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Ref No: IAFS-20)23/24-F	R1-

THE UNIVERSITY OF HONG KONG FACULTY OF ENGINEERING INNOVATION ACADEMY

Application for the Funding Scheme for student projects/activities by Tam Wing Fan Innovation Fund and Philomathia Foundation Innovation Fund

Applications and the supporting documents should reach the Innovation Academy by October 13, 2023 (Friday).

A. Project profile

Project title:	Smart Wheel Chair
Hosting Department in the Faculty of Engineering (if applicable):	Department of Mechanical Engineering
Category:	Please check the box(es) below if the project covers the related area(s): ☑ Development of projects/activities ☑ Participation in approved competitions, visits and conferences □ Attachment to university and institutes / centres (Mainland and overseas); laboratories and enterprises (local, Mainland and overseas) □ Promotion of STEM / Innovation in the community □ Others (Please specify:
Expected start date:	November 1,2023
Expected end date:	March 1,2024

Supervisor(s) / Advisor(s)

#	Department	Title	Name	Phone number	Email
1.	Mechanical Engineering	Assistant Professor	Dr. Peng LU	+852 3910 2548	lupeng@hku.hk

Team members

#	Role (e.g. leader / member etc.)	Name	Curriculum (Year)	Phone number	Email	Student ID	
1.	Leader	KANG Jian	MPHIL(1)	51937066	u3597147@connect.hku.hk	3035971478	
2.	Member	Zhang Zihan	MSC(1)	56981067	u3619457@connect.hku.hk	3036194572	

Project summary (About 500-600 words.)

(a) Objectives:

The contribution of an autonomous wheelchair to society is multifaceted. It provides individuals with mobility challenges the ability to move independently and participate more fully in society, offering the following benefits:

Promoting personal independence: An autonomous wheelchair enables individuals with mobility limitations to engage in daily activities with greater independence. They no longer depend on others for assistance and can

autonomously navigate to destinations such as shopping malls, parks, hospitals, and more. This autonomy is crucial for improving their quality of life and self-esteem.

Enhancing social inclusion: Individuals with mobility challenges often face social isolation and exclusion. An autonomous wheelchair helps them integrate into society more effectively, enabling face-to-face interactions and social engagement. They can participate in community activities and social gatherings, establish more social connections, and reduce the negative impact of social isolation.

Improving transportation efficiency: Autonomous wheelchairs incorporate intelligent navigation and obstacle avoidance capabilities, allowing for efficient route planning and obstacle avoidance. This reduces the need for manual wheelchair propulsion, alleviating the burden on caregivers and enabling better adaptation to traffic flow in busy environments.

Promoting sustainable development: Autonomous wheelchairs typically employ electric propulsion, reducing reliance on traditional fuels and decreasing environmental pollution and carbon emissions. This contributes to sustainable development and raises awareness of environmental conservation.

And this work will also take part in the humanity competition held by Debi this December.

(b) Contribution to out-of-classroom learning in the team and Innovation Wing:

Learning how to build an electric wheelchair offers several benefits to students in terms of enhancing their AI programming skills, mechanical design abilities, mechanical machining capabilities, programming skills, and fostering a sense of social responsibility:

Improving AI programming skills: Electric wheelchairs often utilize advanced artificial intelligence technologies for autonomous navigation and obstacle avoidance.

Enhancing mechanical design abilities: The design of an electric wheelchair involves knowledge of mechanical structures, kinematics, and dynamics.

Developing mechanical machining capabilities: Building an electric wheelchair requires machining and assembling various components. Students can learn and practice mechanical machining techniques such as cutting, milling, welding, etc.

Enhancing programming skills: The control system of an electric wheelchair typically employs embedded programming to achieve various functions and interactions.

Fostering a sense of social responsibility: Building an electric wheelchair is closely related to providing a social service. By learning how to build an electric wheelchair, students gain a deeper understanding of the needs of individuals with mobility challenges and can use their expertise and skills to improve and address related issues.

(c) Relationship to technology application/development of the project:

Practical opportunities: The electric wheelchair project provides students with practical project opportunities. They can participate in the design, manufacturing, and improvement of electric wheelchairs, learning and applying relevant engineering knowledge and skills.

B. Deliverables of the Project

- 1. Mechanical structure optimization
- 2. Control framework
- 3. Improve the dynamic obstacle avoidance ability
- 4. Attend Prototypes For Humanity held by Dubai

C. Execution Plan (In the form of timeline chart.)

	1 st week	2 nd Week	3 rd Week	4 th Week	5 th week	6 th week	7 th week	8 th Week	9 th Week	10 th Week	11 th Week	12 th month Week
Mechanical												
structure												
optimization												
Control												
framework												
Improve the												
dynamic												
obstacle												
avoidance												
ability												
Attend												
Prototypes												
For Humanity												
held by Dubai												

D. Funding request

- The funding request <u>should normally cover the period from December 1, 2023 to November 30, 2024</u> and should be clearly stated in the following table with detailed justifications.
- Applicants are advised to observe the terms and conditions as stated on the "General Application Guidelines for Funding Scheme for student projects/activities by Tam Wing Fan Innovation Fund and Philomathia Foundation Innovation Fund".
- Please attach a full budget proposal of your project with this application and submit to the Innovation Academy.

	ltem	Detailed specific	ation		Estimated Amount (HK\$)	For office use only	
Α.	Equipment						
1	On board computer	Intel NUC 13 Pro Kit - NUC13ANHi7 x2 、Thunderbolt 4 x2)	/(i7-1360P、DD	R4	5,699.00		
2	3D Lidar	Stereo-Sensing Hybrid Solid-State	LiDAR		3,000.00		
3	Motor	High Performance motor			1,200.00		
4	Deep camera	82635AWGDVKPMP			2,000.00		
5	•						
В.	Consumables and other expenses	I			<u> </u>		
1	Glass fiber	Largest size capable of water jet cu	itting in innowin	g	2,300.00		
2	Carbon fiber	Largest size capable of water jet cu	itting in innowin	g	3,000.00		
3	Aluminum profile	40mmx40mm			1,000.00		
4	Aluminum tube	Different type			2,000.0		
5							
C. 5	Subsidy for student travel and accor	nmodation			I		
1	Air Fare tickets	For 2 people			9,000		
2	Accommodation	For 2 people			9,000		
3	Transport in Dubai	Bus,			1,000		
4							
5							
		Total funding	request to this s	cheme:	30199.00		
			Total I	oudget:	31000.00		
Other information:							
Ot	her funding source(s):						
		native sources (such as the HKUEAA Exper			nary Scholarship Fund Stu	udent	
Exp		t Ho Experiential Learning Fund, departm			Chahrra		
	Funding s	ource	Amount		Status		
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				□ Application submitted
				☐ Application submitted
				☐ Application approved.
				☐ Others:
				☐ Application submitted
				☐ Application approved.
				☐ Others:
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	· -	r each academic year:		
	Media		' 54 inches height with 150dpi (5,4	100 * 8 100 pivals)
			ver image and at least 5 project ir	•
	•	Video – a one-minute vid	_	mages in printable quality.
	A proje	ect completion report	1 /1 - 1	
		en student sharing from eac	ch team member	
	Acknowledge	wledgement of support of	the Faculty of Engineering and tl	he respective funding source(s) on the
	poster, imag	ges, videos, written reports	or other written publications.	
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Remarks:

Disapproved

Endorsed by		Date:	
_	Director of Tam Wing Fan Innovation Wing,		
	Faculty of Engineering, HKU		
Endorsed by		Date:	
	Head of Innovation Academy,		
	Faculty of Engineering HKII		