



```
{
  if (driving_mode == Chassis::COMPLETE_AUTO_DRIVE) {
    driving_mode = Chassis::AUTO_STEER_ONLY;
    gear_control_command.gear_location();
    throttle_control_command.throttle();
    acceleration_control_command.acceleration();
    brake_control_command.brake();
    setpbrake(control_command);
    setthrottle(control_command);
  }

  if (driving_mode == Chassis::COMPLETE_AUTO_DRIVE) {
    driving_mode = Chassis::AUTO_STEER_ONLY;
    control_command.has_steer() {
      setturn(control_command);
      setturnsignal(control_command);
      setbrake(control_command);
    }
  }

  return ErrorCode::OK;
}
```