### Recovery and analysis of intra-site spatial data

#### **Issues:**

- 1. Locations of activities what happened where and why?
- 2. Locations of social groups who lived where and why? -class, gender, ethnicity, etc.

#### Sources of data:

- 1. patterns in the location of features: *site structure* 
  - -buildings
  - -pits
  - -fences
- 2. patterns in the horizontal distribution of artifacts

#### Multiple spatial scales:

- -meters x 1/10
- -meters
- -meters x 10
- -meters x 100 ...
- -But which is right? (see O'Connell 1993)

### Patterns in the horizontal distribution of artifacts

### 1. The spatial data recovery process

- Model how we collect spatial data.

#### 2. The analysis process

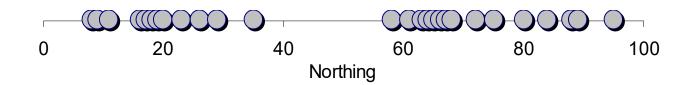
- Mapping raw data and statistical summaries of them.



# Creamware 3890900 Predicted Northing 60 40 20 3890800 11498600 11498650 11498700 11498750 11498800 Easting

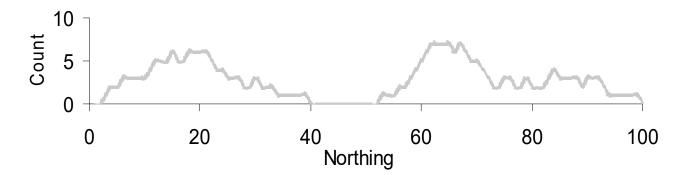
### Recovery

The Point Process:



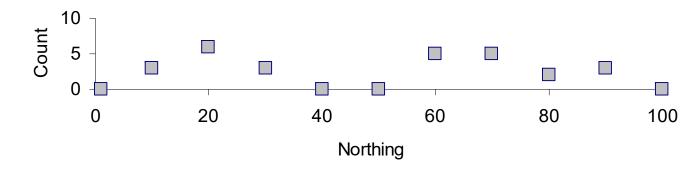
The Moving-Average Process:

(quadrat diameter=10)



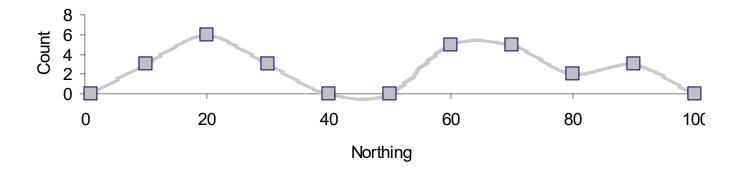
Sample the M-A Process

(quadrat spacing =10)



# **Analysis**

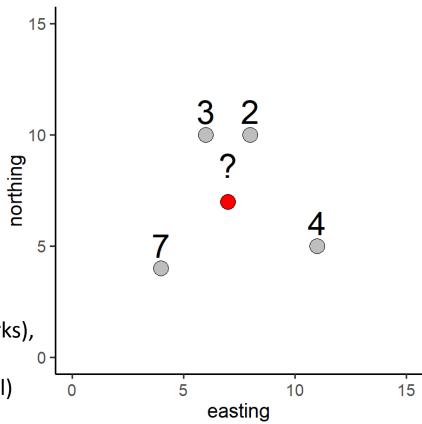
Estimate the M-A Process from the sample:



# Interpolation

#### Many methods...

- 1. Inverse distance weighting (IDW)
- 2. Kriging
- 3. Others
- -TINs (triangulated irregular networks),
- -splines (radial basis functions)
- -polynomial regression (local, global)



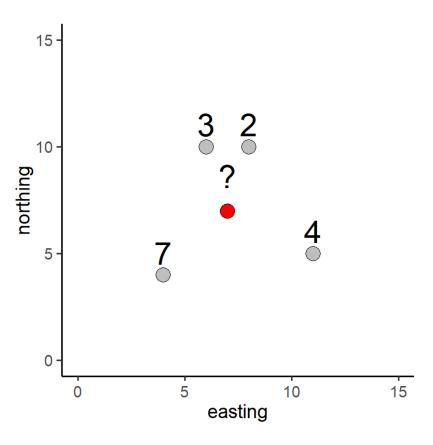
1. and 2. both make estimates of value of the z variable at an unsampled point in (x,y) space, as a **weighted average of the values at nearby points**, where z values are known.

So....

$$\hat{z}_j = \frac{\sum_{i=1}^n w_i z_i}{\sum_{i=1}^n w_i}$$

# **Inverse Distance Weighting**

$$w_i = \frac{1}{d_{ij}}^p$$

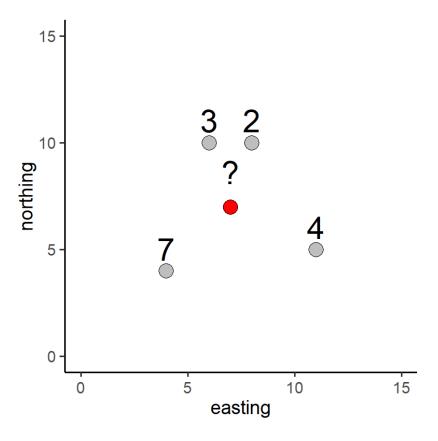


Point ID	northing	easting	Z	$Distance = d_{ij}$	$w_i=1/d_{ij}$	$W_i^*Z$	
1	11	5	4	4.47	0.22	0.89	
2	6	10	3	3.16	0.32	0.95	
3	8	10	2	3.16	0.32	0.63	
4	4	4	7	4.24	0.24	1.65	
Sum					1.09	4.13	

5 7 7

# **Inverse Distance Weighting**

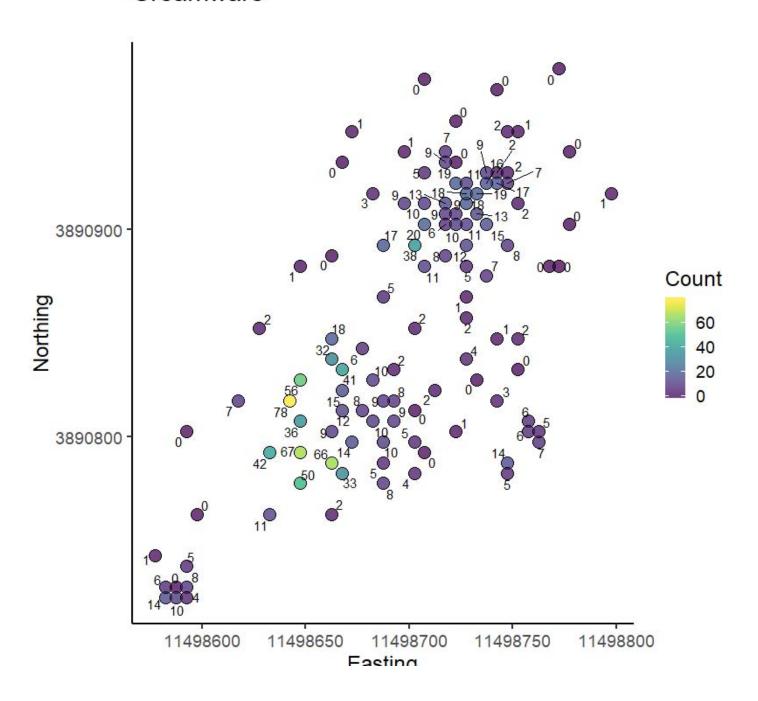
$$w_i = \frac{1}{d_{ij}}^p$$

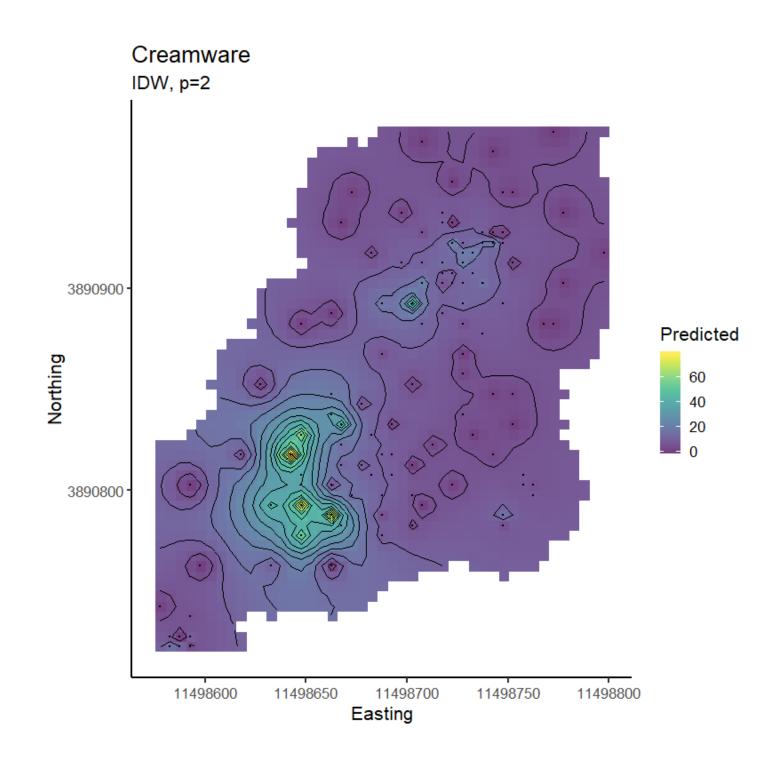


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5 7 
$$7.4.13/1.09 = 3.8$$

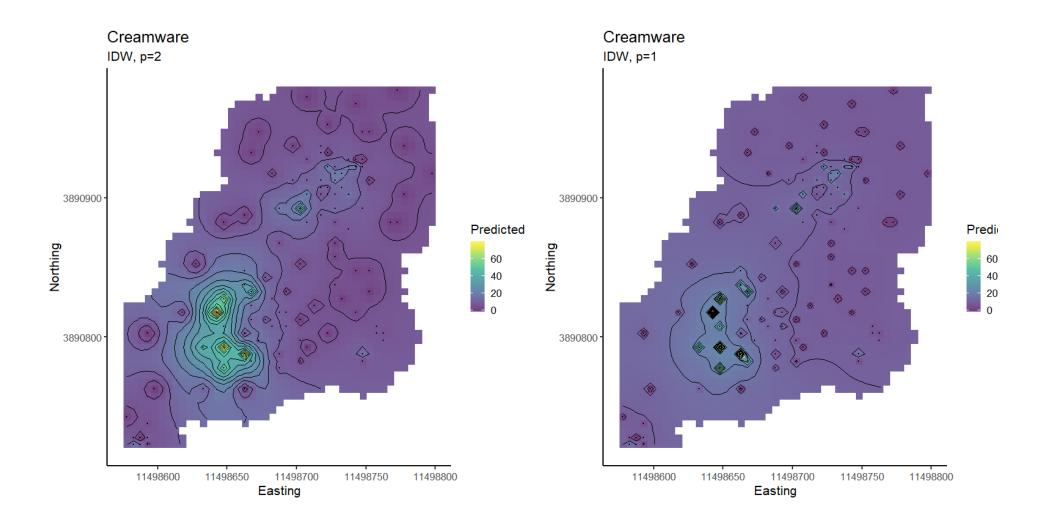
### Creamware





# **Pesky Questions about IDW**

- what value for *p*?

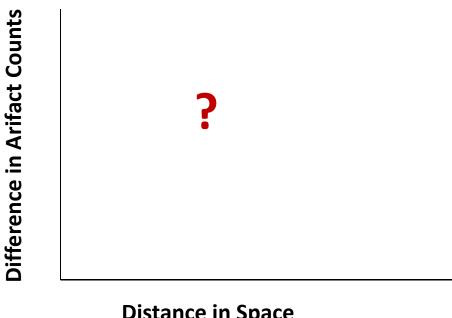


### **Doing Better than IDW**

- p should depend on the manner in which differences between z-values increase with *distances* between *x,y* coordinates....

#### "Spatial autocorrelation"

To what extent do quadrats that are farther apart in 2-d space (e.g. Easting and Northing) tend to have variable values (e.g. artifact counts) that are more different.



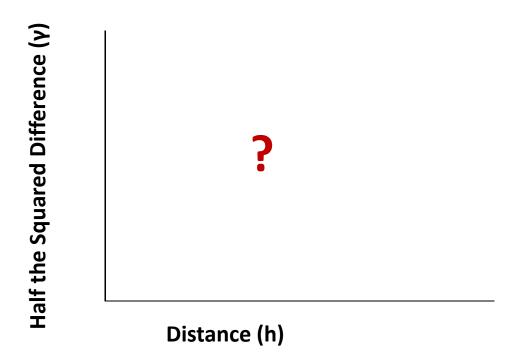
**Distance in Space** 

### **Kriging** (after D.R Krige)

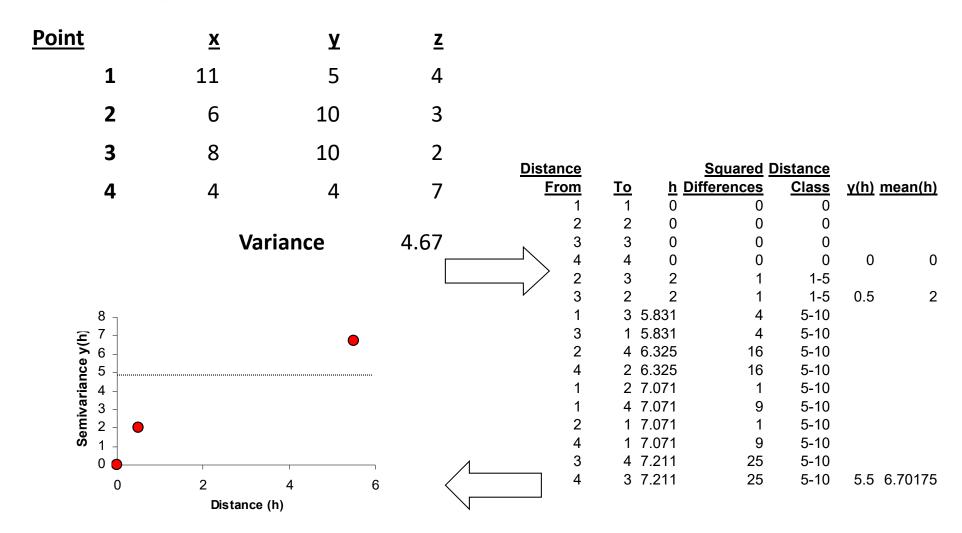
A weighted-averging interpolation method in which the **weights depend on the spatial autocorrelation structure of the data**, AND that produces estimates of Z that are designed to minimize mean-squared prediction error.

# Variogram

The graphical tool we use to measure the autocorrelation structure of spatial data.

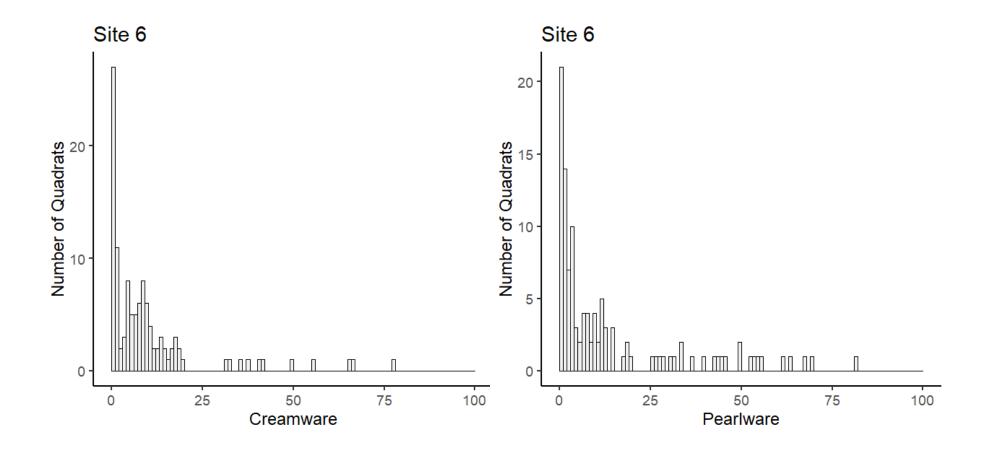


				Dis	stance			Squared
					<u>From</u>	<u>To</u>	<u>d</u>	<u>Differences</u>
<u>Point</u>	<u>X</u>	Y	<u>Z</u>		1	1	0	0
1	11	5	4	_	1	2	7.07	1
2	6	10	3		1	3	5.83	4
3	8	10	2	,	1	4	7.07	9
4	4	4	7		2	1	7.07	1
					2	2	0	0
					2	3	2	1
<b>30</b> ¬					2	4	6.32	16
<b>S</b> 25				•	3	1	5.83	4
20 - euce (			•		3	2	2	1
Half the Squared Differerence (y)				•	3	3	0	0
± □ 5 - 0 —	•		•		3	4	7.21	25
0	2	4	6	8	4	1	7.07	9
	D	istance	(h)		4	2	6.32	16
"The variogram cloud" — each graph point reoresent a difference-distance pair.					4	3	7.21	25
					4	4	0	0

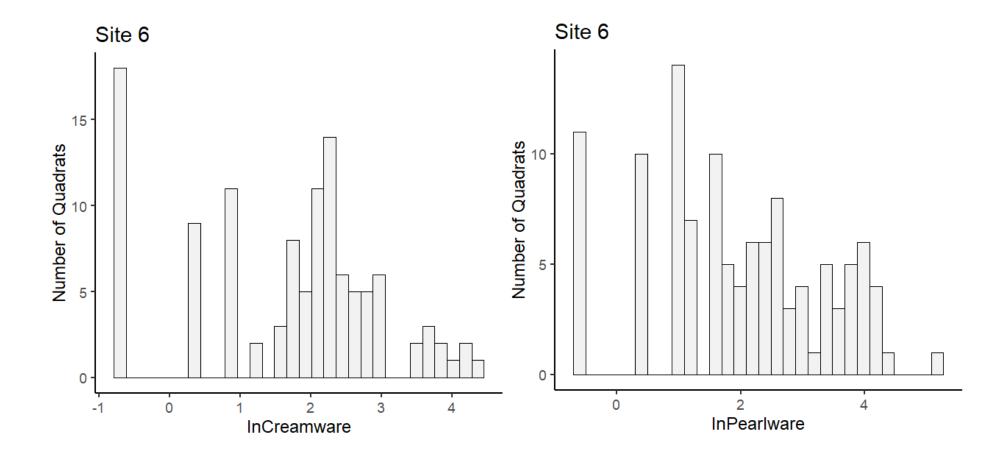


"The variogram" – each graph point represents the means of several difference-distance pairs.

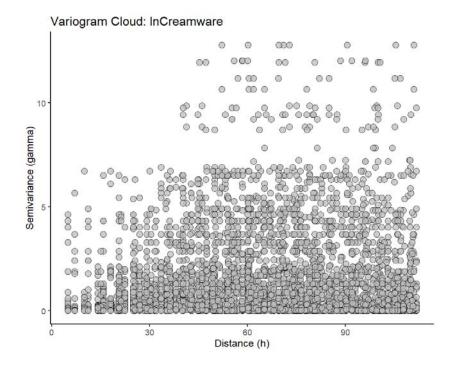
- The mathematical model behind the variogram and kriging assumes that the spatially distbuted variable has a normal of Gaussian distribution.
- But artifact counts always have long right tails...

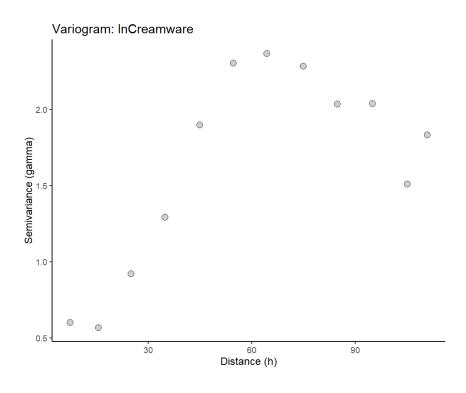


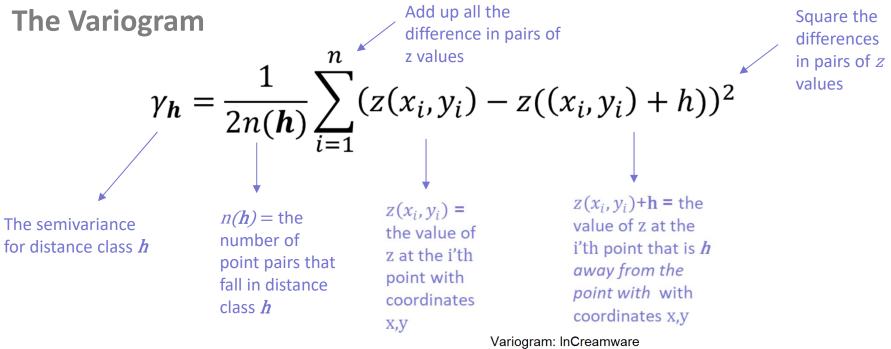
- Transforming the counts to a log scale helps.
- Because In(0) is undefined, we take logs of "started counts"
  - e.g. In(Creamware +.5)



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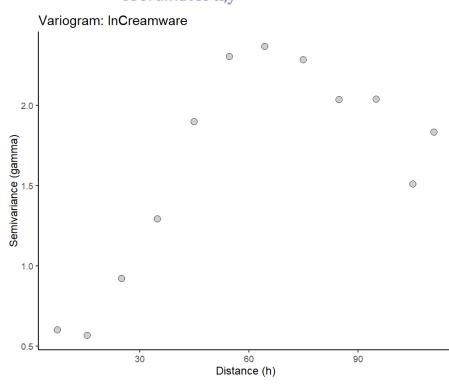




(x, y) are 2-d spatial coordinates (easting, northing)

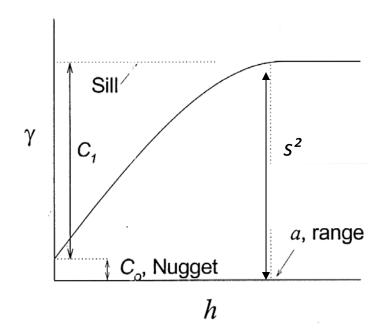
z is the variable value (artifact counts)

**h** is a distance and direction vector: "all the points that are a certain distance apart from the i'th x,y pair".

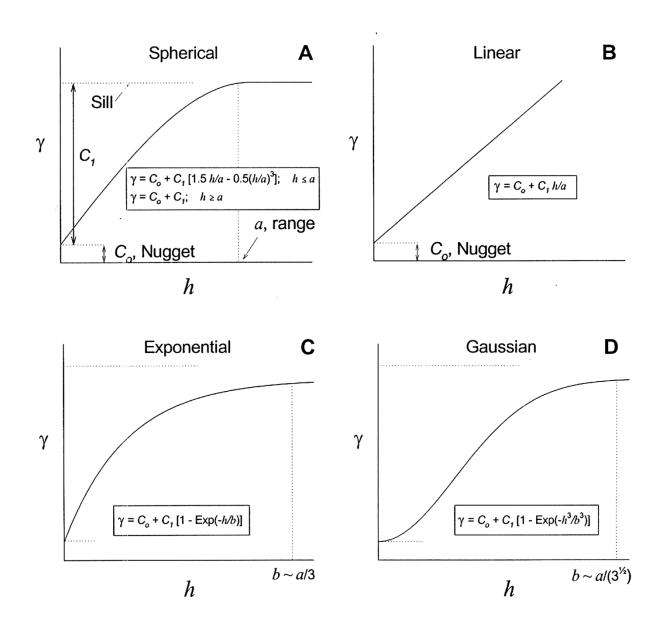


### Variogram Lingo

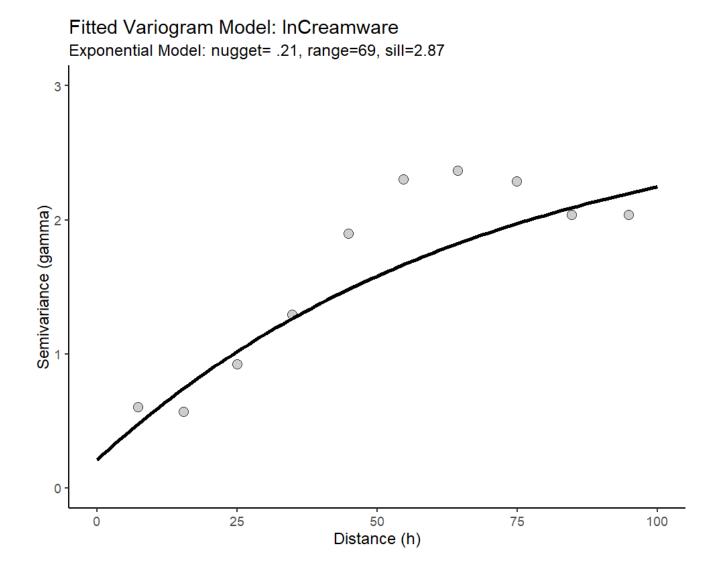
- **Sill**: for larger values of *h* the variogram levels out, indicating that there no longer is any auto correlation between data points.
- If the data are "well behaved" (Gaussian and stationary) the sill should be equal to the **variance** (s<sup>2</sup>) of the z values.
- Range: is the value of h where the sill occurs (or 95% of the value of the sill).
   This is the distance beyond which pairs of values are no longer autocorrelated.
- Nugget variance: a non-zero value for gamma when h = 0. Produced by various sources of unexplained error (e.g. measurement error).

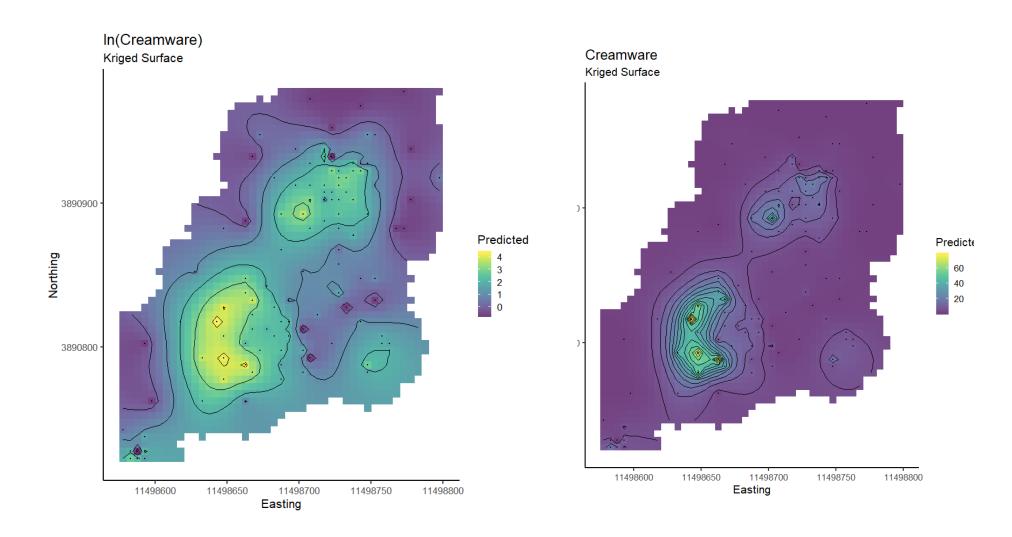


Variogram Models: Differently shaped curves, defined by different equations.



Variogram Models: Differently shaped curves, defined by different equations.





# The variogram is a useful spatial data analysis tool!!

You can use it during and excavation to see if your spatial sampling stratrgy is sufficient to capture spatial pattering

- Quadrat size (too small?)
- Quadrat spacing (too far part?)
- Given quadrat size and spacing is interpolation reasonable?

