

# EE2211 Pre-Tutorial 4

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# Agenda

- Recap
- Self-learning
- Tutorial 4



# Recap

- Operations on Vectors and Matrices
  - Dot-product, matrix inverse
- System of Linear Equations
  - Matrix-vector notation, linear dependency, invertible
  - Even-, over-, under-determined linear systems
- Set and Functions
  - Inner product function
  - Linear and affine functions

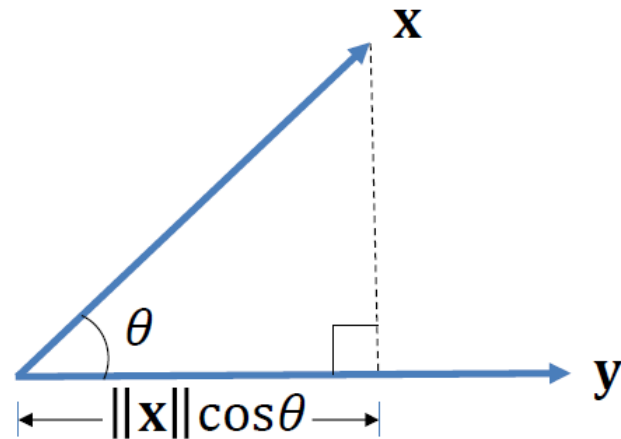
# Operations on Vectors and Matrices

## Dot Product or Inner Product of Vectors:

$$\begin{aligned}\mathbf{x} \cdot \mathbf{y} &= \mathbf{x}^T \mathbf{y} \\ &= [x_1 \ x_2] \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \\ &= x_1 y_1 + x_2 y_2\end{aligned}$$

Geometric definition:

$$\mathbf{x} \cdot \mathbf{y} = \|\mathbf{x}\| \|\mathbf{y}\| \cos \theta$$



Where  $\theta$  is the angle between  $\mathbf{x}$  and  $\mathbf{y}$ , and  $\|\mathbf{x}\| = \sqrt{\mathbf{x} \cdot \mathbf{x}}$  is the Euclidean length of vector  $\mathbf{x}$

# Operations on Vectors and Matrices

## Matrix inversion computation

$$A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$$

- $\det(A)$  is the determinant of  $A$
- $\text{adj}(A)$  is the adjugate or adjoint of  $A$

## Determinant computation

Example: 2x2 matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det(A) = |A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

# Systems of Linear Equations

## Even-, over-, under-determined linear systems

$X \in \mathbb{R}^m \times d$   
e.g. Samples of features

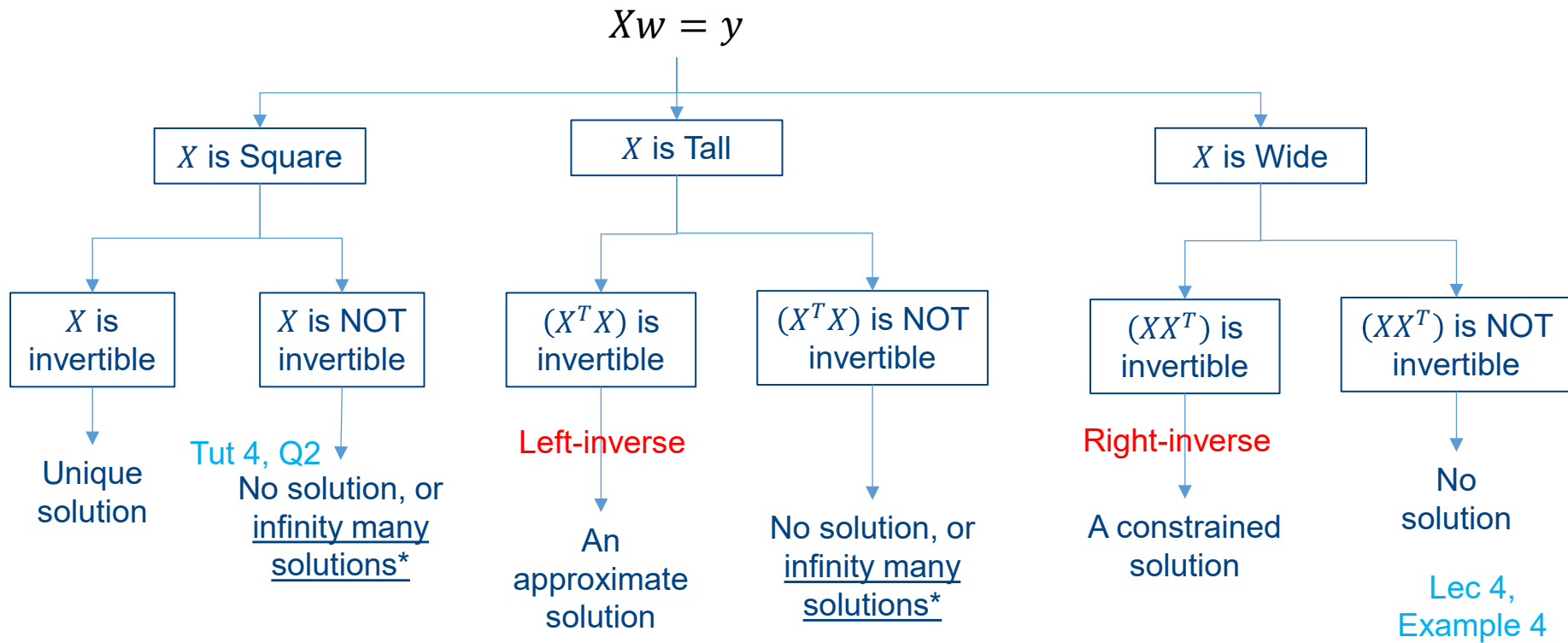
$Xw = y$

$y$ : Target values

$w$ : Weightings

$X$ is Square	Even-determined	$m = d$	One unique solution in general	$\hat{w} = X^{-1}y$
$X$ is Tall	Over-determined	$m > d$	No exact solution in general; An approximated solution	$\hat{w} = (X^T X)^{-1} X^T y$ Left-inverse
$X$ is Wide	Under-determined	$m < d$	Infinite number of solutions in general; Unique constrained solution	$\hat{w} = X^T (X X^T)^{-1} y$ Right-inverse

# Systems of Linear Equations



# Functions

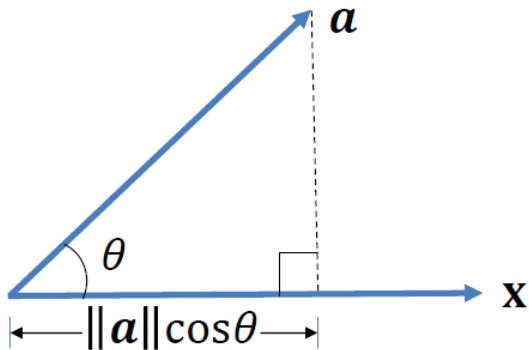
## The inner production function

- Suppose  $\mathbf{a}$  is a  $d$ -vector. We can define a scalar valued function  $f$  of  $d$ -vectors, given by

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} = a_1 x_1 + a_2 x_2 + \cdots a_d x_d \quad (1)$$

for any  $d$ -vector  $\mathbf{x}$

- The inner product of its  $d$ -vector argument  $\mathbf{x}$  with some (fixed)  $d$ -vector  $\mathbf{a}$
- We can also think of  $f$  as forming a **weighted sum** of the elements of  $\mathbf{x}$ ; the elements of  $\mathbf{a}$  give the weights





# Functions

## Linear Functions

### Superposition and linearity

- The inner product function  $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x}$  defined in equation (1) (slide 9) satisfies the property

$$\begin{aligned} f(\alpha \mathbf{x} + \beta \mathbf{y}) &= \mathbf{a}^T (\alpha \mathbf{x} + \beta \mathbf{y}) \\ &= \mathbf{a}^T (\alpha \mathbf{x}) + \mathbf{a}^T (\beta \mathbf{y}) \\ &= \alpha (\mathbf{a}^T \mathbf{x}) + \beta (\mathbf{a}^T \mathbf{y}) \\ &= \alpha f(\mathbf{x}) + \beta f(\mathbf{y}) \end{aligned}$$

for all  $d$ -vectors  $\mathbf{x}$ ,  $\mathbf{y}$ , and all scalars  $\alpha$ ,  $\beta$ .

- This property is called **superposition**, which consists of **homogeneity** and **additivity**
- A **function** that satisfies the superposition property is called **linear**

# Functions

## Linear and Affine Functions

A linear function plus a constant is called an affine function

A linear function  $f: \mathcal{R}^d \rightarrow \mathcal{R}$  is **affine** if and only if it can be expressed as  $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + b$  for some  $d$ -vector  $\mathbf{a}$  and scalar  $b$ , which is called the **offset (or bias)**

**Example:**

$$f(\mathbf{x}) = 2.3 - 2x_1 + 1.3x_2 - x_3$$

This function is affine, with  $b = 2.3$ ,  $\mathbf{a}^T = [-2, 1.3, -1]$ .



**THANK YOU**