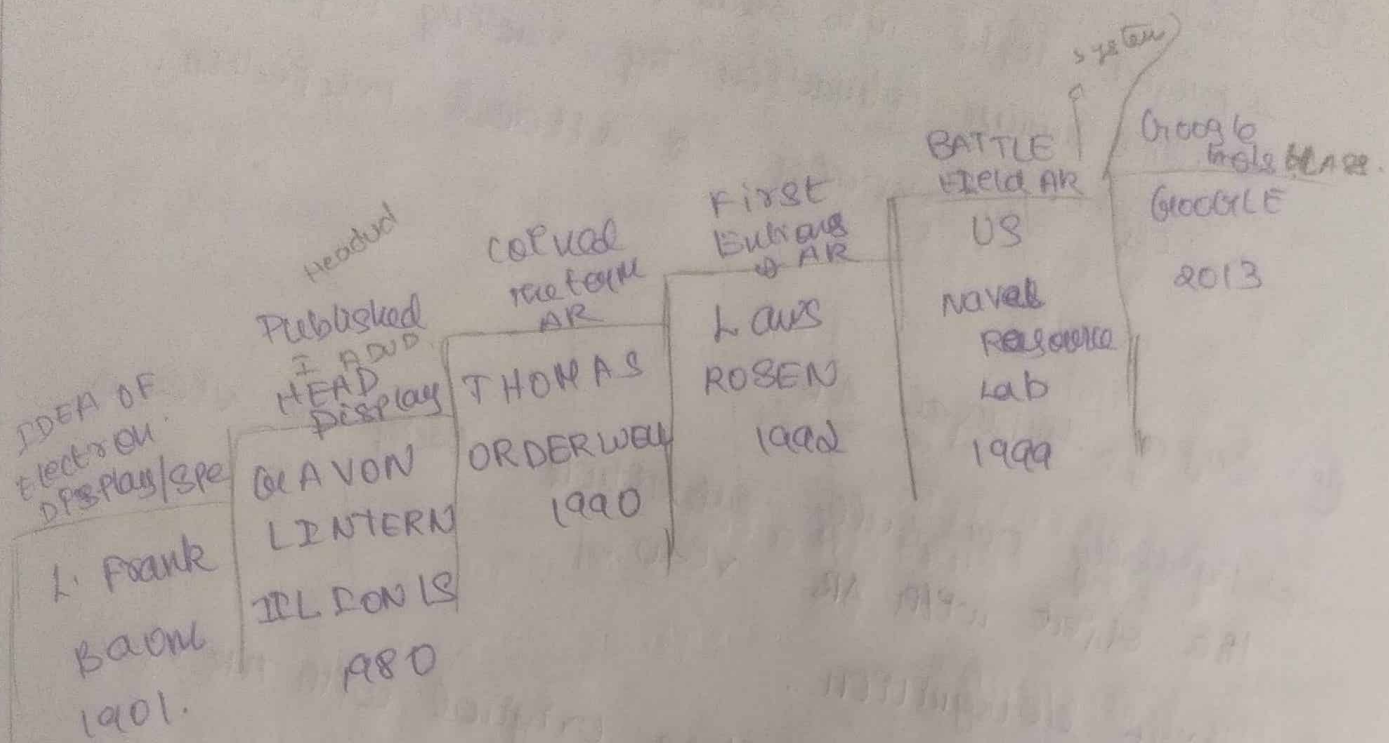
\* Cameras

\* Processing unit

\* Reflection



## → CHRONOLOGICAL ORDER OF AR :-



## → Types of AR :-

### ① MARKER BASED AR :-

→ O/P :- When Reader Sense by camera & visual visual marker.

Camera :- difference b/w marker & real objects.  
 Marker :- Distinct feature can be easily processed.

### ② MARKER LESS AR :-

→ Mapping Directions.  
 → Location Based on GPS, digital compass, or accelerometer.  
 → attached to the device.

### ③ Projection Screen AR:-

- Project light into real world surfaces.
- allow human interaction by sending lights.
- Diff B/w expected & altered projection.

### ④ Super Imposed AR:-

- Partially or fully substitute original view of the object with AR view.
- Object recognition.
- Application cannot replace original with AR view.

## VR

\* Mixture of Hardware or software Based artificial Environment.

\* Realistic 3D Image created.

\* Presented to the user → Interact with real or physical world.



## → Key Features :-

- \* Create & enhance. Emag Envrny reality.
- \* Physically present in non-physical
- \* Incorporate auditory & sensory feedback.
- \* Allow user to get naturally absorbed to virtual.

→ CHRONOLOGICAL ORDER of VR :-

Experience Theatre	Sword & Demo class	Conference VR	Produced & NW	Large Experience Area	Google I 38 Page
Film Makel Worton 1962	IVAN Sutherland MIT, comp Scientist 1968	JACOB LANIER 1987 Scientist	DAVID 1977- 1984	ERIC HOLLAT 1979	Michael 2015