

2025-06-04

EX 1

1.1

$$\begin{cases} -\frac{d}{dx} \left(\varepsilon(1+x^2) \frac{du}{dx} \right) + \frac{du}{dx} = 0 & 0 < x < 1 \\ u(0) = 0 & \rightarrow \Gamma_0 \\ u(1) = 1 & \rightarrow \Gamma_D \neq 0 \Rightarrow \text{(LIFTING)} \end{cases} \quad 0 < \varepsilon \ll 1$$

WEAK FORMULATION:

Spazio funzioni test: $V_0 = H^1_0((0,1))$

Spazio soluzioni: $V = \{v \in H^1((0,1)) \text{ s.t. } \underbrace{v(1)=1}_{\substack{\text{Dirichlet} \\ \text{boundary condition}}}\}$

Let $v \in V_0$:

$$\boxed{- \int_0^1 \frac{d}{dx} \left(\varepsilon(1+x^2) \frac{du}{dx} \right) \cdot v \, dx + \int_0^1 \frac{du}{dx} \cdot v \, dx = 0}$$

$\underbrace{= \mu(x)}$

$$\int_0^1 \varepsilon(1+x^2) \frac{du}{dx} \frac{dv}{dx} \, dx - \left[\varepsilon(1+x^2) \frac{du}{dx} \cdot m \cdot v \right]_{x=0}^{x=1} + \int_0^1 \frac{du}{dx} \cdot v \, dx = 0$$

because $v \in V_0$, and
 $v(0) = v(1) = 0$

$$\int_0^1 \varepsilon(1+x^2) \frac{du}{dx} \frac{dv}{dx} \, dx + \int_0^1 \frac{du}{dx} \, v \, dx = 0$$

$\underbrace{a(u, v)}$

$$\boxed{\text{find } u \in V \text{ s.t. } a(u, v) = F(v) \quad \forall v \in V_0} \quad (\text{WP})$$

LIFTING: I want to find solutions in V_0 ; suppose $\exists R_g \in V$
s.t. $u = \hat{u} + R_g$ and $\hat{u} \in V_0$

$$a(\hat{u} + R_g, v) = F(v) = 0$$

$$a(\hat{u}, v) + a(R_g, v) = 0$$

$$a(\hat{u}, v) = -a(R_g, v)$$

$$\bullet a(\hat{u}, v) = \int_0^1 \varepsilon(1+x^2) \frac{d\hat{u}}{dx} \frac{dv}{dx} \, dx + \int_0^1 \frac{d\hat{u}}{dx} \, v \, dx @$$

$$\bullet G(v) = -a(R_g, v)$$

nel testo ci viene chiesto $F(v)$, che dovrebbe essere il termine noto $G(v)$

Final (WP):

Find $\hat{u} \in V_0$ s.t.:

$$a(\hat{u}, v) = G(v) \quad \forall v \in V_0$$

COERCIVITY:

$$\begin{aligned} a(v, v) &= \int_0^1 \varepsilon (1+x^2) \frac{dv}{dx} \frac{dv}{dx} dx + \int_0^1 \frac{dv}{dx} v dx = \\ &= \int_0^1 \varepsilon (1+x^2) \left(\frac{dv}{dx} \right)^2 dx + \int_0^1 \frac{dv}{dx} v dx \geq \\ &\geq \underbrace{\varepsilon \cdot \left(1 + \min_{x \in [0,1]} (x^2) \right)}_{\geq 0} \cdot \int_0^1 \left(\frac{dv}{dx} \right)^2 dx + \underbrace{\int_0^1 \frac{dv}{dx} v dx}_{\geq 0} = \end{aligned}$$

~~ε < 0~~ ~~0 < ε < 1~~ ~~0 < ε < 1~~ ~~0 < ε < 1~~

$$= \mu_{\min} \|v'\|_{L^2(0,1)}^2 - \frac{1}{2} \int_0^1 v^2 dx$$

??

$$-\frac{1}{2} < 0$$

disguise.

triangle

CONTINUITY:

$$\begin{aligned} |a(u, v)| &\leq \left| \int_0^1 \varepsilon (1+x^2) \frac{du}{dx} \frac{dv}{dx} dx \right| + \left| \int_0^1 \frac{du}{dx} v dx \right| \leq \\ &\leq \max_{x \in (0,1)} |\varepsilon (1+x^2)| \cdot \int_0^1 \frac{du}{dx} \frac{dv}{dx} dx + \left| \int_0^1 u' v dx \right| \stackrel{C-S}{\leq} \\ &\leq \mu_{\max} \cdot \|u'\|_{L^2(0,1)} \cdot \|v'\|_{L^2(0,1)} + \|u'\|_{L^2(0,1)} \cdot \|v'\|_{L^2(0,1)} \leq \\ &\leq (\mu_{\max}) \|u\|_{H^1} \|v\|_{H^1} + \|u\|_{H^1} \|v\|_{H^1} = \\ \text{per } x=1: \quad (2\varepsilon+1) &= \underbrace{(2\varepsilon+1)}_{=M} \cdot \|u\|_{H^1} \cdot \|v\|_{H^1} \end{aligned}$$

NORM $\|F\|_{V_1}$:

DONNE B.BE + S.SERB D MA
HO FORTI DURBI

EXERCISE 2

TIME - DEPENDENT STOKES

$d=2$

$$\left\{ \begin{array}{l} -\mu \Delta \vec{u} + \nabla p = \vec{f} \\ \operatorname{div} \vec{u} = 0 \\ \vec{u} = 0 \\ \mu \frac{\partial \vec{u}}{\partial \vec{n}} - p \vec{n} = 0 \quad \text{if } x=-1 \text{ or } x=1 \end{array} \right. \quad \left\{ \begin{array}{l} (x, t) \in \Omega = (-1, 1)^2 \\ (x, y) \in \Omega \\ \text{if } y=-1 \text{ or } y=1 \quad \Gamma_D \\ \text{if } x=-1 \text{ or } x=1 \quad \Gamma_N \end{array} \right.$$

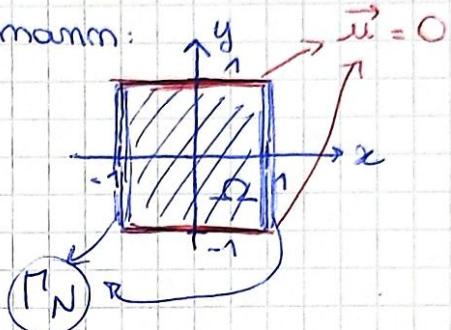
With $\mu=2$ and $\vec{f} = [1 + \sin^2(x), 0]^T$.

(2.1)

Mixed dirichlet-neumann:

$$V = [H^1_{\Gamma_D}(\Omega)]^2$$

$$Q = L^2(\Omega)$$



Let $\vec{v} \in V, q \in Q$:

$$(a) \int_{\Omega} -\mu \Delta \vec{u} \cdot \vec{v} dx + \int_{\Omega} \nabla p \cdot \vec{v} dx = \int_{\Omega} \vec{f} \cdot \vec{v} dx$$

$$\left(\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} dx - \int_{\partial \Omega} \mu (\nabla \vec{u} \cdot \vec{n}) \cdot \vec{v} dy \right) - \left(\int_{\Omega} \operatorname{div} \vec{v} \cdot p dx + \int_{\partial \Omega} p \cdot \vec{n} \cdot \vec{v} dy \right) = \int_{\Omega} \vec{f} \cdot \vec{v} dx$$

$$\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} dx - \int_{\Omega} \nabla \cdot \vec{v} \cdot p dx - \int_{\Omega} \left(\mu \frac{\partial \vec{u}}{\partial \vec{n}} - p \vec{n} \right) \cdot \vec{v} dy = \int_{\Omega} \vec{f} \cdot \vec{v} dx$$

because $\vec{v} \in V$
and $\vec{v}|_{\Gamma_D} = 0$

$$\Rightarrow \underbrace{\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} dx}_{=a(\vec{u}, \vec{v})} - \underbrace{\int_{\Omega} \nabla \cdot \vec{v} \cdot p dx}_{=b(\vec{v}, p)} = \underbrace{\int_{\Omega} \vec{f} \cdot \vec{v} dx}_{F(\vec{v})}$$

$$(b) - \int_{\Omega} \operatorname{div} \vec{u} \cdot q = 0$$

$$\underbrace{- \int_{\Omega} \operatorname{div} \vec{u} \cdot q}_{=b(\vec{u}, q)}$$

Find $\vec{u} \in V, p \in Q$ st.

$$(a) a(\vec{u}, \vec{v}) + b(\vec{v}, p) = F(\vec{v})$$

$$(b) b(\vec{u}, q) = 0$$

$$\forall \vec{v} \in V$$

(WP)

$$\forall q \in Q$$

2.2 MESH-TRIANGULATION:

① Partition of Ω : K_c , $c=1, \dots, N_{\text{ele}}$ s.t. $\bigcup_{i=1}^{N_{\text{ele}}} K_i = \Omega$
 $K_i \cap K_j = \emptyset \quad \forall i \neq j$

② $X_h^{\infty, d}(\Omega) = \{u \in [C^0(\Omega)]^d, u|_{K_i} \in [P^{\infty}(K_i)]^d \quad \forall j\}$

• $V_h = V \cap X_h^{3,2}(\Omega)$ → fem space for vel

• $Q_h = Q \cap X_h^{2,1}(\Omega)$ → fem space for press

$N_{V_h} < \infty$

$N_{Q_h} < \infty$

(WIP) is:

Find $\vec{u}_h \in V_h$, $p_h \in Q_h$ s.t.:

(a) $a(\vec{u}_h, \vec{v}_h) + b(\vec{v}_h, p_h) = F(\vec{v}_h) \quad \forall \vec{v}_h \in V_h$

(b) $b(\vec{u}_h, q_h) = 0 \quad \forall q_h \in Q_h$

$\{\vec{\varphi}_j(x)\}_{j=1}^{N_{V_h}}$ → basis for V_h

$\{\psi_j(x)\}_{j=1}^{N_{Q_h}}$ → basis for Q_h

Expansions:

$$\vec{u}_h(x) = \sum_{j=1}^{N_{V_h}} u_j \cdot \vec{\varphi}_j(x)$$

$$p_h(x) = \sum_{j=1}^{N_{Q_h}} p_j \cdot \psi_j(x)$$

$$\vec{v}_h(x) = \vec{\varphi}_{i_1}(x)$$

$$q_h(x) = \psi_{k_1}(x)$$

$$\vec{u} = [u_1, \dots, u_{N_{V_h}}]$$

$$\vec{p} = [p_1, \dots, p_{N_{Q_h}}]$$

Therefore:

(a) $a\left(\sum_{j=1}^{N_{V_h}} u_j \cdot \vec{\varphi}_j(x), \vec{\varphi}_i(x)\right) + b\left(\vec{\varphi}_i(x), \sum_{j=1}^{N_{Q_h}} p_j \cdot \psi_j(x)\right) = F(\vec{\varphi}_i(x)) \quad \forall i$

$$\underbrace{\sum_{j=1}^{N_{V_h}} u_j \cdot a(\vec{\varphi}_j(x), \vec{\varphi}_i(x))}_{A_{ij}} + \underbrace{\sum_{j=1}^{N_{Q_h}} p_j \cdot b(\vec{\varphi}_i(x), \psi_j(x))}_{B_{ji}} = F(\vec{\varphi}_i(x)) \quad \forall i$$

$$\Rightarrow (a): A \vec{u} + B^T \vec{p} = \vec{F}$$

(b) $b\left(\sum_{j=1}^{N_{V_h}} u_j \cdot \vec{\varphi}_j(x), \psi_k(x)\right) = 0 \quad \forall i$

$$\underbrace{\sum_{j=1}^{N_{V_h}} u_j \cdot b(\vec{\varphi}_j(x), \psi_k(x))}_{B_{ij}} = 0 \quad \forall i$$

$$\Rightarrow (b): B \vec{u} = 0$$

2.3 STABILITY for TAYLOR-HOOD:

PR: $\exists!$ of \vec{u}_h, p_h

Assume that:

- ① $a: V \times V \rightarrow \mathbb{R}$ is $\begin{cases} \text{lilinear} \\ \text{continuous} \\ \text{coercive} \end{cases}$

② Assume that $\delta: V \times Q \rightarrow \mathbb{R}$ is:
 ↗ bilinear
 ↗ continuous
 ↘ LBB satisfied

$\Rightarrow \exists! \vec{u}_h, p_h$ solution to (G); moreover:

- $\|\vec{u}_h\|_V \leq \frac{1}{\alpha} \|F\|_V$
 - $\|p_h\|_Q \leq \frac{1}{\beta} \left(1 + \frac{\gamma}{\alpha}\right) \|F\|_V$
- $= C$
- } Stability properties
 \Rightarrow we have (G) stable

2.4 ERROR ESTIMATE for T-H elements.

$$\underbrace{\|\vec{u} - \vec{u}_h\|_V}_{\substack{\text{error on} \\ \text{velocity}}} + \underbrace{\|p - p_h\|_Q}_{\substack{\text{error on} \\ \text{pressure}}} \leq C \underbrace{\eta^{k+1}}_{\substack{\text{degree}}} \left(\|\vec{u}\|_{H^{k+2}(\Omega)}^4 + \|p\|_{H^{k+1}(\Omega)}^2 \right)$$

2.5 NON-SINGULARITY of the system: $\rightarrow \begin{cases} A\vec{u} + B^T \vec{p} = \vec{F} \\ B\vec{u} = 0 \end{cases}$

S is non-singular because LBB is satisfied.

$\exists \beta > 0$ s.t. $\forall q_h \in Q_h \quad \exists \vec{v}_h \in V_h: \delta(\vec{v}_h, q_h) \geq \beta \|\vec{v}_h\|_V \|q_h\|_Q$

$$\Leftrightarrow \exists \beta \text{ s.t. } \inf_{\substack{q_h \in Q_h \\ Q_h \neq \emptyset}} \sup_{\substack{\vec{v}_h \in V_h \\ \vec{v}_h \neq \emptyset}} \frac{\delta(\vec{v}_h, q_h)}{\|\vec{v}_h\|_V \|q_h\|_Q} \geq \beta$$