

CSE 6140/ CX 4140

Computational Science and Engineering  
ALGORITHMS

**NP Completeness 2**

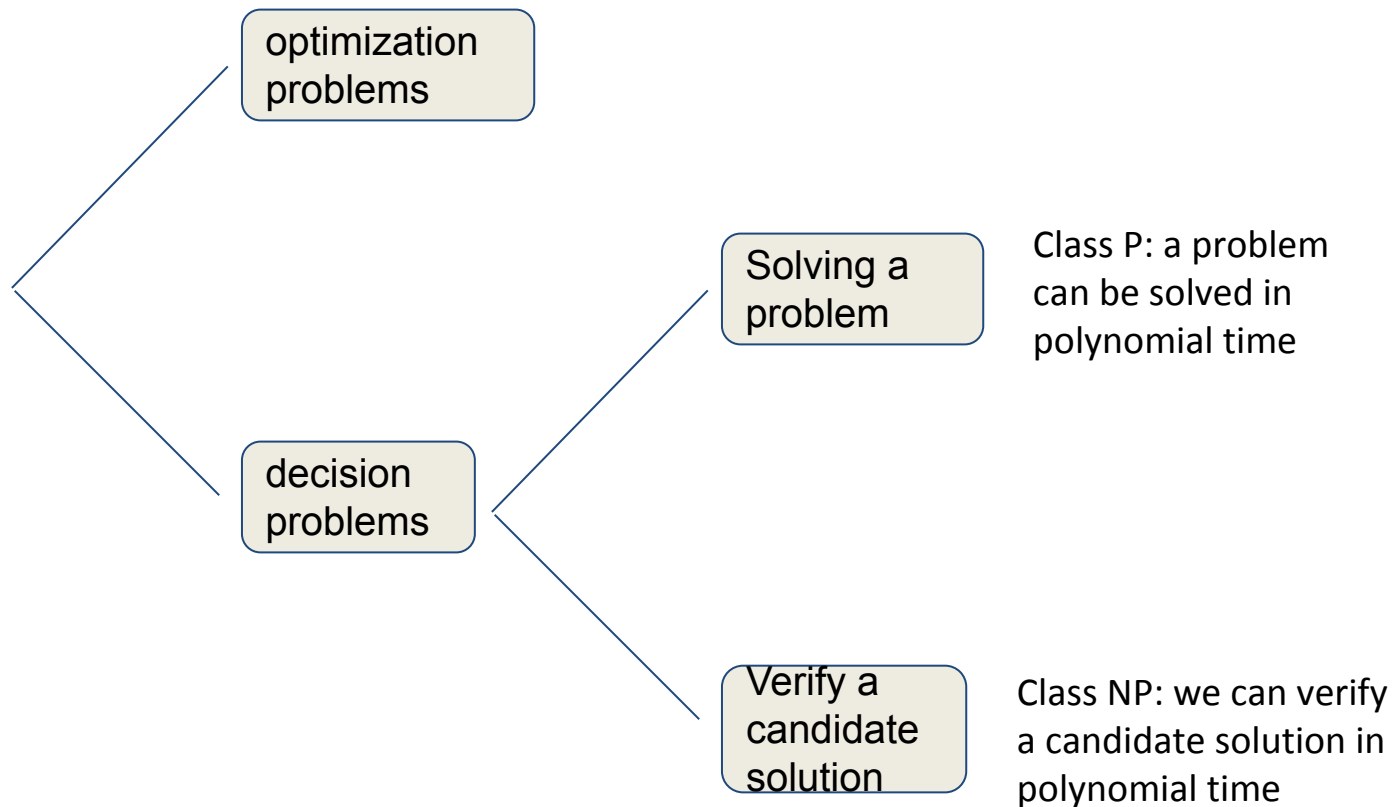
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Based on slides by Prof. Ümit V. Çatalyürek

# Summary of last lecture



## Verifying a Candidate Solution vs. Solving a Problem

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- Intuitively it seems much harder (more time consuming) in some cases to **solve** a problem from scratch than to **verify** that a candidate solution actually solves the problem.
  - If there are many candidate solutions to check, then even if each individual one is quick to check, overall it can take a long time

# Is $P = NP$ ?

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- Any problem in  $P$  is also in  $NP$ :

$$P \subseteq NP$$

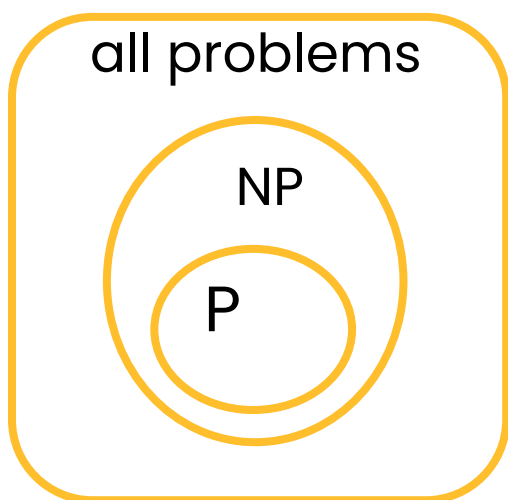
- The big (and **open question**) is whether  $NP \subseteq P$  or  $P = NP$ 
  - i.e., if it is always easy to check a solution, should it also be easy to find a solution?

# Is $P = NP$ ?

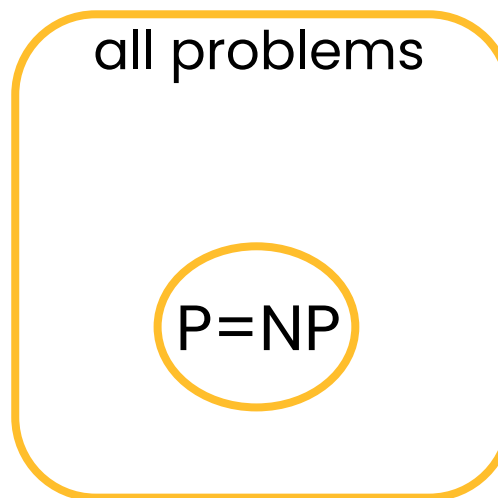
- Any problem in  $P$  is also in  $NP$ :

$$P \subseteq NP$$

- The big (and **open question**) is whether  $NP \subseteq P$  or  $P = NP$ 
  - i.e., if it is always easy to check a solution, should it also be easy to find a solution?
- Most computer scientists believe that this is false but we do not have a proof ...



or

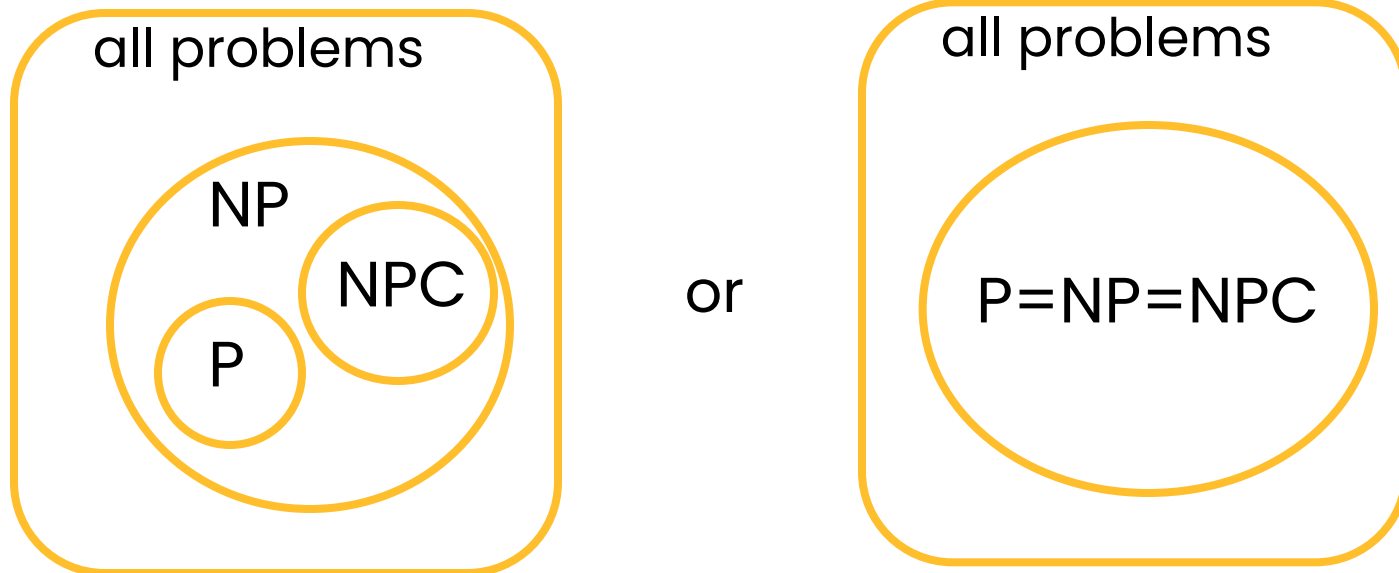


# NP-Complete Problems

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- NP-complete problems is class of "hardest" problems in NP.
- If you can solve an NP-complete problem, then you can solve all NP problems (show later).
- Hence, if any NP-complete problem can be solved in poly time, then all problems in NP can be, and thus  $P = NP$ .
- Precise definition coming later...

# Possible Worlds



$NPC = NP\text{-complete}$

# Reductions

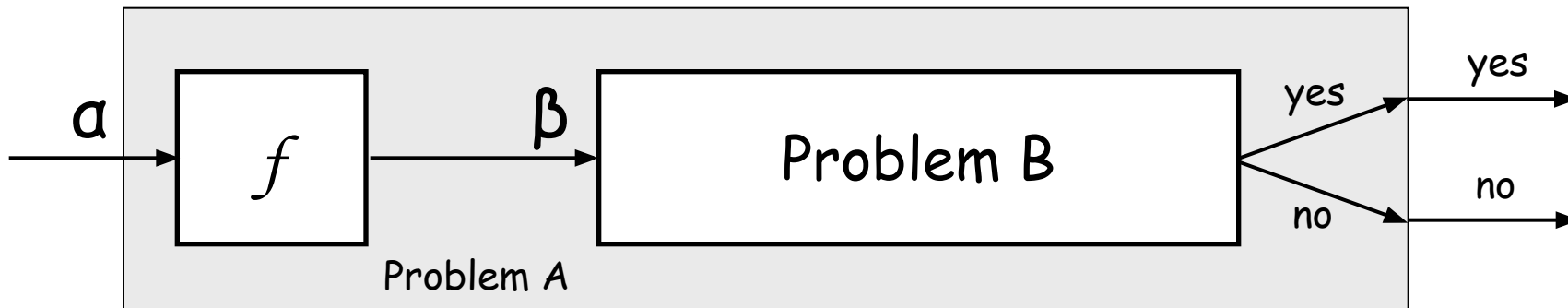
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- Reduction from A to B is showing that we can solve A using the algorithm that solves B
- We say that problem A is easier than problem B, (i.e., we write “ $A \leq B$ ”)



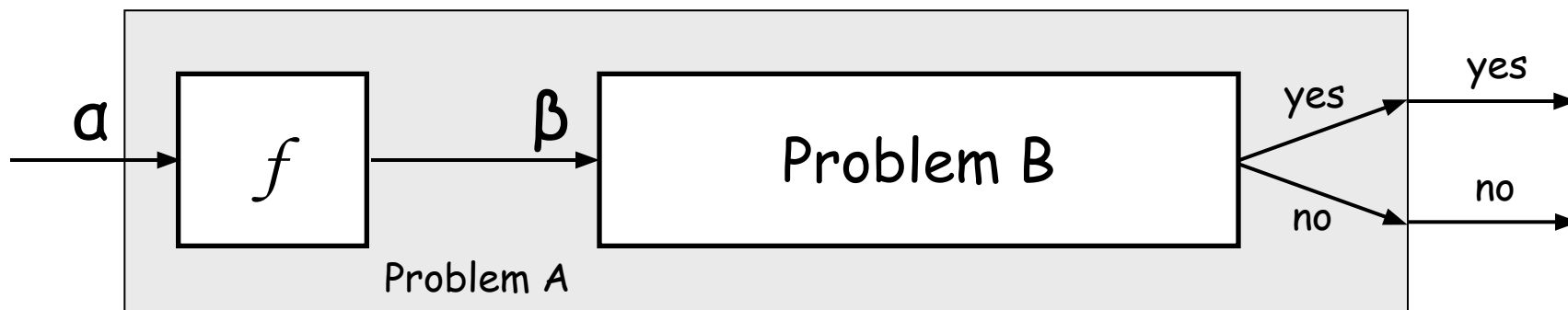
# Reductions

- “ $A \leq B$ ”: Reduction from A to B is showing that we can solve A using the algorithm that solves B
- If we have an oracle for solving B, then we can solve A by making polynomial number of computations and polynomial number of calls to the oracle for B (Cook)
- **Idea:** transform the inputs of A to inputs of B (single call to oracle) (Karp)



# Have we already done reductions in class?

- All pairs shortest path: multiple calls to Dijkstra
- K-clustering: use of MST
- We can also do reductions on poly time algorithms

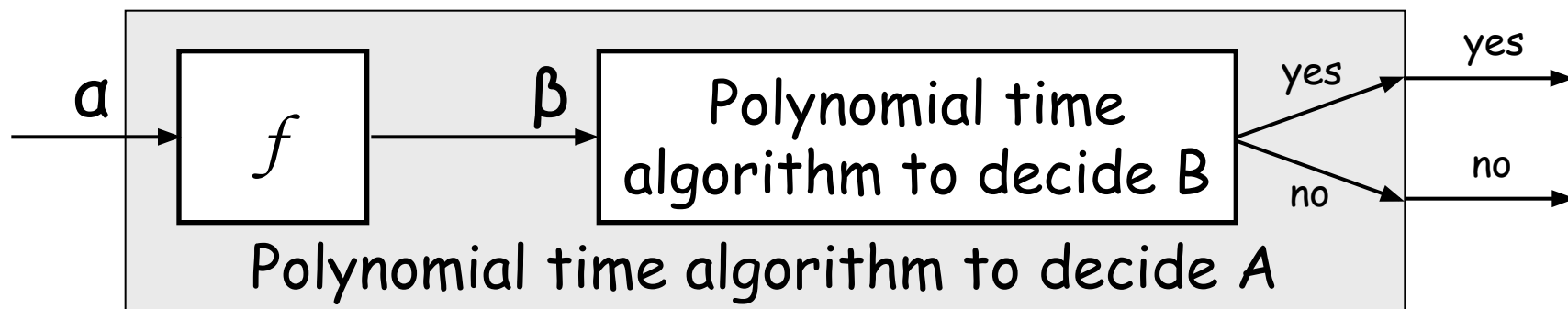


# Polynomial Reductions

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- Given two problems A, B, we say that A is polynomially **reducible** to B ( $A \leq_p B$ ) if:
  1. There exists a function  $f$  that converts the input of A **to** inputs of B in polynomial time
  2.  $A(i) = \text{YES} \Leftrightarrow B(f(i)) = \text{YES}$


# Proving Polynomial Time



1. Use a **polynomial time** reduction algorithm to transform A into B
2. Run a known **polynomial time** algorithm for B
3. Use the answer for B as the answer for A

(e.g. k-Clustering problem was reduced to MST)

# Implications of Polynomial-Time Reductions

- **Purpose.** Classify problems according to **relative** difficulty.
- **Design algorithms.** If  $X \leq_p Y$  and  $Y$  can be solved in polynomial-time, then  $X$  can also be solved in polynomial time.
- **Establish intractability.** If  $X \leq_p Y$  and  $X$  cannot be solved in polynomial-time, then  $Y$  cannot be solved in polynomial time.
- **Establish equivalence.** If  $X \leq_p Y$  and  $Y \leq_p X$ , we use notation  $X \equiv_p Y$ .  
  
up to cost of reduction
- **Transitivity:** if  $X \leq_p Y$  and  $Y \leq_p Z$ , then  $X \leq_p Z$

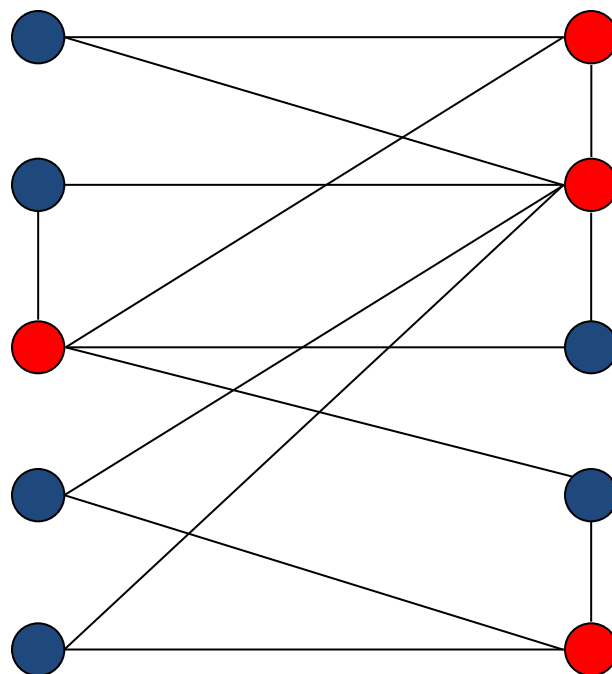
# Reduction By Simple Equivalence

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- Basic reduction strategies.
  - Reduction by simple equivalence.
  - Reduction from special case to general case.
  - Reduction by encoding with gadgets.

# Vertex Cover

- **MINIMUM VERTEX COVER**: Given a graph  $G = (V, E)$ , **find the smallest** subset of vertices  $S \subseteq V$  such that for each edge at least one of its endpoints is in  $S$ ?
- **VERTEX COVER**: Given a graph  $G = (V, E)$  and an integer  $k$ , **is there a subset** of vertices  $S \subseteq V$  such that  $|S| \leq k$ , and for each edge, at least one of its endpoints is in  $S$ ?
- Ex. Is there a vertex cover of size  $\leq 4$ ?
- Ex. Is there a vertex cover of size  $\leq 3$ ?



 vertex cover

# Set Cover

- **SET COVER:** Given a set  $U$  of elements, a collection  $S_1, S_2, \dots, S_m$  of subsets of  $U$ , and an integer  $k$ , does there exist a collection of  $\leq k$  of these sets whose union is equal to  $U$ ?
- Sample application.
  - $m$  available pieces of software.
  - Set  $U$  of  $n$  capabilities that we would like our system to have.
  - The  $i$ th piece of software provides the set  $S_i \subseteq U$  of capabilities.
  - Goal: achieve all  $n$  capabilities using fewest pieces of software.

Example

$$U = \{ 1, 2, 3, 4, 5, 6, 7 \}$$

$$k = 2$$

$$S_1 = \{3, 7\}$$

$$S_4 = \{2, 4\}$$

$$S_2 = \{3, 4, 5, 6\}$$

$$S_5 = \{5\}$$

$$S_3 = \{1\}$$

$$S_6 = \{1, 2, 6, 7\}$$



# Vertex cover reduces to set cover

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**Theorem.**  $\text{VERTEX-COVER} \leq_p \text{SET-COVER}$ .

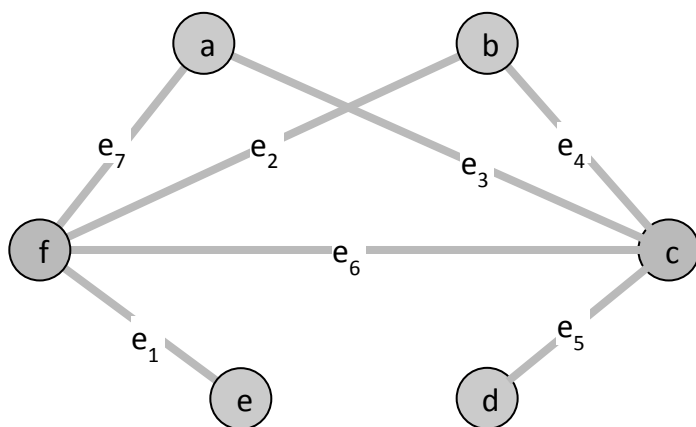
# Vertex cover reduces to set cover

**Theorem.**  $\text{VERTEX-COVER} \leq_p \text{SET-COVER}$ .

**Pf.** Given a  $\text{VERTEX-COVER}$  instance  $G = (V, E)$  and  $k$ , we construct a  $\text{SET-COVER}$  instance  $(U, S, k)$  that has a set cover of size  $k$  iff  $G$  has a vertex cover of size  $k$ .

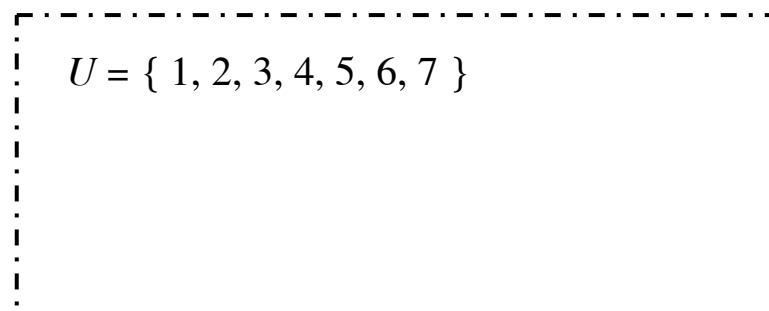
**Construction.**

- Universe  $U = E$ .



$k = 2$

vertex cover instance  
( $k = 2$ )



set cover instance  
( $k = 2$ )

# Vertex cover reduces to set cover

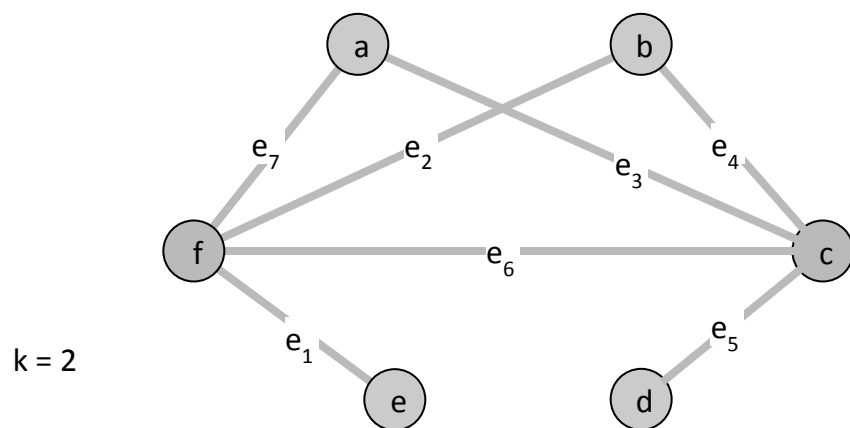
**Theorem.**  $\text{VERTEX-COVER} \leq_p \text{SET-COVER}$ .

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## Construction.

- Universe  $U = E$ .
- Create one subset for each node  $v \in V$ :  $S_v = \{e \in E : e \text{ incident to } v\}$ .

Show that the reduction algorithm is polynomial



vertex cover instance  
( $k = 2$ )

$$\begin{aligned}
 U &= \{ 1, 2, 3, 4, 5, 6, 7 \} \\
 S_a &= \{ 3, 7 \} & S_b &= \{ 2, 4 \} \\
 S_c &= \{ 3, 4, 5, 6 \} & S_d &= \{ 5 \} \\
 S_e &= \{ 1 \} & S_f &= \{ 1, 2, 6, 7 \}
 \end{aligned}$$

set cover instance  
( $k = 2$ )

# Vertex cover reduces to set cover

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Next: show that  
 $VC(i)=\text{yes}$  iff  
 $SC(f(i))=\text{yes}$

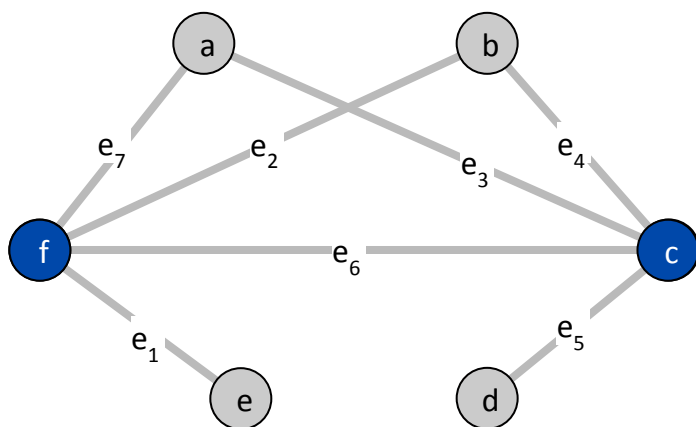
# Vertex cover reduces to set cover

**Lemma.**  $G = (V, E)$  contains a vertex cover of size  $k$  iff  $(U, S, k)$  contains a set cover of size  $k$ .

That is,  $VC(i) = \text{yes} \iff SC(f(i)) = \text{yes}$

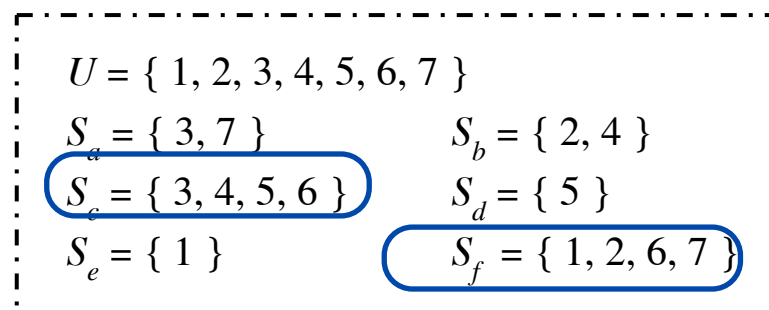
**Pf.**  $\Rightarrow$  Let  $X \subseteq V$  be a vertex cover of size  $k$  in  $G$ .

Then  $Y = \{ S_v : v \in X \}$  is a set cover of size  $k$ . ■



$k = 2$

vertex cover instance  
( $k = 2$ )



set cover instance  
( $k = 2$ )

# Vertex cover reduces to set cover

$$\text{VC}(i) = \text{yes} \implies \text{SC}(f(i)) = \text{yes}$$

$\text{VC}(i)$  is a yes instance  $\implies$  it has a solution let  $V' \subseteq V$  be such a solution  
 $|V'| \leq k$ , every edge has at least one end point in  $V'$

$$V' = \{i_1, i_2, \dots, i_l\}, \quad l \leq k$$

Consider  $A = \{S_{i_1}, S_{i_2}, \dots, S_{i_l}\}$

For the sake of contradiction assume  $A$  is not a solution to  $\text{SC}(f(i))$

Number of sets in  $A$  is  $l \leq k$  

then it must be the case that  $S_{i_1} \cup S_{i_2} \cup \dots \cup S_{i_l} \neq U$

$\implies \exists e \in U$  that is not in  $S_{i_1} \cup S_{i_2} \cup \dots \cup S_{i_l}$

$e$  also corresponds to an edge in  $\text{VC}(i)$

$e = (u, v)$ , so  $S_u$  and  $S_v$  are not in  $A$ , i.e.,  $S_u, S_v \notin A$

$\implies u, v \notin V'$  (by construction of  $A$ )

$e = (u, v)$  would have been not covered by  $V'$

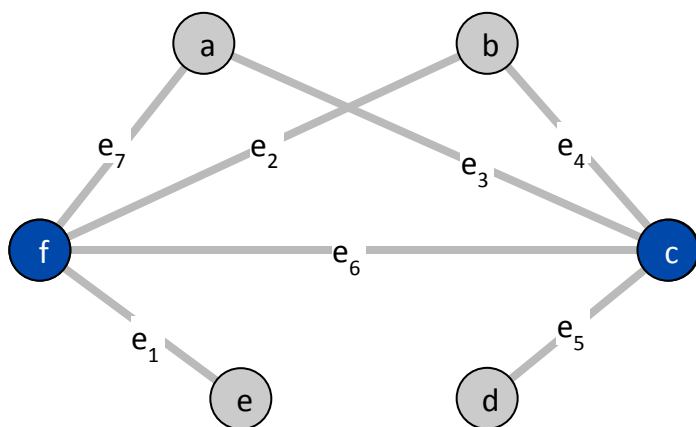
$\rightarrow \leftarrow$  contradicts  $V'$  be solution to VC

# Vertex cover reduces to set cover

**Lemma.**  $G = (V, E)$  contains a vertex cover of size  $k$  iff  $(U, S, k)$  contains a set cover of size  $k$ .

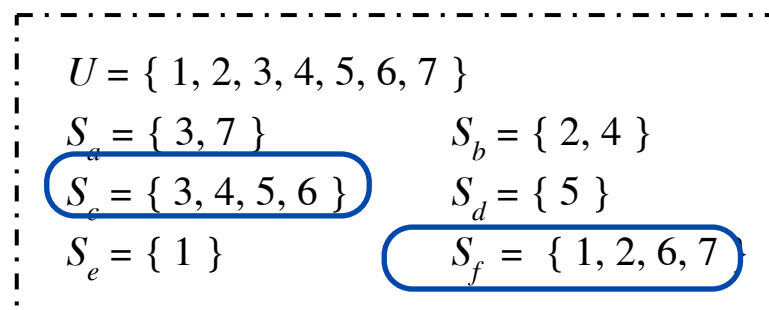
**Pf.**  $\Leftarrow$  Let  $Y \subseteq S$  be a set cover of size  $k$  in  $(U, S, k)$ .

- Then  $X = \{ v : S_v \in Y \}$  is a vertex cover of size  $k$  in  $G$ .  $\blacksquare$



$k = 2$

vertex cover instance  
( $k = 2$ )



set cover instance  
( $k = 2$ )

# Vertex cover reduces to set cover

$$SC(f(i)) = \text{yes} \implies VC(i) = \text{yes}$$

■  $SC(f(i))$  is a yes instance

$\implies$  It has a solution and let  $A = \{S_{i_1}, S_{i_2}, \dots, S_{i_l}\}$  be such a solution

$\implies l \leq k$  and  $S_{i_1} \cup S_{i_2} \cup \dots \cup S_{i_l} = U$  (by definition of SC)

Consider the vertex set  $V' = \{i_1, i_2, \dots, i_l\}$

for the sake of contradiction assume  $V'$  is **not** a solution to  $VC(i)$

the number of vertices  $l \leq k$  ✓

$\implies$  it must be breaking the edge covering requirement of VC

$\implies \exists e = (u, v) \in E$  such that  $u \notin V', v \notin V'$

$\implies S_u, S_v$  were not included in solution A

$e = (u, v) \in U$  (by construction of  $f(i)$ )

$S_u, S_v$  were the only sets that contain  $e$  (by construction)

$\implies e \notin S_{i_1} \cup S_{i_2} \cup \dots \cup S_{i_l}$ , i.e.,  $e$  is not covered by the solution set A,

$\rightarrow \leftarrow$  contradiction with A being solution



# Summary

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- **Problems**

- Decision problems (yes/no)
- Optimization problems (solution with best score)

- **P**

- Decision problems (decision problems) that can be solved in polynomial time
- Can be solved “efficiently”

- **NP**

- Decision problems whose “YES” answer can be verified in polynomial time, if we already have the proof (or witness)

# NP-Completeness (formally)

- A problem  $Y$  is **NP-hard** if  $X \leq_p Y$  for all  $X \in \text{NP}$ 
  - A problem is NP-hard iff an polynomial-time algorithm for it implies a polynomial-time algorithm for every problem in NP
  - NP-hard problems are at least as hard as any NP problem
- A problem  $Y$  is **NP-complete** if:
  - (1)  $Y \in \text{NP}$
  - (2)  $Y$  is NP-hard

NP-hard problems *do not have to be in NP*,  
and *they do not have to be decision problems*.

