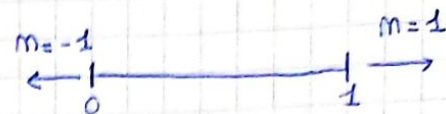


2025-06-04

EX 1

1.1
$$\begin{cases} -\frac{d}{dx} \left(\varepsilon(1+x^2) \frac{du}{dx} \right) + \frac{du}{dx} = 0 \\ u(0) = 0 \rightarrow \Gamma_0 \\ u(1) = 1 \rightarrow \Gamma_1 \neq 0 \Rightarrow \text{LIFTING} \end{cases}$$

$0 < x < 1 \quad 0 < \varepsilon < 1$



WEAK FORMULATION:

Spazio funzioni test: $V_0 = H_0^1(0,1)$

Spazio soluzioni: $V = \{v \in H^1(0,1) \text{ s.t. } \underbrace{v(1)=1}_{\text{Dirichlet boundary condition}}\}$

Let $v \in V_0$:

$$\int_0^1 \frac{d}{dx} \left(\varepsilon(1+x^2) \frac{du}{dx} \right) \cdot v \, dx + \int_0^1 \frac{du}{dx} \cdot v \, dx = 0$$

$= u(x)$

$$\int_0^1 \varepsilon(1+x^2) \frac{du}{dx} \frac{dv}{dx} \, dx - \left[\varepsilon(1+x^2) \frac{du}{dx} \cdot m \cdot v \right]_{x=0}^{x=1} + \int_0^1 \frac{du}{dx} \cdot v \, dx = 0$$

because $v \in V_0$, and $v(0) = v(1) = 0$

$$\int_0^1 \varepsilon(1+x^2) \frac{du}{dx} \frac{dv}{dx} \, dx + \int_0^1 \frac{du}{dx} v \, dx = 0 \quad \underbrace{\hspace{10em}}_{F(v)}$$

$a(u, v)$

find $u \in V$ s.t. $a(u, v) = F(v) \quad \forall v \in V_0$ (WP)

LIFTING: I want to have solutions in V_0 ; suppose $\exists R_g \in V$ s.t. $u = \hat{u} + R_g$ and $\hat{u} \in V_0$

$$a(\hat{u} + R_g, v) = F(v) = 0$$

$$a(\hat{u}, v) + a(R_g, v) = 0$$

$$a(\hat{u}, v) = -a(R_g, v)$$

nel testo ci viene chiesto $F(v)$, che dovrebbe essere il termine noto $G(v)$

$$a(\hat{u}, v) = \int_0^1 \varepsilon(1+x^2) \frac{d\hat{u}}{dx} \frac{dv}{dx} \, dx + \int_0^1 \frac{d\hat{u}}{dx} v \, dx = G(v)$$

$$G(v) = -a(R_g, v)$$

Final (WP):

$$\boxed{\begin{aligned} \text{Find } \hat{u} \in V_0 \text{ s.t.:} \\ a(\hat{u}, v) = G(v) \quad \forall v \in V_0 \end{aligned}}$$

GG:

$$-\frac{1}{2} \int_0^1 v^2 dx + \frac{1}{2} [v^2]_0^1 = 0 \quad \left. v \right|_{x=0} = 0, \quad \left. v \right|_{x=1} = 0$$

$$= -\frac{1}{2} \int_0^1 v^2 dx$$

COERCIVITY:

$$\begin{aligned} a(v, v) &= \int_0^1 \varepsilon(1+x^2) \frac{dv}{dx} \frac{dv}{dx} dx + \int_0^1 \frac{dv}{dx} v dx = \\ &= \int_0^1 \varepsilon(1+x^2) \left(\frac{dv}{dx} \right)^2 dx + \int_0^1 \frac{dv}{dx} v dx \geq \\ &\geq \underbrace{\varepsilon \cdot \left(1 + \min_x (x^2) \right)}_{\geq 0} \cdot \int_0^1 \left(\frac{dv}{dx} \right)^2 dx + \underbrace{\int_0^1 \frac{dv}{dx} v dx}_{=0} = \end{aligned}$$

~~$$= \mu_{\min} \|v'\|_{L^2(0,1)}^2 - \frac{1}{2} \int_0^1 v^2 dx$$~~

$$= \mu_{\min} \|v'\|_{L^2(0,1)}^2 - \frac{1}{2} \int_0^1 v^2 dx \quad ?? \quad -\frac{1}{2} < 0$$

disuguaglianza
triangolare

CONTINUITY:

$$\begin{aligned} |a(u, v)| &\leq \left| \int_0^1 \varepsilon(1+x^2) \frac{du}{dx} \frac{dv}{dx} dx \right| + \left| \int_0^1 \frac{du}{dx} v dx \right| \leq \\ &\leq \max_{x \in (0,1)} |\varepsilon(1+x^2)| \cdot \int_0^1 \frac{du}{dx} \frac{dv}{dx} dx + \left| \int_0^1 u' v dx \right| \leq \quad \text{C-S} \\ &\leq \mu_{\max} \cdot \|u'\|_{L^2(0,1)} \cdot \|v'\|_{L^2(0,1)} + \|u'\|_{L^2(0,1)} \cdot \|v\|_{L^2(0,1)} \leq \\ &\leq \underbrace{\mu_{\max}}_{\text{per } x=1:} \|u\|_{H^1} \|v\|_{H^1} + \|u\|_{H^1} \cdot \|v\|_{H^1} = \\ &\quad \underbrace{(2\varepsilon + 1)}_{=M} \cdot \|u\|_{H^1} \cdot \|v\|_{H^1} \end{aligned}$$

NORM $\|F\|_{V_1}$:

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EXERCISE 2

TIME-DEPENDENT STOKES

$d=2$

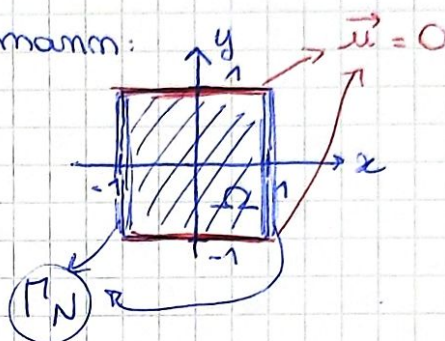
$$\begin{cases} -\mu \Delta \vec{u} + \nabla p = \vec{f} \\ \operatorname{div} \vec{u} = 0 \\ \vec{u} = 0 \\ \mu \frac{\partial \vec{u}}{\partial \vec{m}} - p \vec{m} = 0 \end{cases} \quad \begin{aligned} (x, y) \in \Omega = (-1, 1)^2 \\ (x, y) \in \Omega \\ \text{if } y = -1 \text{ or } y = 1 \quad \Gamma_D \\ \text{if } x = -1 \text{ or } x = 1 \quad \Gamma_N \end{aligned}$$

With $\mu=2$ and $\vec{f} = [1 + x \sin^2(x), 0]^T$.

2.1 Mixed dirichlet-neumann:

$$V = [H_{\vec{m}}^1(\Omega)]^2$$

$$Q = L^2(\Omega)$$



Let $\vec{v} \in V, q \in Q$:

$$(a) \int_{\Omega} -\mu \Delta \vec{u} \cdot \vec{v} \, dx + \int_{\Omega} \nabla p \cdot \vec{v} \, dx = \int_{\Omega} \vec{f} \cdot \vec{v} \, dx$$

$$\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} \, dx - \int_{\partial \Omega} \mu \nabla \vec{u} \cdot \vec{m} \cdot \vec{v} \, dy = - \int_{\Omega} \operatorname{div} \vec{v} \cdot p \, dx + \int_{\partial \Omega} p \cdot \vec{m} \cdot \vec{v} \, dy =$$

$$\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} \, dx - \int_{\Omega} \nabla \cdot \vec{v} \cdot p \, dx - \int_{\partial \Omega} \left(\mu \frac{\partial \vec{u}}{\partial \vec{m}} - p \vec{m} \right) \cdot \vec{v} \, dy = \int_{\Omega} \vec{f} \cdot \vec{v} \, dx$$

because $\vec{v} \in V$ and $\vec{v}|_{\Gamma_D} = 0$

$$\int_{\Gamma_D} (\dots) \cdot \vec{v} \, dy + \int_{\Gamma_N} \left(\mu \frac{\partial \vec{u}}{\partial \vec{m}} - p \vec{m} \right) \cdot \vec{v} \, dy = 0 \quad (*)$$

$$\Rightarrow \underbrace{\int_{\Omega} \mu \nabla \vec{u} \cdot \nabla \vec{v} \, dx}_{=a(\vec{u}, \vec{v})} - \underbrace{\int_{\Omega} \nabla \cdot \vec{v} \cdot p \, dx}_{=b(\vec{v}, p)} = \underbrace{\int_{\Omega} \vec{f} \cdot \vec{v} \, dx}_{F(\vec{v})}$$

$$(b) - \int_{\Omega} \operatorname{div} \vec{u} \cdot q = 0$$

$= b(\vec{u}, q)$

Find $\vec{u} \in V, p \in Q$ s.t.

$$(a) \quad a(\vec{u}, \vec{v}) + b(\vec{v}, p) = F(\vec{v})$$

$$(b) \quad b(\vec{u}, q) = 0$$

$$\forall \vec{v} \in V$$

$$\forall q \in Q$$

(WP)

2.2 MESH-TRIANGULATION:

① Partition of Ω : $K_c, c=1, \dots, N_{ee}$ s.t. $\bigcup_{i=1}^{N_{ee}} K_i = \Omega$
 $K_i \cap K_j = \emptyset \quad \forall i \neq j$

② $X_R^{x,d}(\Omega) = \{v \in [C^0(\Omega)]^d, v_R|_{K_i} \in [P^x(K_i)]^d \quad \forall j\}$

• $V_R = V \cap X_R^{3,2}(\Omega) \rightarrow$ form space for vel ! $N_{V_R} < +\infty$

• $Q_R = Q \cap X_R^{2,1}(\Omega) \rightarrow$ form space for press ! $N_{Q_R} < +\infty$

(WP) is:

Find $\vec{u}_R \in V_R, p_R \in Q_R$ s.t.:

$$(a) \quad a(\vec{u}_R, \vec{v}_R) + b(\vec{v}_R, p_R) = F(\vec{v}_R) \quad \forall \vec{v}_R \in V_R \quad (G)$$

$$(b) \quad b(\vec{u}_R, q_R) = 0 \quad \forall q_R \in Q_R$$

$\{\vec{\varphi}_j(x)\}_{j=1}^{N_{V_R}} \rightarrow$ basis for V_R

$\{\psi_j(x)\}_{j=1}^{N_{Q_R}} \rightarrow$ basis for Q_R

Expansions:

$$\vec{u}_R(x) = \sum_{j=1}^{N_{V_R}} u_j \cdot \vec{\varphi}_j(x)$$

$$\vec{v}_R(x) = \vec{\varphi}_i(x)$$

$$p_R(x) = \sum_{j=1}^{N_{Q_R}} p_j \cdot \psi_j(x)$$

$$q_R(x) = \psi_k(x)$$

$$\vec{u} = [u_1, \dots, u_{N_{V_R}}] ;$$

$$\vec{p} = [p_1, \dots, p_{N_{Q_R}}]$$

Therefore:

$$(a) \quad a\left(\sum_{j=1}^{N_{V_R}} u_j \cdot \vec{\varphi}_j(x), \vec{\varphi}_i(x)\right) + b\left(\vec{\varphi}_i(x), \sum_{j=1}^{N_{Q_R}} p_j \cdot \psi_j(x)\right) = F(\vec{\varphi}_i(x)) \quad \forall i$$

$$\sum_{j=1}^{N_{V_R}} u_j \cdot \underbrace{a(\vec{\varphi}_j(x), \vec{\varphi}_i(x))}_{A_{ij}} + \sum_{j=1}^{N_{Q_R}} p_j \cdot \underbrace{b(\vec{\varphi}_i(x), \psi_j(x))}_{B_{ji}} = F(\vec{\varphi}_i(x)) \quad \forall i$$

$$\Rightarrow (a): \quad A \vec{u} + B^T \vec{p} = \vec{F}$$

$$(b) \quad b\left(\sum_{j=1}^{N_{V_R}} u_j \cdot \vec{\varphi}_j(x), \psi_k(x)\right) = 0 \quad \forall k$$

$$\sum_{j=1}^{N_{V_R}} u_j \cdot \underbrace{b(\vec{\varphi}_j(x), \psi_k(x))}_{B_{kj}} = 0 \quad \forall k$$

$$\Rightarrow (b): \quad B \vec{u} = 0$$

2.3 STABILITY for TAYLOR-HOODS:

TH: $\exists!$ of \vec{u}_R, p_R

Assume that:

① $a: V \times V \rightarrow \mathbb{R}$ is $\begin{cases} \text{bilinear} \\ \text{continuous} \\ \text{coercive} \end{cases}$

② Assume that $b: V \times Q \rightarrow \mathbb{R}$ is: $\begin{cases} \text{bilinear} \\ \text{continuous} \\ \text{LBB satisfied} \end{cases}$

$\Rightarrow \exists! \vec{u}_h, p_h$ solution to (G); moreover:

$$\left. \begin{aligned} \bullet \|\vec{u}_h\|_V &\leq \frac{1}{\alpha} \|F\|_V \\ \bullet \|p_h\|_Q &\leq \frac{1}{\beta} \left(1 + \frac{\gamma}{\alpha}\right) \|F\|_V \end{aligned} \right\} \begin{array}{l} \text{stability properties} \\ \Rightarrow \text{we have (G) stable} \end{array}$$

$= C$

2.4 ERROR ESTIMATE for T-H elements.

$$\underbrace{\|\vec{u} - \vec{u}_h\|_V}_{\text{error on velocity}} + \underbrace{\|p - p_h\|_Q}_{\text{error on pressure}} \leq C \underbrace{h^{k+1}}_{\text{degree}} \left(\|\vec{u}\|_{[H^{k+2}(\Omega)]^2} + \|p\|_{H^{k+1}(\Omega)} \right)$$

2.5 NON-SINGULARITY of the system: $\rightarrow \begin{cases} A\vec{u} + B^T \vec{p} = \vec{F} \\ B\vec{u} = 0 \end{cases}$

S is non-singular because LBB is satisfied:

$$\exists \beta > 0 \text{ s.t. } \forall q_h \in Q_h \quad \exists \vec{u}_h \in V_h : b(\vec{u}_h, q_h) \geq \beta \|\vec{u}_h\|_V \|q_h\|_Q$$

$$\Leftrightarrow \exists \beta \text{ s.t. } \inf_{\substack{q_h \in Q_h \\ q_h \neq 0}} \sup_{\substack{\vec{u}_h \in V_h \\ \vec{u}_h \neq 0}} \frac{b(\vec{u}_h, q_h)}{\|\vec{u}_h\|_V \cdot \|q_h\|_Q} \geq \beta$$