

# AN INTRODUCTION TO HUMAN SPATIAL HEARING

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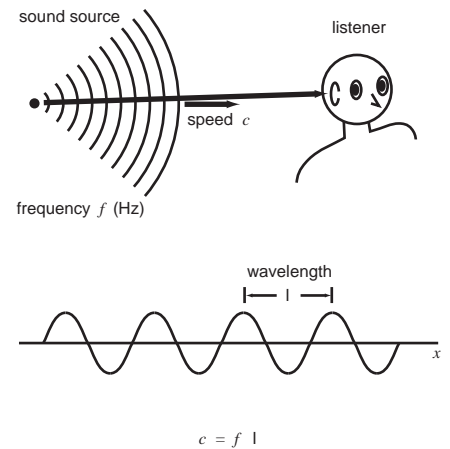
umd00\_00a.sl

## OVERVIEW

- Physics of sound
- Acoustic cues for sound localization
  - Azimuth
  - Elevation
  - Range
- Head-related transfer functions (HRTFs)
- Approaches to synthesizing spatial sound
- Opportunities and challenges

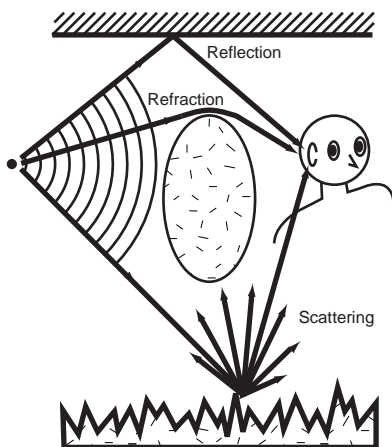
umd00\_overview.sl

## SOUND PROPAGATION



ph\_propagation.sl

## MULTIPATH PROPAGATION



ph\_paths.sl

## AXIOM I

The sound pressure at the two ear drums is a sufficient stimulus.

Producing the same sound pressure will produce the same auditory perception.

### Caveats:

- Bone conduction
- Adaptation
- Conflicting visual cues
- Conflicting expectations

umd00\_axiom\_1.sl

## AXIOM II

Exact reproduction of the sound pressure is not necessary for producing the same auditory perception.

The limitations of neural responses allow different (and simpler) stimuli to produce the same response.

### Examples:

- Bandwidth (20 Hz to 20 kHz)
- Amplitude (1-dB resolution)
- Monaural phase (2-ms resolution)
- Latency (10-ms resolution)
- Spectral fine structure (critical bands,  $Q = 8$ )

umd00\_axiom\_2.sl

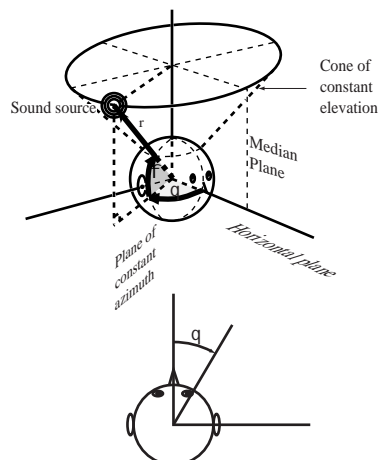
## AXIOM III

Although it is not necessary to reproduce all of the cues exactly, conflicting cues degrade perception.

Key engineering challenge -- find the most cost-effective approximation.

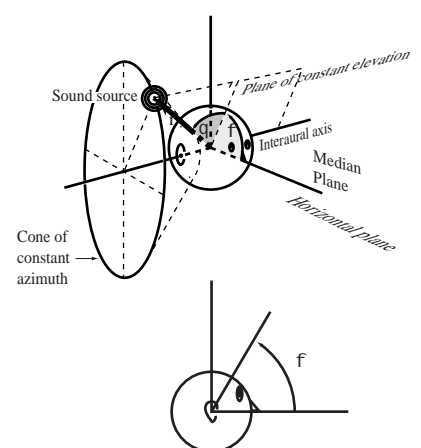
umd00\_axiom\_3.sl

## VERTICAL-POLAR COORDINATES



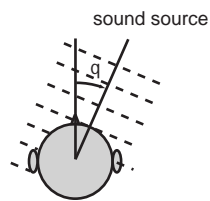
usc\_vp\_coords.sl

## INTERAURAL-POLAR COORDINATES



usc\_ip\_coords.sl

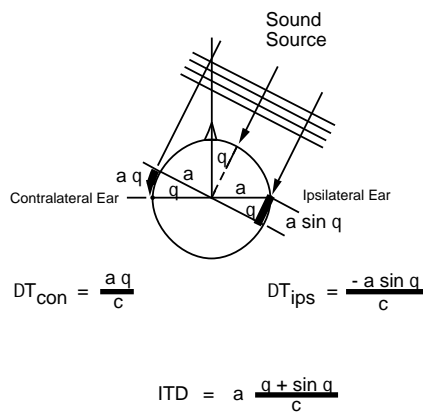
## AZIMUTH CUES



- ITD (Interaural Time Difference)
- ILD (Interaural Level Difference)

jh\_azimuth\_cues.ai

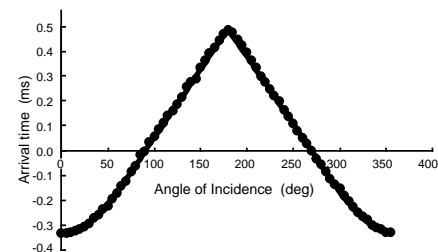
## WOODWORTH'S FORMULA



ubc\_delay.ai

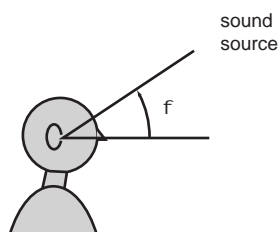
## ARRIVAL TIME

- Rayleigh's solution (20% rise time)
- Woodworth's formula



ubc\_delay\_curve.ai

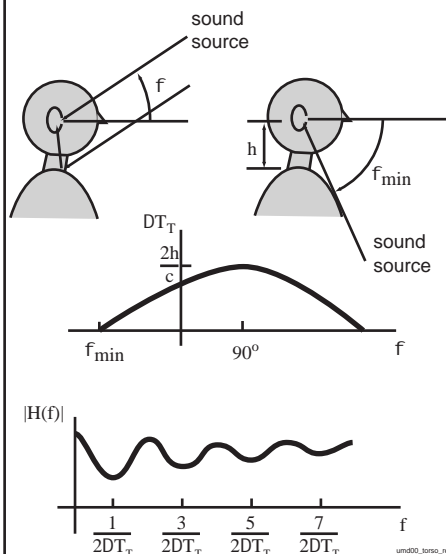
## ELEVATION CUES



- Pinna reflections and resonances
- Torso and shoulder reflections

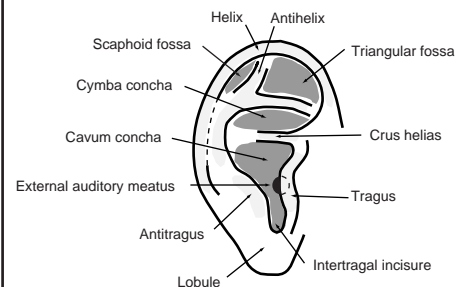
jh\_elevation\_cues.ai

## TORSO REFLECTION



umd03\_torso\_refl1.ai

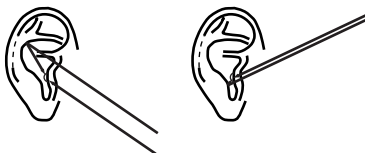
## THE PINNA



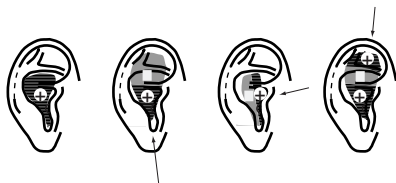
ubc\_pinna\_somenclature.ai

## PINNA PHENOMENA

Pinna reflections (Batteau)

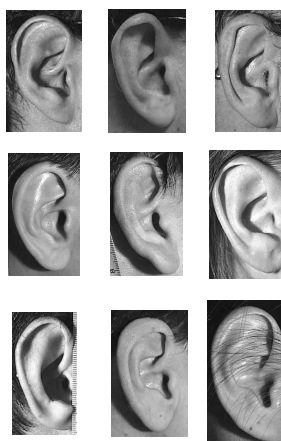


Pinna resonances (Shaw)



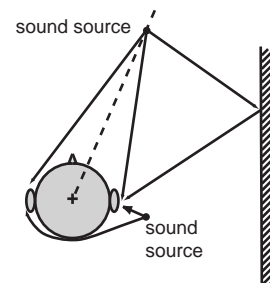
ubc\_pinna\_models.ai

## PINNAE



ubc\_pinnae.ai

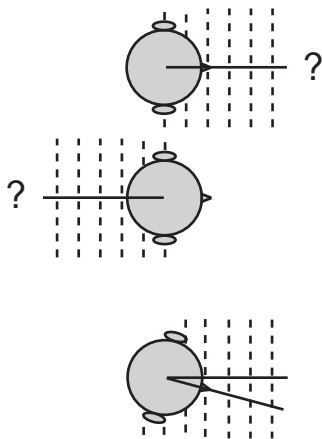
## RANGE CUES



- Loudness (for familiar sources)
- Excess ILD (for close sources)
- Direct/reverberant (for distant sources)

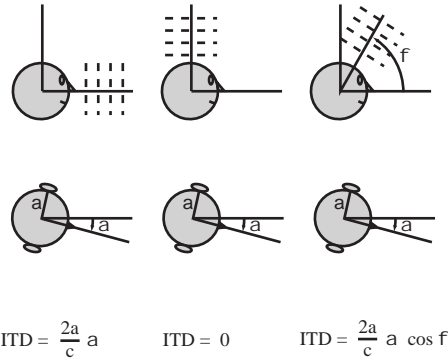
jh\_elevation\_cues.ai

## HEAD-MOTION CUES AND FRONT/BACK CONFUSION



um000\_dynamic\_cues1.ai

## HEAD-MOTION CUES AND ELEVATION MAGNITUDE



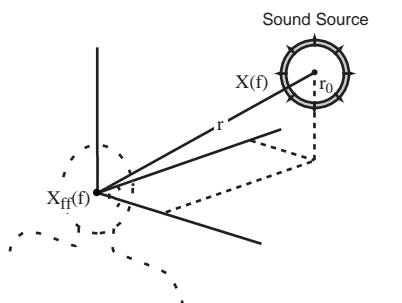
um000\_dynamic\_cues2.ai

## OTHER CUES

- Visual cues
  - Synchronized motion
  - Absence
- Knowledge of source
- Knowledge of environment

um000\_other\_cues.ai

## FREE-FIELD RADIATION FROM A SPHERICAL SOURCE



$X(f)$  = Fourier transform of source pressure  
 $X_{ff}(f)$  = Free-field pressure at head center

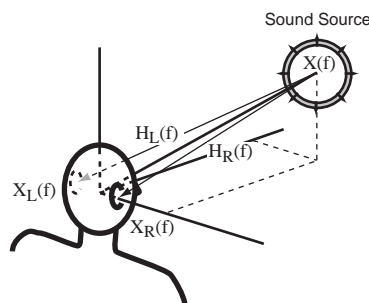
$$X_{ff} = H_{ff} X$$

$$H_{ff}(f) = \frac{r_0}{r} e^{-j k r} \quad , \quad k = \frac{2 \pi f}{c}$$

↑ Inverse range      ↑ Propagation delay

ph\_synthesis.ai

## THE HEAD-RELATED TRANSFER FUNCTION

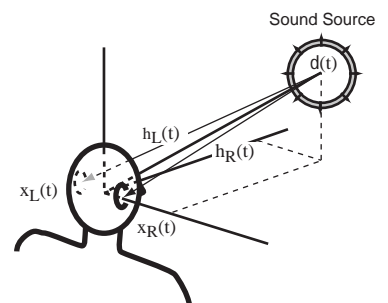


$X(f)$  = Fourier transform of source pressure  
 $X_L(f)$  = Fourier transform of left ear pressure  
 $X_R(f)$  = Fourier transform of right ear pressure  
 $X_{ff}(f)$  = Free-field pressure at the origin

$$X_L(f) = H_L(f) X_{ff}(f) \quad X_R(f) = H_R(f) X_{ff}(f)$$

abc\_HRTF\_def.ai

## THE HEAD-RELATED IMPULSE RESPONSE

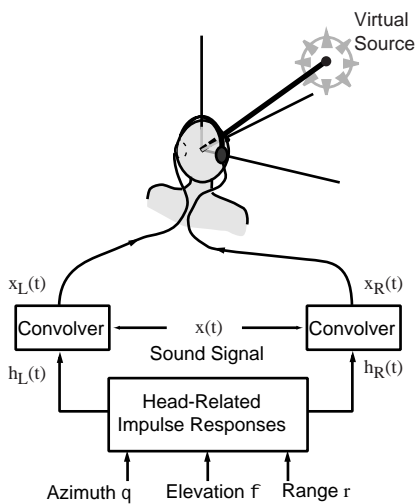


$x_L(t)$  = Left ear pressure  
 $x_R(t)$  = Right ear pressure  
 $x_{ff}(t)$  = Free-field pressure at the origin

$$x_L(t) = \int_{-\infty}^{\infty} h_L(t) x_{ff}(t-t) dt \quad x_R(t) = \int_{-\infty}^{\infty} h_R(t) x_{ff}(t-t) dt$$

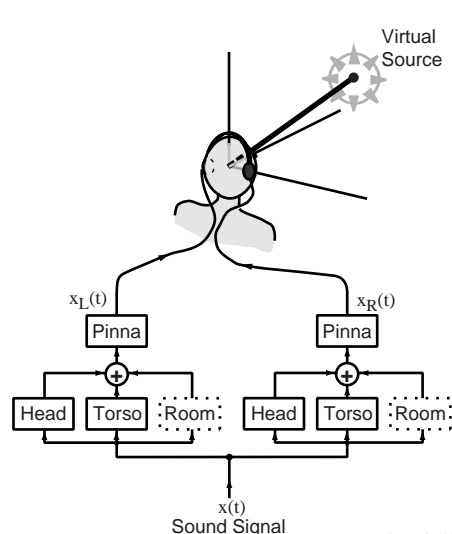
abc\_HRR\_def.ai

## HRIR SOUND SYNTHESIS



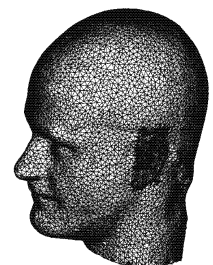
ph\_synthesis.ai

## A STRUCTURAL MODEL



ph\_structural\_model.ai

## COMPUTING HRTFs BY BOUNDARY ELEMENT METHODS



- Digitize with a 3-D scanner
- Solve wave equation numerically

\* See Kahana et al.

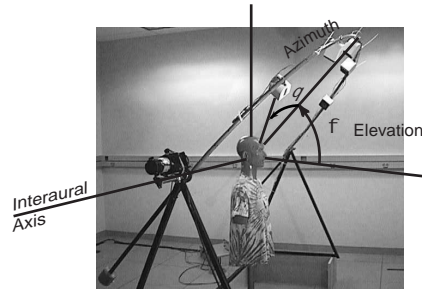
abc\_bem.ai

## THE KEMAR ACOUSTIC MANIKIN



ubc\_kemar.ai

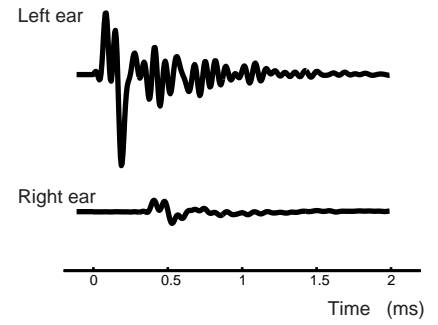
## ACOUSTIC HRTF MEASUREMENT



um00\_hoop.it

## KEMAR HRIR

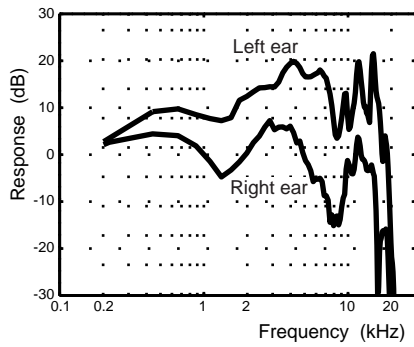
Azimuth =  $-45^\circ$ , Elevation =  $0^\circ$



jh\_kemar\_hrir\_m45.ai

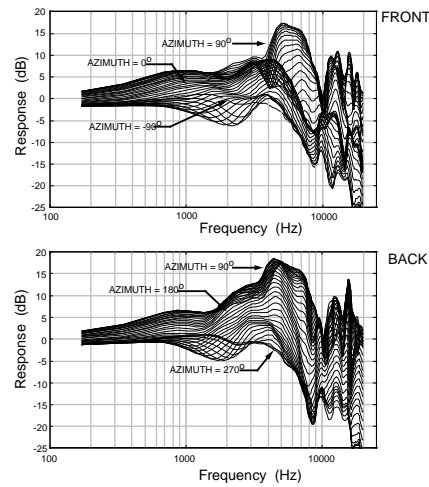
## KEMAR HRTF

Azimuth =  $-45^\circ$ , Elevation =  $0^\circ$



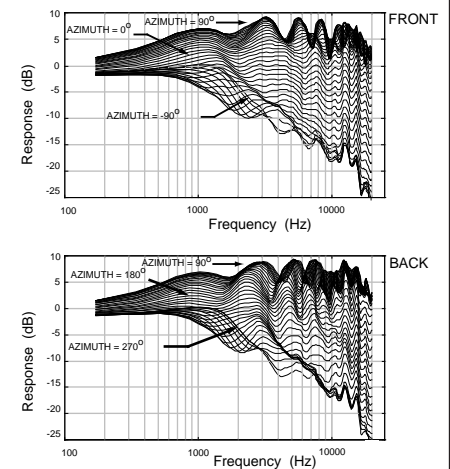
jh\_kemar\_hrif\_m45.ai

## RIGHT-EAR HRTF FOR KEMAR (Horizontal Plane)



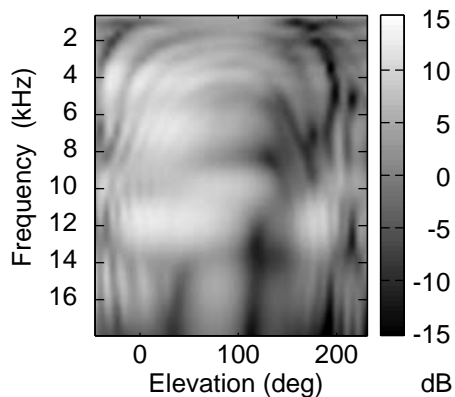
ubc\_ke\_freq.ai

## HRTF FOR KEMAR, NO PINNA (Horizontal Plane)



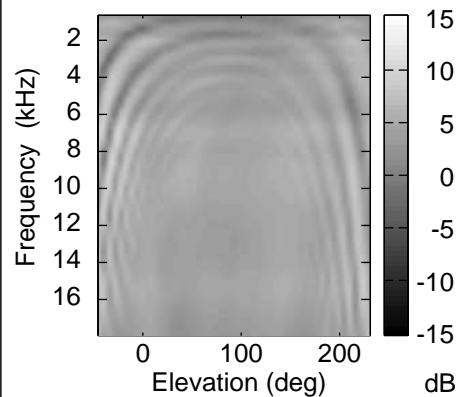
ubc\_ke\_freq.ai

## HRTF ELEVATION DEPENDENCE



um00\_full\_HRTF.ai

## HRTF WITHOUT PINNA



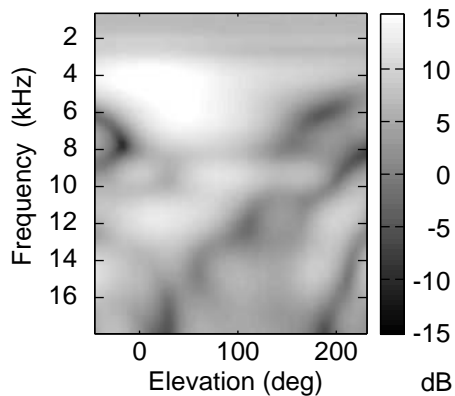
um00\_HRTF\_nopinna.ai

## A PINNA ON A PLANE



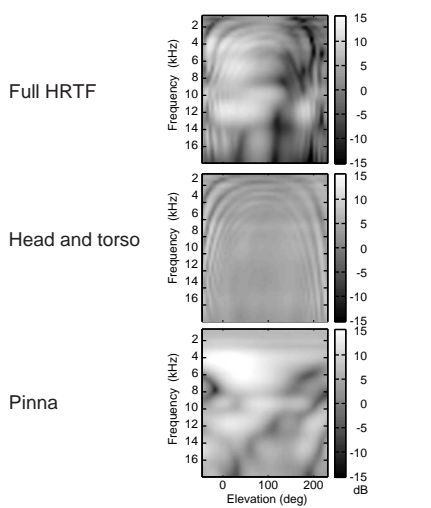
um00\_pinnacle.ai

## HRTF FOR ISOLATED PINNA



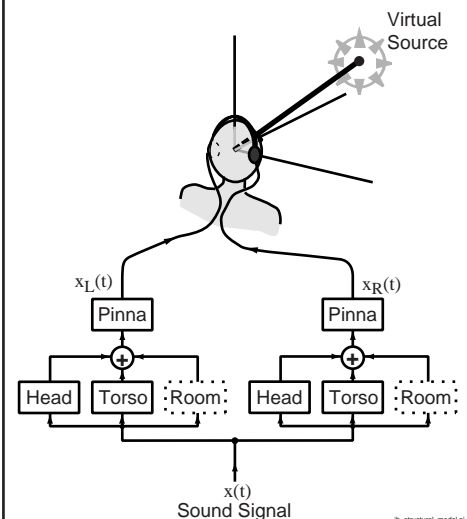
um00\_HRTF\_pinna.ai

## CONTRIBUTIONS TO THE HRTF



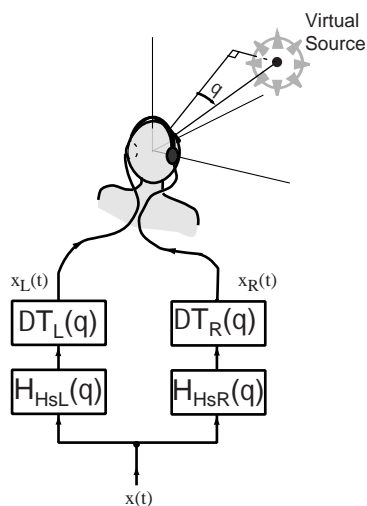
um00\_HRTF\_contributions.ai

## A STRUCTURAL MODEL



jh\_structural\_model.ai

## THE SPHERICAL-HEAD MODEL



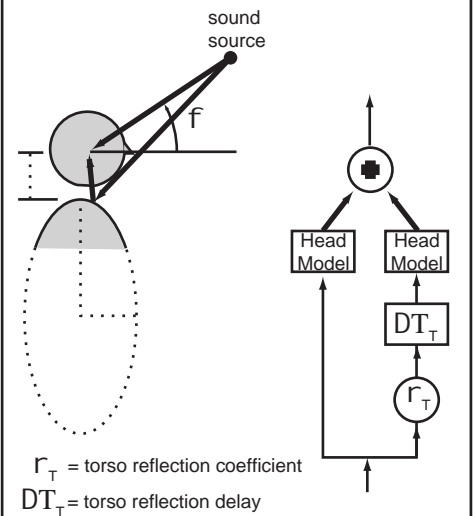
ubc\_sphere\_model.ai

## ASSESSING THE SPHERICAL HEAD MODEL

- Only one parameter -- easily customized
- Well focused
- Good left/right position
- No up/down control -- image elevated
- With a head tracker:
  - Moderately externalized
  - Little front/back confusion
- Without a head tracker:
  - Internalized
  - Usually seems to be in back

jh\_sphere\_assess.ai

## ELLIPSOIDAL-TORSO MODEL



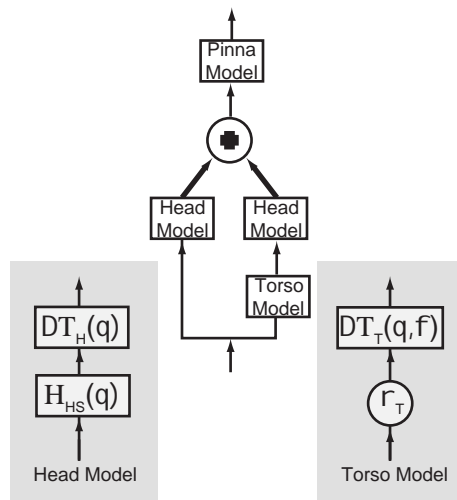
jh\_torso\_reflections.ai

## ASSESSING THE ELLIPSOIDAL TORSO MODEL

- Five parameters; still easily customized
- Provides an elevation cue
  - Significant below 3 kHz
  - Ineffective in median plane
- Only one component of a full model

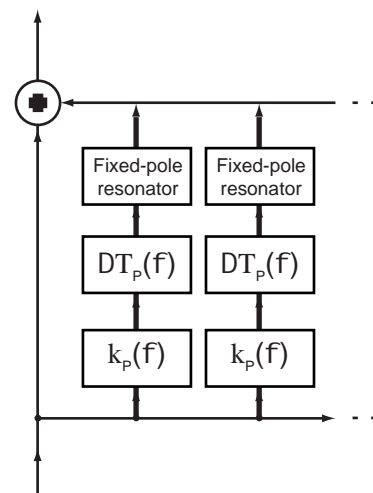
jh\_ellipsoid\_assess.ai

## STRUCTURAL HRTF MODEL



jh\_structural\_model\_2.ai

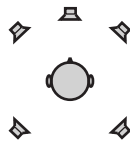
## SIMPLIFIED PINNA MODEL



jh\_structural\_model\_3.ai

## SPATIAL SOUND SYSTEMS

Multichannel



Two-channel:  
headphones

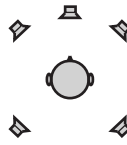


Two-channel:  
crosstalk-canceled  
loud speakers



umd00\_systems1.ai

## MULTICHANNEL SYSTEMS



### Pros

- Works with a large audience
- No customization needed
- Conceptually simple

### Cons

- Speakers must be distant
- Many channels needed for full 3-D
- Space consuming, expensive

umd00\_systems2.ai

## TWO-CHANNEL: HEADPHONES



### Pros

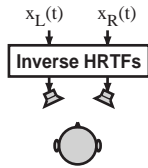
- Can reproduce full 3-D with only 2 channels
- Private and non-interfering
- Conceptually simple

### Cons

- Uncomfortable for extended use
- Clumsy for a large audience
- Requires customization for full 3-D
- Difficult to achieve frontal externalization

umd00\_systems3.ai

## TWO-CHANNEL: CROSSTALK-CANCELED LOUD SPEAKERS



### Pros

- Can reproduce full 3-D with only 2 channels
- Unencumbered listening

### Cons

- Small "sweet spot"
- Cannot be used with a large audience
- Requires customization for full 3-D
- Difficult to get near or rear locations

umd00\_systems4.ai

## APPROACHES TO CUSTOMIZATION

- Measure exact HRTF for each person
  - Acoustic
  - Computational
- Nearest-neighbor
  - Trial and error
  - Anthropometry
- Scale a standard HRTF
  - Global
  - Pinna/head/torso components
- Use an adaptive model
  - Match to anthropometry
  - Match to exact HRTF

umd00\_customization.ai

## CHALLENGES AND OPPORTUNITIES

- Frequency range  
(combining partial HRTFs)
- Elevation perception
  - Front/back confusion
  - Low elevations
- Range perception
  - Headphones: externalization
    - Median plane
    - Frontal
  - Speakers: back locations
- Transducers
  - Headphone compensation
  - Loudspeaker "sweet spot"
- Latency in dynamic systems
- Room acoustics

umd00\_problems.ai