Computational Complexity of real functions

Amaury Pouly

April 8, 2015

Outline

- Computability and computational complexity
 - Computability
 - Computational complexity
 - Turing degrees
 - Conclusion
- Complexity of real functions
 - Introduction
 - Computable Analysis
 - GPAC
 - Analog Church Thesis
- Toward a Complexity Theory for the GPAC
 - What is the problem ?

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Example (Sorting)

SORT: given n integers x_1, \ldots, x_n , find a permutation σ such that $x_{\sigma(1)} \leqslant \infty$

$$X_{\sigma(2)} \leqslant \ldots \leqslant X_{\sigma(n)}$$
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Example (Ackermann function)

ACK: given n and m, compute $A_{m,n}$ defined by

$$A_{0,n} = n+1$$
 $A_{m,0} = A_{m-1,1}$ $A_{m,n} = A_{m-1,A_{m,n-1}}$

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 \Rightarrow "clearly computable"...but slow ? ($A_{4,2} \approx 10^{20000}$)

Example (Collatz/Syracuse sequence)

COLLATZ: given *n* decide if this sequence converges to 1:

$$u_0 = n$$
 $u_{k+1} = \begin{cases} \frac{u_k}{2} & \text{if } u_k \text{ is even} \\ 3u_k & \text{otherwise} \end{cases}$

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⇒ what does a "program" mean?

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⇒ "looks quite hard" → we can check all strategies!

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- ⇒ undecidable even if we assume we can "solve" HALT

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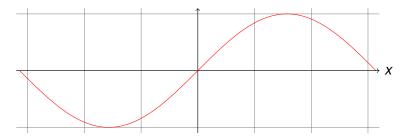
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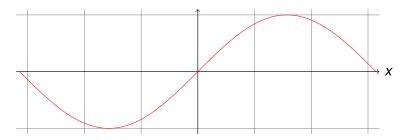
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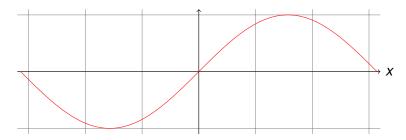
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- how do you represent a real number ? (infinite object)
- what is a program working on them ?

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- ⇒ Very analytic, approximation theory

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Example (Non-computable real)

$$r = \sum_{n=0}^{\infty} d_n 2^{-n}$$

where

 $d_n = 1 \Leftrightarrow \text{the } n^{th} \text{ Turing Machine halts on input } n$

Definition (Computable function)

 $f:[a,b]\to\mathbb{R}$ is computable iff $\exists m,\psi$ computable functions s.t $\forall n\in\mathbb{N}$:

- $\forall x, y, |x y| \leq 2^{-m(n)} \Rightarrow |f(x) f(y)| \leq 2^{-n} \blacktriangleright$ effective continuity
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Example (Counter-Example)

$$f(x) = \lceil x \rceil$$

▶ not continuous

reuses existing theory on Turing machines

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Question

Can we give a purely analog model of computation?

GPAC

General Purpose Analog Computer

by Claude Shanon (1941)

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- circuit built from:

A constant unit

$$u = x - uv$$

An multiplier unit

 $u = x - uv$

An integrator unit

GPAC: beyond the circuit approach

Theorem

y is generated by a GPAC iff it is a component of the solution $y=(y_1,\ldots,y_d)$ of the ordinary differential equation (ODE):

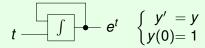
$$\begin{cases} y' = p(y) \\ y(t_0) = y_0 \end{cases}$$

where p is a vector of polynomials.

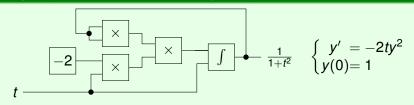
Example (One variable, linear system)

$$t - \int e^t \quad \begin{cases} y' = y \\ y(0) = 1 \end{cases}$$

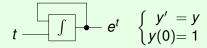
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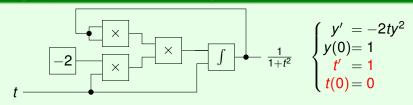
Example (One variable, nonlinear system)



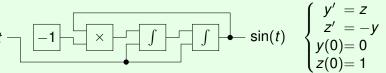
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Example (Two variable, nonlinear system)

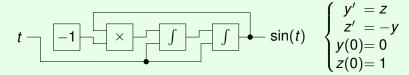


Example (Two variables, linear system)

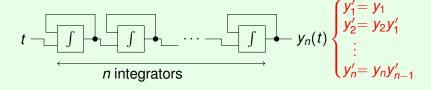


$$\begin{cases} y' = z \\ z' = -y \\ y(0) = 0 \\ z(0) = 1 \end{cases}$$

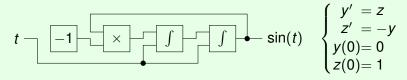
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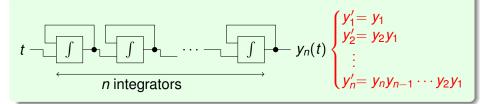
Exercice (Tear your mind apart)



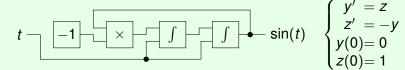
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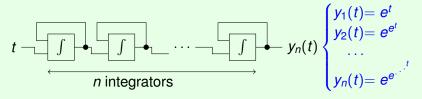
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Slight issue is...

the GPAC generated functions are analytical

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- the GPAC generated functions are analytical
- the computable functions from Computable Analysis are continuous

Question

Can we bridge the gap? Why should we?

The case of discrete computations

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- Turing machines
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And

Church Thesis

All reasonable discrete models of computation are equivalent.

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f is **computable** by a GPAC iff $\exists p, q$ polynomials s.t. $\forall x \in \mathbb{R}$, the solution $y = (y_1, \dots, y_d)$ of:

$$\begin{cases} y' = p(y) \\ y(t_0) = q(x) \end{cases}$$

satisfies $f(x) = \lim_{t \to \infty} y_1(t)$.

GPAC: back to the basics

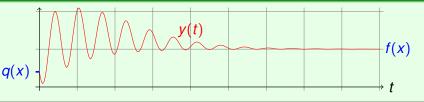
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Example



Computable Analysis = GPAC ? (again)

Theorem (Bournez, Campagnolo, Graça, Hainry)

f is GPAC-computable functions iff it is computable (in the sense of Computable Analysis).

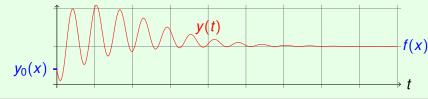
System	#1	#2
PIVP	$\begin{cases} y'(t) = p(y(t)) \\ y(1) = q(x) \end{cases}$	$\begin{cases} z'(t) = u(t)p(z(t)) \\ u'(t) = u(t) \\ z(t_0) = q(x) \\ u(1) = 1 \end{cases}$

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Remark

Same curve, different speed: $u(t) = e^t$ and $z(t) = y(e^t)$

Example



System	#1	#2
PIVP	$\begin{cases} y'(t) = p(y(t)) \\ y(1) = q(x) \end{cases}$	$\begin{cases} z'(t) = u(t)p(z(t)) \\ u'(t) = u(t) \\ z(t_0) = q(x) \\ u(1) = 1 \end{cases}$
Computed Function	S	ame

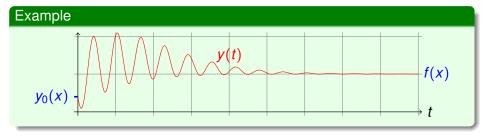
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Example

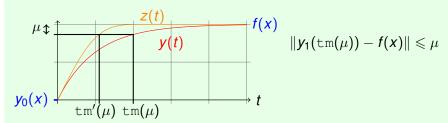


PIVP	y'=p(y)	$z(t) = y(e^t) ightarrow egin{cases} z' = up(z) \ u' = u \end{cases}$
Computed Function		Same
Convergence		Exponentially faster



PIVP	y'=p(y)	$z(t) = y(e^t) ightarrow egin{cases} z' = up(z) \ u' = u \end{cases}$
Computed Function	Same	
Time for precision μ	$tm(\mu)$	$tm'(\mu) = log(tm(\mu))$

Example



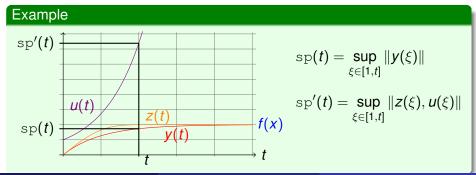
Remark

tm is not a good measure of complexity.

PIVP at time t

PIVPy' = p(y) $z(t) = y(e^t) \rightarrow \begin{cases} z' = up(z) \\ u' = u \end{cases}$ Computed FunctionSameTime for precision μ $tm(\mu)$ $tm'(\mu) = log(tm(\mu))$ Bounding box for $tm(\mu)$

sp(t)



 $sp'(t) = max(sp(e^t), e^t)$

PIVP	y'=p(y)	$z(t) = y(e^t) ightarrow egin{cases} z' = up(z) \ u' = u \end{cases}$
Computed Function	Same	
Time for precision μ	$tm(\mu)$	$tm'(\mu) = log(tm(\mu))$
Bounding box for PIVP at time <i>t</i>	sp(t)	$sp'(t) = max(sp(e^t), e^t)$

Remark

• $tm(\mu)$ and sp(t) depend on the convergence rate

PIVP	y'=p(y)	$egin{aligned} z(t) = y(e^t) ightarrow egin{cases} z' = up(z) \ u' = u \end{cases} \end{aligned}$	
Computed Function	Same		
Time for precision μ	$tm(\mu)$	$tm'(\mu) = log(tm(\mu))$	
Bounding box for PIVP at time <i>t</i>	sp(t)	$sp'(t) = max(sp(e^t), e^t)$	
Bounding box for PIVP at precision μ	$sp(tm(\mu))$	$\max(\operatorname{sp}(\operatorname{tm}(\mu)),\operatorname{tm}(\mu))$	

Remark

- $tm(\mu)$ and sp(t) depend on the convergence rate
- $sp(tm(\mu))$ seems not

Proper Measures

Proper measures of "complexity":

- time scaling invariant
- property of the curve

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Proper measures of "complexity":

- time scaling invariant
- property of the curve

Possible choices:

- Bounding Box at precision $\mu \Rightarrow \mathsf{Ok}$ but geometric interpretation ?
- Length of the curve until precision $\mu \Rightarrow$ Much more intuitive

Questions?

Do you have any questions ?