

CSE 6140/ CX 4140

Computational Science and Engineering ALGORITHMS

NP Completeness 3

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Based on slides by Prof. Ümit V. Çatalyürek

Reductions

- Reduction from A to B is showing that we can solve A using the algorithm that solves B
- We say that problem A is easier than problem B, (i.e., we write “ $A \leq B$ ”)

Does it mean that the running time of A is less than B?

Not necessarily.

Polynomial Reductions

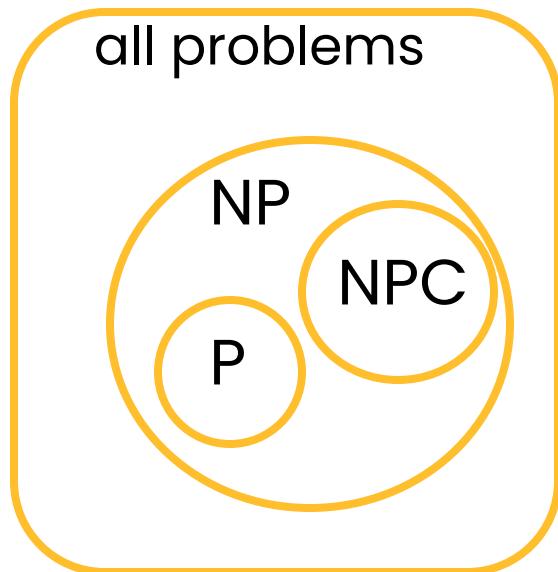
- Given two problems A , B , we say that A is polynomially **reducible** to B ($A \leq_p B$) if:
 1. There exists a function f that converts the input of A **to** inputs of B in polynomial time
 2. $A(i) = \text{YES} \iff B(f(i)) = \text{YES}$

Summary

- **P**
 - Decision problems that can be solved in polynomial time
 - Can be solved “efficiently”
- **NP**
 - Decision problems whose “YES” answer can be verified in polynomial time, if we already have the candidate solution
- **NP-complete**
 - The “hardest” problems in NP: a problem Y in NP with the property that for every problem X in NP, $X \leq_p Y$.

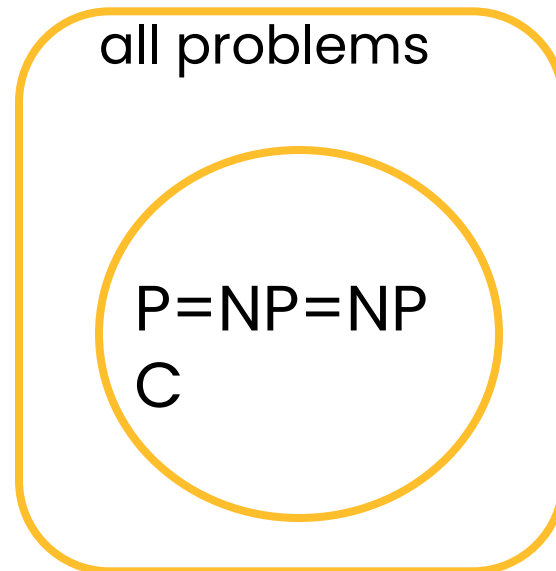
Possible Worlds

$P \neq NP$



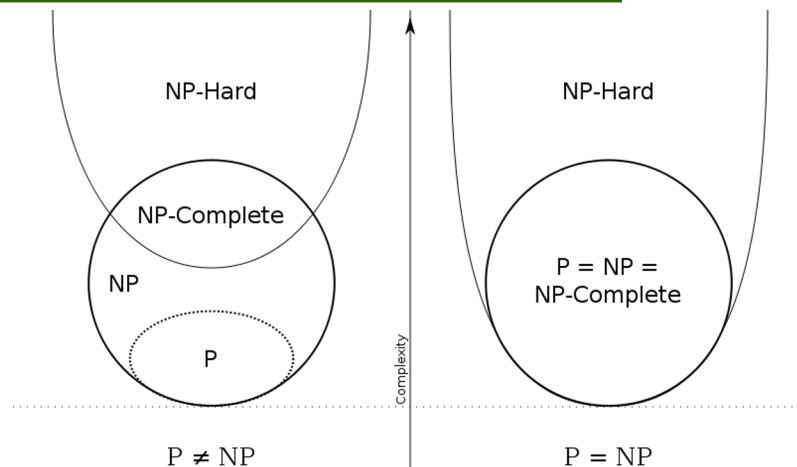
or

$P = NP$




NPC: NP-complete

Revisit “Is $P = NP$?”



- **Theorem.** Suppose Y is an NP -complete problem. Y is solvable in poly-time if and only if $P = NP$.
- **Pf. \Leftarrow** If $P = NP$ then Y is in P . Hence Y can be solved in poly-time.
- **Pf. \Rightarrow** Suppose Y can be solved in poly-time.
 - Let X be any problem in NP . Then, we know that $X \leq_p Y$ by definition of NP -complete and Y being NP -complete problem. Then we can solve X in poly-time by solving Y in poly-time. This implies any problem X in NP is also in P , i.e. $NP \subseteq P$.
 - We already know $P \subseteq NP$. Thus $P = NP$. ▪

Implications of Polynomial-Time Reductions

- **Purpose.** Classify problems according to **relative** difficulty.
- **Design algorithms.** If $X \leq_p Y$ and Y can be solved in polynomial-time, then X can also be solved in polynomial time.
- **Establish intractability.** If $X \leq_p Y$ and X cannot be solved in polynomial-time, then Y cannot be solved in polynomial time.
- **Establish equivalence.** If $X \leq_p Y$ and $Y \leq_p X$, we use notation $X \equiv_p Y$.

up to cost of reduction
- **Transitivity:** if $X \leq_p Y$ and $Y \leq_p Z$, then $X \leq_p Z$

Reduction By Simple Equivalence

- Basic reduction strategies.
 - Reduction by simple equivalence.
 - Reduction from special case to general case.
 - Reduction by encoding with gadgets.

Establishing NP-Completeness

- Recipe to establish **NP-completeness** of problem Y.
 - Step 1. Show that Y is in NP.
 - Describe how a potential **solution**/witness will be represented
 - Describe a **procedure to check** whether the potential witness is a correct solution to the problem instance, and argue that this procedure takes **polynomial time**
 - Step 2. Choose an NP-complete problem X.
 - Step 3. Prove that $X \leq_p Y$ (X is **poly-time reducible** to Y).
 - Describe a **procedure f that converts** the inputs i of X to inputs of Y in **polynomial time**
 - Show that the reduction is correct by showing that $X(i) = \text{YES} \Leftrightarrow Y(f(i)) = \text{YES}$ (**if and only if**, proof in both directions)

P & NP-Complete Problems

- **Shortest simple path**

- Given a graph $G = (V, E)$ find a **shortest** path from a source to all other vertices
- Polynomial solution: $O(VE)$

- **Longest simple path**

- Given a graph $G = (V, E)$ find a **longest** path from a source to all other vertices
- NP-complete

P & NP-Complete Problems

- **Euler tour**

- $G = (V, E)$ a connected, directed graph find a cycle that traverses **each edge** of G exactly once (may visit a vertex multiple times)
- Polynomial solution $O(E)$

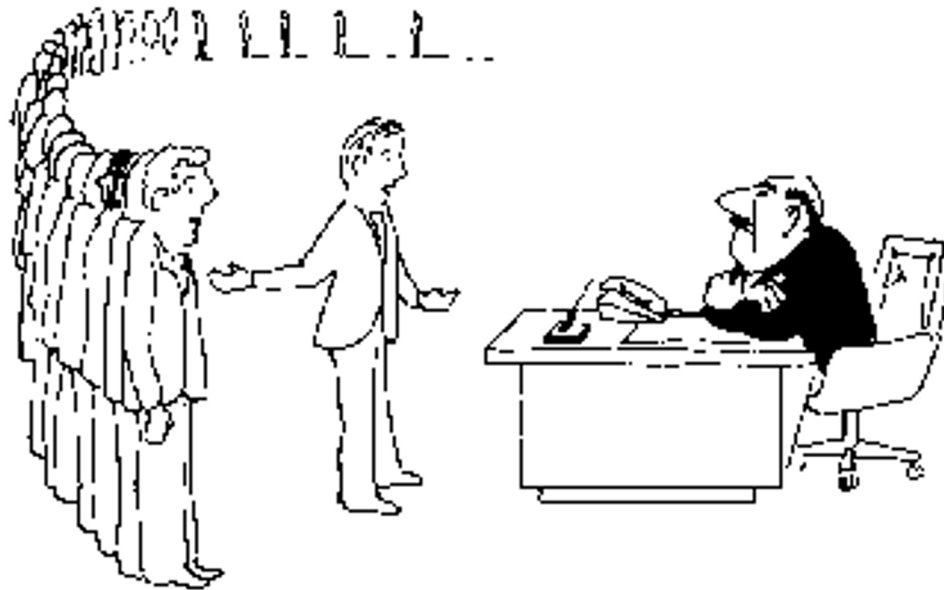
- **Hamiltonian cycle**

- $G = (V, E)$ a connected, directed graph find a cycle that visits **each vertex** of G exactly once
- NP-complete

More Hard Computational Problems

- **Aerospace engineering:** optimal mesh partitioning for finite elements.
- **Biology:** protein folding.
- **Chemical engineering:** heat exchanger network synthesis.
- **Civil engineering:** equilibrium of urban traffic flow.
- **Economics:** computation of arbitrage in financial markets with friction.
- **Electrical engineering:** VLSI layout.
- **Environmental engineering:** optimal placement of contaminant sensors.
- **Financial engineering:** find minimum risk portfolio of given return.
- **Game theory:** find Nash equilibrium that maximizes social welfare.
- **Genomics:** phylogeny reconstruction.
- **Mechanical engineering:** structure of turbulence in sheared flows.
- **Medicine:** reconstructing 3-D shape from biplane angiocardialogram.
- **Operations research:** optimal resource allocation.
- **Physics:** partition function of 3-D Ising model in statistical mechanics.
- **Politics:** Shapley-Shubik voting power.
- **Statistics:** optimal experimental design.

Practical applications of NP-completeness



“I can’t find an efficient algorithm, but neither can all these famous people.”

[Garey & Johnson, Computers and Intractability: A Guide to the Theory of NP-Completeness, Freeman, 1979.]

Satisfiability Problem (SAT)

Satisfiability problem: given a logical expression Φ , find an assignment of values (F, T) to variables x_i that causes Φ to evaluate to T

$$\Phi = x_1 \vee \neg x_2 \wedge x_3 \vee \neg x_4$$

- **boolean variables:** take on values T or F
 - Ex: x, y
- **literal:** variable or negation of a variable
 - Ex: $x, \neg x$ (also denoted by \bar{x})

Logical Operands

- $x = \{0,1\}$ or $\{F,T\}$

Not

x	$\neg x$ (negation)
0	1
1	0

And

x_1	x_2	$x_1 \wedge x_2$ (AND)
1	1	1
1	0	0
0	1	0
0	0	0

Or

x_1	x_2	$x_1 \vee x_2$ (OR)
1	1	1
1	0	1
0	1	1
0	0	0

Satisfiability Problem (SAT)

- **Satisfiability problem:** given a logical expression Φ , find an assignment of values (F, T) to variables x_i that causes Φ to evaluate to T

$$\Phi = x_1 \vee \neg x_2 \wedge x_3 \vee \neg x_4$$

- SAT is in NP: given a value assignment, check the Boolean logic of Φ evaluates to True (linear time)
- SAT was the first problem shown to be NP-complete! (**Cook–Levin theorem**)

CNF Satisfiability

- CNF is a special case of SAT
- Φ is in “Conjunctive Normal Form” (CNF)
 - “AND” of expressions (i.e., clauses)
 - Each clause contains only “OR”s of the variables and their negations

E.g.: $\Phi = (x_1 \vee x_2) \wedge (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee \neg x_2)$

clauses



SAT-CNF is NP-Complete

In the following, SAT means SAT-CNF

Definition of 3SAT / 3CNF

- A subcase of CNF problem:
 - Contains **three** literals per clause
- E.g.:
 - $\Phi = (x_1 \vee \neg x_1 \vee \neg x_2) \wedge (x_3 \vee x_2 \vee x_4) \wedge (\neg x_1 \vee \neg x_3 \vee \neg x_4)$
- **Is 3SAT in NP?**
 - Yes, because SAT is in NP. Also easy to prove it directly.
- **Is 3SAT NP-complete?**
 - Not obvious. It has a more regular structure, which can perhaps be exploited to get an efficient algorithm
 - In fact, 2SAT does have a polynomial time algorithm

Showing 3SAT is NP-Complete by Reduction

- (1) To show 3SAT is in NP:
 - A certificate is a truth (0/1) assignment to the variables
 - Certifier: check that each clause has at least one literal set to true according to the certificate
- (2) Choose SAT as known NP-complete problem
- (3) Describe a reduction from SAT inputs to 3SAT inputs
 - Computable in poly time
 - SAT input is satisfiable iff constructed 3SAT input is satisfiable
- (3a) Transform I_1 (instance of SAT) into I_2 (instance of 3SAT) in polynomial time
- (3b,3c) Prove that I_1 has a solution $\Leftrightarrow I_2$ has a solution

(3a) Reduction from SAT to 3SAT: $I_1 \rightarrow I_2$

- We are given an arbitrary CNF formula $C = c_1 \wedge c_2 \wedge \dots \wedge c_m$ over set of variables U , this is instance I_1
 - each c_i is a clause (disjunction of literals)
- We will replace each clause c_i with a set of clauses C_i' , and may use some extra variables U_i' just for this clause
- Each clause in C_i' will have exactly 3 literals
- Transformed input will be conjunction of all the clauses in all the C_i' , this is an instance I_2 of 3SAT
- New clauses are carefully chosen...

(3a) Reduction from SAT to 3SAT: $I_1 \rightarrow I_2$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$ (the z 's are literals)

- Case 1: $k = 1$.

- E.g. $c_i = z_1$
- Use extra variables y_i^1 and y_i^2 .
- Replace clause c_i with 4 clauses:

$$(z_1 \vee \overline{y_i^1} \vee y_i^2)$$

$$(z_1 \vee y_i^1 \vee \overline{y_i^2})$$

$$(z_1 \vee \overline{y_i^1} \vee \overline{y_i^2})$$

$$(z_1 \vee y_i^1 \vee y_i^2)$$

z_1 can be replaced by the intersection of these 4 clauses

- Note that no matter what values we give the y variables, in one of the 4 clauses we will be forced to use z_1 to satisfy it

(3a) Reduction from SAT to 3SAT: $I_1 \rightarrow I_2$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 2: $k = 2$.
 - E.g. $c_i = z_1 \vee z_2$
 - Use extra variable y_i^1 .
 - Replace c_i with 2 clauses:

$$(z_1 \vee z_2 \vee \overline{y_i^1})$$

$$(z_1 \vee z_2 \vee y_i^1)$$

(3a) Reduction from SAT to 3SAT: $I_1 \rightarrow I_2$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 3: $k = 3$.
 - No extra variables are needed.
 - Keep c_i :
 $(z_1 \vee z_2 \vee z_3)$

(3a) Reduction from SAT to 3SAT: $I_1 \rightarrow I_2$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

(3a) Why is Reduction Poly Time?

- The running time of the reduction (the algorithm to compute the 3SAT formula C' , given the SAT formula C) is proportional to the size of C'
- Rules for constructing C' are simple to calculate

(3a) Size of New Formula

- **Original clause with 1 literal** becomes 4 clauses with 3 literals each (1 to 12 literals conversion)
- **Original clause with 2 literals** becomes 2 clauses with 3 literals each (2 to 6 literals conversion)
- **Original clause with 3 literals** becomes 1 clause with 3 literals
- **Original clause with $k > 3$ literals** becomes $k-2$ clauses with 3 literals each (k to $3(k-2)$ literals conversion)
- So new formula C' is only a constant factor larger than the original formula
 - total L literals in formula C to cL literals in C' , where c is a constant

(3bc) Correctness of Reduction

- Show that CNF formula C is satisfiable iff the 3-CNF formula C' constructed is satisfiable, i.e., $\text{sol}(I_1) \Leftrightarrow \text{sol}(I_2)$
- Step 3b (\Rightarrow) Suppose original CNF formula C is satisfiable, i.e., I_1 has a solution. That means it has a truth assignment A to the variables that make the formula C evaluate to true.
- Come up with a satisfying truth assignment for the reduced 3SAT formula C' , i.e., a solution to instance I_2 .
 - For variables in U , use same truth assignments as for C .
 - How to assign T/F to the new variables in C' ?

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = z_1$

- Case 1: $k = 1$.
- Use extra variables y_i^1 and y_i^2 .
 - Replace c_i with 4 clauses:

$$(z_1 \vee \overline{y_i^1} \vee y_i^2)$$

$$(z_1 \vee y_i^1 \vee \overline{y_i^2})$$

$$(z_1 \vee \overline{y_i^1} \vee \overline{y_i^2})$$

$$(z_1 \vee y_i^1 \vee y_i^2)$$

Since z_1 is true, it does not
matter how we assign
 y_i^1 and y_i^2

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = (z_1 \vee z_2)$

- Case 2: $k = 2$.
 - Use extra variable y_i^1 .
 - Replace c_i with 2 clauses:
 $(z_1 \vee z_2 \vee \overline{y_i^1})$
 $(z_1 \vee z_2 \vee y_i^1)$

Since either z_1 or z_2 is true,
it does not matter how we
assign y_i^1

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = z_1 \vee z_2 \vee z_3$

- Case 3: $k = 3$.
 - No extra variables are needed.
 - Keep c_i :
 $(z_1 \vee z_2 \vee z_3)$

No new variables.

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

If first true literal is z_1 or z_2 , set all y_i 's to false:
then all later clauses have a true literal

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

If first true literal is z_{k-1} or z_k , set all y_i 's to true:
then all earlier clauses have a true literal

(3b) Truth Assignment for New Var.: $\text{sol}(I_1) \Rightarrow \text{sol}(I_2)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

If first true literal is in between, set all earlier y_i 's to true
and set all later y_i 's to false

(3c) Correctness of Reduction: $\text{sol}(I_2) \Rightarrow \text{sol}(I_1)$

- (\Leftarrow) Suppose the newly constructed 3SAT formula C' is satisfiable, i.e., I_2 has a solution. We must show that the original SAT formula C is also satisfiable, i.e., I_1 has a solution.
- Use the same satisfying truth assignment for C as for C' (ignoring new variables).
- Show each original clause has at least one true literal in it.

$(3c) \text{ sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1$

- Case 1: $k = 1$.
- Use extra variables y_i^1 and y_i^2 .
 - Replace c_i with 4 clauses:

$$(z_1 \vee \overline{y_i^1} \vee y_i^2)$$

$$(z_1 \vee y_i^1 \vee \overline{y_i^2})$$

$$(z_1 \vee \overline{y_i^1} \vee \overline{y_i^2})$$

$$(z_1 \vee y_i^1 \vee y_i^2)$$

For every assignment of y_i^1 and y_i^2 ,
in order for all
4 clauses to have a true literal,
 z_1 must be true.

$(3c) \text{ sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = (z_1 \vee z_2)$

- Case 2: $k = 2$.
 - Use extra variable y_i^1 .
 - Replace c_i with 2 clauses:
 $(z_1 \vee z_2 \vee \overline{y_i^1})$
 $(z_1 \vee z_2 \vee y_i^1)$

For either assignment of y_i^1 ,
in order for both clauses
to have a true literal,
 z_1 or z_2 must be true.

$$(3c) \text{ sol}(I_2) \Rightarrow \text{sol}(I_1)$$

Let $c_i = z_1 \vee z_2 \vee z_3$

- Case 3: $k = 3$.
 - No extra variables are needed.
 - Keep c_i :
 $(z_1 \vee z_2 \vee z_3)$

No new variables.

$(3c) \text{ sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

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$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

Suppose in contradiction
all z_i 's are false.

(3c) $\text{sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

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$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

Suppose in contradiction
all z_i 's are false.
Then y_i^1 must be true.

(3c) $\text{sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

Suppose in contradiction
all z_i 's are false.
Then y_i^1 must be true.
Then y_i^2 must be true...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

(3c) $\text{sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

Suppose in contradiction
all z_i 's are false.
Then y_i^1 must be true.
Then y_i^2 must be true...

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

(3c) $\text{sol}(I_2) \Rightarrow \text{sol}(I_1)$

Let $c_i = z_1 \vee z_2 \vee \dots \vee z_k$

- Case 4: $k > 3$.
 - Use extra variables y_i^1, \dots, y_i^{k-3} .
 - Replace c_i with $k-2$ clauses:

$$(z_1 \vee z_2 \vee y_i^1)$$

$$(\overline{y_i^1} \vee z_3 \vee y_i^2)$$

$$(\overline{y_i^2} \vee z_4 \vee y_i^3)$$

...

Suppose in contradiction
all z_i 's are false.

Then y_i^1 must be true.

Then y_i^2 must be true...

...

So the last clause is False

...

$$(\overline{y_i^{k-5}} \vee z_{k-3} \vee y_i^{k-4})$$

$$(\overline{y_i^{k-4}} \vee z_{k-2} \vee y_i^{k-3})$$

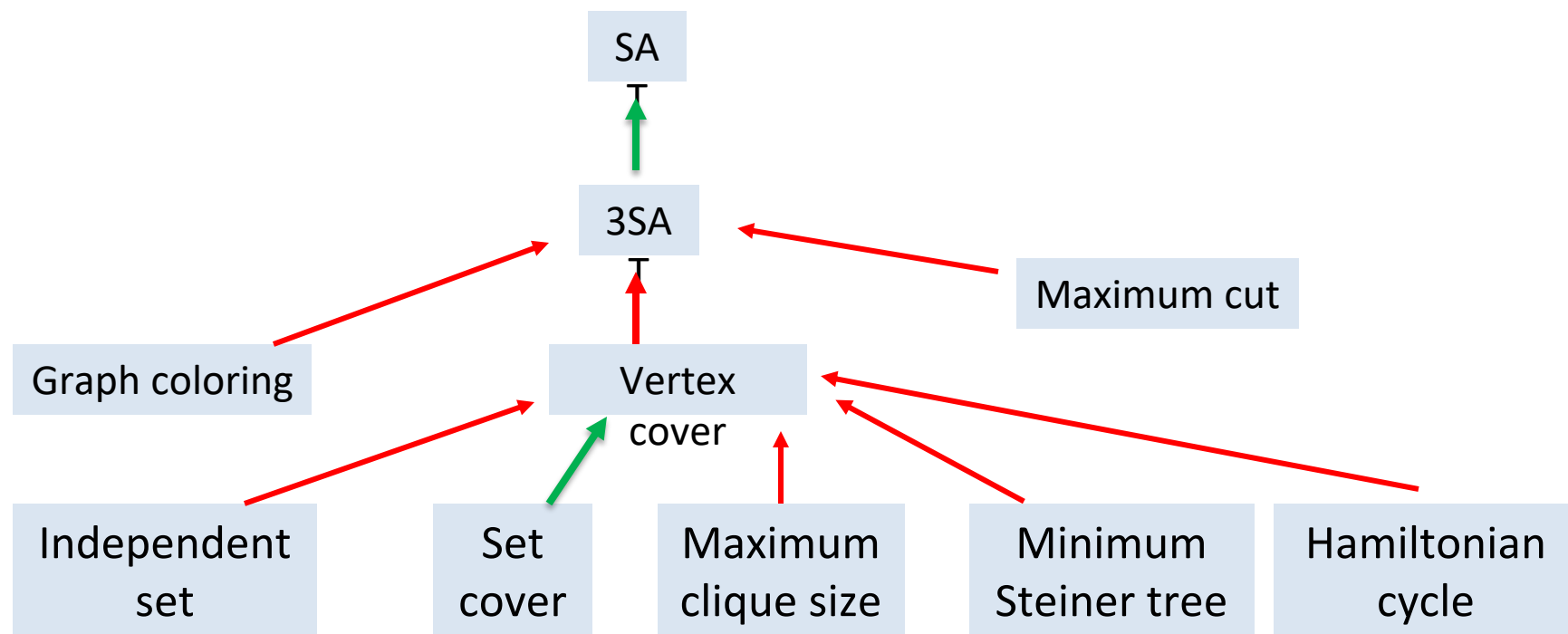
$$(\overline{y_i^{k-3}} \vee z_{k-1} \vee z_k)$$

Conclusion

- (1) 3SAT is in NP
- (2) We know that SAT is NPC, we want to prove that 3SAT is more difficult than SAT, hence $SAT \leq_p 3SAT$
- (3a) Take an instance I_1 of SAT, transform it in polynomial time into an instance I_2 of 3SAT
- (3b) Show that if I_1 has a solution, then I_2 has a solution
- (3c) Show that if I_2 has a solution, then I_1 has a solution
- 3SAT is NP-complete! This is your very first NP-completeness proof. Now you can do reductions from 3SAT.
- (All pbs in NP) $\leq_p SAT \leq_p 3SAT$

Examples of NP-complete problems

Summary of some NPC problems



find more NP-complete problems in

- http://en.wikipedia.org/wiki/List_of_NP-complete_problems
- **Garey-Johnson: Computers and Intractability: A Guide to the Theory of NP-Completeness**

Genres of NP-complete problems

- Six basic genres of NP-complete problems and paradigmatic examples.
 - **Packing problems**: SET-PACKING, **INDEPENDENT SET**.
 - **Covering problems**: SET-COVER, VERTEX-COVER.
 - **Constraint satisfaction problems**: SAT, 3-SAT.
 - **Sequencing problems**: HAMILTONIAN-CYCLE, TSP.
 - **Partitioning problems**: 3-COLOR, 3D-MATCHING.
 - **Numerical problems**: 2-PARTITION, SUBSET-SUM, KNAPSACK.