

Numerical Methods for Partial Differential Equations

A.Y. 2024/2025

Written exam - February 10, 2025

Maximum score: 26. Duration: 2h 15m.

Answers to questions must be provided on paper (handwritten). Source code and picture files should be uploaded to the dedicated WeBeep folder. **All uploaded files (including source code) must be appropriately referenced when answering to questions on paper** (e.g. “The solution is depicted in `exercise-1-plot.png`”).

Questions marked with (*) should be skipped by multichance students.

Exercise 1.

Consider the parabolic problem

$$\begin{cases} -u'' - xu' + u = f & 0 < x < 1 , \\ u(0) = u(1) = 0 , \end{cases} \quad (1)$$

where $f(x) = 0$.

1.1. [2 pt] Write the weak formulation of (1), under the form:

$$\text{find } u \in V \text{ such that } a(u, v) = F(v) \text{ for all } v \in V ,$$

and provide the definitions of V , $a(u, v)$ and $F(v)$.

1.2. [3 pt] Prove that the bilinear form $a(\cdot, \cdot)$ is continuous, coercive and find its continuity constant M and its coercivity constant α .

1.3. [1 pt] Find the expression of the exact solution, that is $u(x) = \dots$

1.4. [2 pt] Approximate the weak problem in Exercise 1.1 by piecewise quadratic finite elements and provide the error estimate for both $H^1(0, 1)$ and $L^2(0, 1)$ norms.

1.5. [1 pt] Consider now the case where f is different from zero, and derive the expression for f such that the exact solution to (1) is $u_{\text{ex}} = x(1 - x)$.

1.6. [3 pt] Using `deal.II`, implement a finite element solver for (1). Consider the definition of f computed at previous point. The program must solve the problem for different values of the mesh size h and compute the L^2 and H^1 norms of the error against the exact solution. Use the internal functions of `deal.II` to generate the mesh. Upload the source code of the solver.

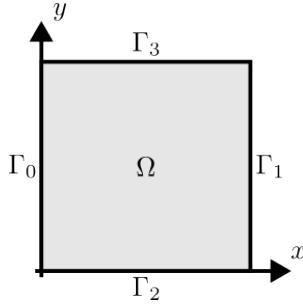


Figure 1: Domain for Exercise 2. Each boundary subset Γ_i corresponds to the tag i in the provided mesh files.

1.7. [1 pt] Compute the solution setting $h = 0.1$ and using finite elements of degree 1. Upload a plot of the solution.

1.8. [2 pt] Using finite elements of degree 1, perform a convergence study with respect to h . Repeat the convergence test using finite elements of degree 2. Report the results and discuss them in light of the theory.

Exercise 2.

Consider the problem

$$\begin{cases} \frac{\partial u}{\partial t} - \Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \subset \mathbb{R}^2, t > 0, \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega, t > 0, \\ \mathbf{u}(\mathbf{x}, t = 0) = \mathbf{u}_0 & \text{in } \Omega, \\ \left(\frac{\partial \mathbf{u}}{\partial \mathbf{n}} - p \mathbf{n} \right) (\mathbf{x}, t) = \varphi(\mathbf{x}, t) & \text{on } \partial \Omega, t > 0, \end{cases} \quad (2)$$

where \mathbf{u}_0 and φ are two given functions, sufficiently regular.

2.1. [2 pt] Find the weak formulation of problem (2).

2.2. [1 pt] Approximate the weak formulation by the Taylor-Hood finite elements in space of degree 3 for the velocity and 2 for the pressure, and by the backward Euler method in time.

2.3. [1 pt] At any time step $t^n = n\Delta t$, discuss the well-posedness of the corresponding problem.

2.4. [3 pt] Is the approximation of Exercise 2.2 stable in time? Provide the corresponding error estimate.

2.5. [3 pt] Using `deal.II`, implement a finite element solver for (2). Consider the square domain $\Omega = (0, 1)^2$ depicted in Figure 1. Consider the following problem data:

$$\begin{aligned} \mathbf{u}_0(\mathbf{x}) &= \mathbf{0} && \text{in } \Omega , \\ \boldsymbol{\varphi}(\mathbf{x}, t) &= -g(\mathbf{x})\mathbf{n} , && \text{on } \partial\Omega, t > 0 , \\ g(\mathbf{x}) &= \begin{cases} 0 & \text{on } \Gamma_0 , \\ 1 & \text{on } \Gamma_1 , \\ 2 & \text{on } \Gamma_2 , \\ 3 & \text{on } \Gamma_3 \end{cases} && \text{on } \partial\Omega . \end{aligned}$$

Use the mesh \mathcal{T}_h of $h = 0.1$ that can be found at <https://github.com/michelebucelli/nmpde-labs-aa-24-25/tree/main/examples/gmsh>. Use finite elements of degree 2 and 1 for velocity and pressure respectively. Set the time step to $\Delta t = 0.1$ and the final time to $T = 1$. Upload the source code of the solver.

Hint: for simplicity, you can reassemble every time step the whole system (that is, you are not required to store matrices that do not change between time steps).

Hint: to evaluate the velocity on quadrature nodes of the current cell, you can use the following code snippet:

```
fe_values[velocities].get_function_values(solution, velocity_loc)
```

Refer to `deal.II`'s documentation for `FEValuesViews::Vector` for more information.

2.6. [1 pt] Upload a plot of the solution at time $t = 1$.