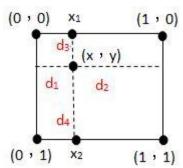
## **Scaling**

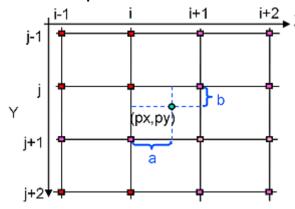
#### Discussion on bilinear interpolation



Bilinear interpolation uses the **nearest four points** to predict the value of the target  $(x_t, y_t)$ . Define f(x, y) means the value at that point, i.e. f(0, 0) = 0, f(1, 1) = 255. In bilinear interpolation, we compute the linear equation between x and f(x, y) for every row first. Therefore, we need to get these equations.  $f(x, 0) = a_0 x + b_0$  and  $f(x, 1) = a_1 x + b_1$ 

We could get  $a_0$  and  $b_0$  by f(0, 0) and f(1, 0) and get  $a_1$  and  $b_1$  by f(0, 1) and f(1, 1). After the computation, we can get two equation f(x, 0) and f(x, 1). We put  $x_t$  (x value of target) to get two point:  $f(x_t, 0)$  at point  $x_1$  and  $f(x_t, 1)$  at point  $x_2$ . Again, we could compute the equation:  $f(x_t, y) = a_3 y + b_3$  by  $f(x_t, 0)$  and  $f(x_t, 1)$ . Finally, we have  $f(x_t, y)$  and just put  $y_t$  in it to get  $f(x_t, y_t)$ .

### **Bicubic interpolation**



Bicubic interpolation uses the same concept of bilinear interpolation, but bicubic interpolation uses the most **nearest 16 points** to predict the value of target F(x', y'). Using the concept of bilinear, I compute the following equation for each row first.

$$F(x,j-1) = a_0x^3 + b_0x^2 + c_0x + d_0$$

$$F(x,j) = a_1x^3 + b_1x^2 + c_1x + d_1$$

$$F(x,j+1) = a_2x^3 + b_2x^2 + c_2x + d_2$$

$$F(x,j+2) = a_3x^3 + b_3x^2 + c_3x + d_3$$

After computing these equations, we could put x' in and get 4 points: F(x', j-1), F(x', j), F(x', j+1) and F(x', j+2). Now, we could compute the equation:

$$F(x', y) = a_4 x^3 + b_4 x^2 + c_4 x + d_4$$

Put y' into F(x', y) and get F(x', y') at the end.

#### Some method I use in program

There is an issue that the result after read bitmap array is **one-dimensional array**. If the file is a 24-bit BMP image, we will get an array like this: [RGBRGBRGB...], every pixel has three values. However, the previous discussions are based on two-dimensional array, so I calculate (x, y) from 1-D array by:

$$x = floor\left(\frac{index}{byte\ per\ pixel}\right)\ mod\ width$$
 
$$y = floor\left(floor\left(\frac{index}{color\ number\ per\ pixel}\right) \div width\right)$$

where *index* is the index of current element in an array

and color number per pixel is typically calculated by  $\frac{bits\ per\ pixel}{8}$ 

because we use one byte to represent value of a color.

After getting (x, y), we could continue to go on our algorithm above, for scaling-up task, we could map this (x, y) to original image by (x/1.5, y/1.5).

# Reference

- [1] Bilinear interpolation (Wiki)
- [2] Bicubic interpolation (Wiki)