

EE2211 Pre-Tutorial 12

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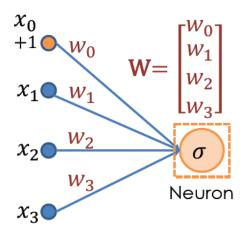
Agenda

- Recap
- Self-learning
- Tutorial 12

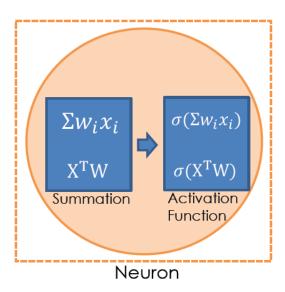
Recap

- Introduction to Neural Networks
 - Perceptron
 - Activation Functions
 - Multi-layer Perceptron
- Training and Testing of Neural Networks
 - Training: Forward and Backward
 - Testing: Forward
- Convolutional Neural Networks

Perceptron



$$\mathbf{X} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$



Output of Neuron: $\sigma(X^TW)$ or $\sigma(\Sigma w_i x_i)$

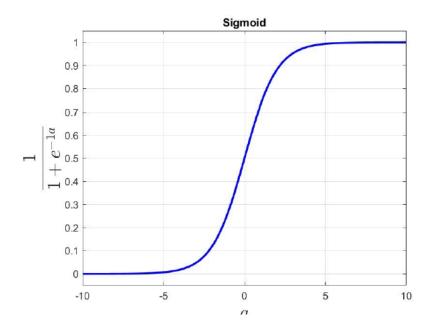
Activation Function: non-linear function to introduce non-linearity into the neural networks!

Goal of training: to learn W!

Activation Functions

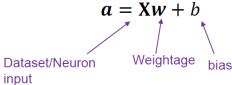
Sigmoid Activation Function

$$\sigma(a) = \frac{1}{1 + e^{-\beta a}},$$



- Output values between 0 to 1
- Used when have to predate the probability as output

$$\sigma(a) = \frac{1}{1 + e^{-\beta a}}$$



Tutorial 8, Question 4

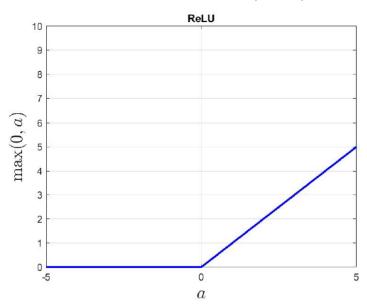
$$\sigma'(x) = \sigma(x) \cdot (1 - \sigma(x)).$$

Activation Functions

ReLU Activation Function

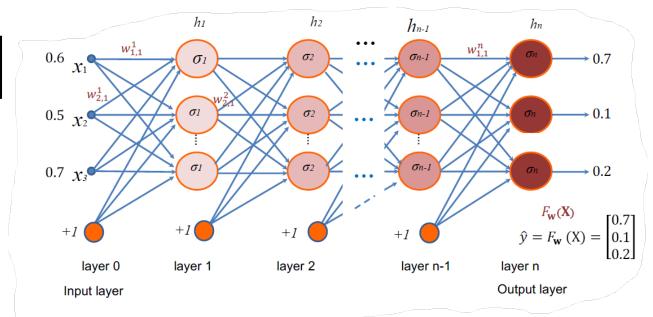
$$\sigma(a) = \max(0, a)$$

Rectified Linear Unit (ReLU)



Goal of Neural Network Training: to Learn W

$$X = \begin{bmatrix} 0.6\\0.5\\0.7 \end{bmatrix}$$

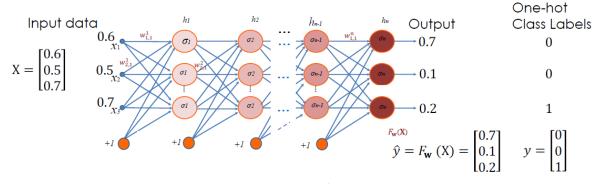


Specifically, W is learned through

- Random initialization
- 2. Backpropagation

Neural Network Training: Backpropagation

Assume we train a NN for 3-class classification



Forward: (weights are fixed)
 To compute network responses
 To compute the errors at each output

2. Backward: (weights are updated)
To pass back the error from the output to the hidden layers
To update all weights to optimize the network

A loss function for a single sample:

$$\min_{\mathbf{w}} \sum_{i=1}^{C} (\hat{y}_i - y_i)^2$$
or
$$\min_{\mathbf{w}} ||\hat{y} - y||^2$$

Update W!

Neural Network Training: Backpropagation

- Recall that the parameters W are randomly initialized.
- We use Backpropagation to update W.
- In essence, Backpropagation is gradient descent!
- Assume we have N samples, each sample denoted by X^j and the output of NN by \hat{y}^j , loss function is then

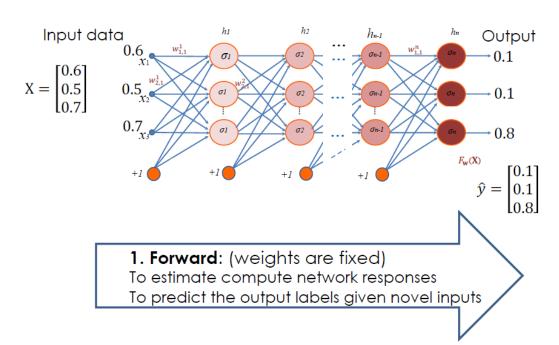
$$J = \sum_{j=1}^{N} \|\hat{y}^{j} - y^{j}\|^{2}, \quad \min_{\mathbf{w}} J$$
Recall gradient descent in Lec 8: $\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla_{\mathbf{w}} J$

- We would therefore like to compute ∇_wJ!
 - -J is a function of \hat{y} , and \hat{y} is a function of \mathbf{w} , i.e., $\hat{y} = F_{\mathbf{w}}(X)$
 - Use gradient descent and chain rule!

Being aware of the basic concept is sufficient for exam. No calculation needed.

Neural Network Testing

Once all network is trained and parameters are updated, we may conduct testing.



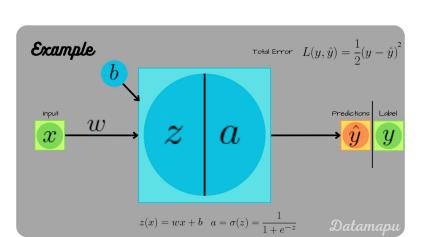


Illustration of a Neural Network consisting of a single Neuron.

https://datamapu.com/posts/deep_learning/backpropagation/

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Training Data

We consider the most simple situation with one-dimensional input data and just one sample x=0.5 and labels $y=\mathbf{1.5}$

Activation Function

As activation function, we use the Sigmoid function

$$\sigma(x) = \frac{1}{1 + e^{-x}}.$$

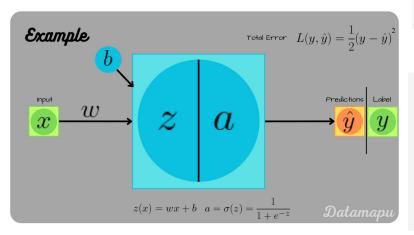
Loss Function

As loss function, we use the Sum of the Squared Error, defined as

$$L(y,\hat{y}) = rac{1}{2} \sum_{p=1}^{n} (y_p - \hat{y}_p)^2,$$

with $y_i = (y_1, \ldots, y_n)$ the labels and $\hat{y} = (\hat{y}_1, \ldots, \hat{y}_n)$ the predicted labels, and n the number of samples. In the examples considered in this post, we are only considering one-dimensional data, which means n = 1 and the formula simplifies to

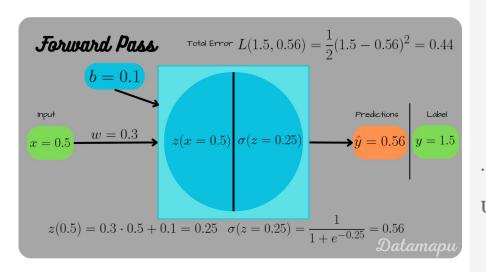
$$L(y,\hat{y})=rac{1}{2}(y-\hat{y})^2.$$



To illustrate how backpropagation works, we start with the most simple neural network, which only consists of one single neuron.

In this simple neural net, $z(x) = w \cdot x + b$ represents the linear part of the neuron and a the activation function, which we chose to be the sigmoid function, i.e. $a = \sigma(z) = \frac{1}{1+e^{-z}}$. For the following calculations, we assume the initial weight w = 0.3 and the initial bias b = 0.1. Further, the learning rate is set to $\alpha = 0.1$. These values are chosen arbitrarily for illustration purposes.

Illustration of a Neural Network consisting of a single Neuron.



The Forward Pass

We can calculate the forward pass through this network as

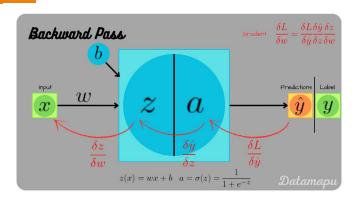
$$\hat{y}=\sigma(z)$$
 $\hat{y}=\sigma(wx+b),$ $\hat{y}=rac{1}{1+e^{-(wx+b)}}$

Using the weight, and bias defined above, we get for x=0.5

$$\hat{y} = \frac{1}{1 + e^{-(0.3 \cdot 0.5 + 0.1)}} = \frac{1}{1 + e^{-0.25}} \approx 0.56$$

The error after this forward pass can be calculated as

$$L(1.5, 0.56) = \frac{1}{2}(1.5 - 0.56)^2 = 0.44.$$



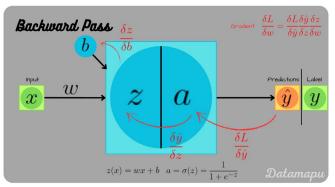


Illustration of backpropagation in a neural network consisting of a single neuron.

The Backward Pass

To update the weight and the bias we use **Gradient Descent**, that is

$$w_{new} = w - lpha rac{\delta L}{\delta w}$$

$$b_{new} = b - lpha rac{\delta L}{\delta b},$$

with $\alpha=0.1$ the learning rate. That is we need to calculate the partial derivatives of L with respect to w and b to get the new weight and bias. This can be done using the chain rule and is illustrated in the plots below.

$$rac{\delta L}{\delta w} = rac{\delta L}{\delta \hat{y}} rac{\delta \hat{y}}{\delta z} rac{\delta z}{\delta w}$$

$$\frac{\delta L}{\delta b} = \frac{\delta L}{\delta \hat{y}} \frac{\delta \hat{y}}{\delta z} \frac{\delta z}{\delta b}$$

 $\delta L \delta \hat{y} \delta z$

$$egin{aligned} rac{\delta w}{\delta w} &= rac{\delta z}{\delta \hat{y}} rac{\delta z}{\delta z} rac{\delta w}{\delta w} \ & rac{\delta L}{\delta b} &= rac{\delta L}{\delta \hat{y}} rac{\delta \hat{y}}{\delta z} rac{\delta z}{\delta b} \end{aligned}$$

We can calculte the indivi
$$rac{\delta L}{\delta \hat{u}} =$$

$$rac{\delta L}{\delta \hat{y}} = rac{\delta}{\delta \hat{y}} rac{1}{2} (y - \hat{y})^2 = -(y - \hat{y}),$$

$$rac{\delta \hat{y}}{\delta z} = rac{\delta}{\delta z} \sigma(z) = \sigma(z) \cdot ig(1 - \sigma(z)ig),$$

 $rac{\delta z}{\delta b} = rac{\delta}{\delta b}(w\cdot x + b) = 1.$

 $rac{\delta z}{\delta w} = rac{\delta}{\delta w}(w \cdot x + b) = x,$

$$\sigma'(x) = \sigma(x) \cdot (1 - \sigma(x)).$$

Tutorial 8, Question 4

For the data we are considering, we get for the first equation $\frac{\delta L}{\delta \hat{x}} = -(y - \hat{y}) = -(1.5 - 0.56) = -0.94.$

$$rac{\delta \hat{y}}{\delta z}$$

$$rac{\delta \hat{y}}{\delta z} =$$

$$rac{\delta \hat{y}}{\delta z} = \sigma(z) \cdot ig(1 - \sigma(z)ig)$$

$$= \frac{1}{1 + e^{-0.25}} \Big(1$$

$$\frac{\delta \hat{y}}{\delta z} = \frac{1}{1 + e^{-0.25}} \left(1 - \frac{1}{1 + e^{-0.25}} \right) = 0.56 \cdot 0.44 = 0.25,$$

$$\frac{\delta z}{\delta z} = \frac{1}{1}$$

$$1 + e^{-0.25}$$

$$rac{\delta z}{\delta w}=x=$$

$$\delta z$$
 1 finally

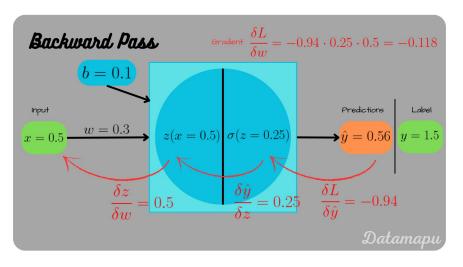
$$x=0.5,$$

$$x = 0.5,$$

$$rac{\delta z}{\delta w}=x=0.5,$$

$$rac{\delta z}{\delta w} =$$

$$rac{\delta w}{\delta h}=1.$$



Putting the equations back together, we get

$$\frac{\delta L}{\delta w} = -0.94 \cdot 0.25 \cdot 0.5 = -0.118$$

$$\frac{\delta L}{\delta b} = -0.94 \cdot 0.25 \cdot 1 = -0.235$$

The calculation for $\frac{\delta L}{\delta w}$ is illustrated in the plot below.

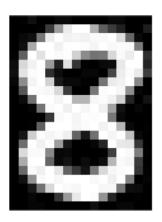
The weight and the bias then update to

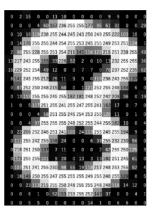
$$w_{new} = 0.3 - 0.1 \cdot (-0.118) = 0.312,$$

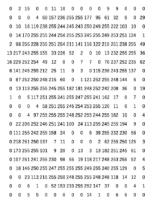
$$b_{new} = 0.1 - 0.1 \cdot (-0.235) = 0.125.$$

Backpropagation for the weight w.

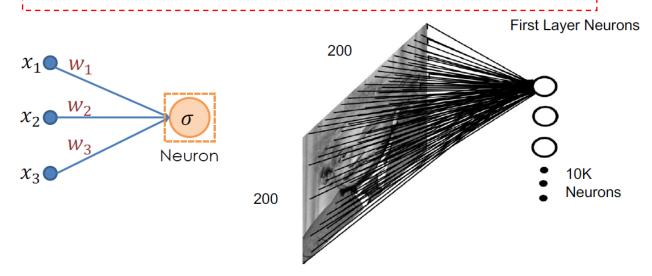
- A convolutional neural network (CNN) is a special type of neural network that significantly reduces the number of parameters in a deep neural network.
- Very popular in image-related applications
- Each image is stored as a matrix in a computer



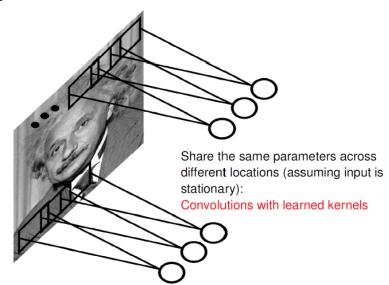




- If we model all matrix entries as inputs all at once
 - Assume we have an image/matrix size of 200x200
 - Assume we have 10K neuros in the first layer
 - We already have 200x200x10K=400 Million parameters to learn!



- Hence, we introduce CNN to reduce the number of parameters.
- Works in a sliding-window manner!



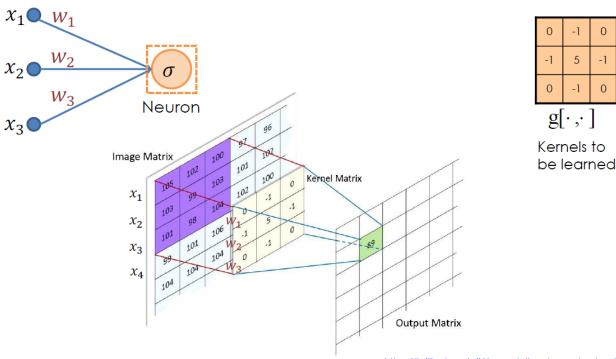
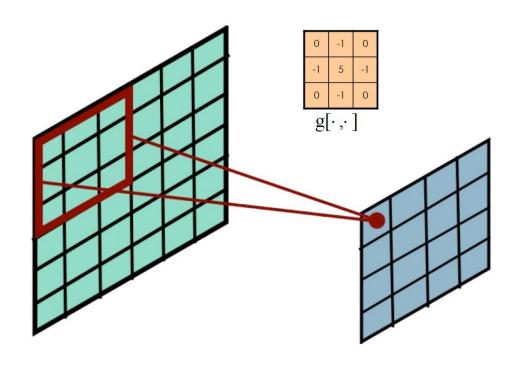
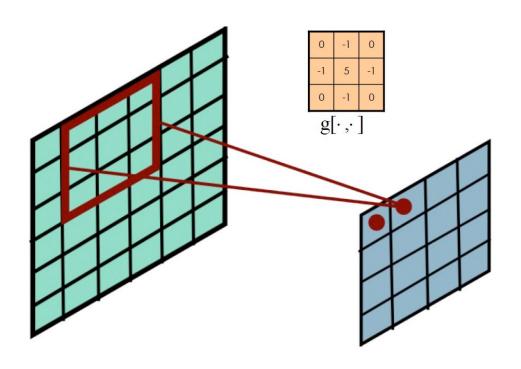
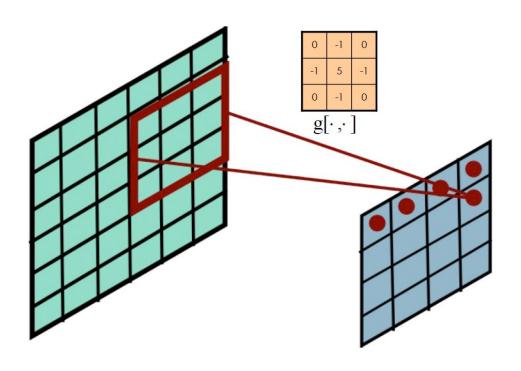
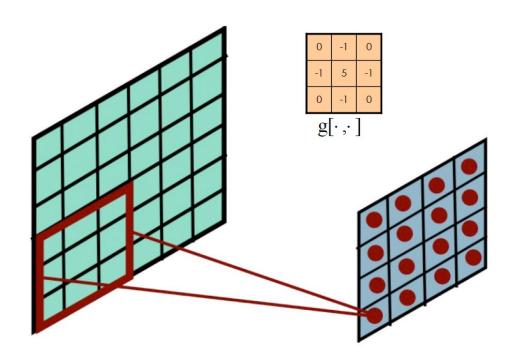


Image source: https://brilliant.org/wiki/convolutional-neural-network/









We take a filter/kernel(3×3 matrix) and apply it to the input image to get the convolved feature. This convolved feature is passed on to the next layer.

1,	1_×0	1,	0	0
O _{×0}	1,	1,0	1	0
0 _{×1}	0,0	1,	1	1
0	0	1	1	0
0	1	1	0	0

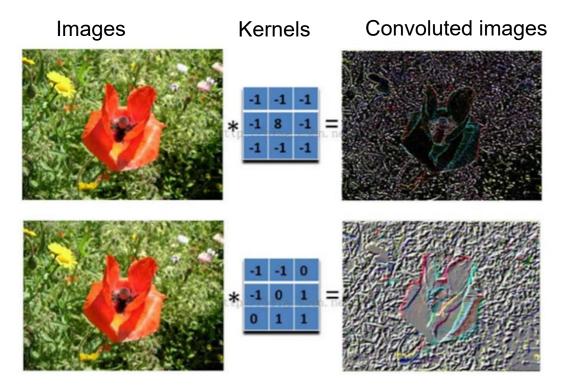
4	

1	0	1
0	1	0
1	0	1

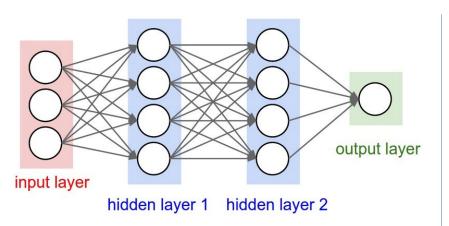
Filter/kernel

Image

Convolved Feature

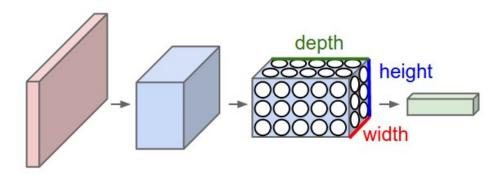


https://setosa.io/ev/image-kernels/



A regular 3-layer Neural Network.

https://cs231n.github.io/convolutional-networks/



A ConvNet arranges its neurons in three dimensions (width, height, depth), as visualized in one of the layers. Every layer of a ConvNet transforms the 3D input volume to a 3D output volume of neuron activations. In this example, the red input layer holds the image, so its width and height would be the dimensions of the image, and the depth would be 3 (Red, Green, Blue channels).

Summary

- Introduction to Neural Networks
 - Multi-layer perceptron
 - Activation Functions
- Training and Testing of Neural Networks
 - Training: Forward and Backward
 - Testing: Forward
- Convolutional Neural Networks

THANK YOU