Working Session 2 Programming the CLEARSY Safety Platform

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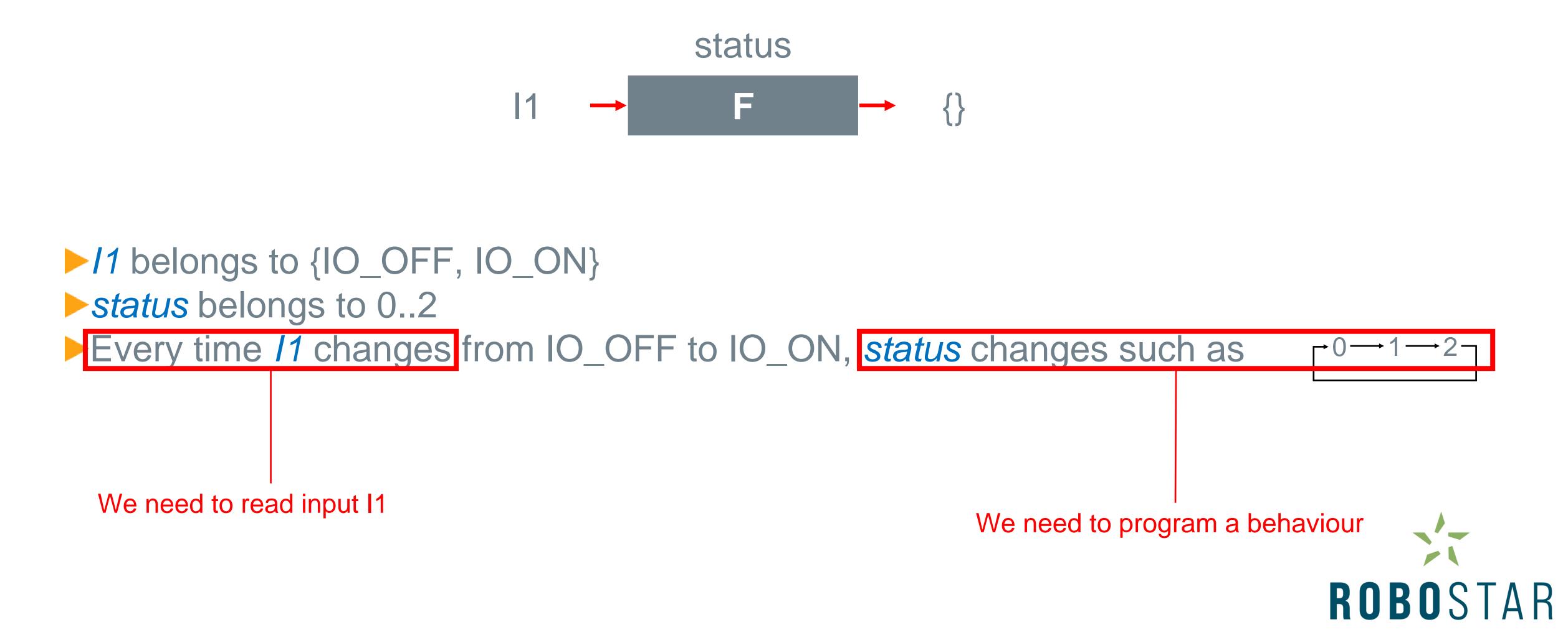
Agenda

- Developing a combinatorial function
- Developing a synchronous / timed function

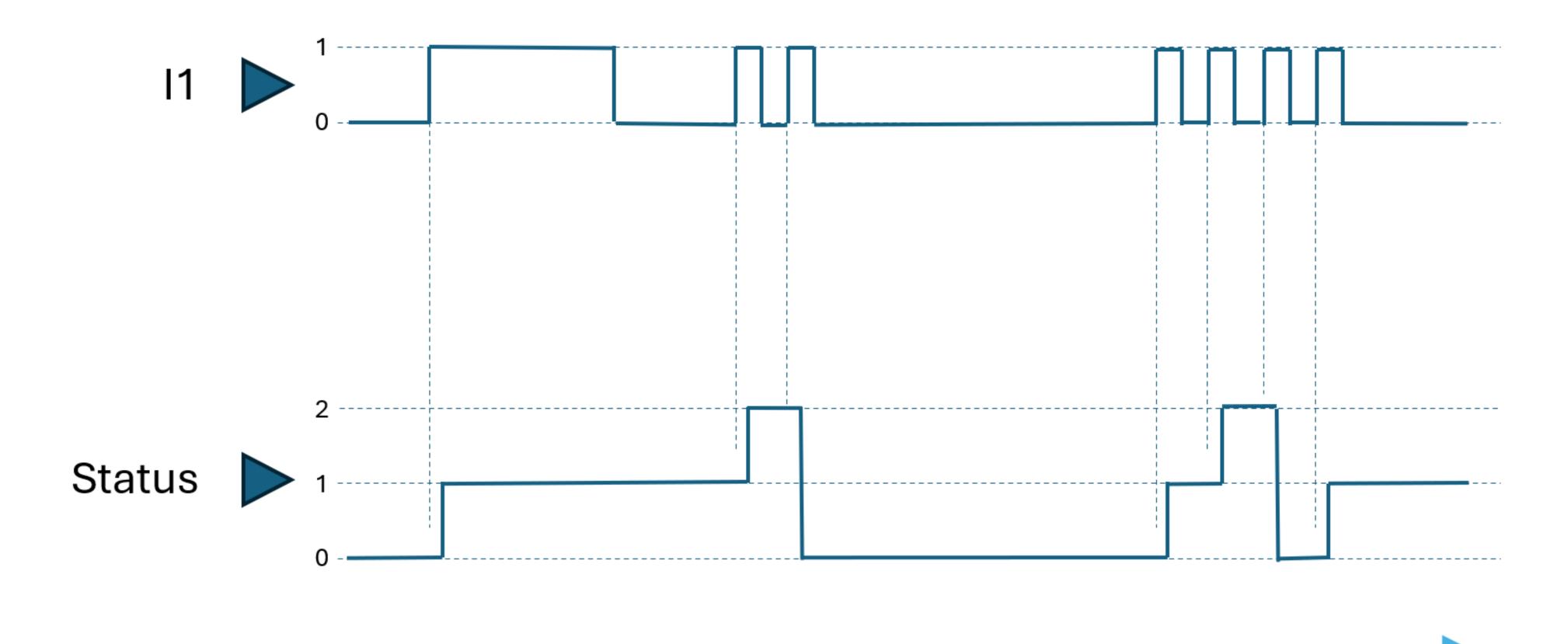


Developping a Combinatorial Function





Combinatorial Function - scenario



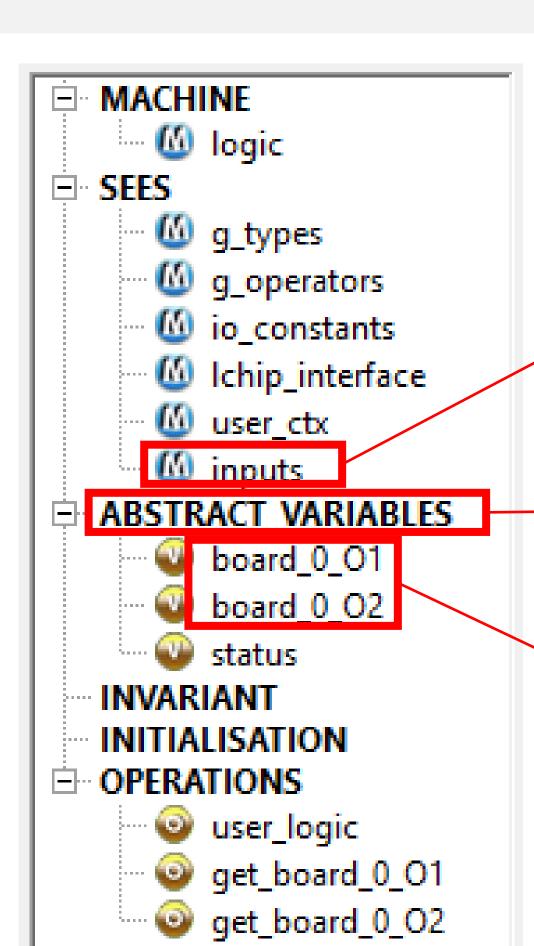


time

Specification component

double-click to open

logic_i



Inputs are not variables of this model.

They are read and accessed from the *inputs* component

Abstract variables are not necessarily implemented.

They could appear only in specification for « reasoning »

Outputs are variables of this component.

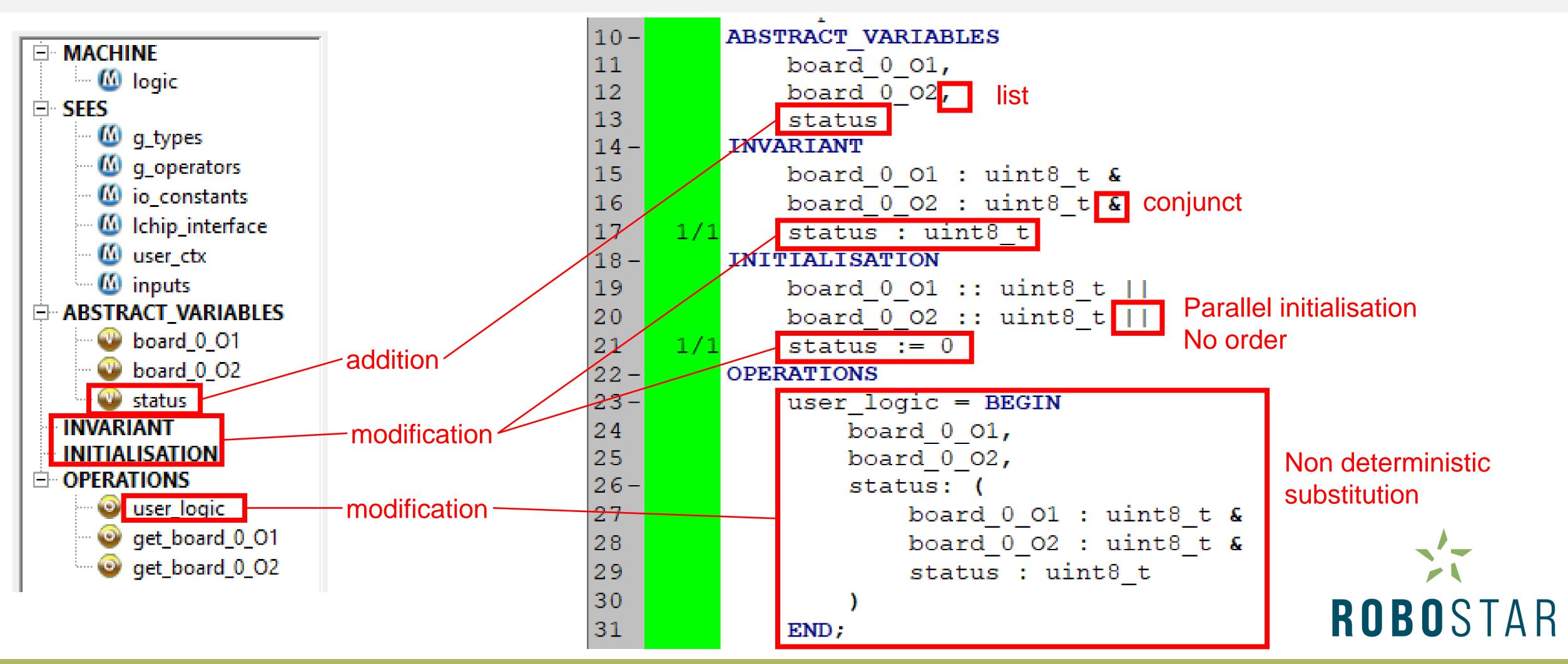
They are modified in this component.

In B, variables are modified in a single component



Specification component





Specification component

double-click to open

logic

logic_

```
ABSTRACT VARIABLES
                                           10-
                                                         board 0 01,
                                           11
                                           12
                                                         board 0 02,
                                           13
                                                         status
                                           14 -
                                                     INVARIANT
                                           15
                                                         board_0_01 : uint8 t &
                                                         board 0 02 : uint8 t &
                                           16
                                                         status : uint8 t
                                                                                       The 3 variables are going to
                                           18-
                                                     INITIALISATION
                                                                                       evolve according to their type
                                           19
                                                         board 0 01 :: uint8 t ||
                                                                                       and could keep the same value
                                           20
                                                         board_0_02 :: uint8_t ||
                                                         status := 0
                                           22 -
                                                     OPERATIONS
                                                         user_logic = BEGIN
                                           23-
                                           24
                                                             board 0 01,
                            xx: (xx: T(xx))
                                                              board 0 02,
                                           26-
                                                              status: (
                                           27
                                                                  board 0 01 : uint8 t &
                                  means.
                                                                  board 0 02 : uint8 t &
                                           28
                                                                  status : uint8_t
                                           29
« xx becomes such that xx belongs to its type »
                                           30
                                                                                                ROBOSTAR
```

END;

31

Specification component

logic_i

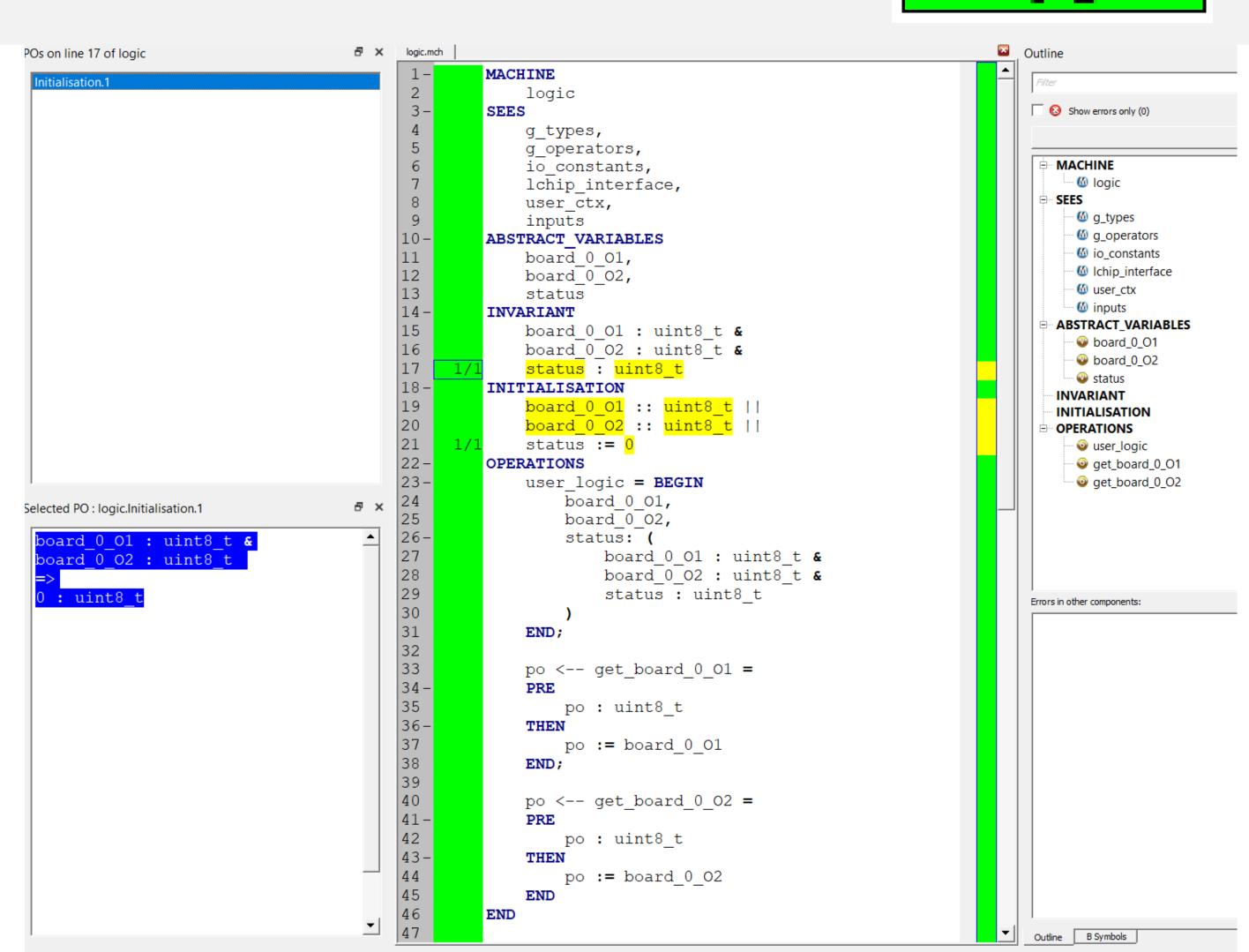
double-click to open

Once the editing is completed

Type Ctrl-S to save

Proof is automatically initiated

You should get a fully green (proved) component

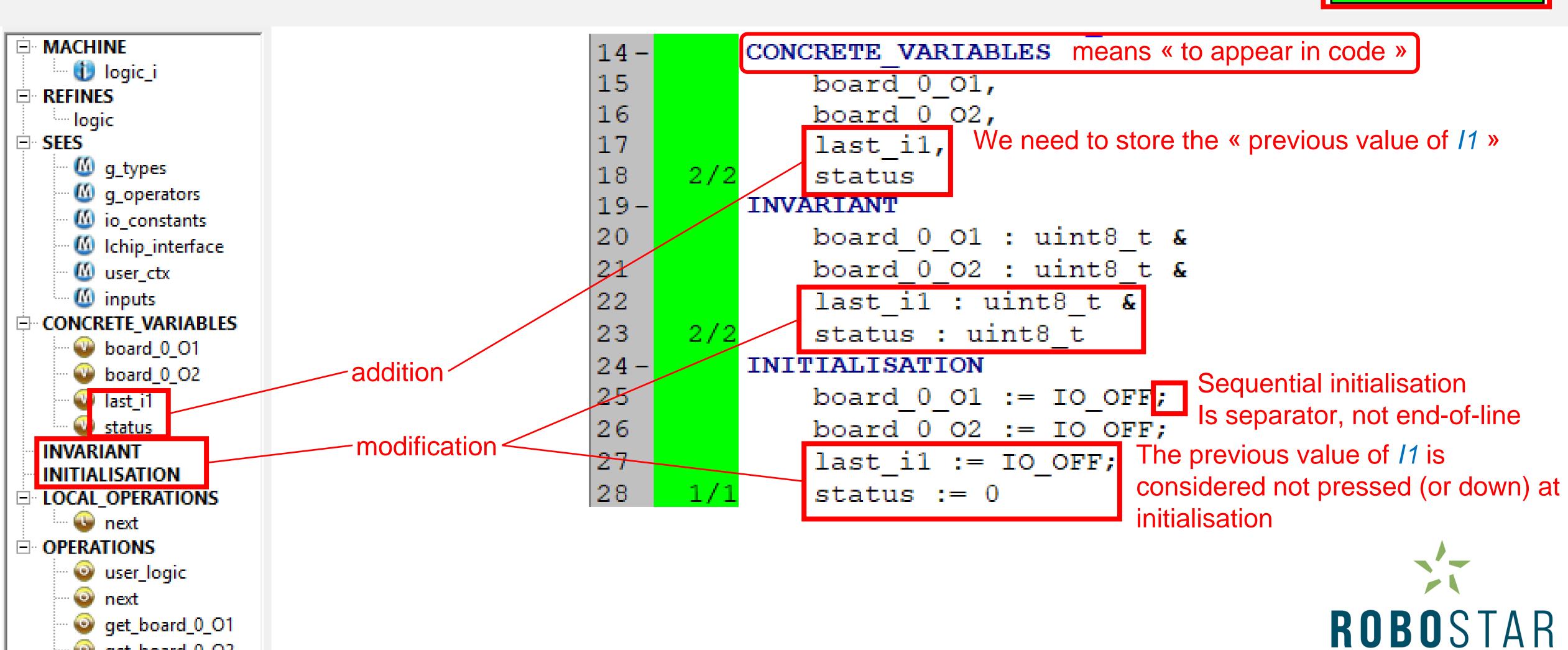


get_board_0_01

get_board_0_02

Implementation component

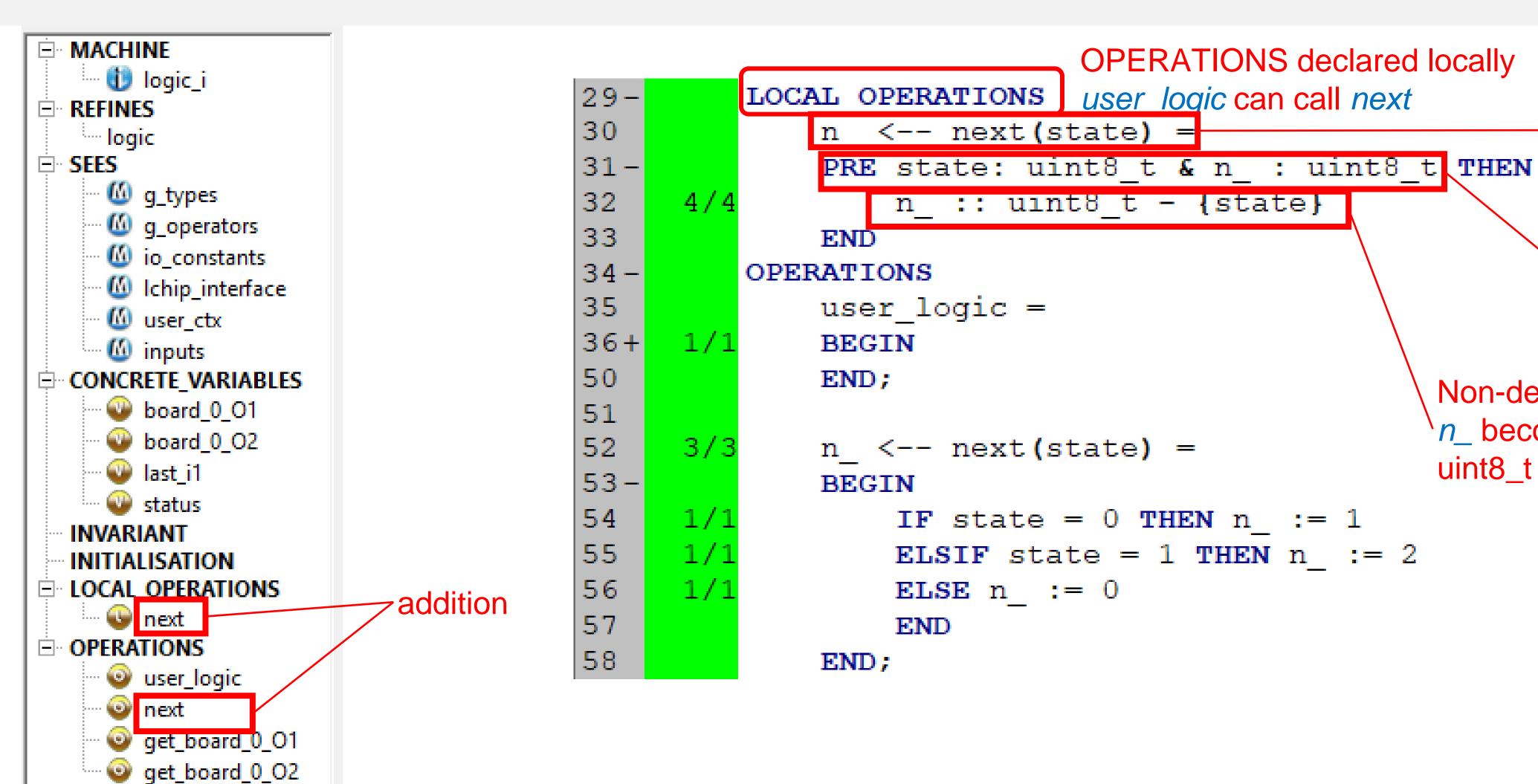




Implementation component

double-click to open





Operation *next* with one parameter *state* returning *n*_

Precondition used to indicate types for parameter and return value

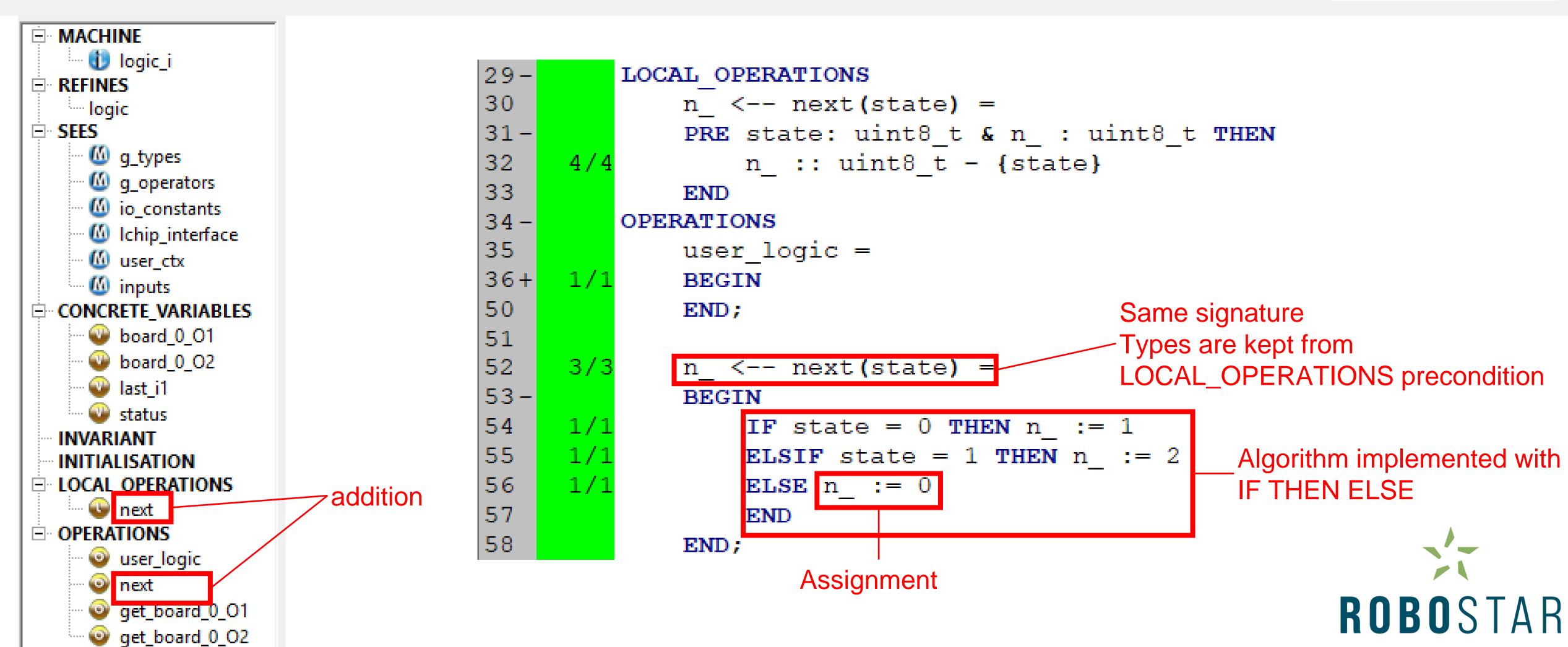
Non-deterministic substitution:

n_ becomes equal to any
uint8_t except the value of state



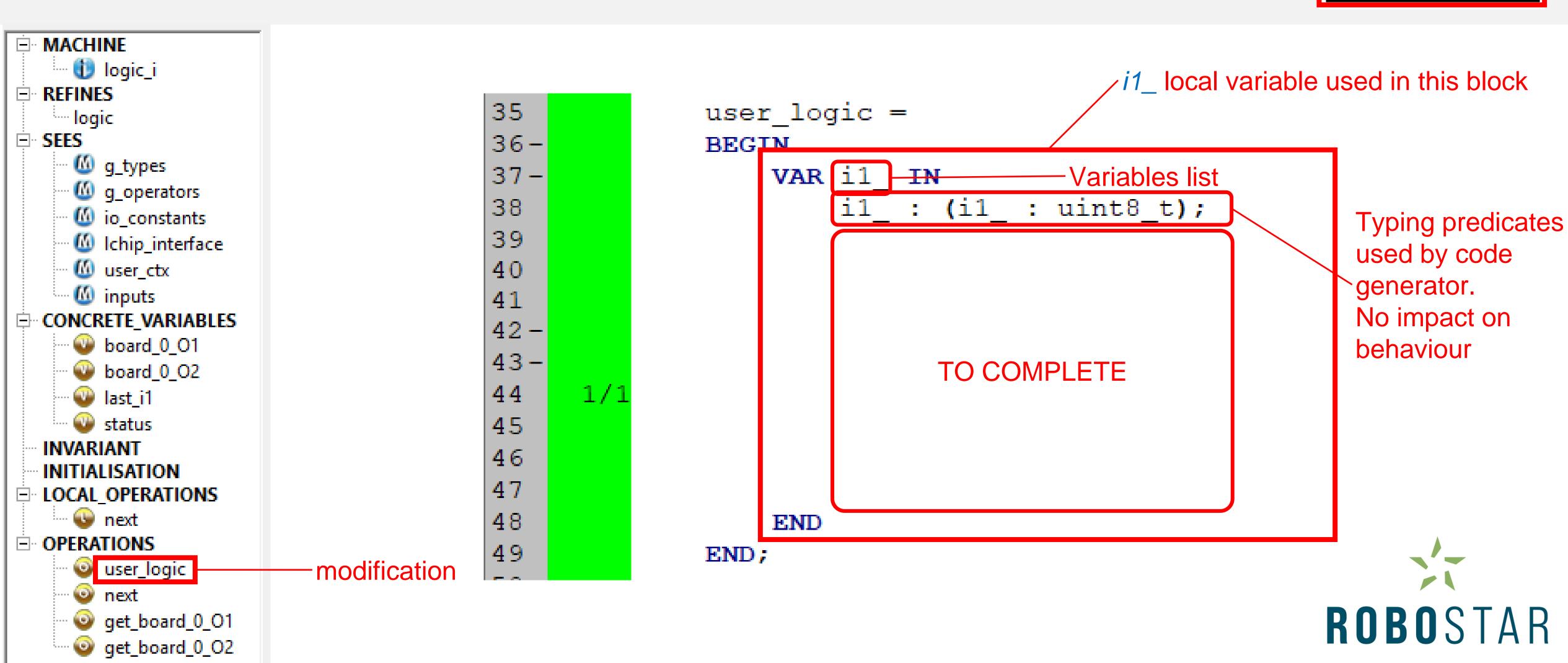
Implementation component





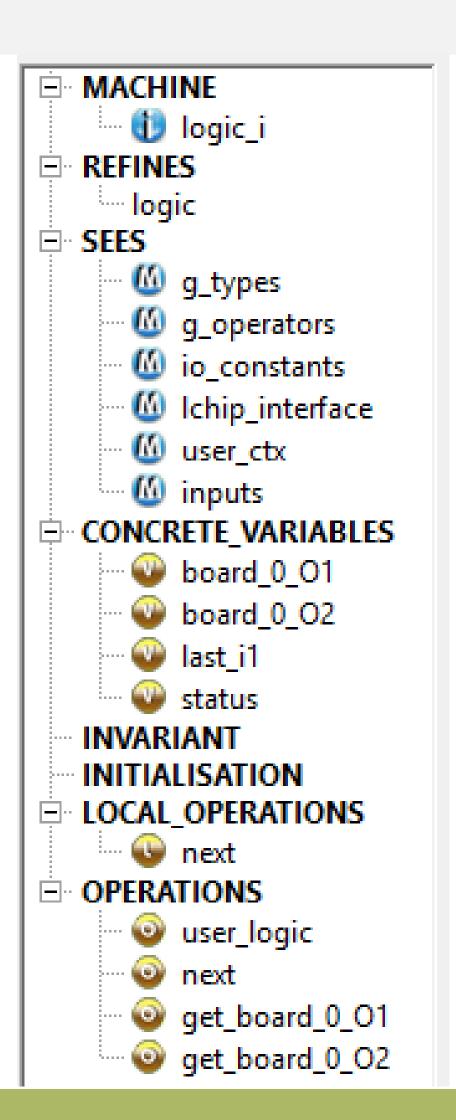
Implementation component





Implementation component





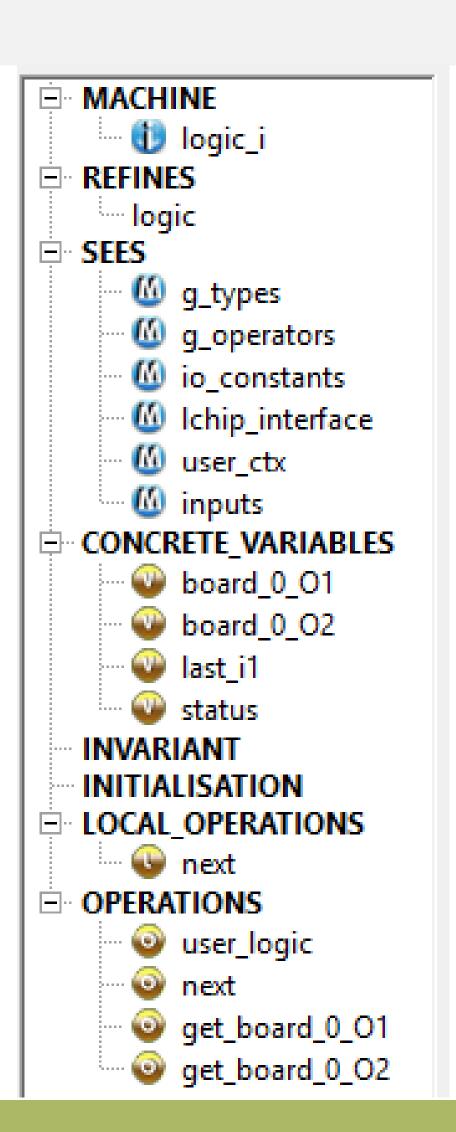
```
35
                user logic =
36-
                BEGIN
37 -
                     VAR il IN
38
                          i1 : (i1 : uint8 t);
39
40
41
                            If I1 has a raising edge then
42 -
                           change status to its next value.
43-
      1/1
44
                             Update the last value of 11
45
46
47
48
                     END
49
                END;
```

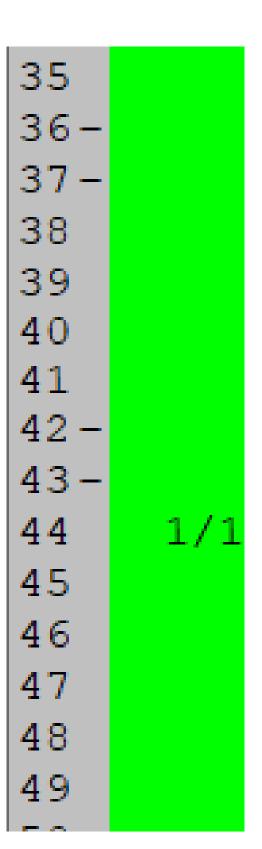


Implementation component

double-click to open







```
user logic =
BEGIN
     VAR il IN
          i1 : (i1 : uint8 t);
            If I1 has a raising edge then
           change status to its next value.
             Update the last value of 11
     END
```

END;

HINT1

Operation call syntax: vv <-- ff(pp)

HINT2

The operation to read *I1* is in the *inputs* component

HINT3

To assign a variable vv: vv := value

CONSTRAINT

Only one condition per IF



Combinatorial Function: your turn

Implementation component

double-click to open



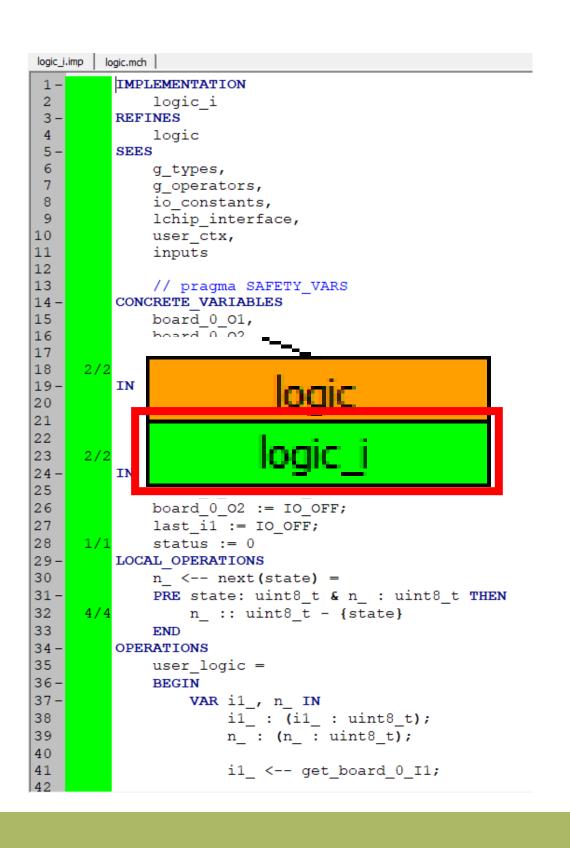
Edit logic and logic_i components

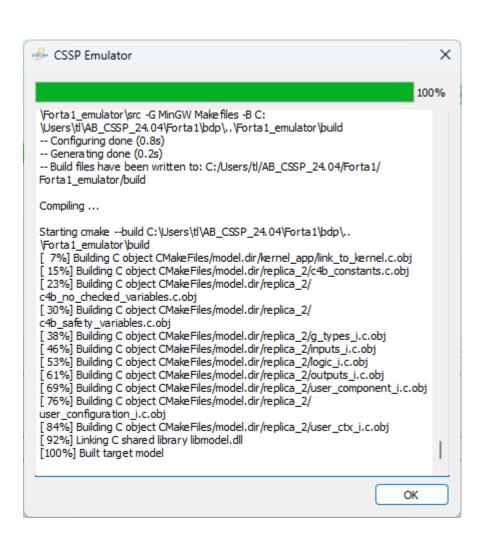
Ctrl-S to save and prove

Models should be « all green »

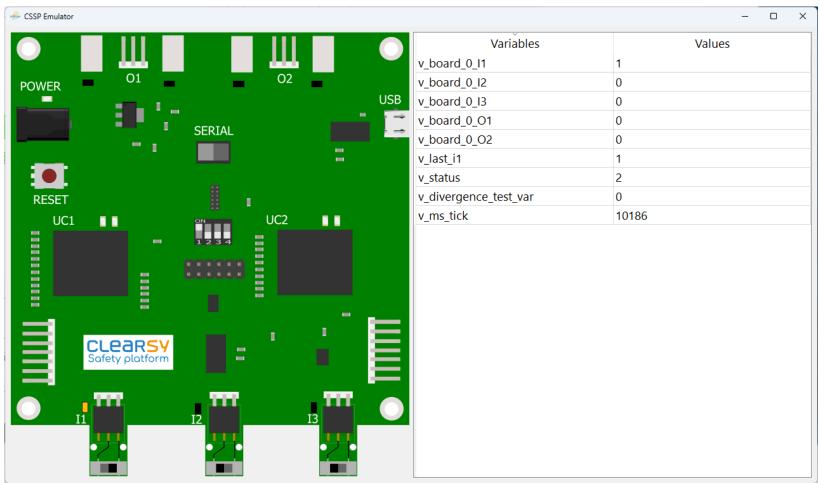
Ctrl-D to start the emulator
Reach « 100% built target model »
Press OK

```
MACHINE
               logic
               g operators,
               io constants,
               lchip_interface,
               user_ctx,
               inputs
          ABSTRACT VARIABLES
               board 0 01,
               board 0 02,
               status
          INVARIANT
               board_0_01 : uint8_t &
               board 0 02 : uint8 t &
18 -
19
20
21
22 -
23 -
24
25
26 -
27
                               logic
                         board 0 01 : uint8 t &
                        board 0 02 : uint8 t &
                        status : uint8 t
               END;
               po <-- get_board_0_01 =
                    po : uint8 t
36-
37
38
39
40
                    po := board_0_01
               po <-- get_board_0_02 =
41-
                    ~~ · · · · · · · + · · · +
```











Combinatorial Function: your turn

Hard Work On Going!

Spoiler Alert: Solution on the next slide!

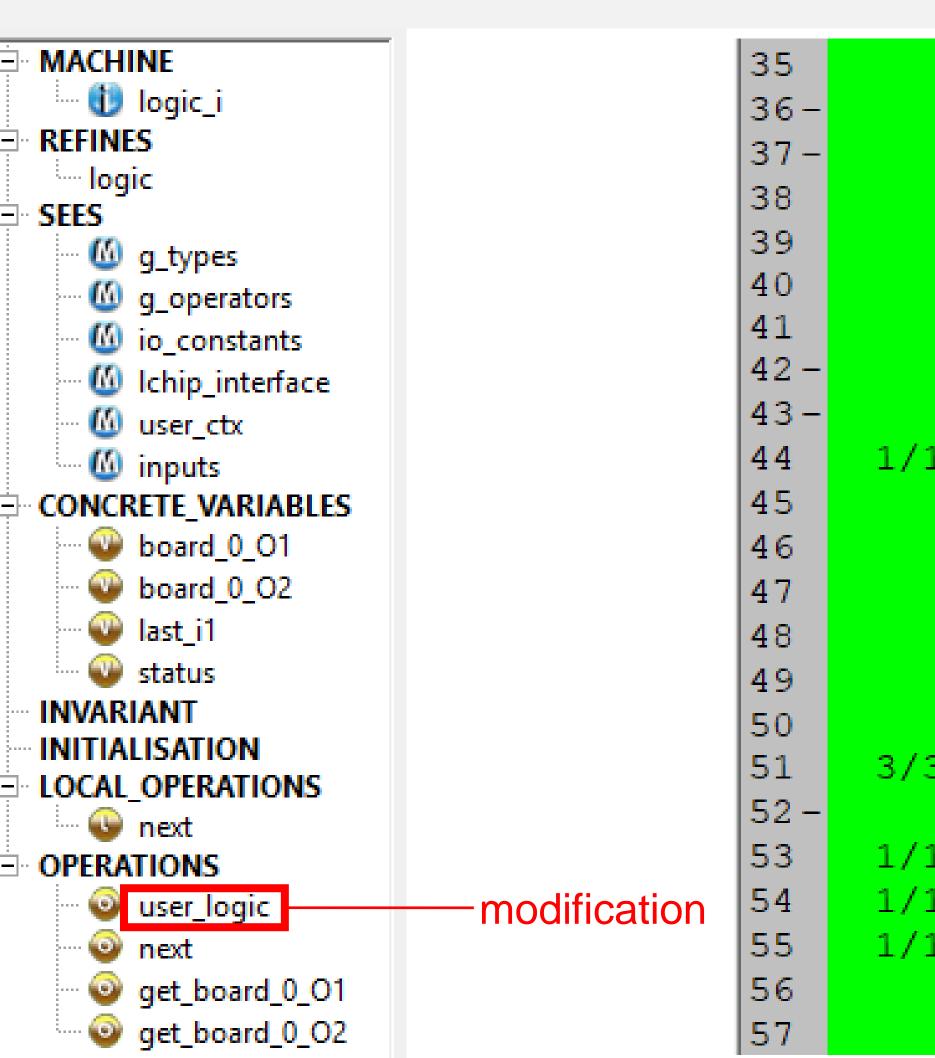


Combinatorial Function: the solution

Implementation component

double-click to open





```
1/1
3/3
1/1
1/1
```

```
user logic =
BEGIN
    VAR il IN
        i1_ : (i1_ : uint8_t);
                                  We call the predefined operation
                                  get_board_0_I1 to get the value of I1
        i1 <-- get board 0 I1;
                                  and store it in i1_
        IF last i1 = IO OFF THEN
            IF i1 = IO ON THEN
                 status <-- next(status)
            END
        END;
        last i1 := i1
    END
END;
n <-- next(state) =
BEGIN
    IF state = 0 THEN n := 1
    ELSIF state = 1 THEN n :=
    ELSE n := 0
    END
END;
```

We call *next* to get the new value of status



Developping a Synchronous Function

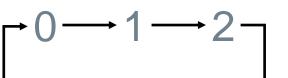




We need to specify a timer

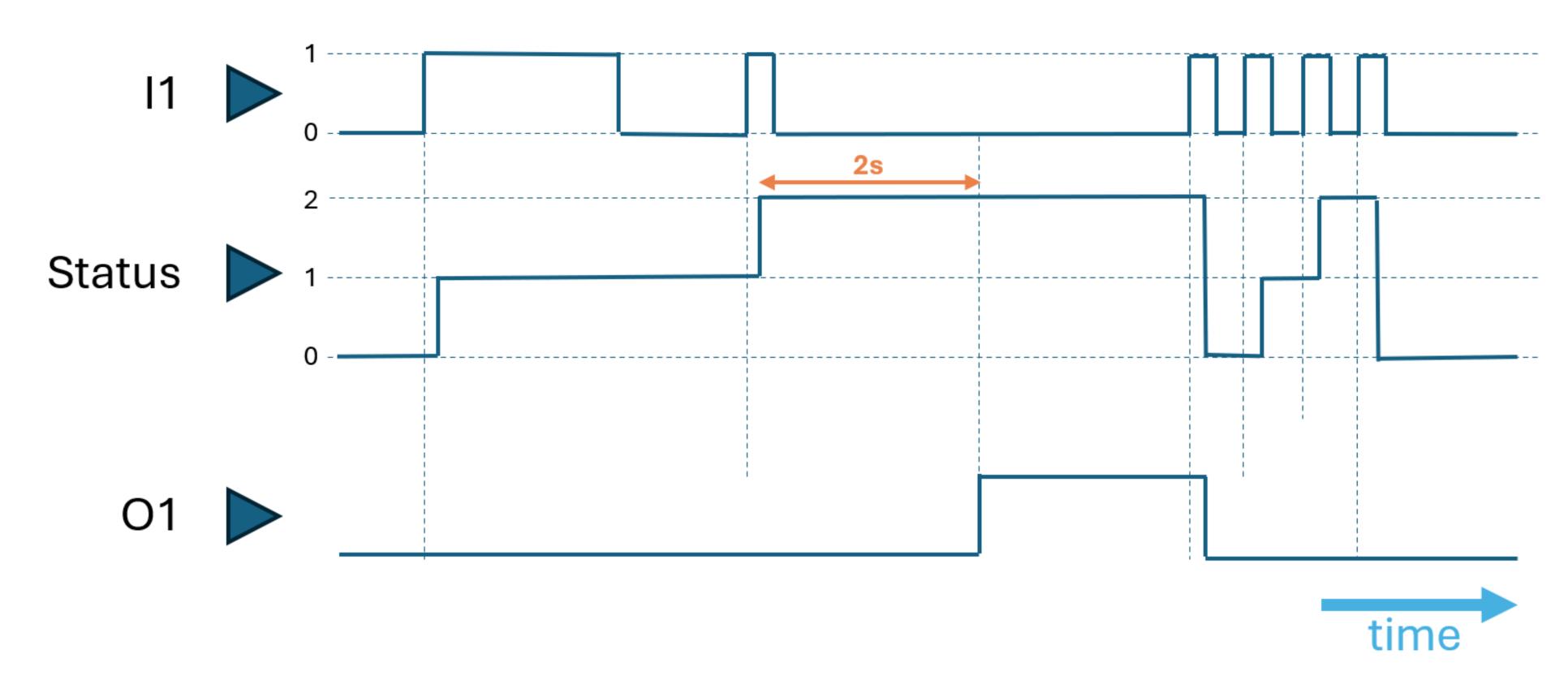
- ►I1 belongs to {IO_OFF, IO_ON}
- status belongs to 0..2
- Every time I1 changes from 10_OFF to IO_ON, status changes such as
- If status = 2 during 2 s or more then sets O1 to IO_ON
- Otherwise sets O1 to IO_OFF

We need to command output O1

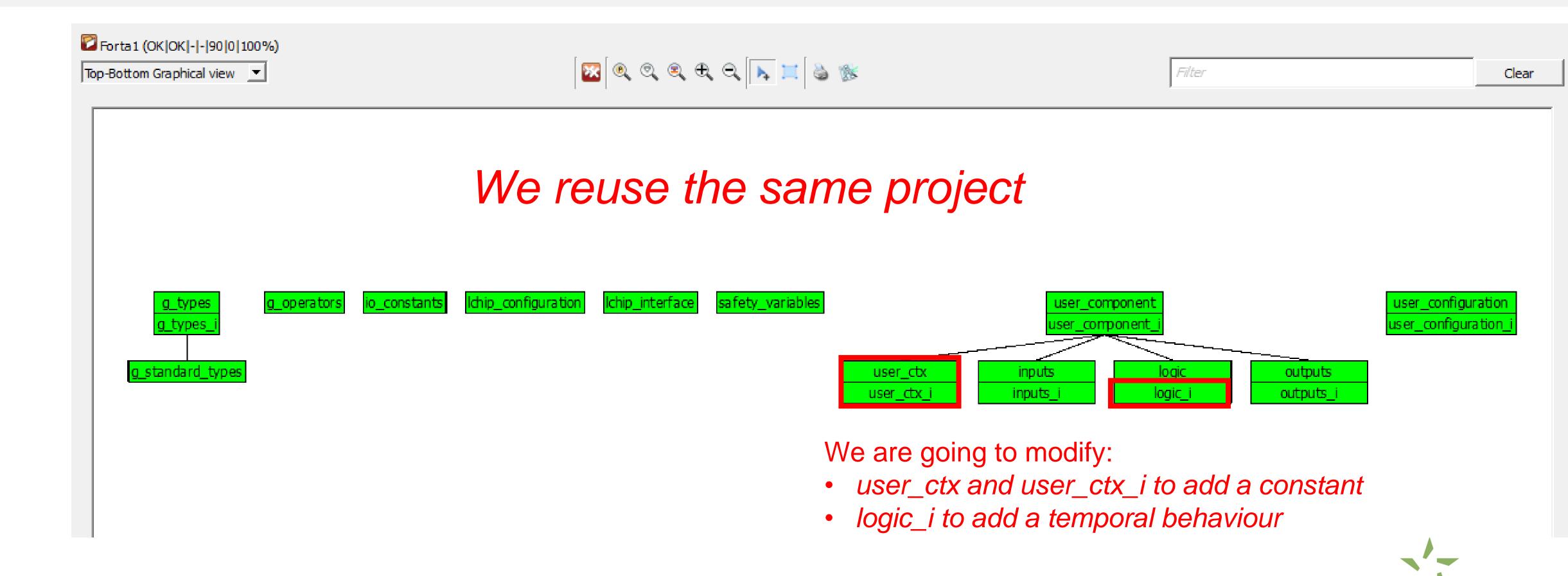




Synchronous Function - scenario

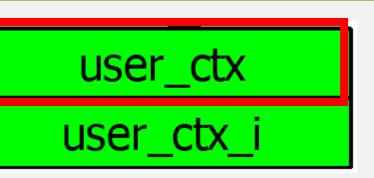


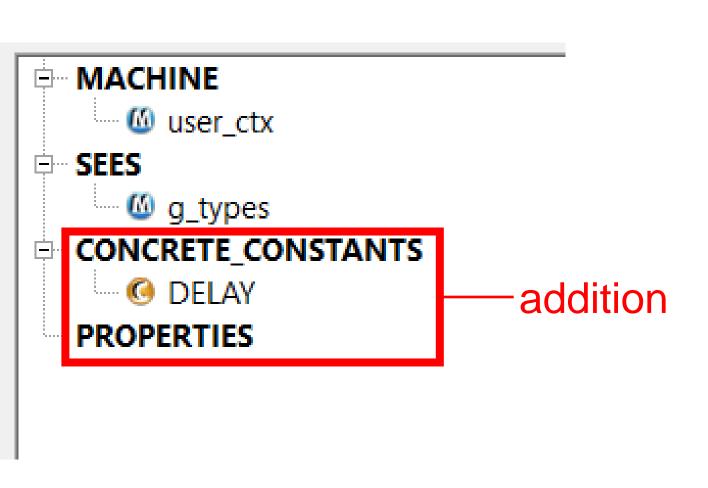


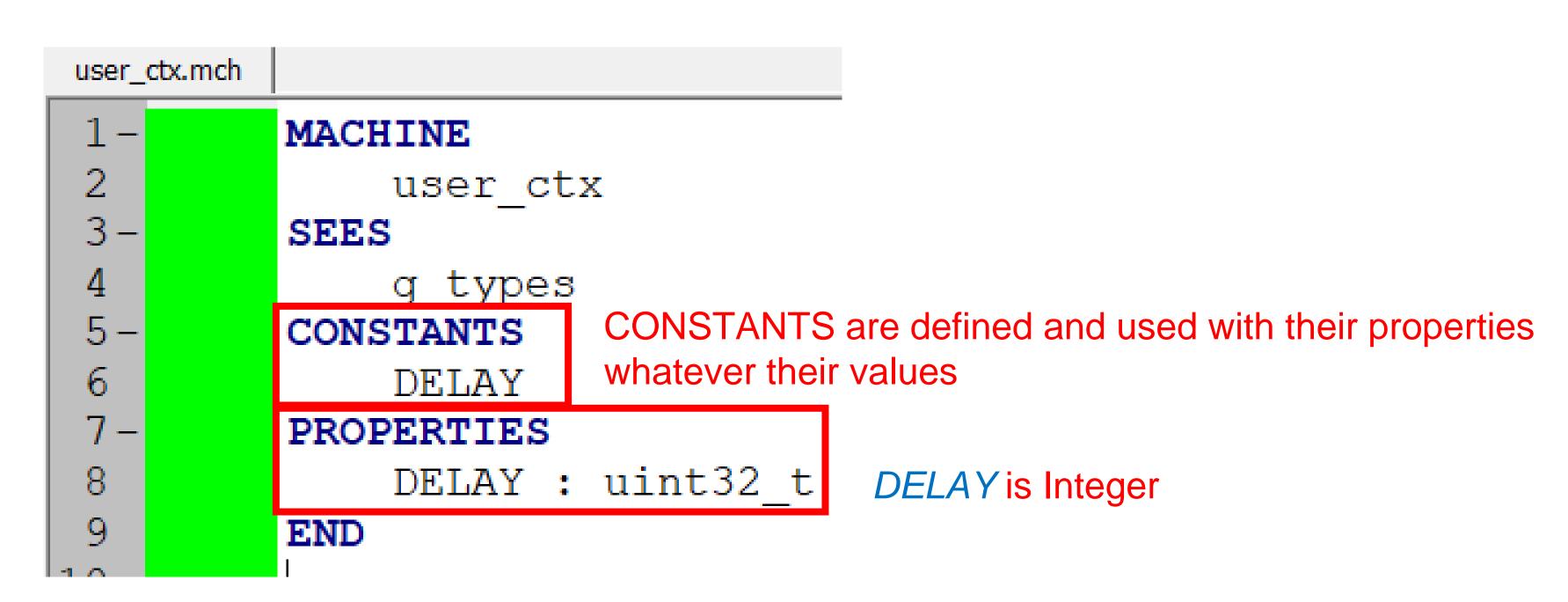


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Specification component



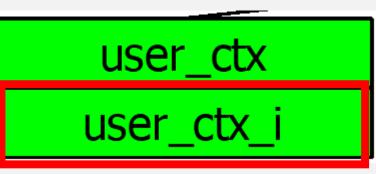


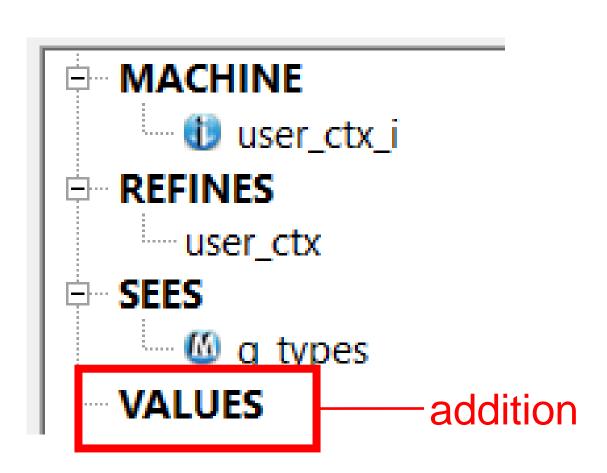


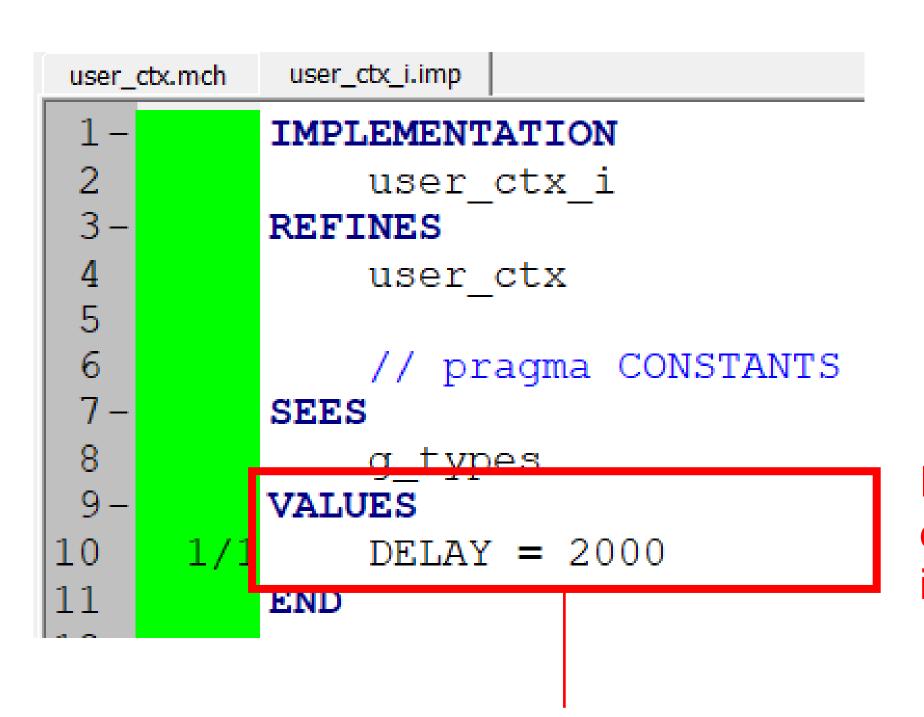


Implementation component

double-click to open







In

DELAY: uint32_t &

DELAY > 10 &

DELAY < 2

It is not possible to value

DELAY: it is a miracle

Each CONSTANT should be valued to demonstrate it is not a miracle i.e. 2000 belongs to uint32_t

Time returned by get_ms_tick OPERATION is in ms
Hence 2s == 2000 ms



Specification component

double-click to open



```
■ MACHINE
   └ logic
  SEES
    @ g_types
    @ g_operators
    io_constants
    Ichip_interface
    user_ctx
    inputs
                       No change!
  ABSTRACT_VARIABLES
    board_0_01
    board_0_02
    status
  INVARIANT
  INITIALISATION
user_logic
```

get_board_0_O1

get_board_0_02

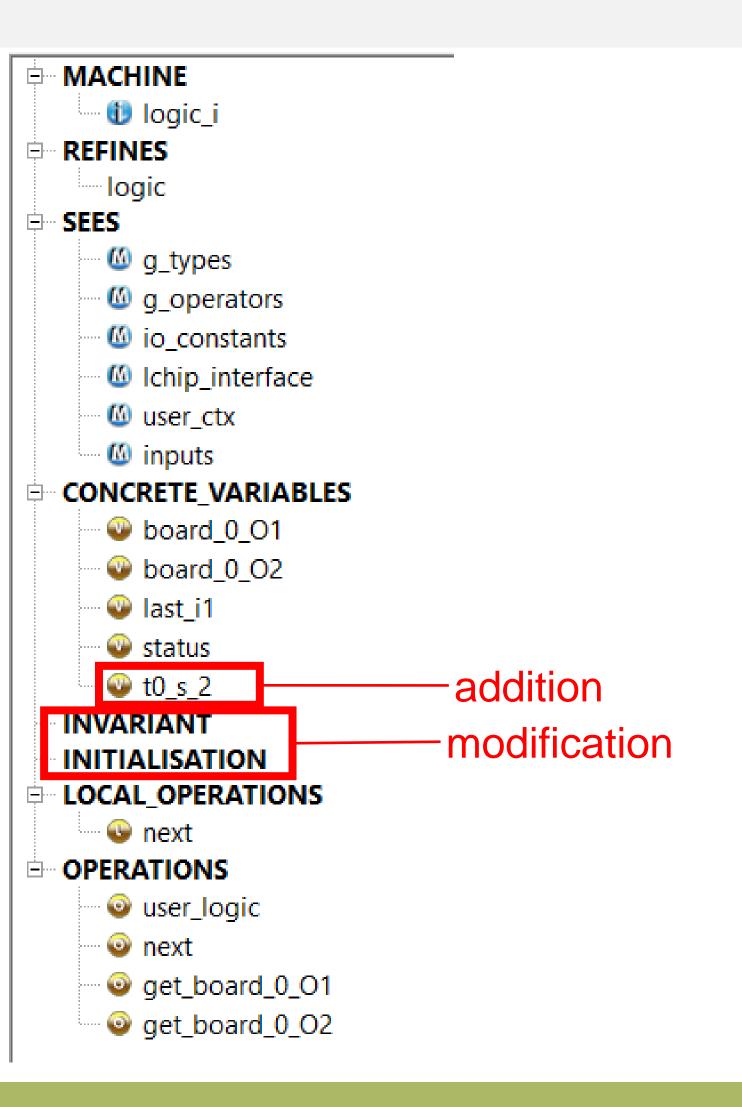
```
logic_i.imp
        logic.mch
         MACHINE
             logic
         SEES
             g_types,
             g operators,
             io constants,
             lchip_interface,
             user ctx,
             inputs
         ABSTRACT VARIABLES
             board_0_01,
             board 0 02,
             status
         INVARIANT
             board_0_01 : uint8_t &
             board_0_02 : uint8_t &
             status : uint8 t
         INITIALISATION
             board_0_01 :: uint8_t ||
             board 0 02 :: uint8 t ||
             status := 0
         OPERATIONS
             user logic = BEGIN
                 board 0 01,
                 board 0 02,
                  status: (
                      board 0 01 : uint8 t &
                      board_0_02 : uint8_t &
                      status : uint8 t
30
31
             END;
```



Implementation component

double-click to open





```
logic_i.imp
14-
         CONCRETE VARIABLES
15
             board 0 01,
16
             board 0 02,
             last il,
18
     4/4
             status,
             t0 s 2
19
     4/4
20-
         INVARIANT
21
             board 0 01 : uint8 t &
             board 0 02 : uint8 t &
23
             last i1 : uint8 t &
24
     4/4
             status : uint8 t &
25
             t0 s 2 : uint32 t
26-
         INITIALISATION
27
             board 0 O1 := IO OFF;
28
             board 0 02 := IO OFF;
             last i1 := IO OFF;
29
30
     1/1
             status := 0;
31
             t0 s 2 := 0
```

We need to store the last time *status* changed to the value 2

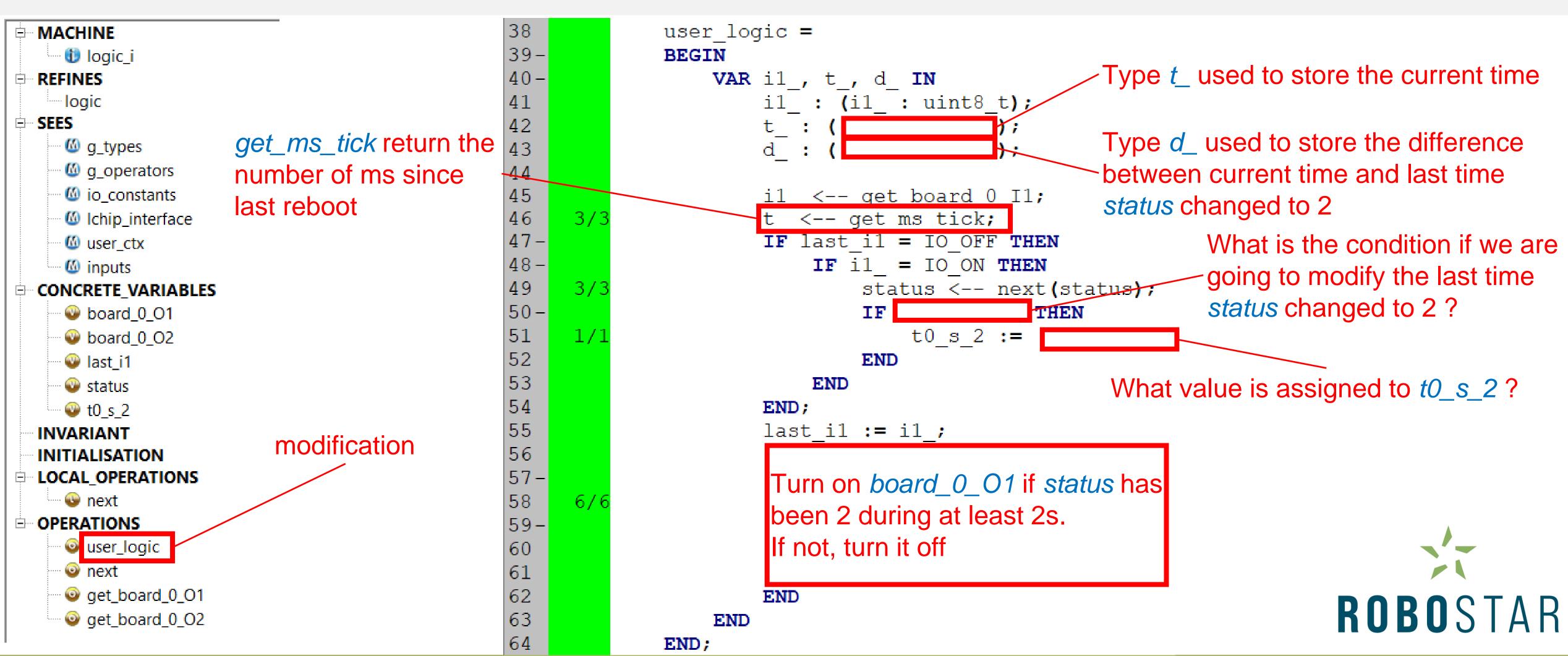
Timing information returned by the board is uint32 t

The initial value is 0, even if *status* is different from 2



Implementation component

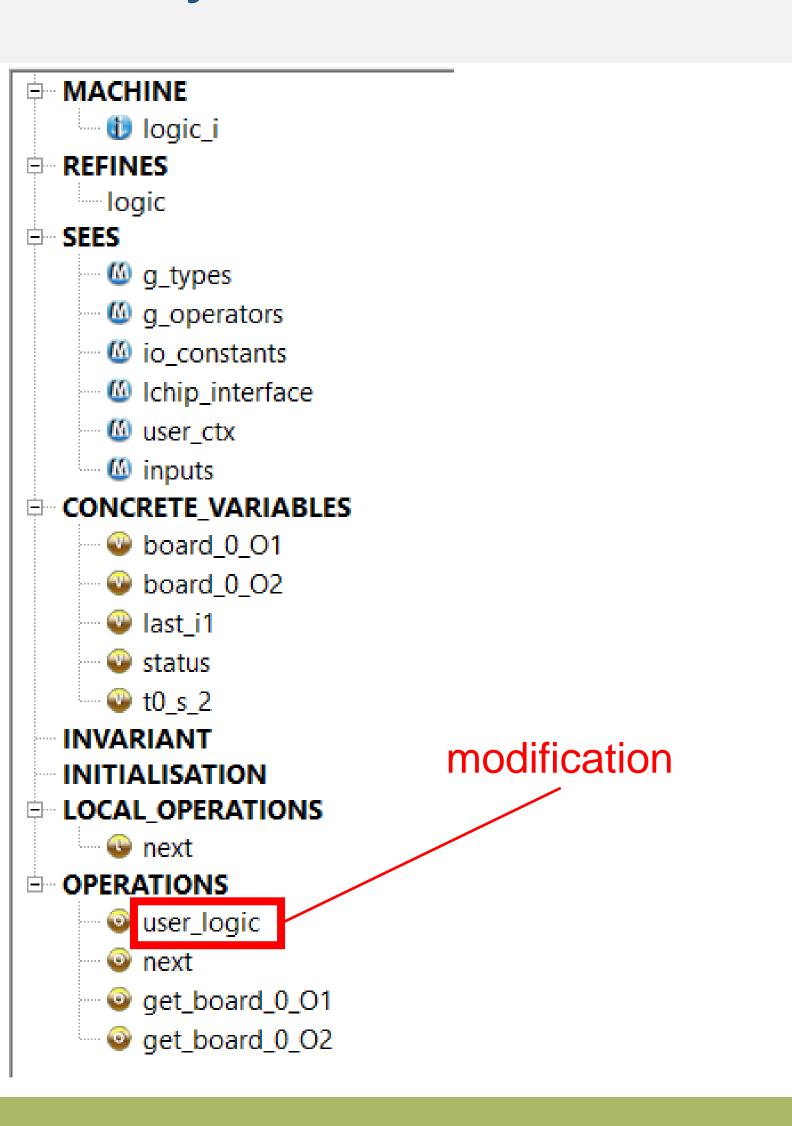




Implementation component

double-click to open





```
38
39-
40-
41
42
43
44
45
46
      3/3
47 –
48-
49
      3/3
50-
51
      1/1
52
53
54
55
56
57-
58
      6/6
59-
60
61
62
63
64
```

END;

```
user_logic =
BEGIN
    VAR i1 _, t_, d_ IN
        il_ : (il_ : uint8_t);
        il <-- get board 0 I1;
        t <-- get ms tick;
        IF last i1 = IO_OFF THEN
            IF i1 = IO ON THEN
                status <-- next(status);
                IF
                               THEN
                    t0_s_2 :=
                END
            END
        END;
        last i1 := i1 ;
         Turn on board_0_01 if status has
        been 2 during at least 2s.
        If not turn off 01
        END
    END
```

HINT1

To turn on an ouput OO

 $OO := IO_ON$

To turn it off

00 := IO_OFF

HINT2

Substraction of two uint32_t with *sub_uint32*

Ex: $vv := sub_uint32(aa,bb)$

CONSTRAINT1

Condition only with values, no calculation

CONSTRAINT2

Only < or <= , no > or >= for condition

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Synchronous / Timed Function: your turn

Implementation component

double-click to open



Edit logic and logic_i components

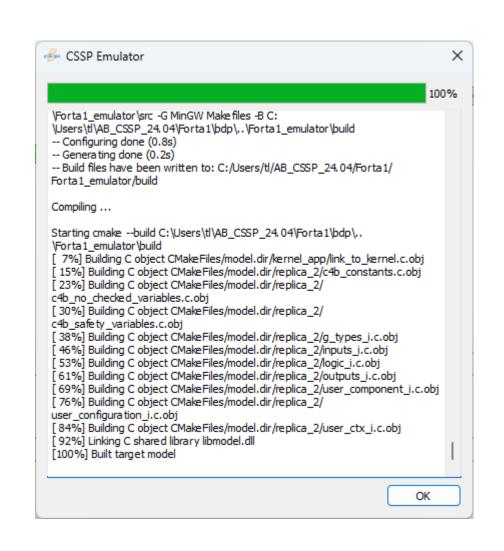
Ctrl-S to save and prove

Models should be « all green »

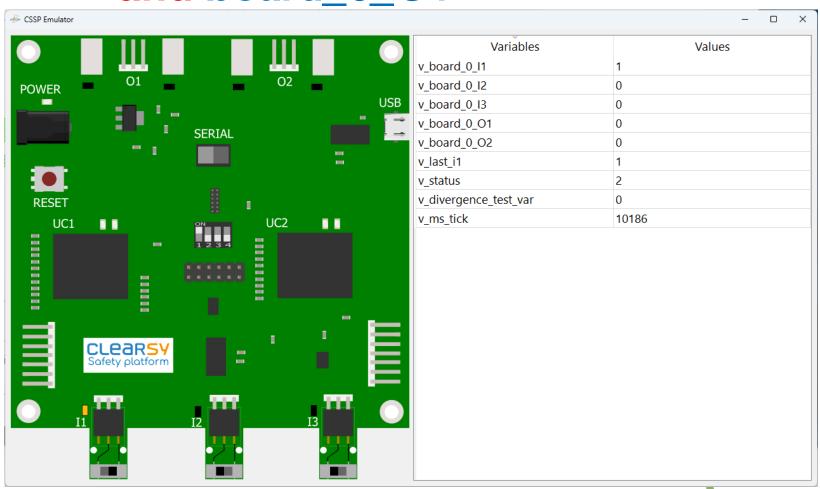
Ctrl-D to start the emulator
Reach « 100% built target model »
Press OK

```
MACHINE
               logic
               g operators,
               io constants,
               lchip interface,
               user_ctx,
               inputs
          ABSTRACT VARIABLES
               board 0 01,
               board 0 02,
               status
          INVARIANT
               board_0_01 : uint8_t &
               board 0 02 : uint8 t &
18 -
19
20
21
22 -
23 -
24
25
26 -
27
                               logic
                         board 0 01 : uint8 t &
                        board 0 02 : uint8 t &
                         status : uint8 t
               po <-- get_board_0_01 =
                   po : uint8 t
36-
37
38
39
40
                   po := board_0_01
               po <-- get_board_0_02 =
41-
                   ~~ · · · · · · · + · · · +
```

```
logic_i.imp | logic.mch |
 1 -
2
3 -
4
5 -
6
7
              logic_i
          REFINES
              logic
              g_operators,
               io constants,
              lchip_interface,
              user_ctx,
11
              inputs
12
13
              // pragma SAFETY VARS
          CONCRETE VARIABLES
14 -
              board_0_01,
              hoard 0 02
19-
20
21
22
23
24-
25
26
              board_0_02 := IO_OFF;
27
              last_i1 := IO_OFF;
              status := 0
          LOCAL OPERATIONS
              n <-- next(state) =
31 -
              PRE state: uint8 t & n : uint8 t THEN
32
                  n_ :: uint8_t - {state}
34 -
          OPERATIONS
              user logic =
37 -
38
39
40
41
                  VAR i1_, n_ IN
                       i1_ : (i1_ : uint8_t);
                       n_ : (n_ : uint8_t);
                       il <-- get board 0 I1;
```



Click on I1 several times and observe the behaviour of *status* and *board_0_01*





Synchronous / Timed Function: your turn

Hard Work On Going!

Spoiler Alert: Solution on the next slide!



Synchronous / Timed Function: the solution Implementation component double-click to open



```
user logic =
■ MACHINE
                                            39-
                                                           BEGIN
    · 👣 logic_i
                                            40-
                                                               VAR i1_, t_, d_ IN
□ REFINES
                                            41
    --logic
                                                                       : (i1 : uint8 t);
□ SEES
                                            42
                                                                       : (t_ : uint32_t);
                                                                                                 Both t and d are unit32_t
    ⋅ 🐠 g_types
                                            43
                                                                          (d : uint32 t);
                                            44
    Ø g_operators
                                            45
    io_constants
                                                                    il <-- get board 0 I1;
                                            46
                                                                    t <-- get ms_tick;
                                                  3/3
    Ichip_interface
                                            47 –
                                                                    IF last i1 = IO OFF THEN
    W user_ctx
                                            48-
                                                                        IF i1 = IO ON THEN
    · 🐠 inputs
                                            49
                                                  3/3
                                                                             status <-- next(status);
 CONCRETE_VARIABLES
                                            50-
                                                                             IF status = 2 THEN
                                                                                                      status has just changed to 2.
    board_0_01
                                            51
                                                  1/1
                                                                                  t0 s 2 := t
    board_0_02
                                                                                                      It is the right time to store the current
                                            52
                                                                             END
    last_i1
                                                                                                      time
                                            53
                                                                        END
    status
                                            54
                                                                    END;
    🐠 t0_s_2
                                                                    last i1 := i1 ;
 INVARIANT
                                            56
                                                                    board 0 01 := IO OFF;
  INITIALISATION
                                            57 –
                                                                    IF status = 2 THEN
 LOCAL_OPERATIONS
                                            58
    · 🕒 next
                                                  6/6
                                                                        d_{:} = sub_uint32(t_{,} t0_s_2);
                                                                                                           d_ is meaningful only if status is 2
                                            59.
                                                                        IF DELAY <= d_ THEN</pre>

    □ OPERATIONS

                                                                             board 0 01 := IO ON
     user_logic
                          modification
                                                                        END
                                            62
    get_board_0_01
                                                                    END
                                                                                                                          ROBOSTAR
                                            63
                                                               END
    get_board_0_02
                                            64
                                                           END;
```

Exercise to Go Further



- ► 11 {IO_OFF, IO_ON}
- ►11 is noisy, changing value up to thousands times per second
- ►Only I1 constant during at least 100 ms have to be considered and are repeated on O1 and O2 has to be IO_ON
- ►If no constant behavior is observed, then O2 has to be IO_OFF in this case, the status of O1 is not considered (could be any value)
- Summary:
- O2 is IO_ON when I1 has been constant during at least 100 ms and O1 has the status of the observed I1
- O2 is IO_OFF when I1 has not been constant during the last 100 ms

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Next

From RoboSim To The CLEARSY Safety Platform

Paulo Bezerra

