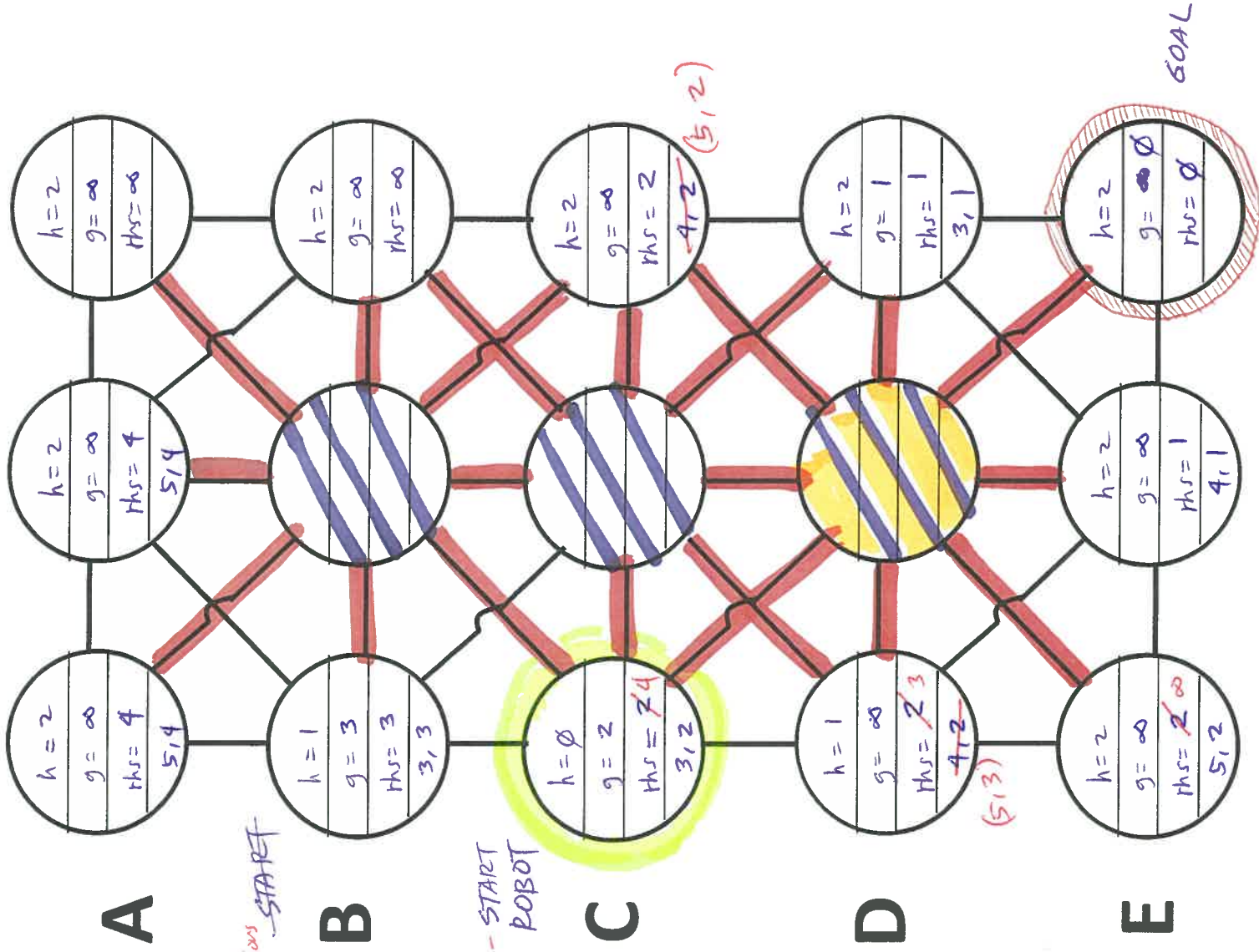


1 2 3



The robot moves to cell C & cell D is detected to be blocked.

REPLANNING

STEP DEQ

Ø

$\begin{pmatrix} A1 \\ g = \infty \\ h_{rs} = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} A2 \\ g = \infty \\ h_{rs} = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} D1 \\ g = \infty \\ h_{rs} = 2 \\ 4, 2 \end{pmatrix}$	$\begin{pmatrix} C3 \\ g = \infty \\ h_{rs} = 2 \\ 4, 2 \end{pmatrix}$	$\begin{pmatrix} E2 \\ g = \infty \\ h_{rs} = 1 \\ 4, 1 \end{pmatrix}$	$\begin{pmatrix} E1 \\ g = \infty \\ h_{rs} = 2 \\ 5, 2 \end{pmatrix}$
--	--	--	--	--	--

$S_{START} = \min_{s'} \text{successor}_s \text{ with } c(s', start) + g(s')$

$$= C1$$

move to $S_{START} = C1$

Scan for changed edge costs:

if edge costs changed,

$$k_m = k_m + h(s_{LAST}, s_{START})$$

$$= \emptyset + 1 = 1$$

Affected nodes due to edge costs change,

$C1, C3, D1, D3, E1, E2, E3$

updateVertex(C1):

$$h_{rs} = 3 + 1 = 4$$

Insert $(3, 2) =$ key is still the same as before but the calculations show that the h-value & km variables have changed

updateVertex(C3):

$$h_{rs} = 1 + 1 = 2$$

Remove, insert back $(5, 2)$ $2 + 2 + 1$

updateVertex(D1):

$$h_{rs} = 2 + 1 = 3$$

Remove, insert back $(5, 3)$ $3 + 1 + 1$

Continuation of STEP	DEQ	ENQ
\emptyset		<div> $\begin{pmatrix} C1 \\ g = 2 \\ h_s = 4 \\ 3, 2 \end{pmatrix}$ $\begin{pmatrix} C3 \\ g = \infty \\ h_s = 2 \\ 5, 2 \end{pmatrix}$ $\begin{pmatrix} D1 \\ g = \infty \\ h_s = 3 \\ 5, 3 \end{pmatrix}$ $\begin{pmatrix} E2 \\ g = \infty \\ h_s = 1 \\ 4, 1 \end{pmatrix}$ </div>
		<div> $\begin{pmatrix} A1 \\ g = \infty \\ h_s = 4 \\ 5, 4 \end{pmatrix}$ $\begin{pmatrix} A2 \\ g = \infty \\ h_s = 4 \\ 5, 4 \end{pmatrix}$ </div>

updateVertex(D3)

$$h_s = 0 + 1 = 1$$

consistent already

updateVertex(E1)

$$h_s = \infty + 1 = \infty$$

remove

consistent already

updateVertex(E2)

$$h_s = \emptyset + 1 = 1$$

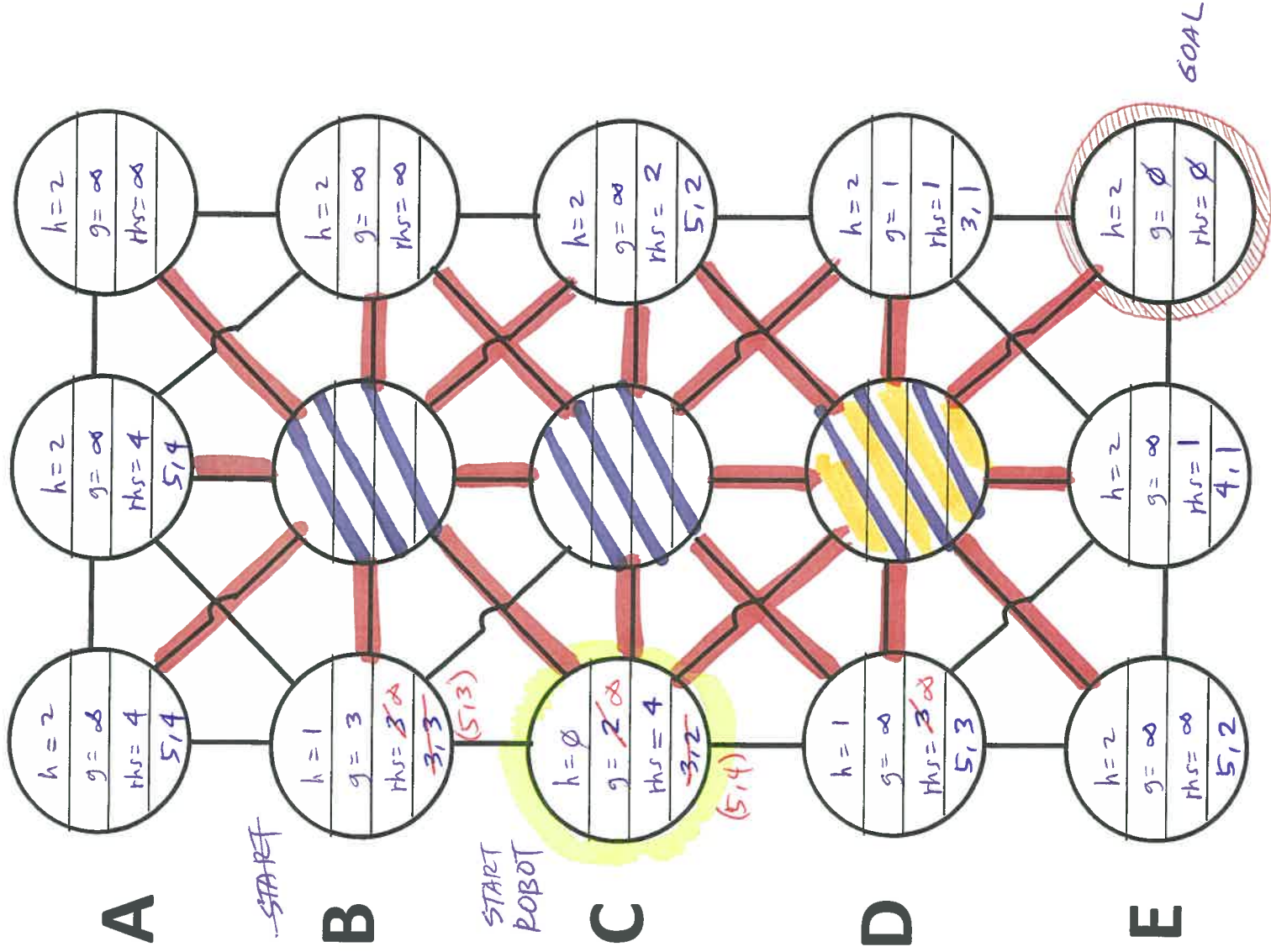
remove, insert $(4, 1)$
1+2+1

updateVertex(E3)

Goal! don't update h_s

consistent already

1 2 3



REPLANNING
STEP 1

STEP	DEA	END
1	$\begin{pmatrix} C1 \\ g = 2 \text{ } \infty \\ hrs = 4 \\ 3, 2 \end{pmatrix}$	$(3, 2) < (3, 2) \text{ or } hrs(stat) \neq g(stat)$

$(3, 2) < (3, 2)$ or $hrs(stat) \neq g(stat)$
 $4 \neq 2$
 false or true

kold = (3, 2)

$g \leq hrs$

$g = \infty$

$prod(C1) \cup \{C1\} : B1, D1, C1$

updateVertex (B1)

$hrs = \infty + 1 = \infty$
 $hreat (5, 3)$

updateVertex (D1)

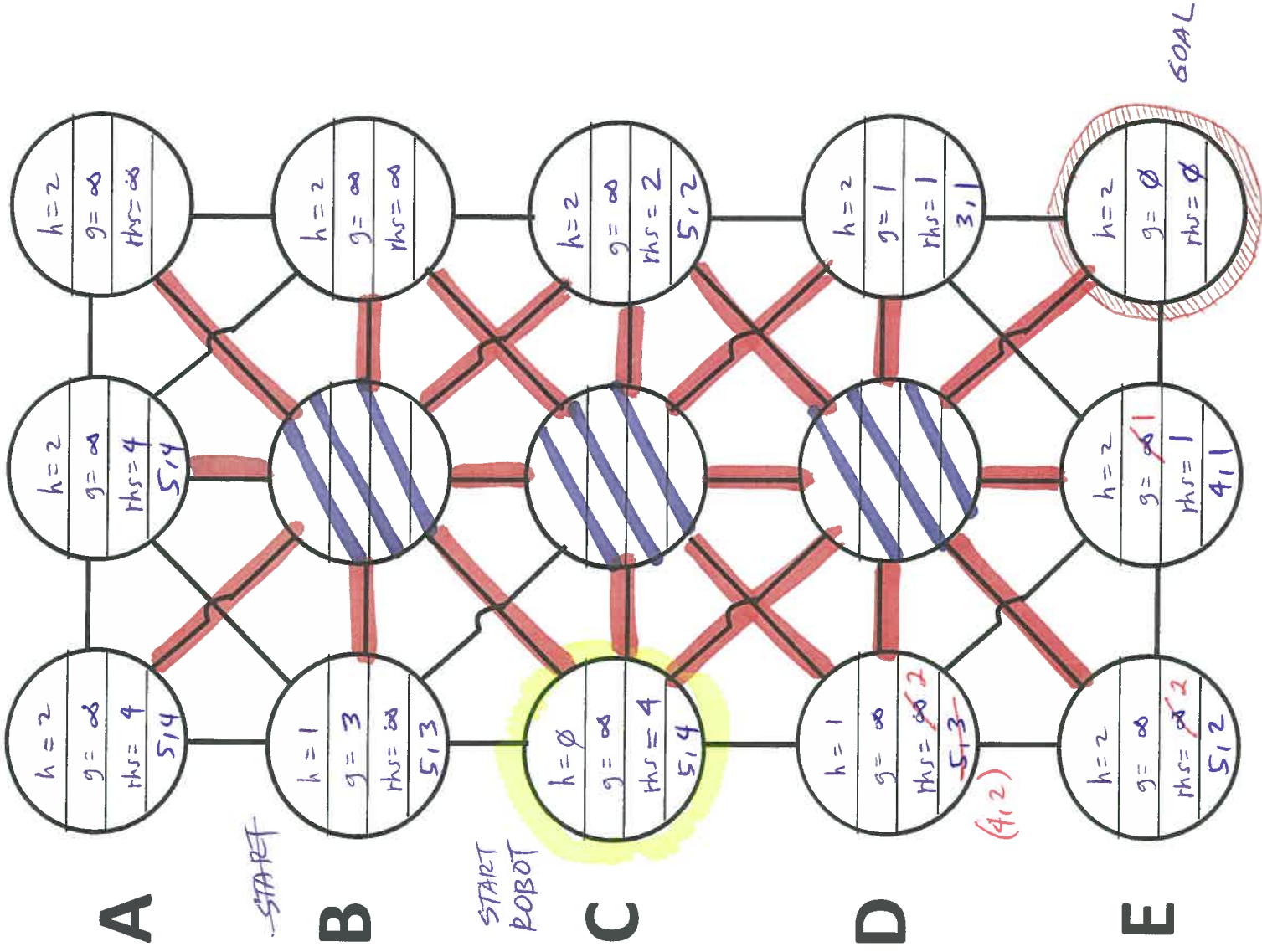
$hrs = \infty + 1 = \infty$
 remove
 consistent already
 updateVertex (C1)

$hrs = 3 + 1 = 4$
 insert (5, 4)
 $4 + 0 + 1$

Queue

$\begin{pmatrix} B1 \\ g = 3 \\ hrs = \infty \\ 5, 3 \end{pmatrix}$	$\begin{pmatrix} C1 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} C3 \\ g = \infty \\ hrs = 2 \\ 5, 2 \end{pmatrix}$	$\begin{pmatrix} E2 \\ g = \infty \\ hrs = 1 \\ 4, 1 \end{pmatrix}$	$\begin{pmatrix} A1 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} A2 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$
---	---	---	---	---	---

1 2 3



STEP 2

STEP	DEQ	ENQ
2	$\begin{pmatrix} E2 \\ g = \infty \\ hrs = 1 \\ 4, 1 \end{pmatrix}$	$(4, 1) < (5, 4) \text{ or } hrs(stat) \neq g(stat)$ $\underbrace{4 \neq \infty}_{\text{true}} \text{ or } \text{true}$

kold = (4, 1)

~~4~~ (4, 1)

if (kold < cdekey (E2))

(4, 1)
1 + 2 + 1

$g > hrs$

pred (E2) : D1, D3, E1, E3

updateVertex (D1)

$hrs = 1 + 1 = 2$
 $hrs = \frac{2 + 1 + 1}{4, 2}$

updateVertex (D3)

$hrs = \infty + 1 = 1$
 consistent

updateVertex (E1)

$hrs = 1 + 1 = 2$
 $hrs = \frac{2 + 2 + 1}{5, 2}$

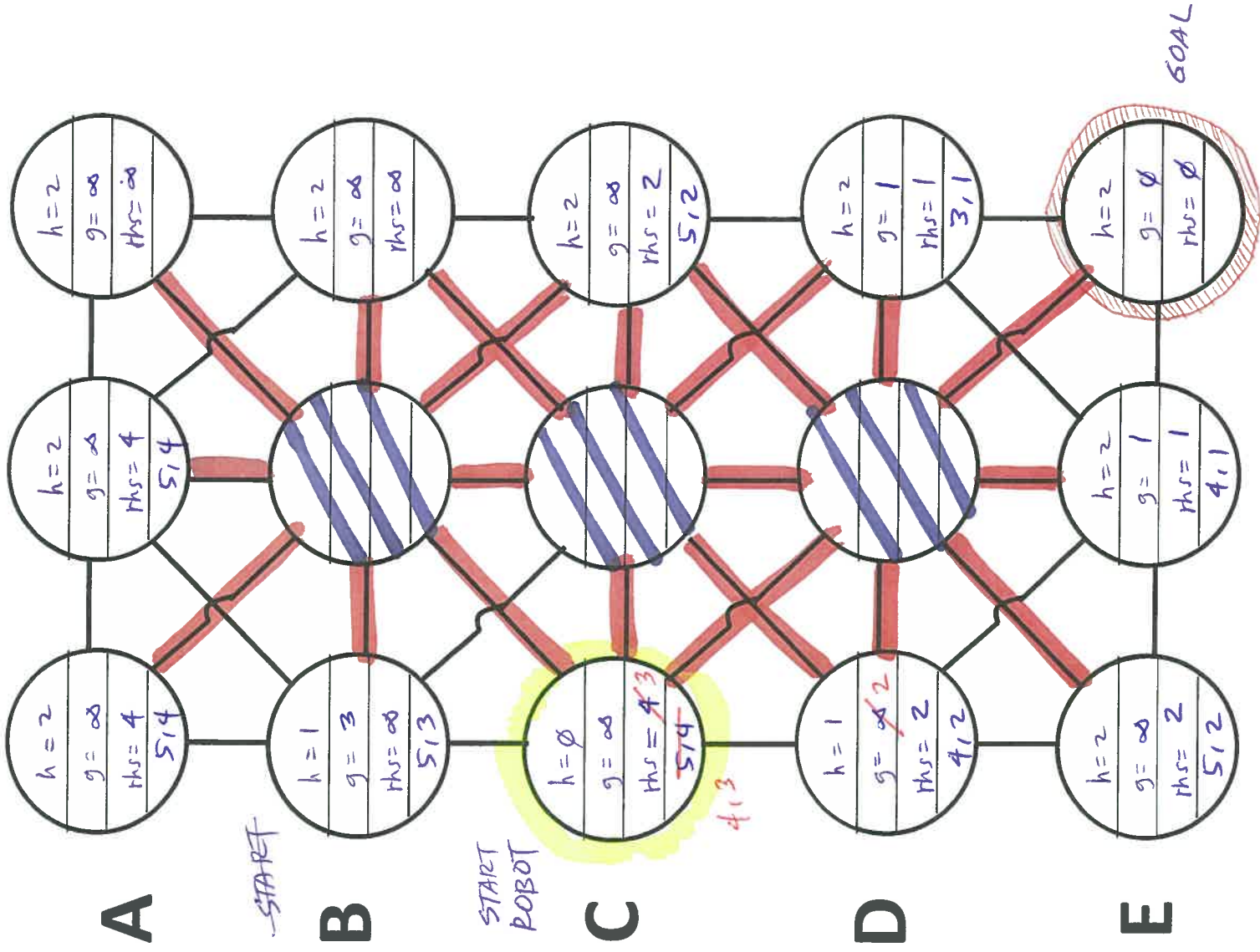
updateVertex (E3)

Good! don't update hrs

consistent already

$\begin{pmatrix} D1 \\ g = \infty \\ hrs = 2 \\ 4, 2 \end{pmatrix}$	$\begin{pmatrix} E1 \\ g = \infty \\ hrs = 2 \\ 5, 2 \end{pmatrix}$	$\begin{pmatrix} B1 \\ g = 3 \\ hrs = \infty \\ 5, 3 \end{pmatrix}$	$\begin{pmatrix} C1 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} A1 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} A2 \\ g = \infty \\ hrs = 4 \\ 5, 4 \end{pmatrix}$
---	---	---	---	---	---

1 2 3



STEP DEQ ENQ

3 $(4, 2) < (5, 4)$ or $hrs(stat) \neq g(stat)$
 $4 \neq \infty$ true or true

kold = 4, 2

if (kold < calcKey(D1))

(4, 2) $2+1+1$

pred (D1): C1, E1, E2

updateVertex(C1)

$hrs = 2+1=3$
 remove, insert back $(4, 3)$
 $3+0+1$

updateVertex(E1)

$hrs = 1+1=2$
 remove, insert back $(5, 2)$
 $2+2+1$

updateVertex(E2)

$hrs = 0+1=1$

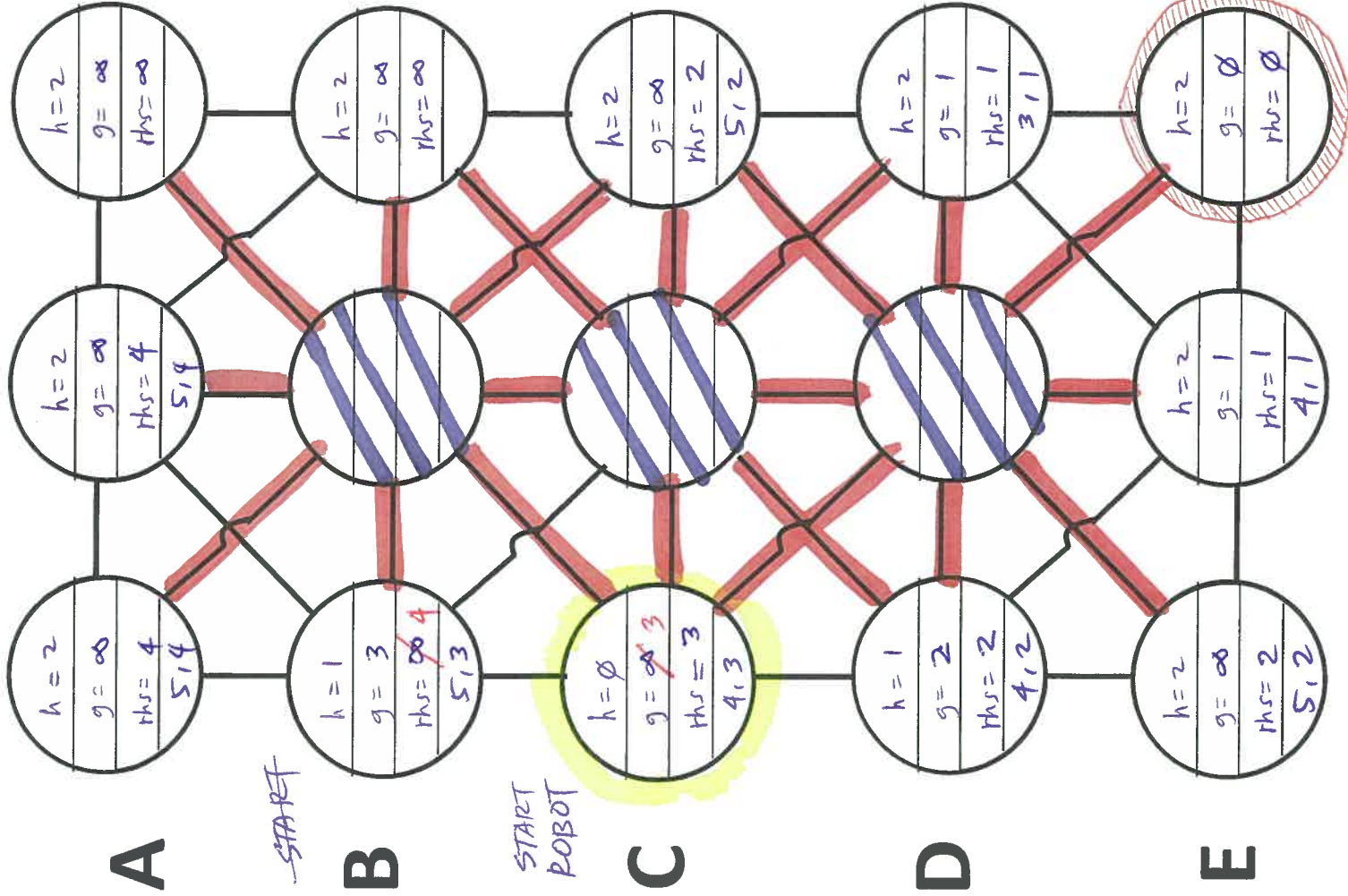
consistent already

~~$(C1)$ $(E1)$ $(B1)$ $(C3)$ $(A1)$ $(A2)$
 $g = \infty$ $g = \infty$ $g = 3$ $g = \infty$ $g = \infty$
 $hrs = 3$ $hrs = 2$ $hrs = \infty$ $hrs = 2$ $hrs = 4$
 $4, 3$ $5, 2$ $5, 3$ $5, 2$ $5, 4$
 $5, 2$ $5, 3$ $5, 4$ $5, 4$~~

1

2

3



STEP	DEQ	ENQ
4	$\begin{pmatrix} C1 \\ g = \cancel{\infty} 3 \\ rhs = 3 \\ 4, 3 \end{pmatrix}$	

$$(4, 3) < (4, 3) \text{ OR } rhs(start) \neq g(start)$$

$\underbrace{3 \neq \infty}_{\text{false}} \quad \text{OR} \quad \text{true} = \text{true}$

$$kold = (4, 3)$$

if (kold < calcK_g(C1))

$$(4, 3) \quad (4, 3) \quad 3+0+1$$

pred(C1) : B1, D1

updateVertex(B1)

$$rhs = 3+1 = 4 \quad 3+1+1$$

remove, insert (5, 3)

updateVertex(D1)

$$rhs = 1+1 = 2$$

consistent already

Queue

$\begin{pmatrix} B1 \\ g = 3 \\ rhs = 4 \\ 5, 3 \end{pmatrix}$	$\begin{pmatrix} E1 \\ g = \infty \\ rhs = 2 \\ 5, 2 \end{pmatrix}$	$\begin{pmatrix} C3 \\ g = \infty \\ rhs = 2 \\ 5, 2 \end{pmatrix}$	$\begin{pmatrix} A1 \\ g = \infty \\ rhs = 4 \\ 5, 4 \end{pmatrix}$	$\begin{pmatrix} A2 \\ g = \infty \\ rhs = 4 \\ 5, 4 \end{pmatrix}$
--	---	---	---	---

STEP	DEQ	ENQ
5		

$$(5, 2) < (4, 3) \text{ OR } rhs(start) \neq g(start)$$

$\underbrace{3 \neq 3}_{\text{false}} \quad \text{OR} \quad \text{false} = \text{false}$
 $\neq \text{No}$