



Turbulence Closure Modeling with Differentiable Physics

JULY 28, 2022

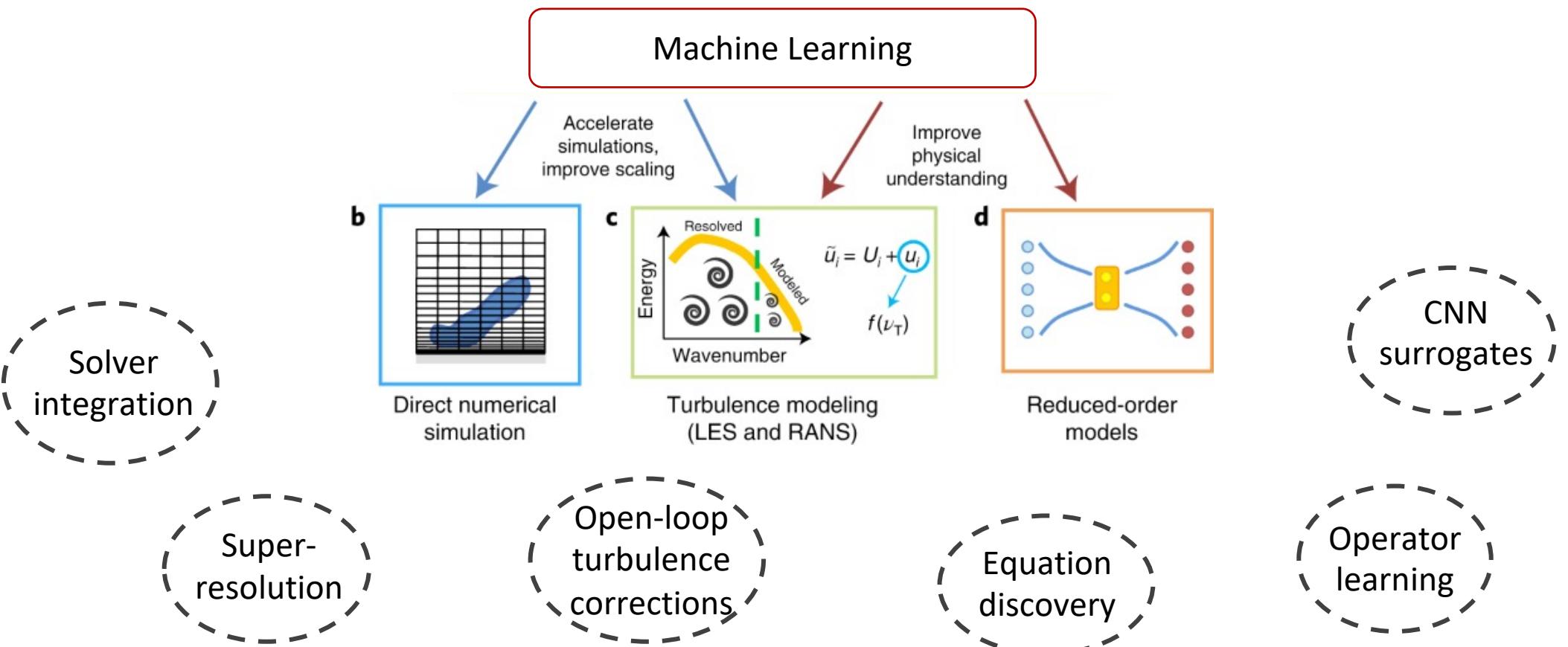
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Agenda

1. Motivation and background
2. Differentiable Neural Closures
 - Learning more accurate closure dynamics
3. Turbulence predictions with equivariant GNNs
 - Reducing time to solution for complex flows
4. Conclusions and future directions

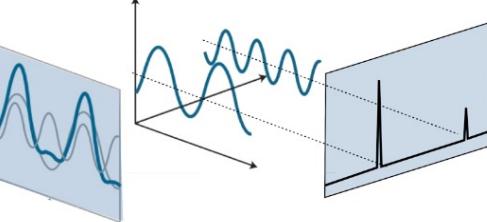
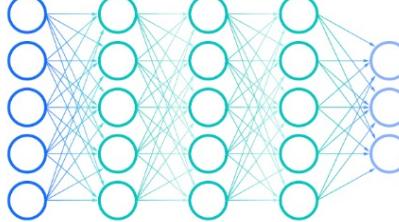
State of ML in CFD



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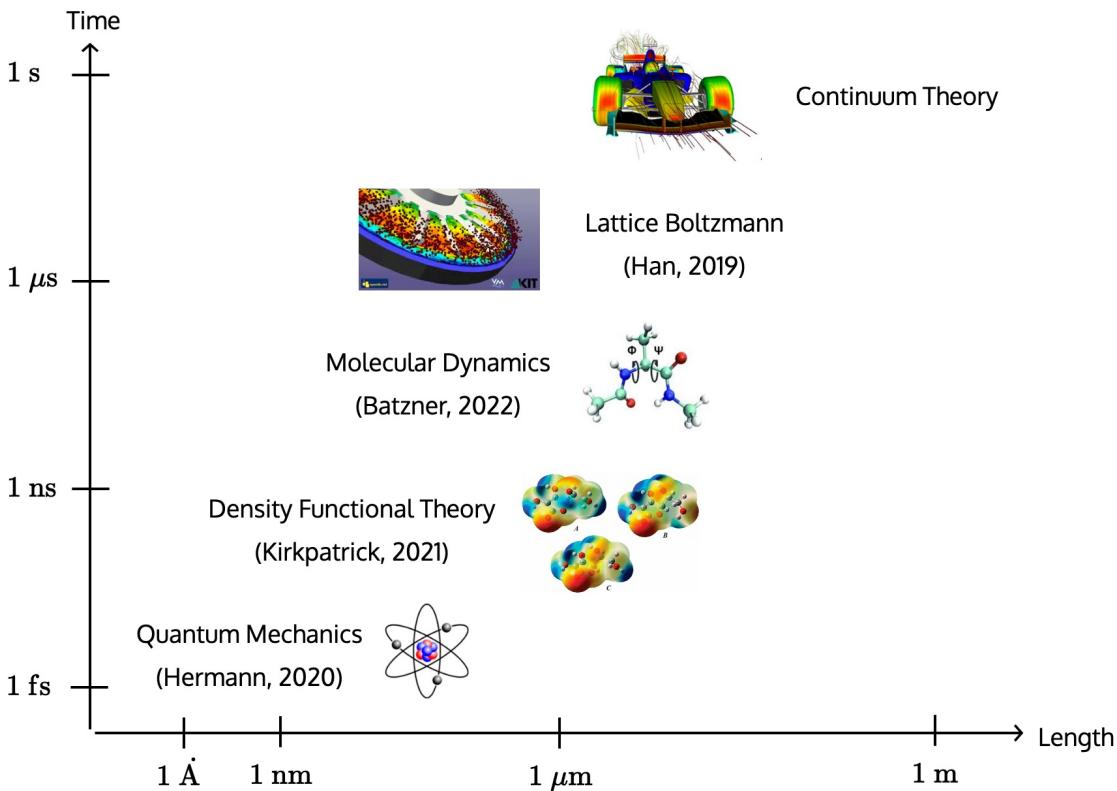
Approximation Theory and Curse of Dimensionality

$$f = \tilde{f} + \mathcal{O}(h)$$

Orthogonal Functions	Deep Neural Networks
$\tilde{f} = \sum_{i=1}^N f_i \phi_i(x)$ 	$\tilde{f} = W_L \circ \sigma(W_{L-1} \circ (\dots (\sigma W_0 x)) + b_{L-1})$ 
$h \sim N^{-c/d}$	$h \sim 1/N$ (for 2 layer networks)

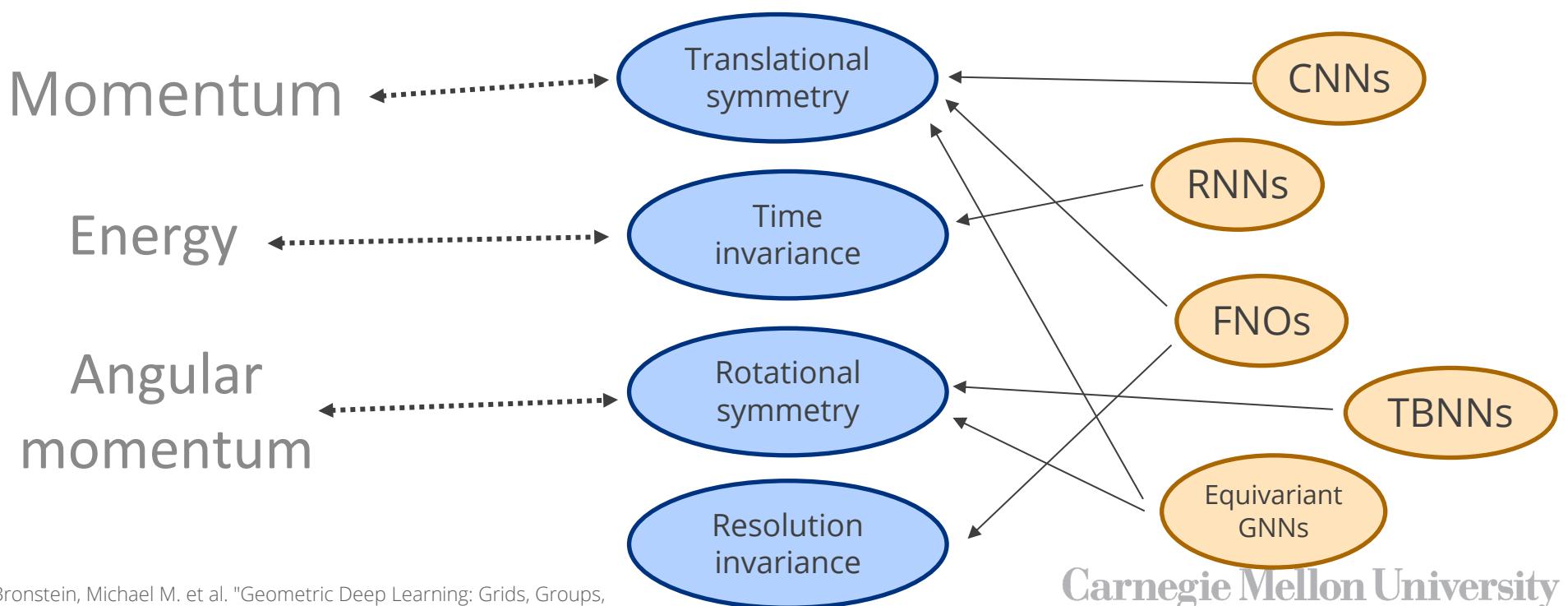
Curse of dimensionality Dimension independent

Machine Learning in Physics

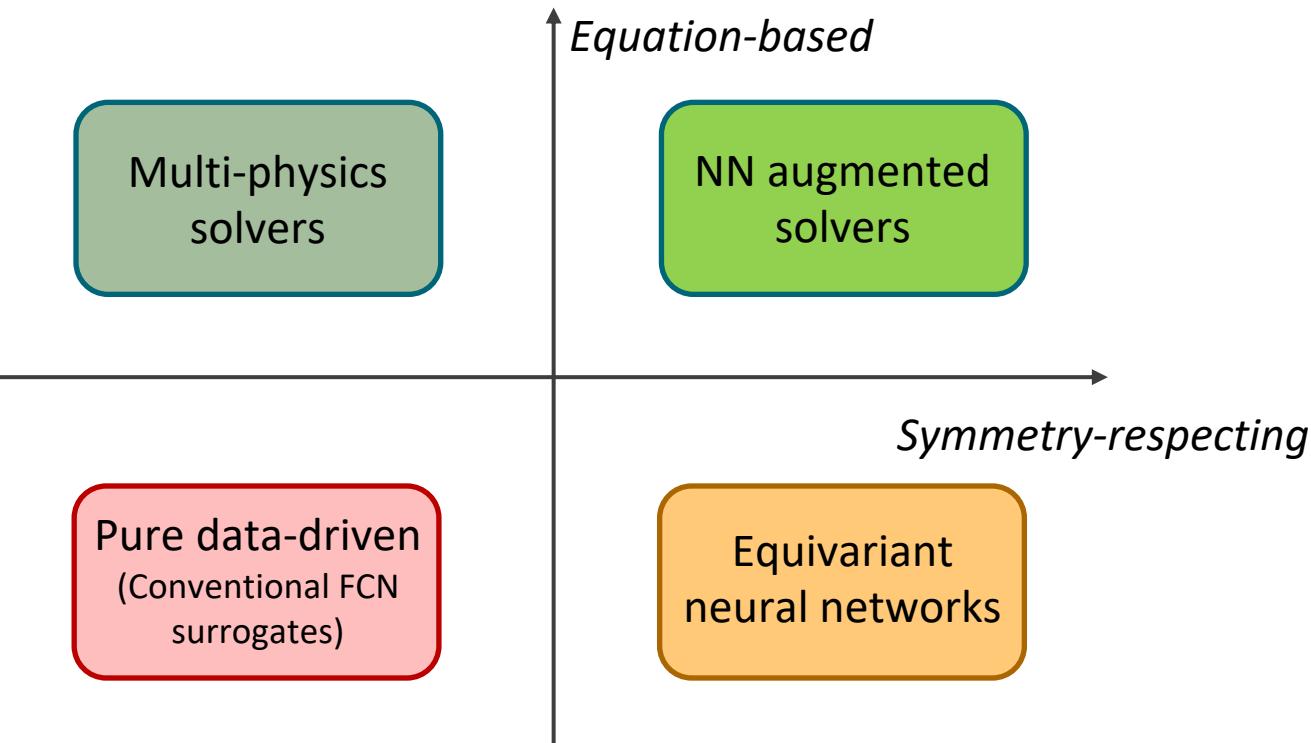


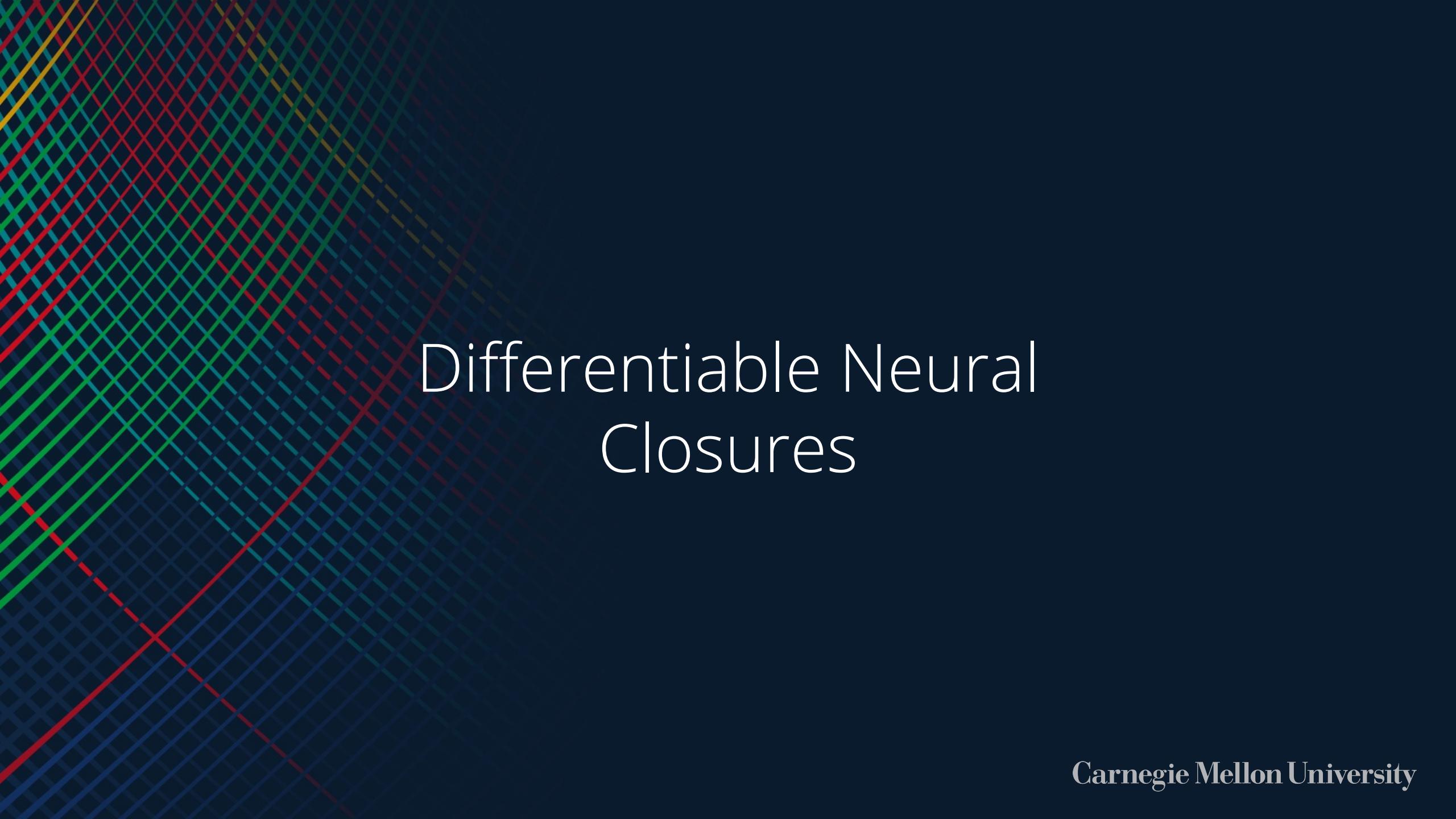
Conservation laws as embedded symmetries

Conservation laws \leftrightarrow Symmetries (Noether's theorem)



Data-driven physics represented as symmetries and equations





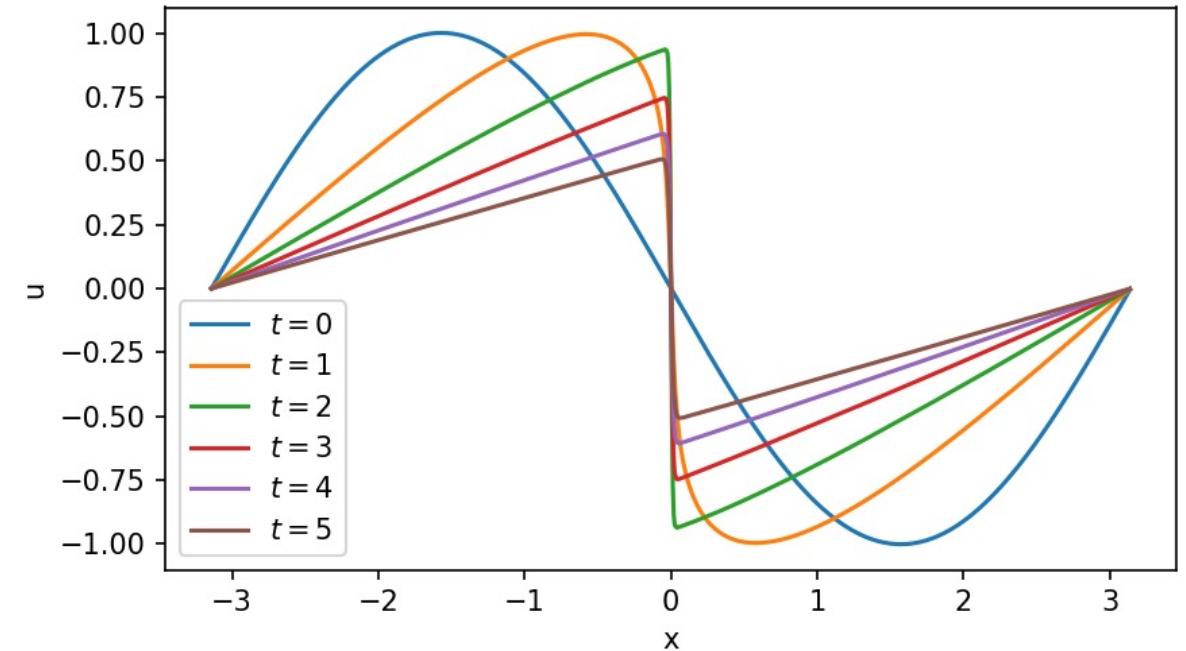
Differentiable Neural Closures

1D Viscous Burgers' Equation

$$\frac{\partial}{\partial t} u(x, t) = \nu \frac{\partial^2}{\partial x^2} u - u \frac{\partial}{\partial x} u$$

$$\bar{u}_t = \nu \bar{u}_{xx} - \bar{u} \bar{u}_x + \eta$$

$$\eta = \frac{\partial}{\partial x} (\nu_T \frac{\partial}{\partial x} \bar{u})$$





Adding structure to the model increases interpretability

$$\eta = f_\theta(\bar{u}; x, t)$$

$$\dot{\bar{u}} = \nu \nabla^2 \bar{u} - \bar{u} \nabla \bar{u} + \nabla (\nu_T \nabla \bar{u})$$

$$\dot{\nu}_T = \alpha_\theta(\bar{u}_x; x, t) \cdot \nu \nabla^2 \nu_T - \beta_\theta(\bar{u}_x; x, t) \cdot \bar{u} \nabla \nu_T$$

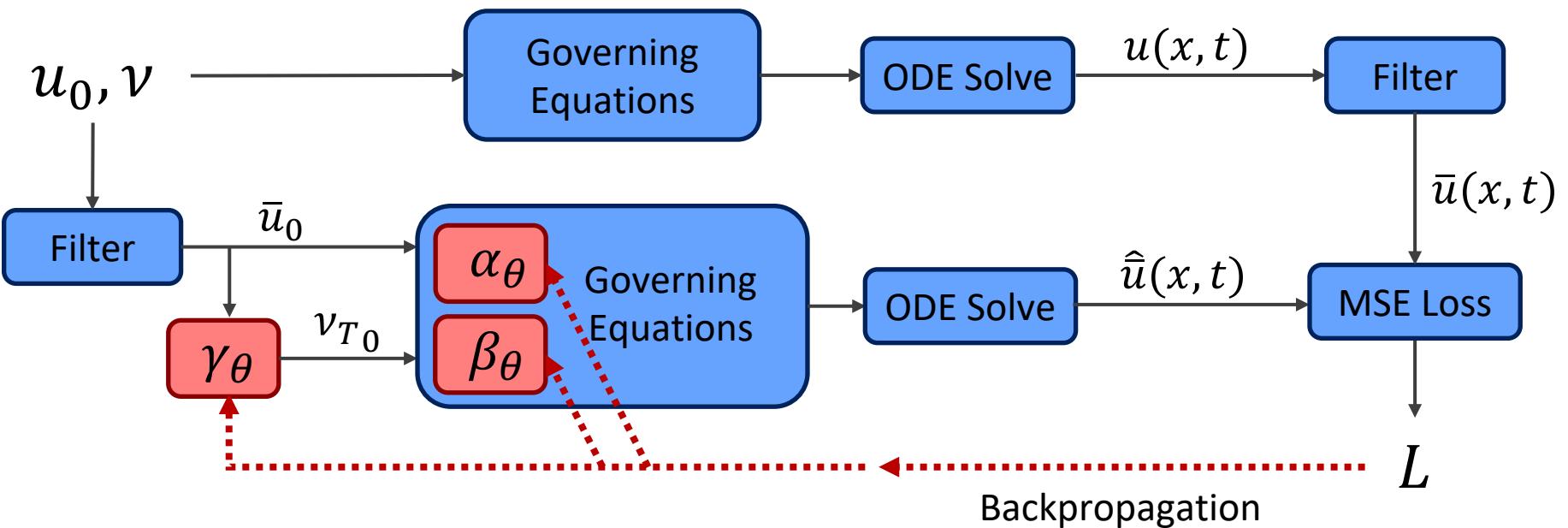
$$\nu_T(x, 0) = \gamma_\theta(\bar{u}_0, \nu; x)$$

*NNs operate in Fourier space

The need for a differentiable solver

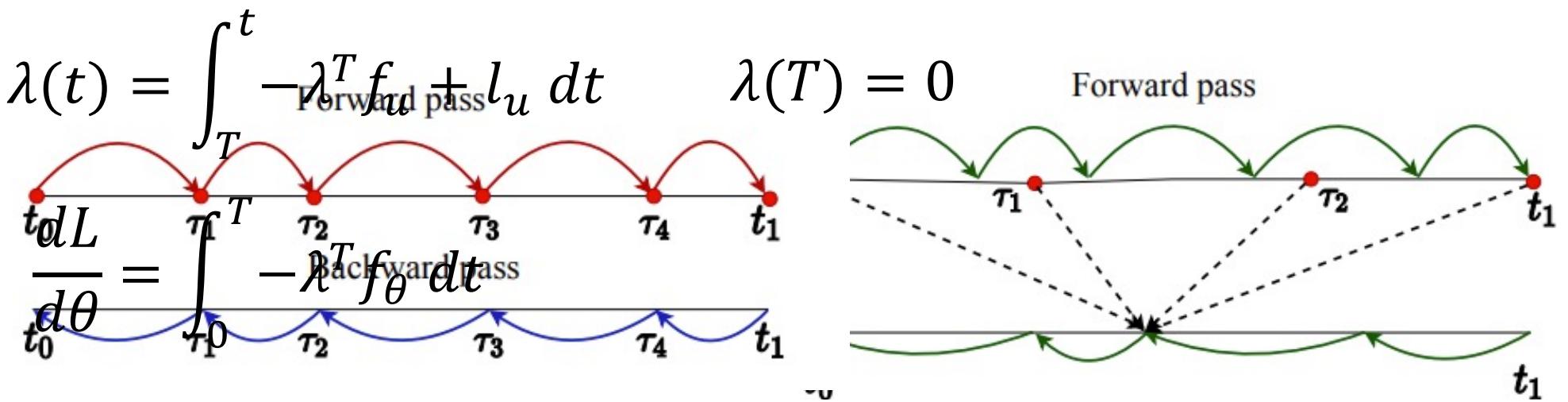
- We're learning a dynamical equation
- The simpler approach
 - Generate high-fidelity solutions
 - Filter solutions and compute closure term
 - Learn the function mapping \bar{u} to the closure term
- Want to learn a-posteriori velocity → evolve coupled system together during training

The need for a differentiable solver



Adjoint method

$$\dot{u} = f(u, \theta) \quad L(u) = \int_0^T l(u, t) dt$$

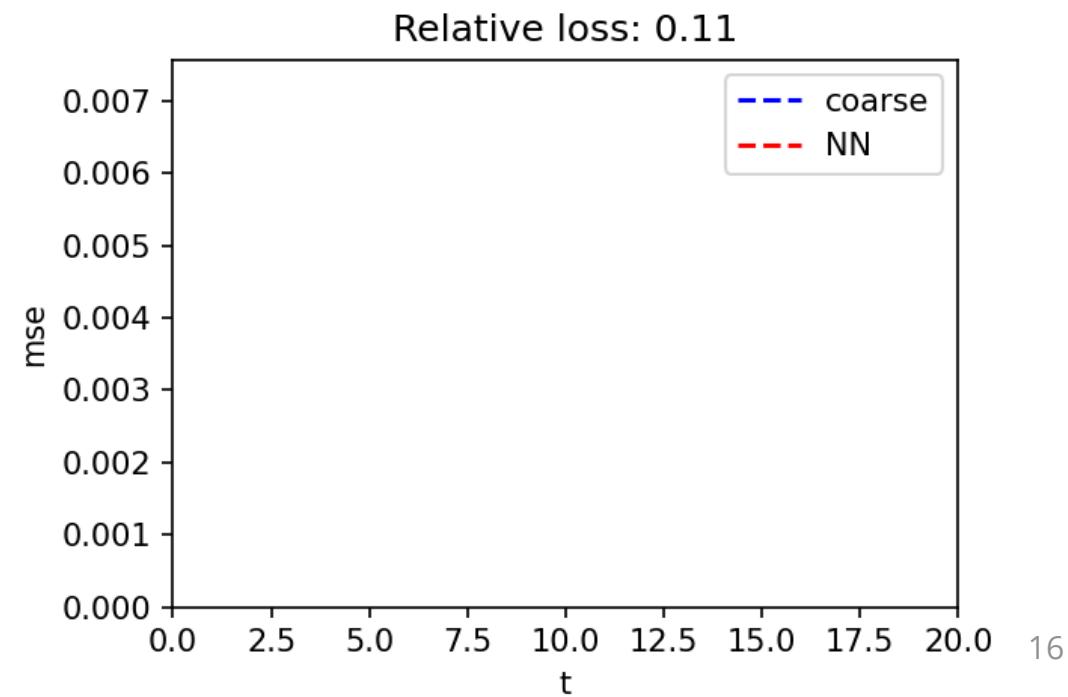
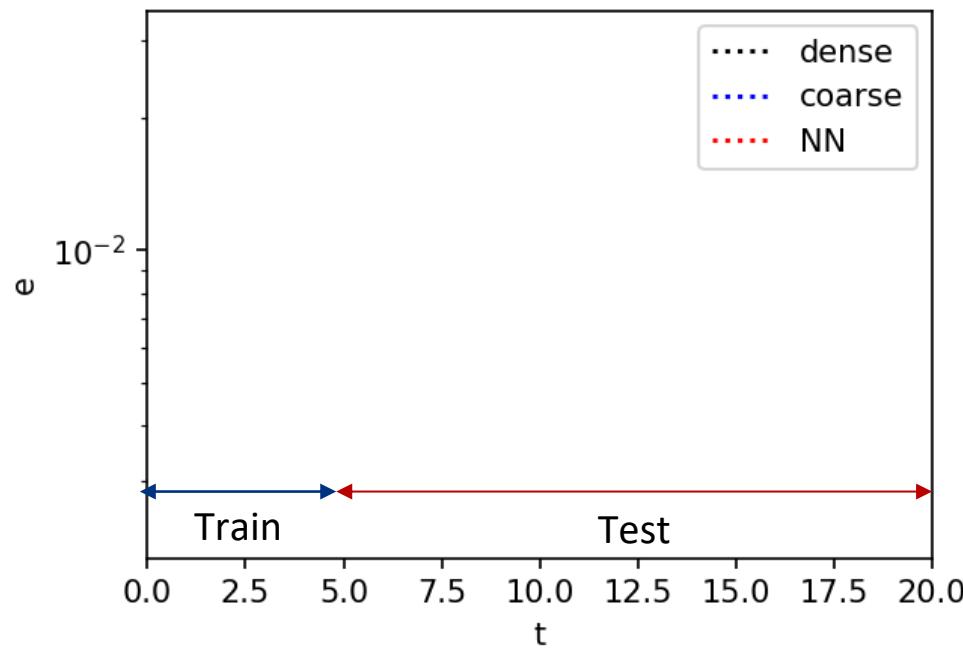
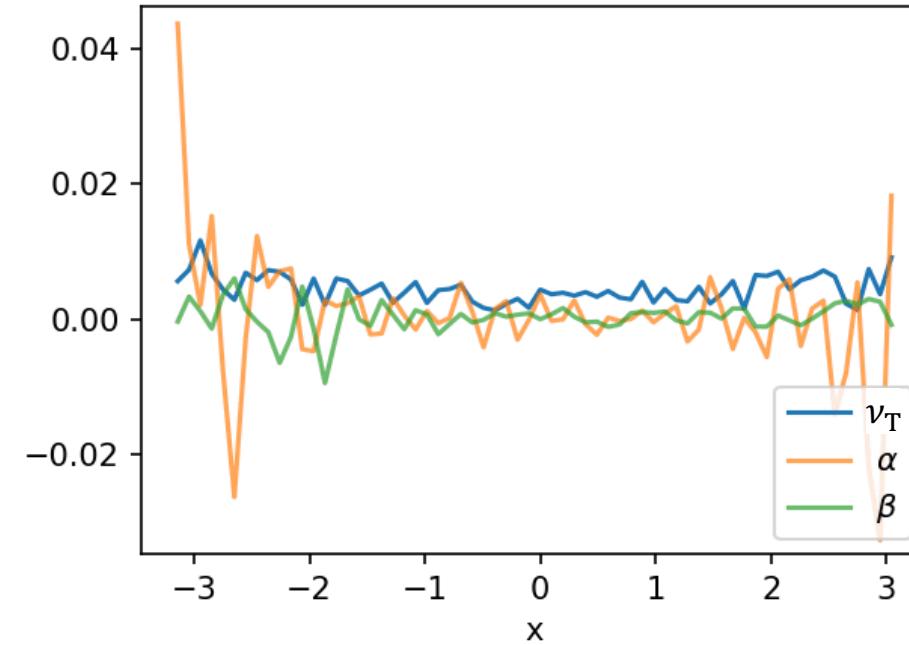
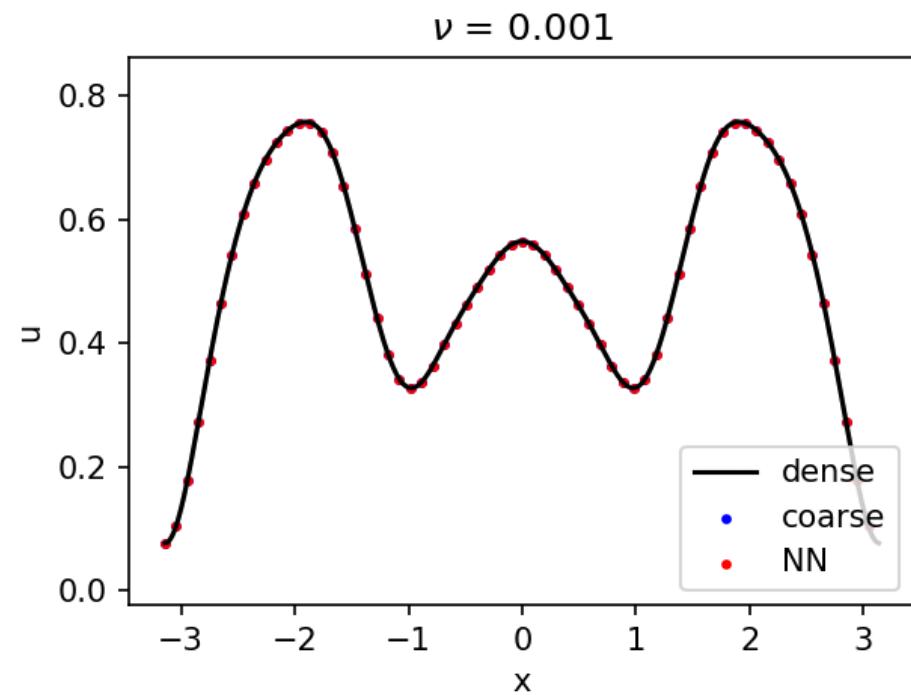


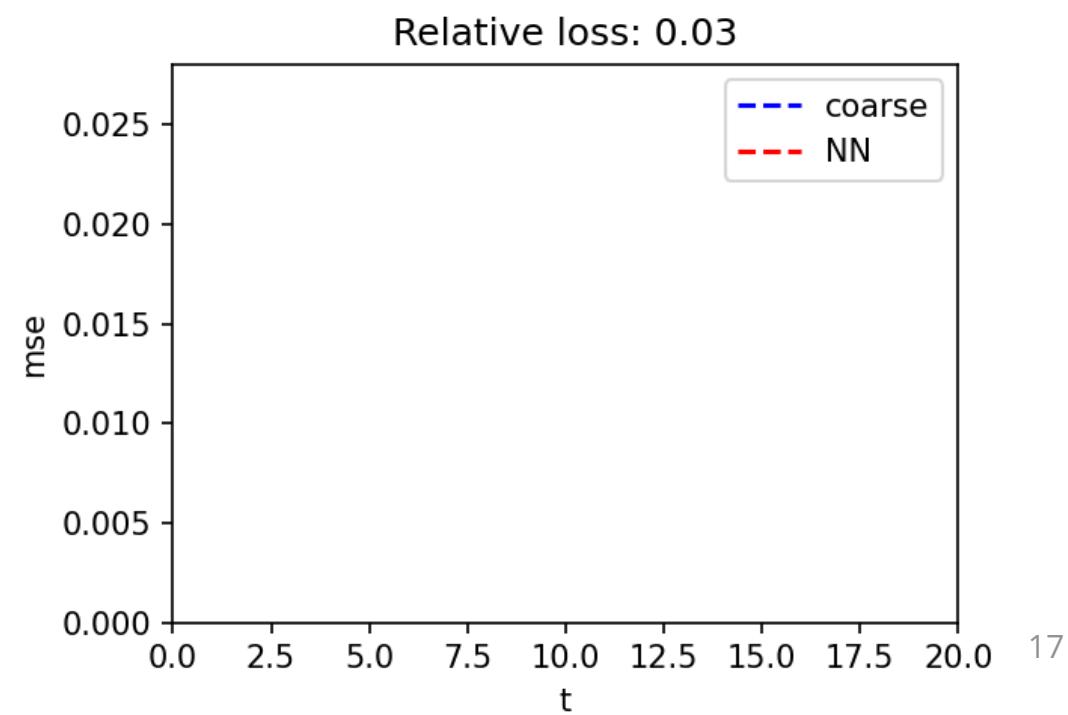
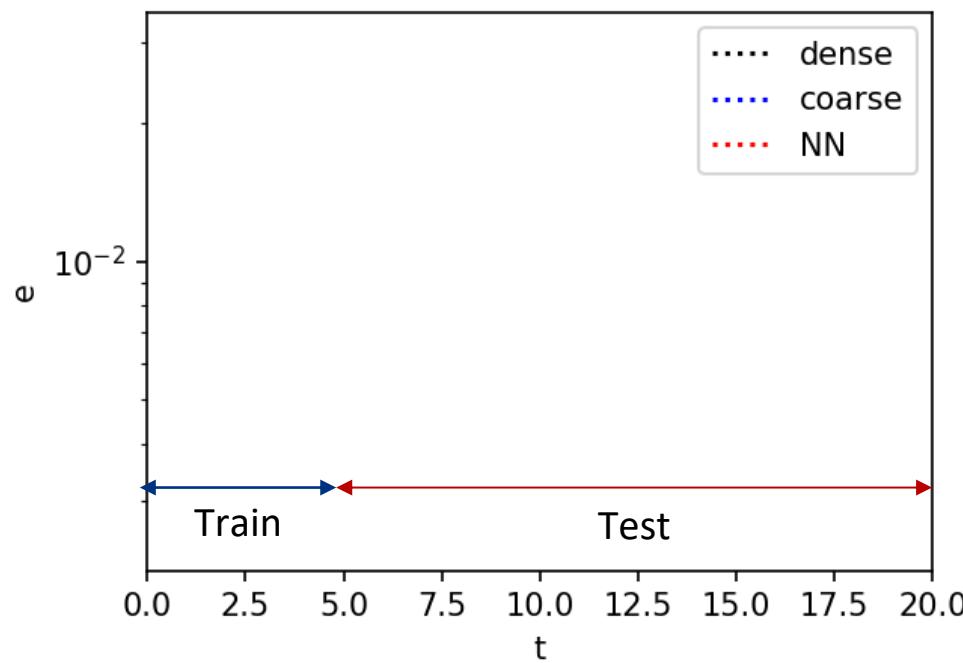
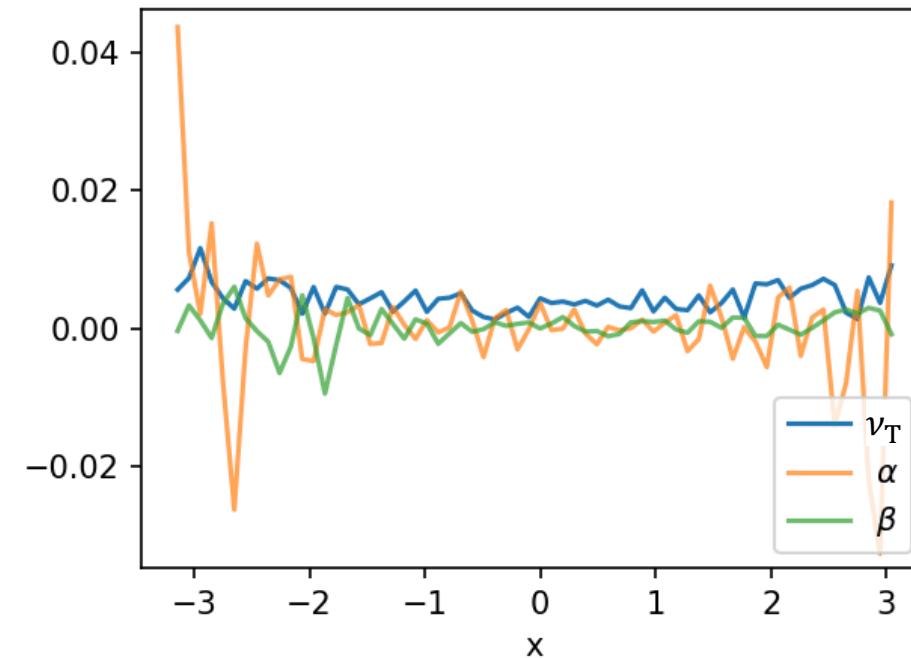
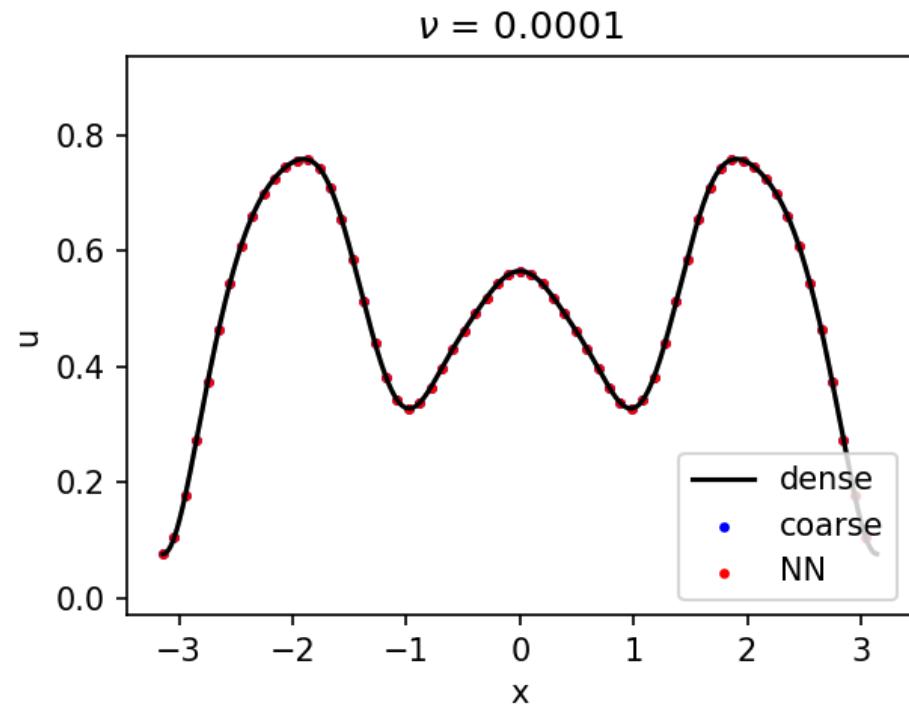
Learning methodology

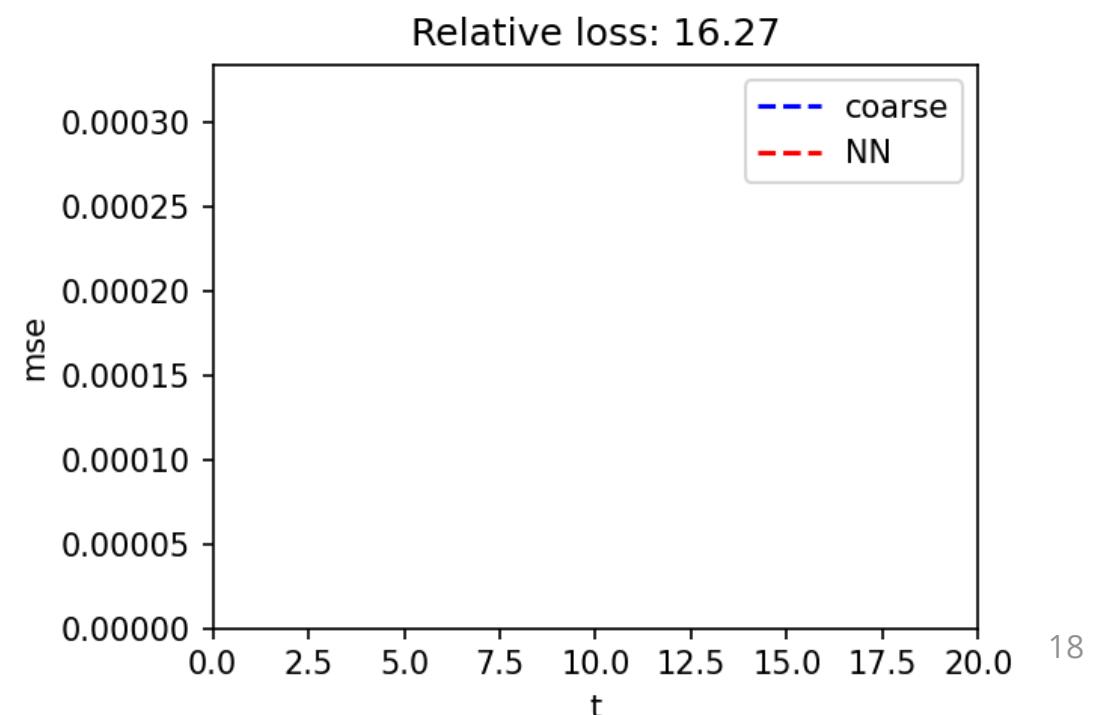
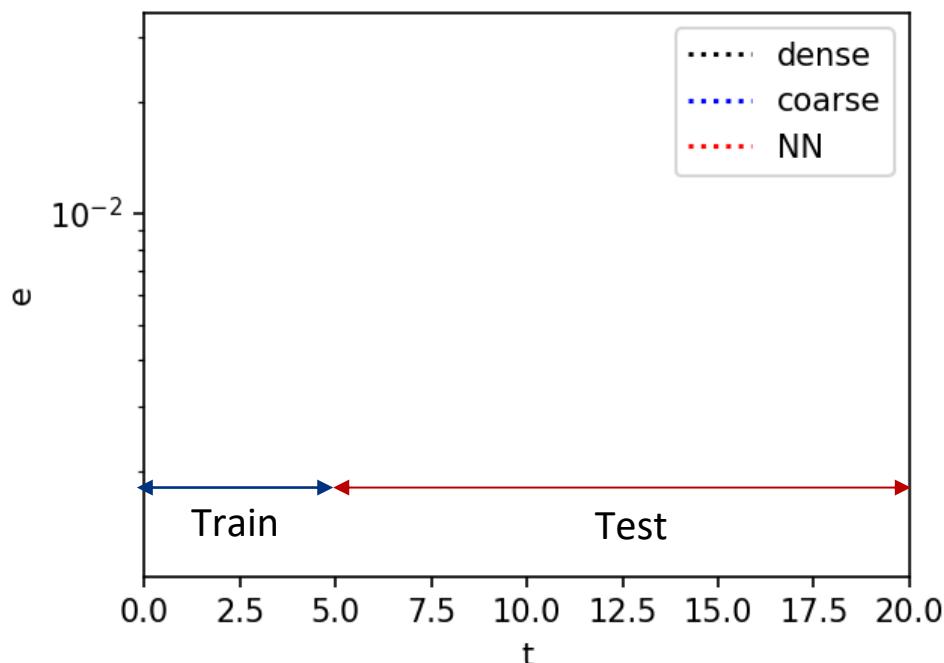
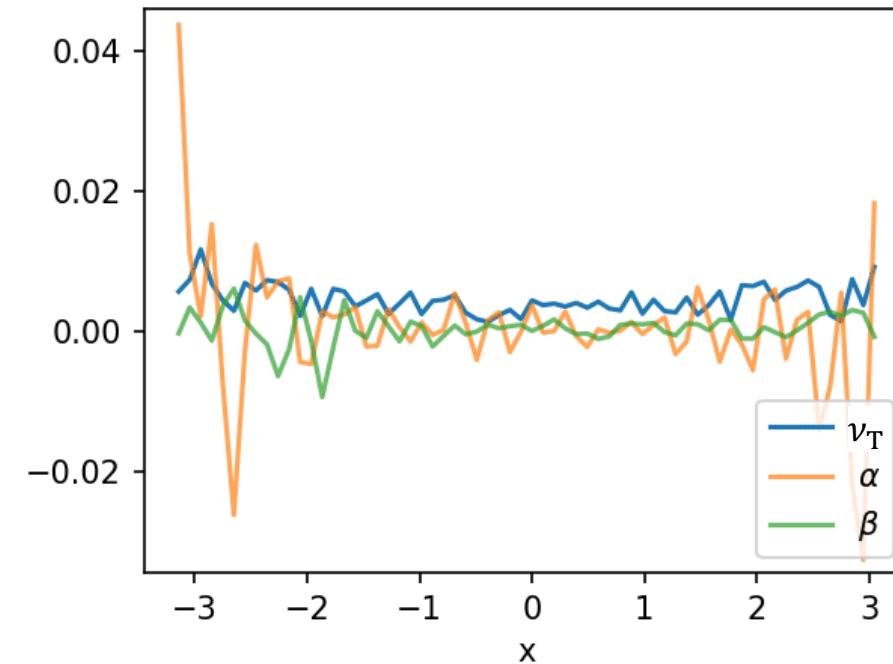
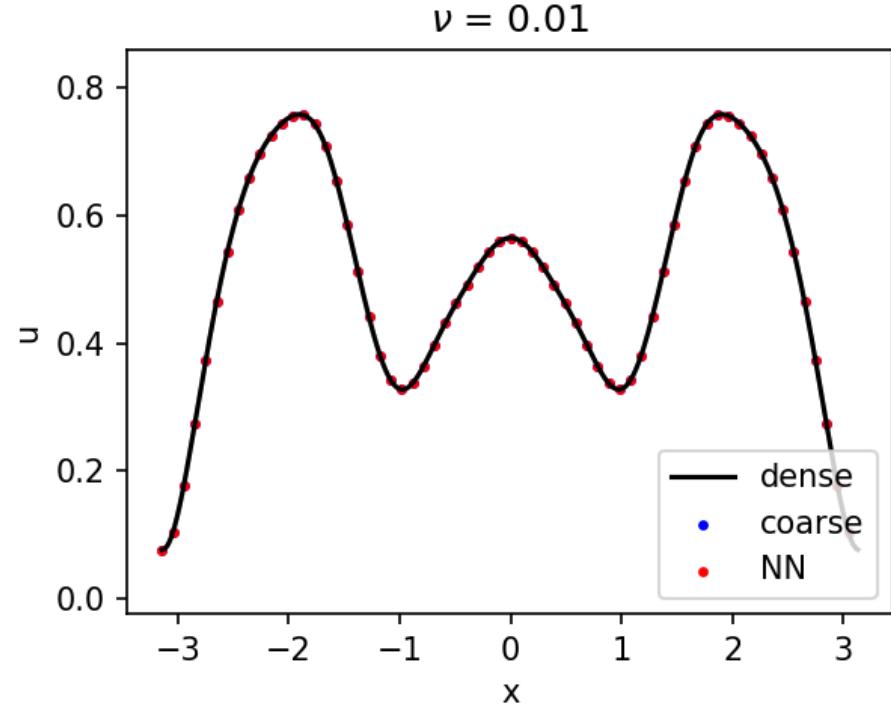
- Desire to learn a one-equation closure transport model for Burgers' equation
 - Neural network approximates ν_T IC and convection/diffusion coefficients of the transport equation in Fourier space
- Data generated on fully-resolving dense grid
- ODE system integrated to produce approximate velocity profiles
- Loss is backpropagated via adjoint method to compute NN parameter gradients

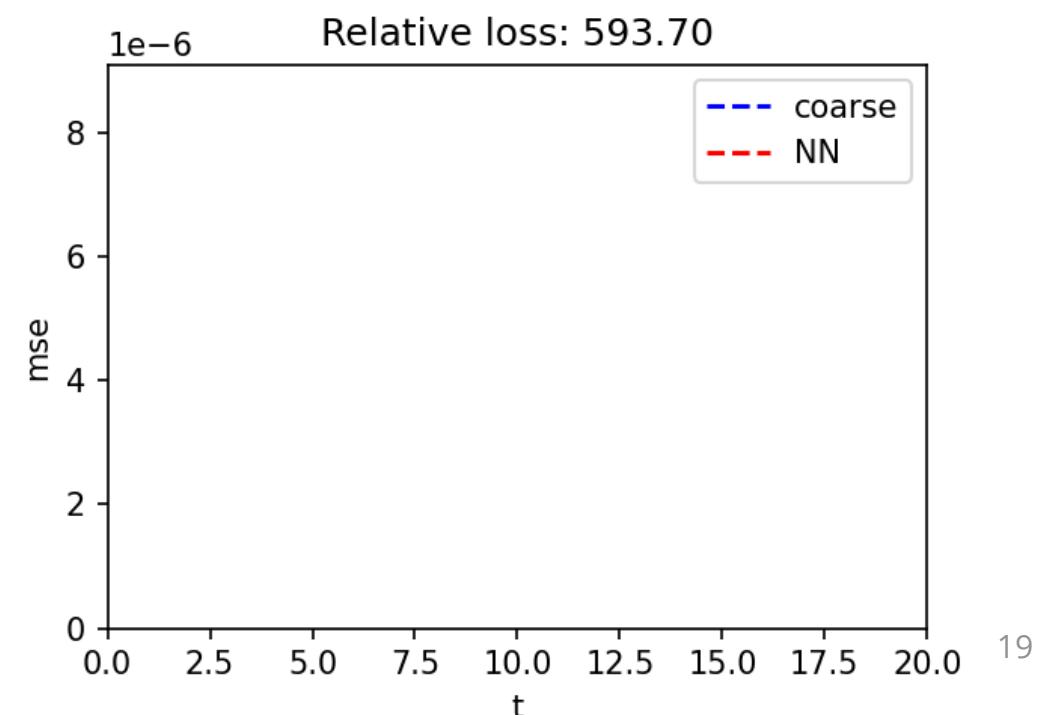
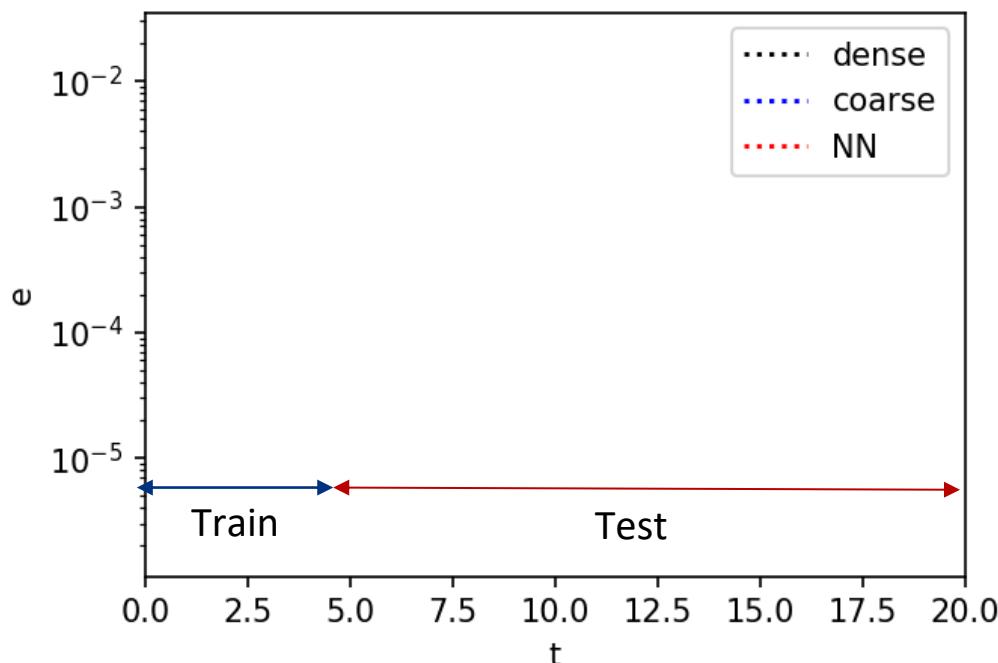
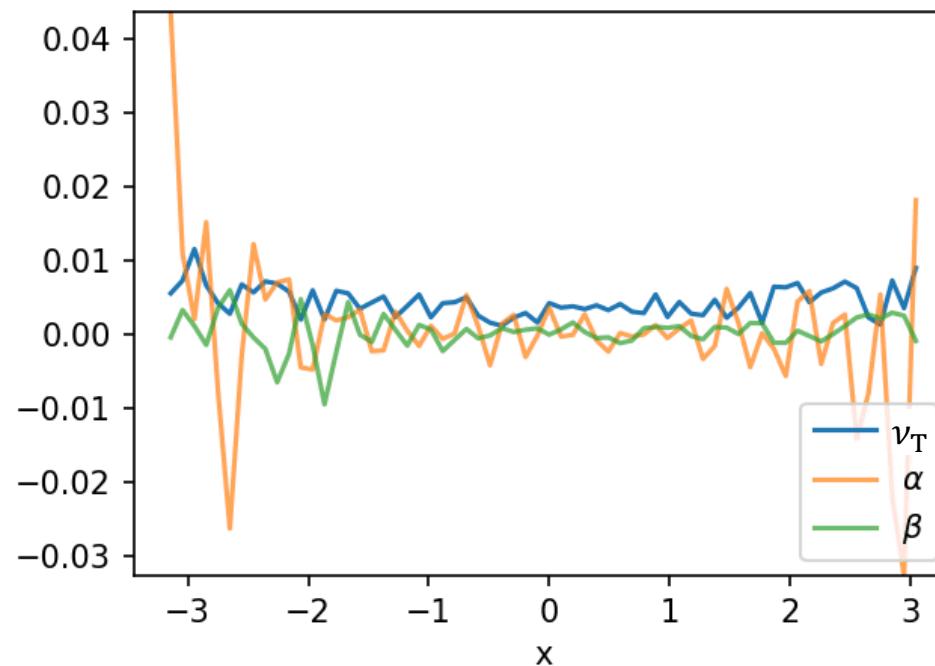
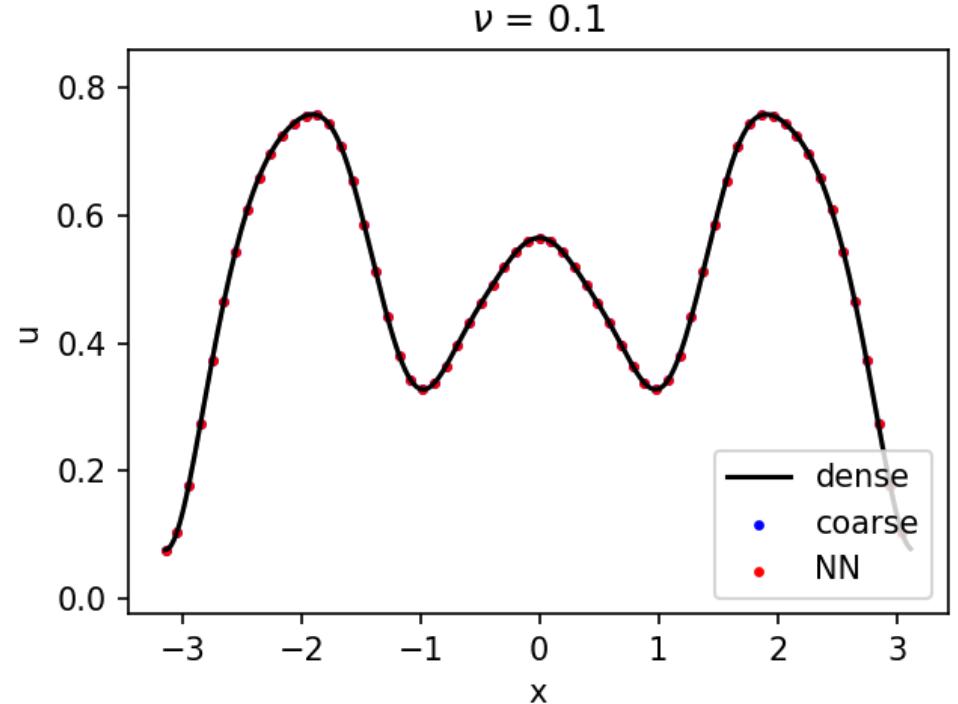
Results

- Model training:
 - Random initial condition
 - $t = 0$ to 5
 - $\nu = 5 \times 10^{-2}$ to 5×10^{-4}



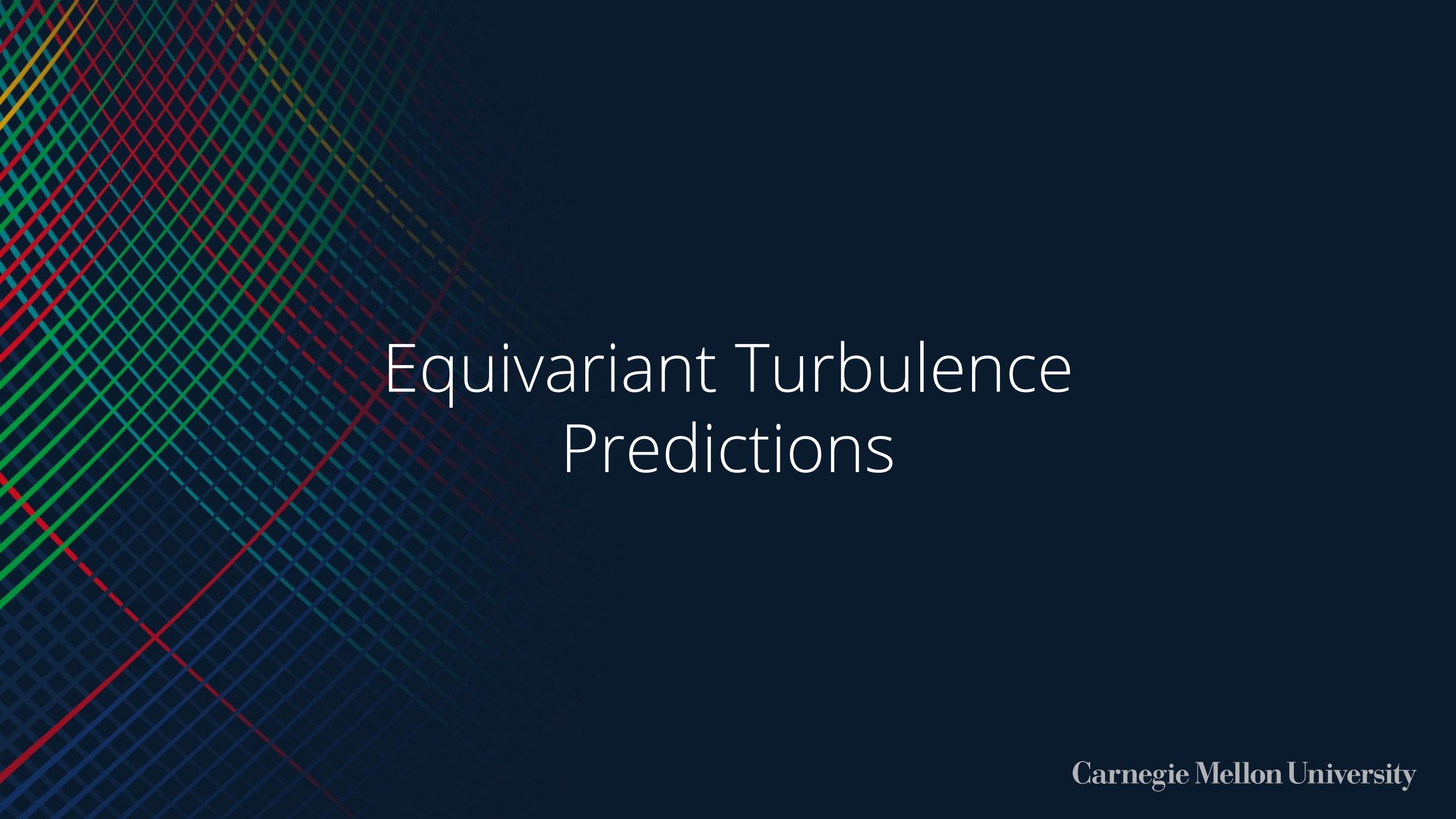






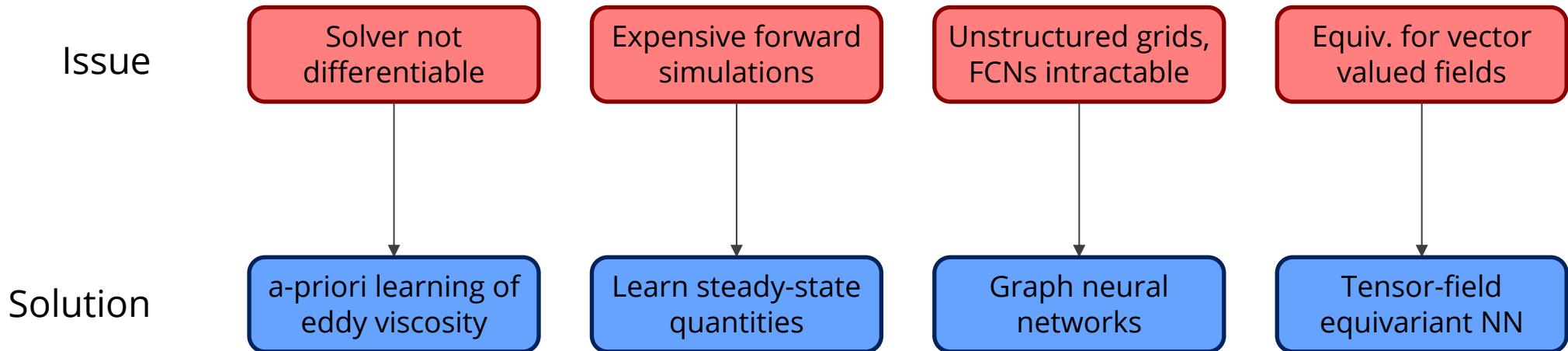
Discussion

- 1-eqn learned transport model for eddy viscosity effective for sub-grid modeling of Burgers' equation
- Interpretable model → improve physical understanding
 - Stationary eddy viscosity for time-varying system
- Model fails at high viscosities → can we learn to "switch off?"
- Scaling to higher dimensions, Navier-Stokes

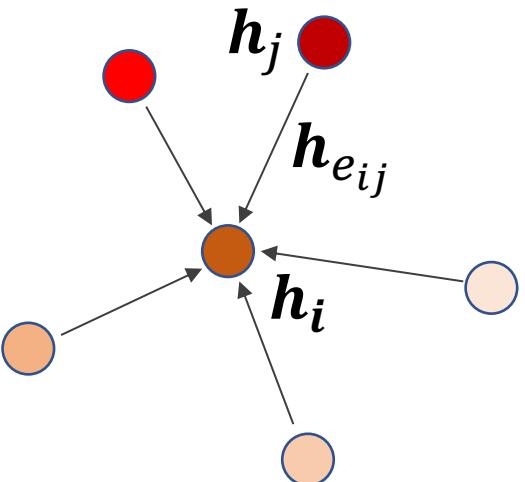


Equivariant Turbulence Predictions

Scaling up introduces challenges



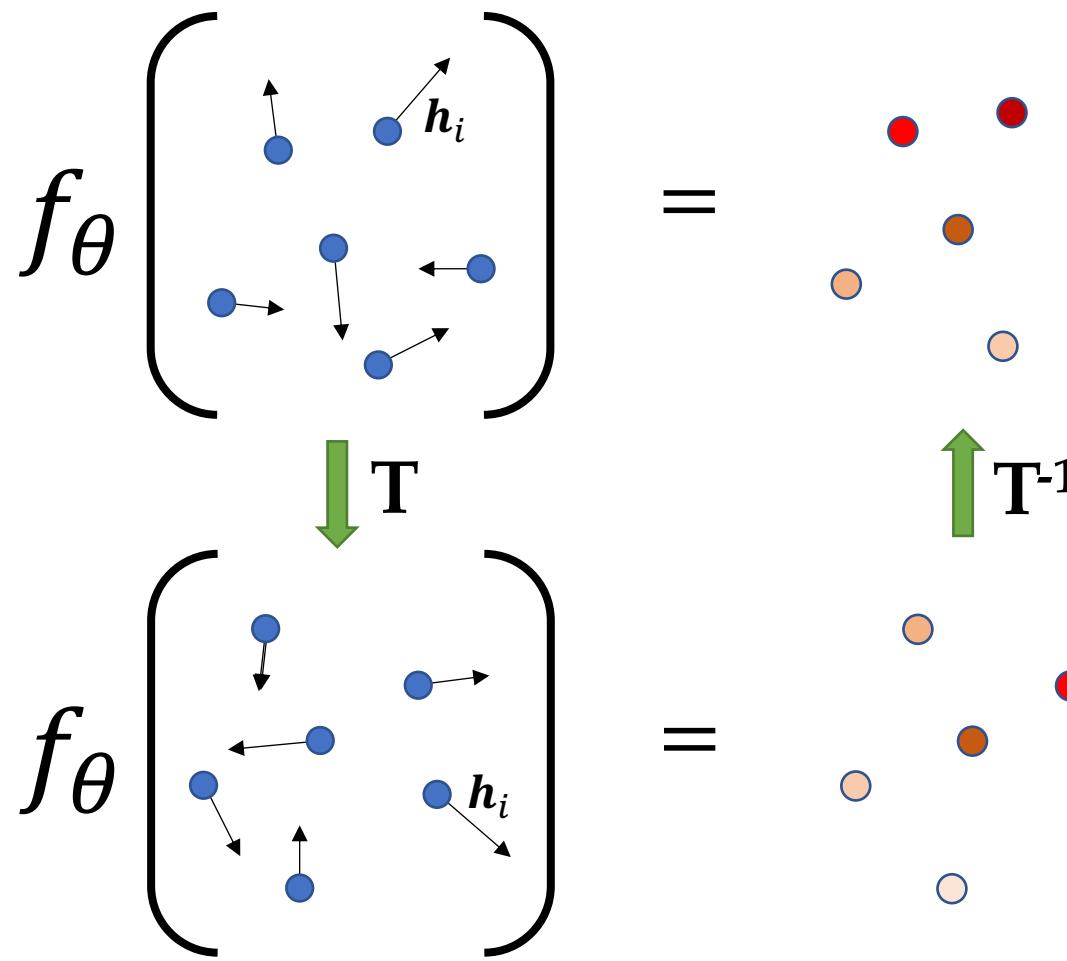
Graph Message-Passing Neural Networks



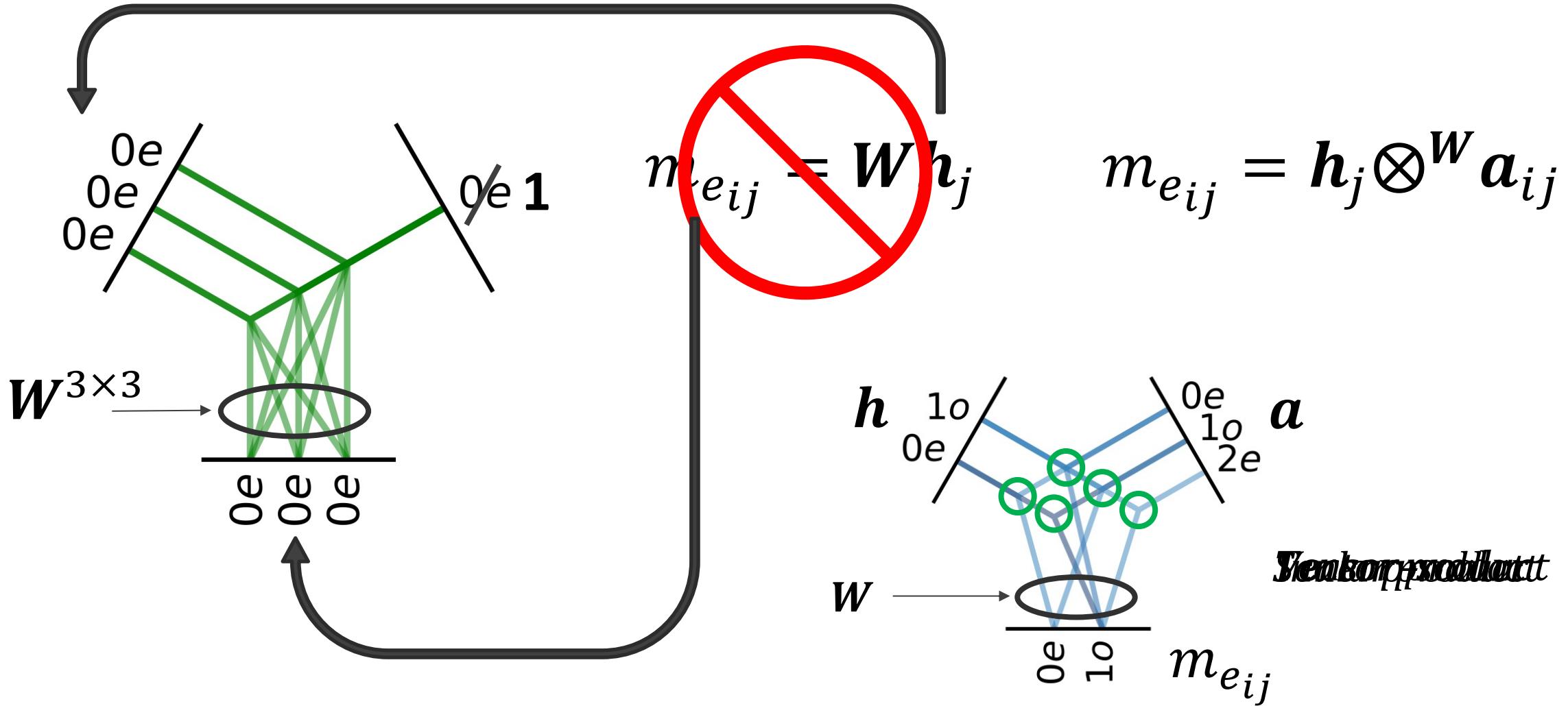
$$h_{e_{ij}}^{n+1} = f_\theta(h_{e_{ij}}^n, h_i^n, h_j^n)$$

$$h_i^{n+1} = g_\theta \left(\sum_{e \in \mathcal{N}} h_{e_{ij}}^{n+1}, h_i^n \right)$$

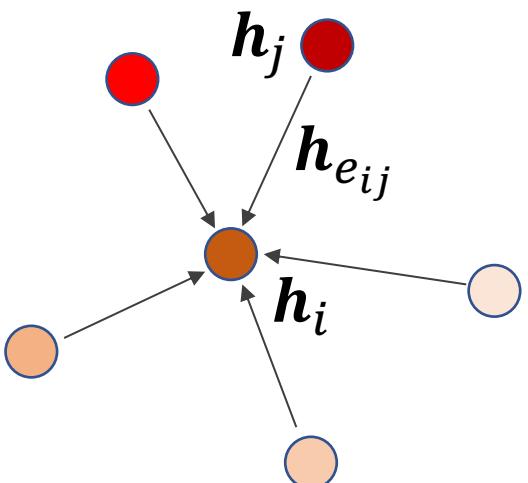
Equivariance



Tensor Products



Equivariant GNNs

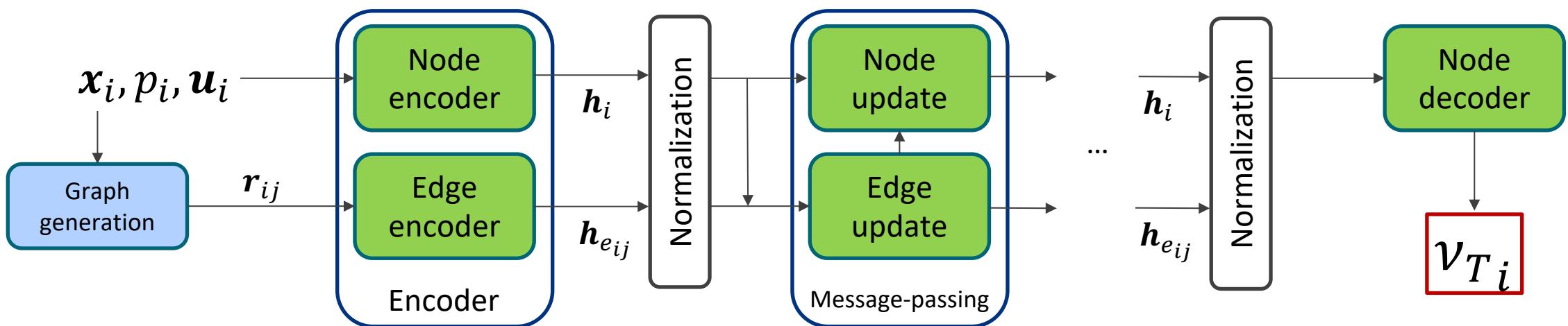


$$\mathbf{h}_{e_{ij}}^{n+1} = f_\theta(\mathbf{h}_{e_{ij}}^n, \mathbf{h}_i^n, \mathbf{h}_j^n)$$

$$f_\theta = [\mathbf{h}_{e_{ij}}, \mathbf{h}_i, \mathbf{h}_j] \otimes^{\mathbf{W}(r_{ij})} Y_{sh}(\mathbf{r}_{ij})$$

$$\mathbf{W}(r_{ij}) = MLP(\|\mathbf{r}_{ij}\|)$$

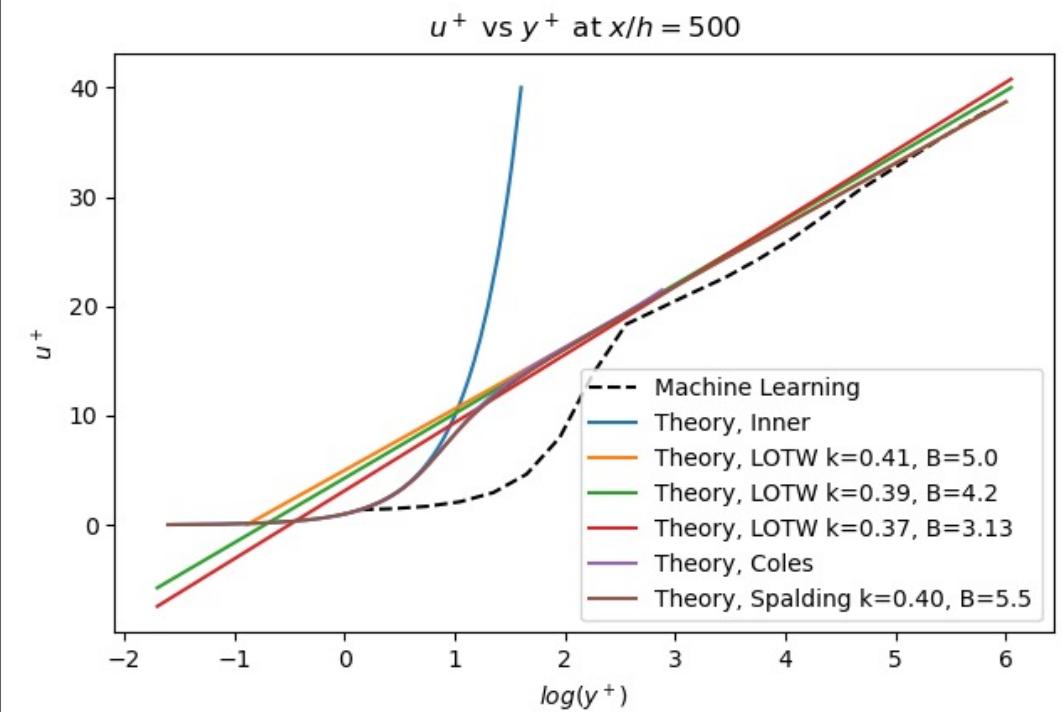
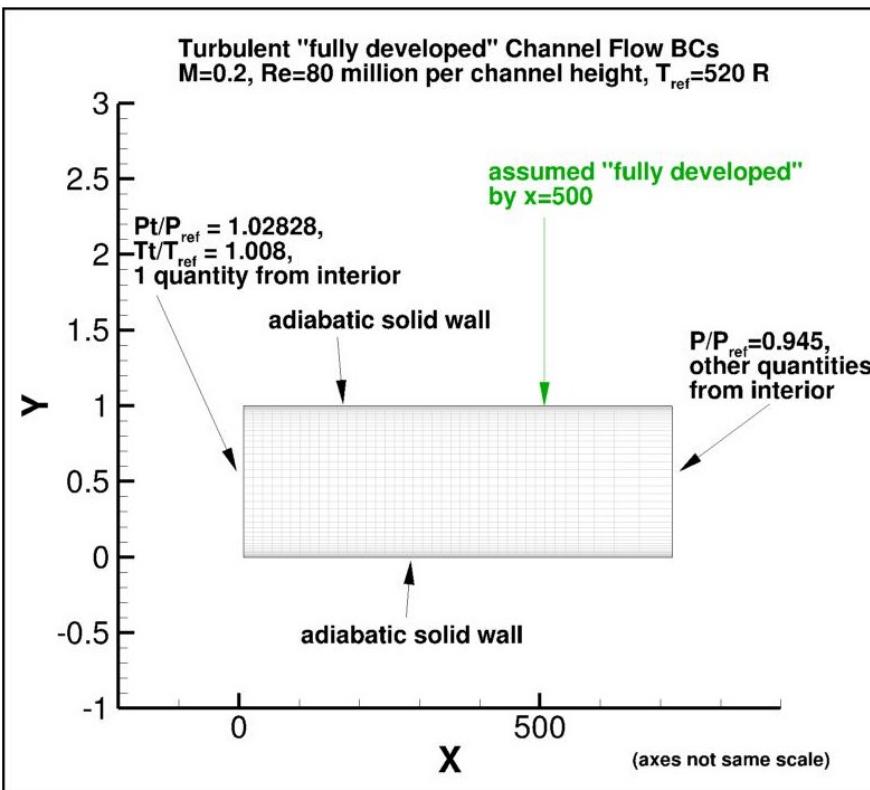
Architecture



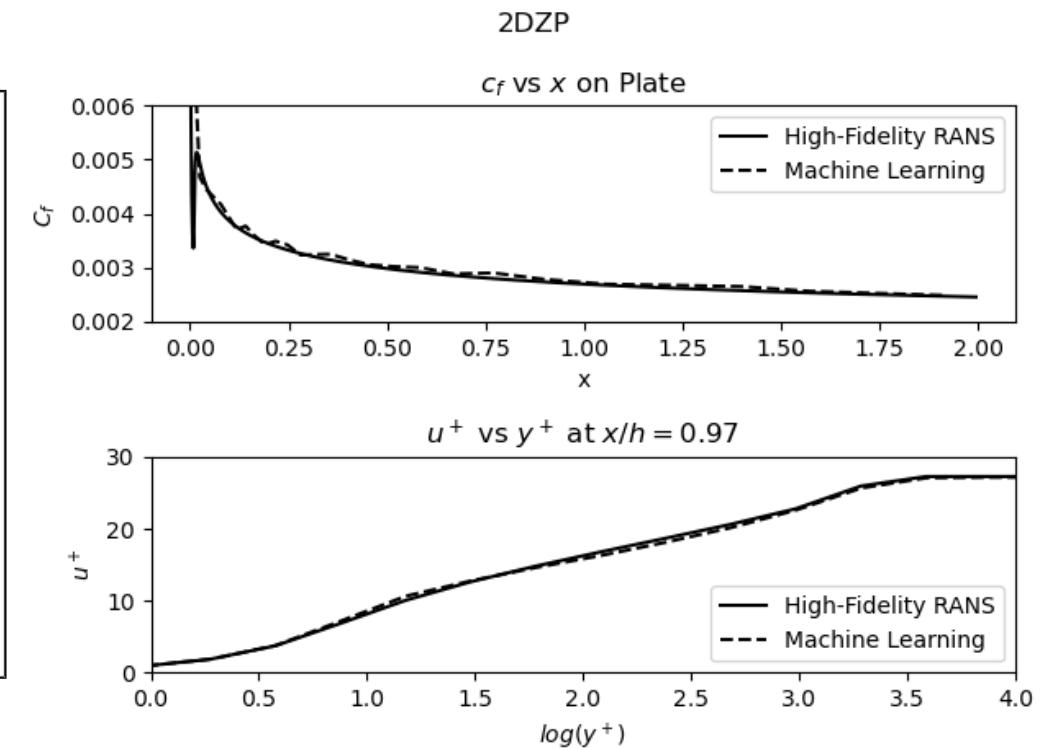
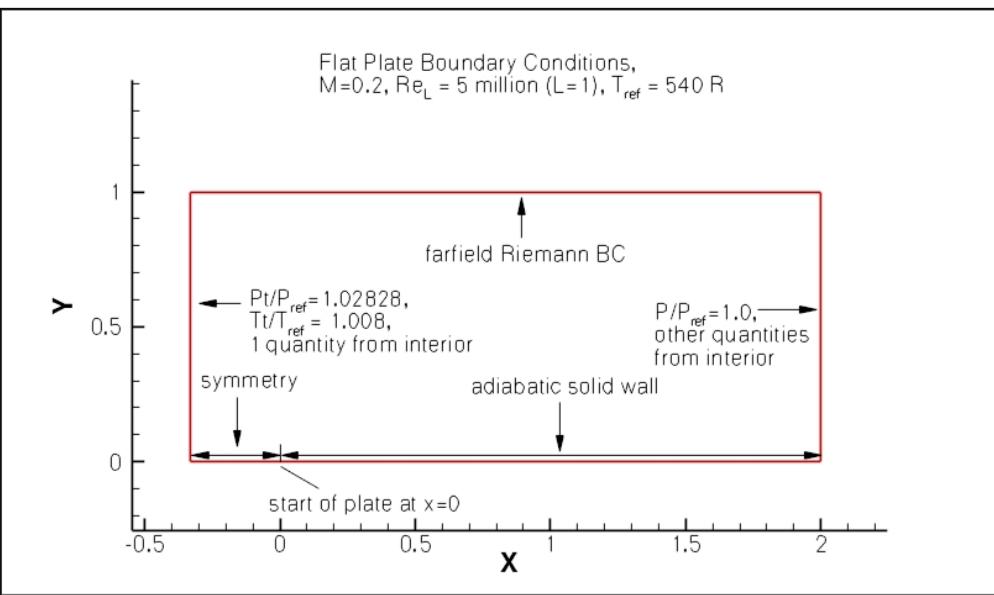
Learning Methodology

- Desire to learn steady-state eddy viscosity from mesh point cloud and initial pressure/velocity fields
 - Neural network approximates ν_T using equivariant graph network
- Data generated using Spalart-Allmaras turbulence model
- Approximate ν_T field used in incompressible solver
 - Only pressure/velocity equations solved
- A-posteriori analysis of solution fields

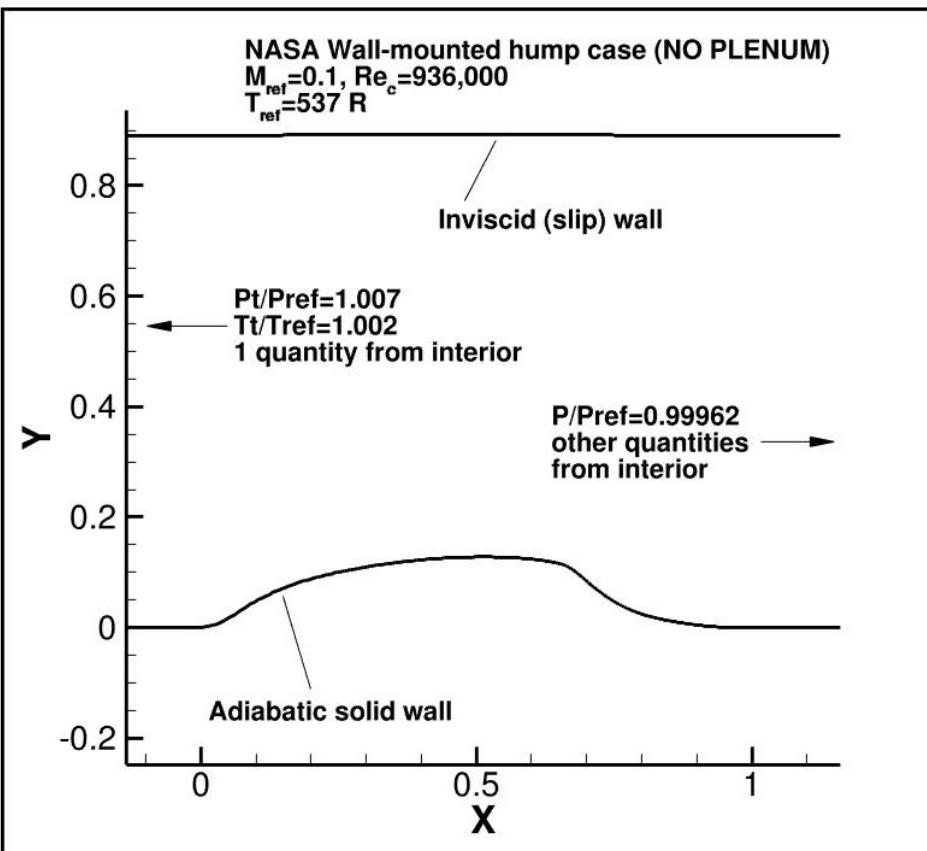
2D Fully Developed Channel Flow ($Re_h=80m$)



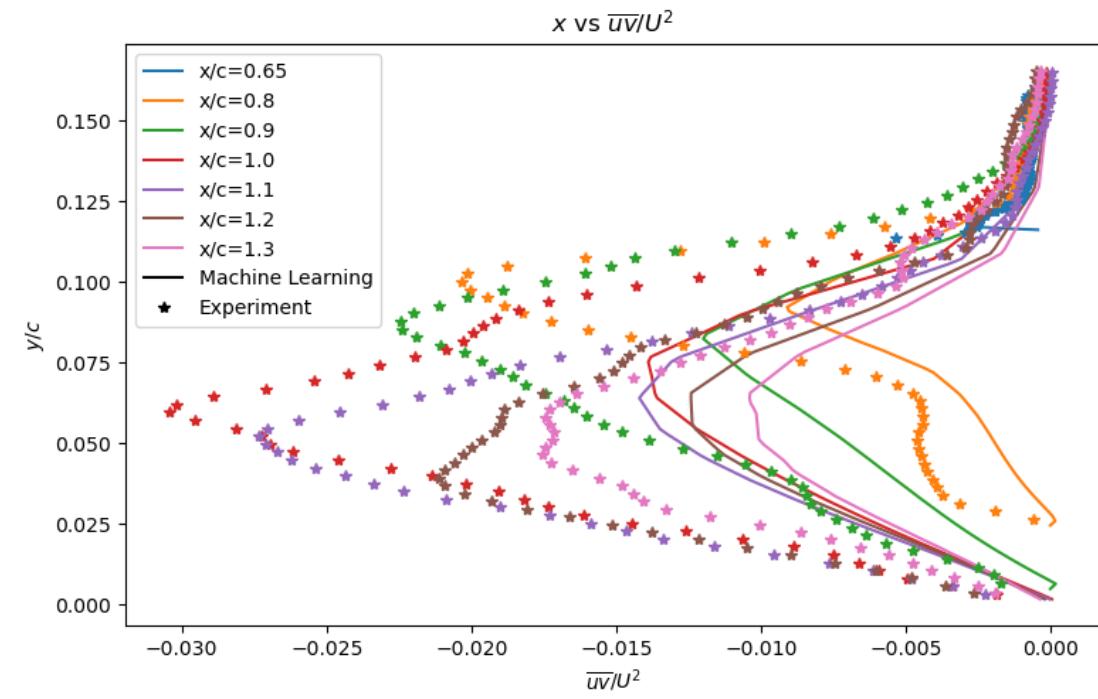
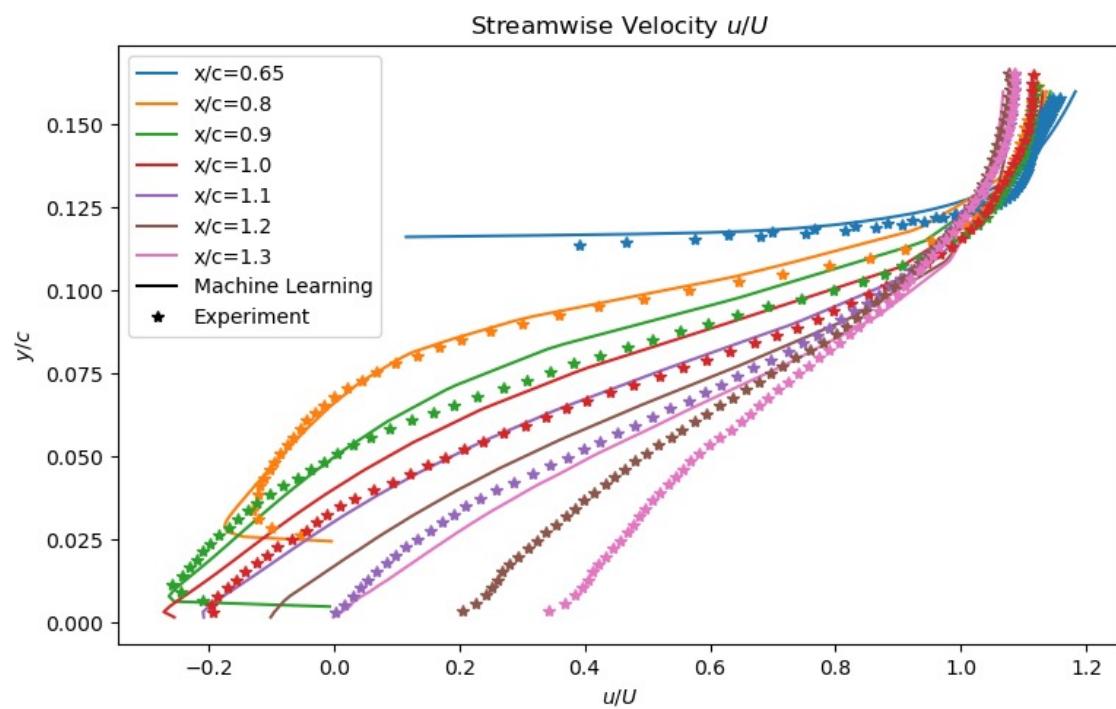
2D Zero Pressure Gradient Flat Plate ($Re_x=5m$)



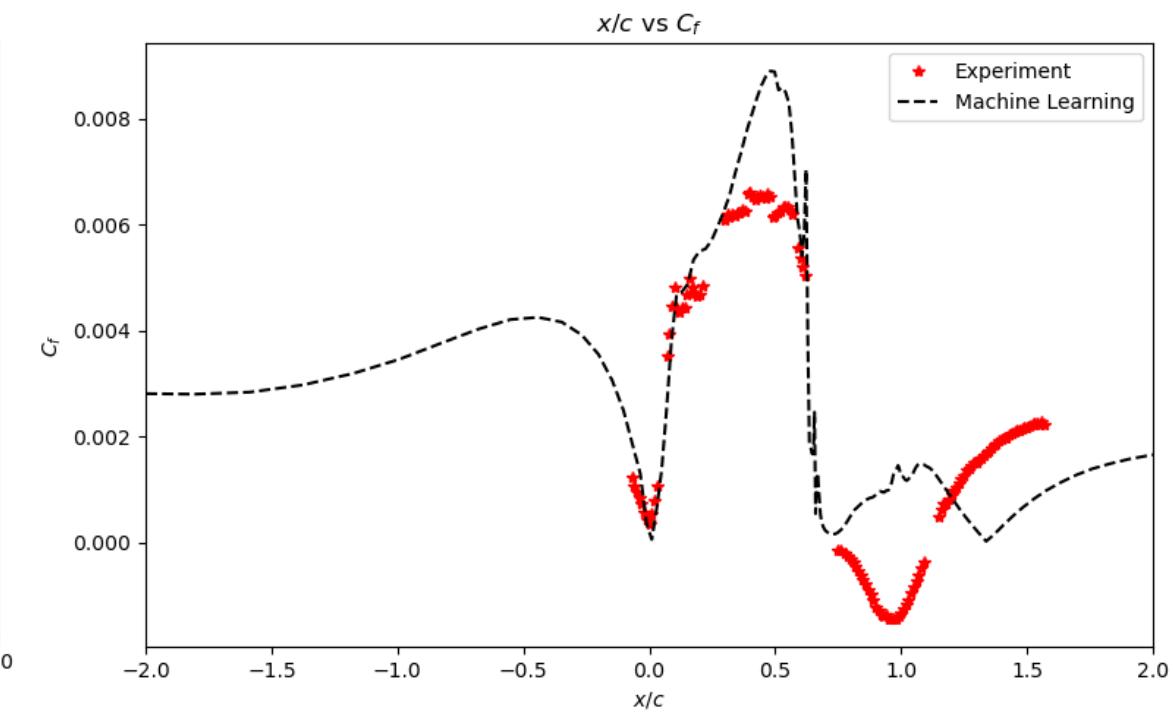
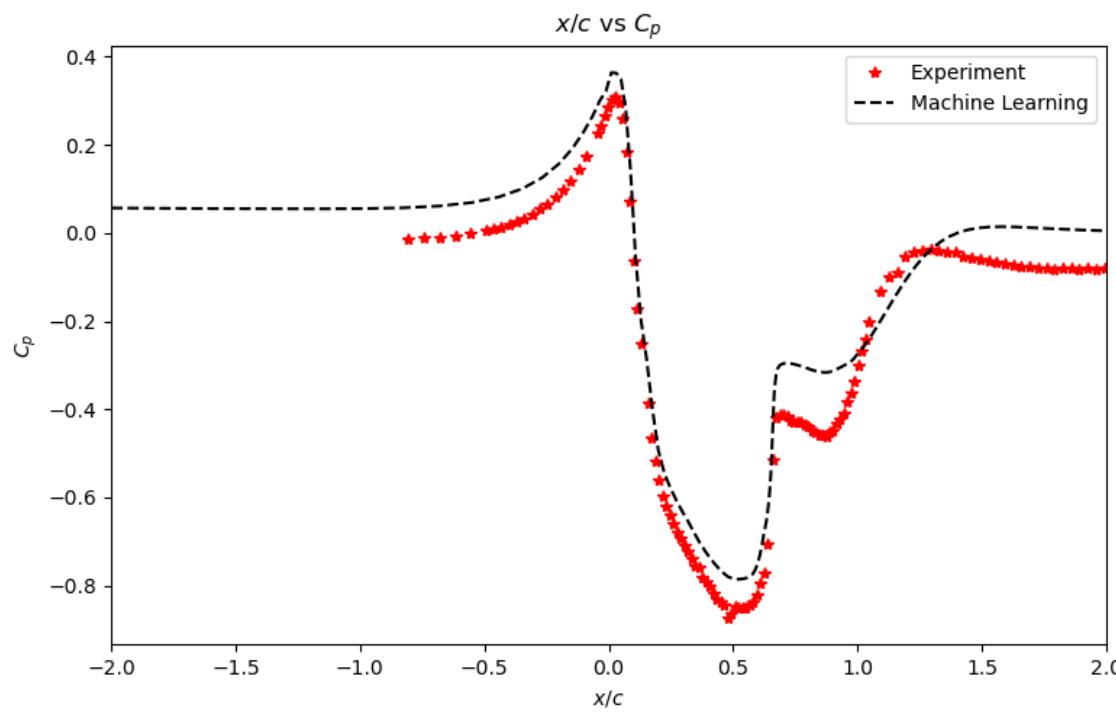
2D Wall Mounted Hump $Re_c=936k$



2D Wall Mounted Hump $Re_c=936k$



2D Wall Mounted Hump $Re_c=936k$



Conclusions and future directions

- Differentiable physics → more interpretable data-driven methods
- Symmetry-respecting architectures as best candidates for learning in the low-data regime
- Can we make strides towards fully differentiable N-S solvers?
- Can we leverage the advantages of DNN scaling and equivariant architectures to learn more robust turbulence models?

Acknowledgements



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