>> Dynamic_Result

m =

m1

m2

mЗ

m4

m5

ans =

-Izz5

ans =

0

ans =

0

ans =

 \cap

ans =

Izz5

 $q_d =$

t1_d

t2_d

t3_d

t4_d

t5_d

q =

t1

t2

```
t3
t4
t5
gT =
                 0 -9.8000
         0
G1 =
0
G2 =
(49*m4*(13*cos(t2 + t3) + 12*cos(t2)))/5 + (49*m5*(13*cos(t2 + t3) + 12*cos(t2)))/5
(49*m3*(1c3*cos(t2 + t3) + 12*cos(t2)))/5 + (49*1c2*m2*cos(t2))/5
G3 =
(49*13*m4*cos(t2 + t3))/5 + (49*13*m5*cos(t2 + t3))/5 + (49*1c3*m3*cos(t2 + t3))/5
G4 =
0
G5 =
0
G =
ĸ
0
(49*m4*(13*cos(t2 + t3) + 12*cos(t2)))/5 + (49*m5*(13*cos(t2 + t3) + 12*cos(t2)))/$
+ (49*m3*(1c3*cos(t2 + t3) + 12*cos(t2)))/5 + (49*1c2*m2*cos(t2))/5
(49*\cos(t2 + t3)*(13*m4 + 13*m5 + 1c3*m3))/5
0
Ľ
0
```

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