Working Session 2 Programming the CLEARSY Safety Platform

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11th March 2025





Agenda

- Setting / checking the modelling environment
- Developing a combinatorial function
- Developing a synchronous / timed function



Setting The Modelling Environment

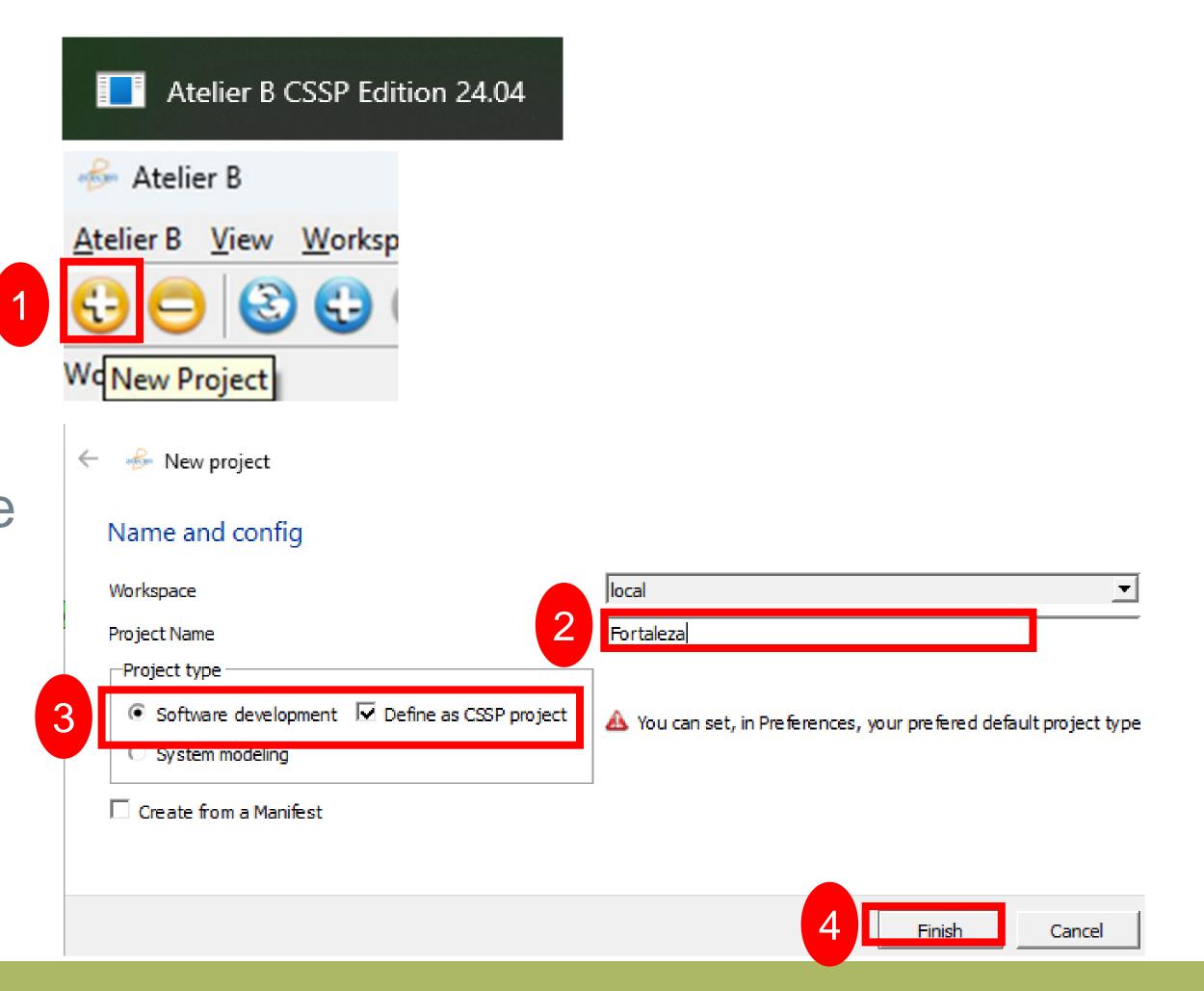


Project Creation 1/3

Start Atelier B

Create a new project

Give a name and a type

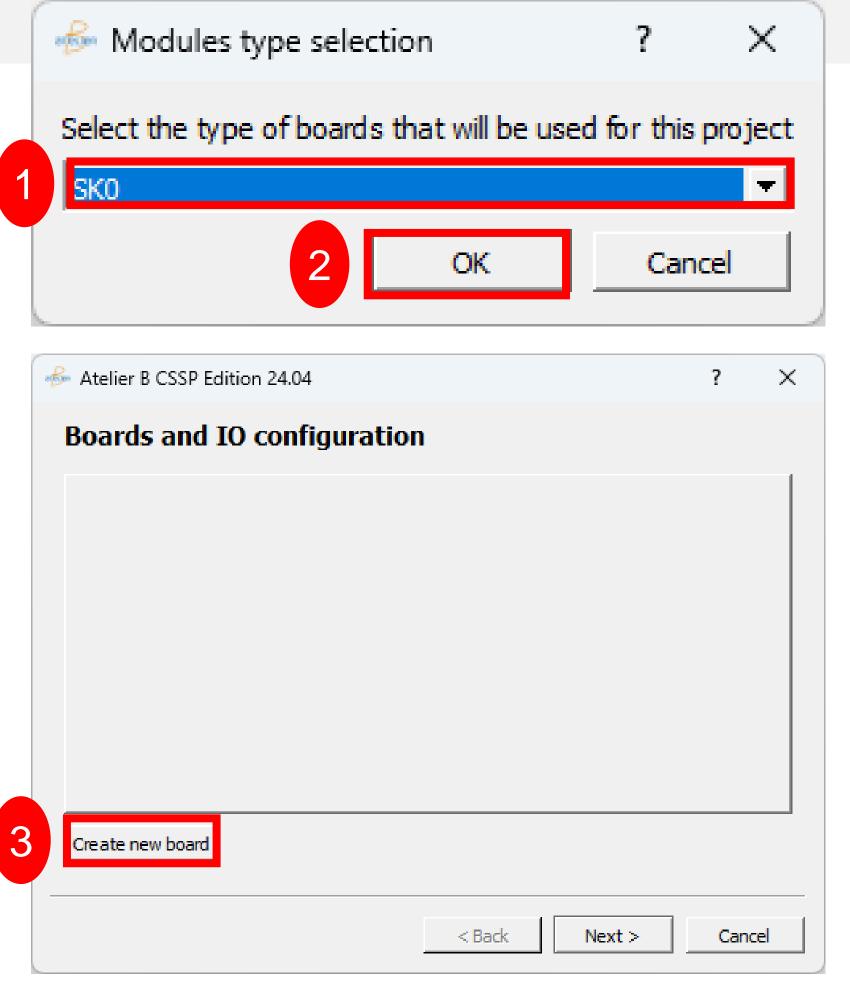


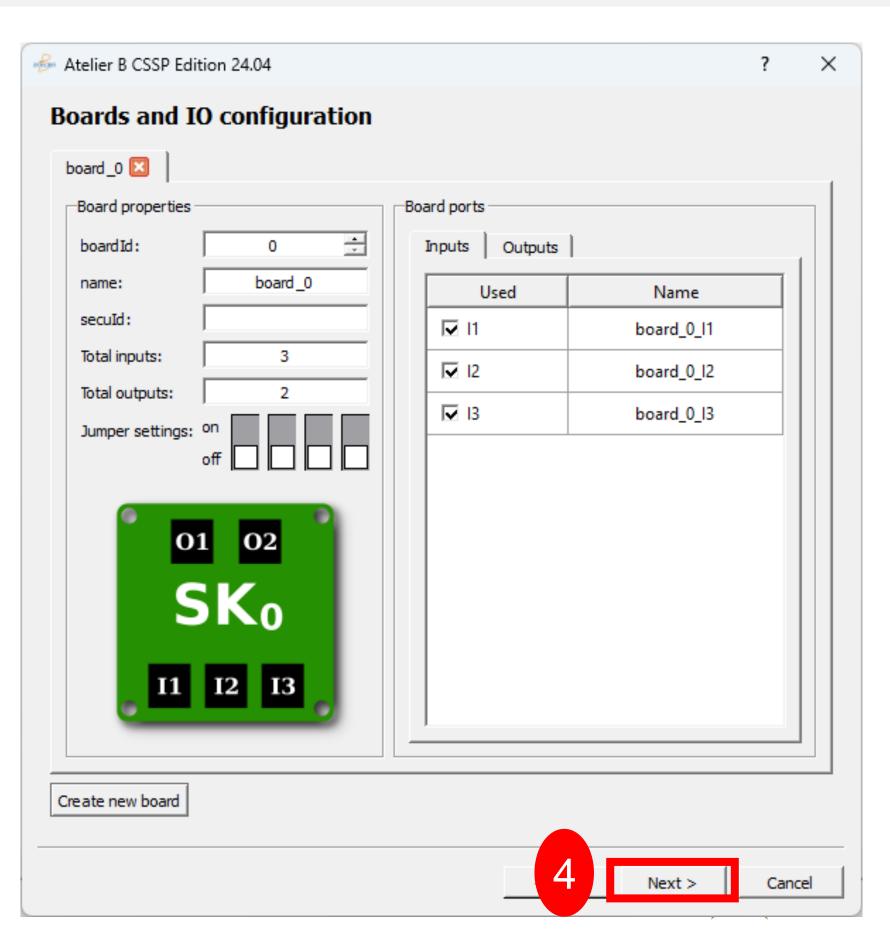


Project Creation 2/3

Select SK0

Create a new board

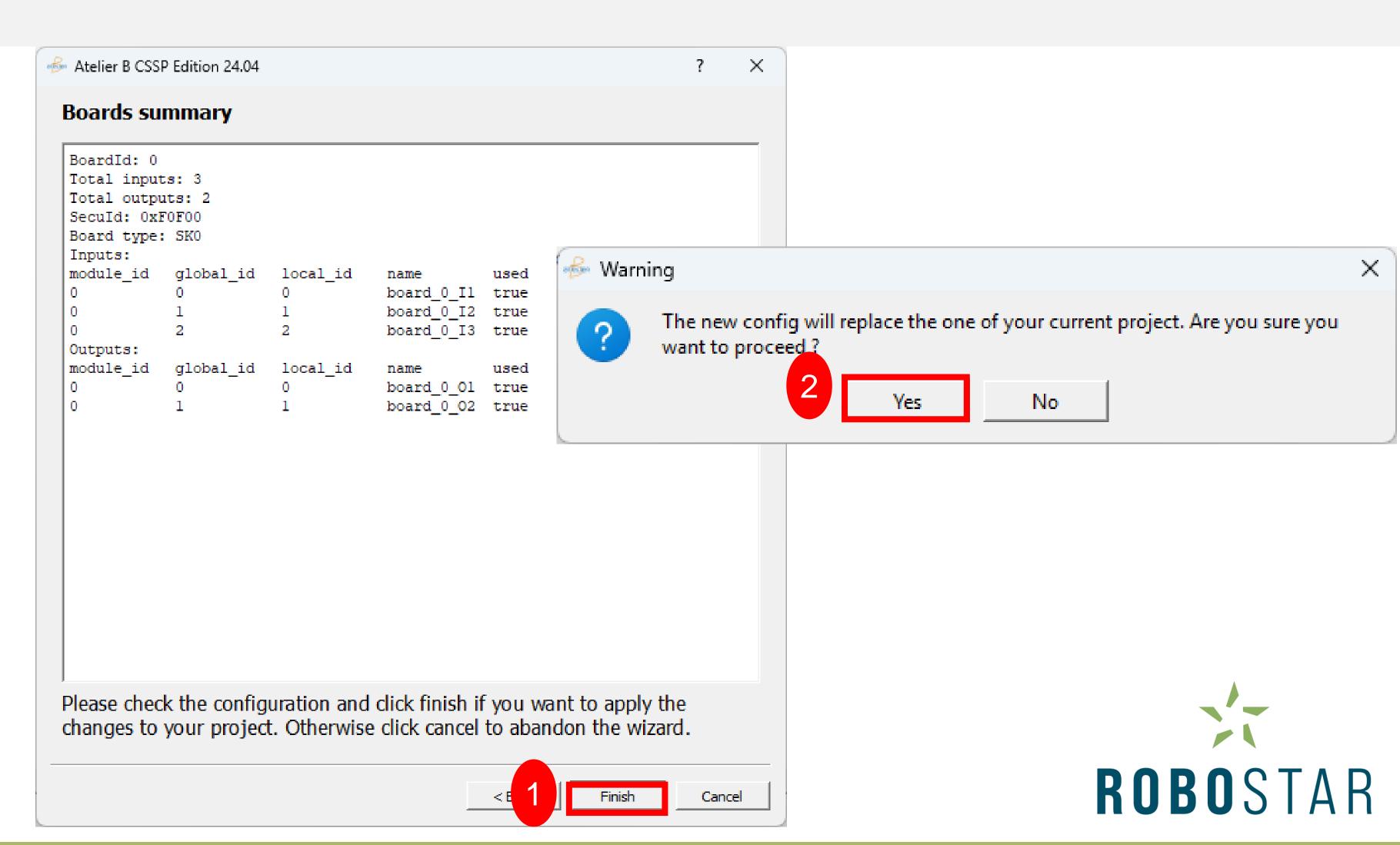




ROBOSTAR

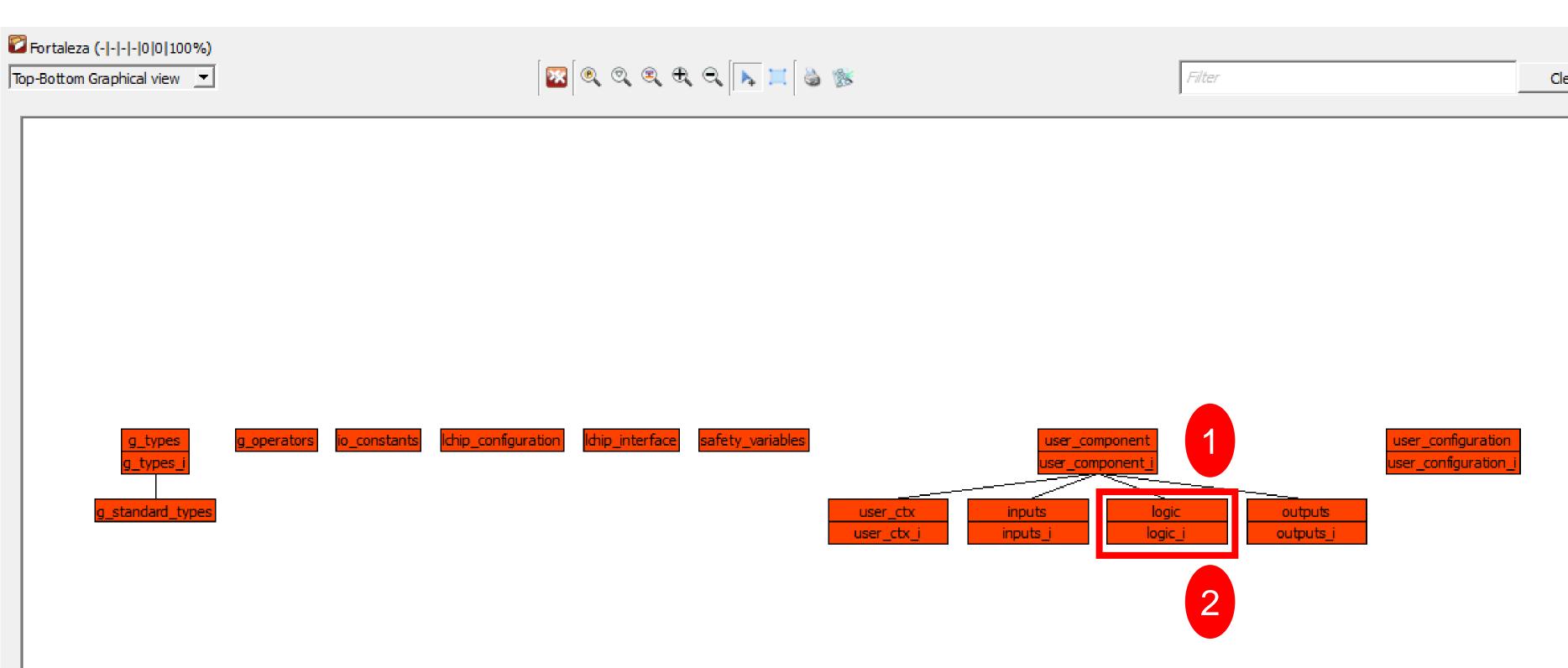
Project Creation 3/3

Finish the creation



Project Created

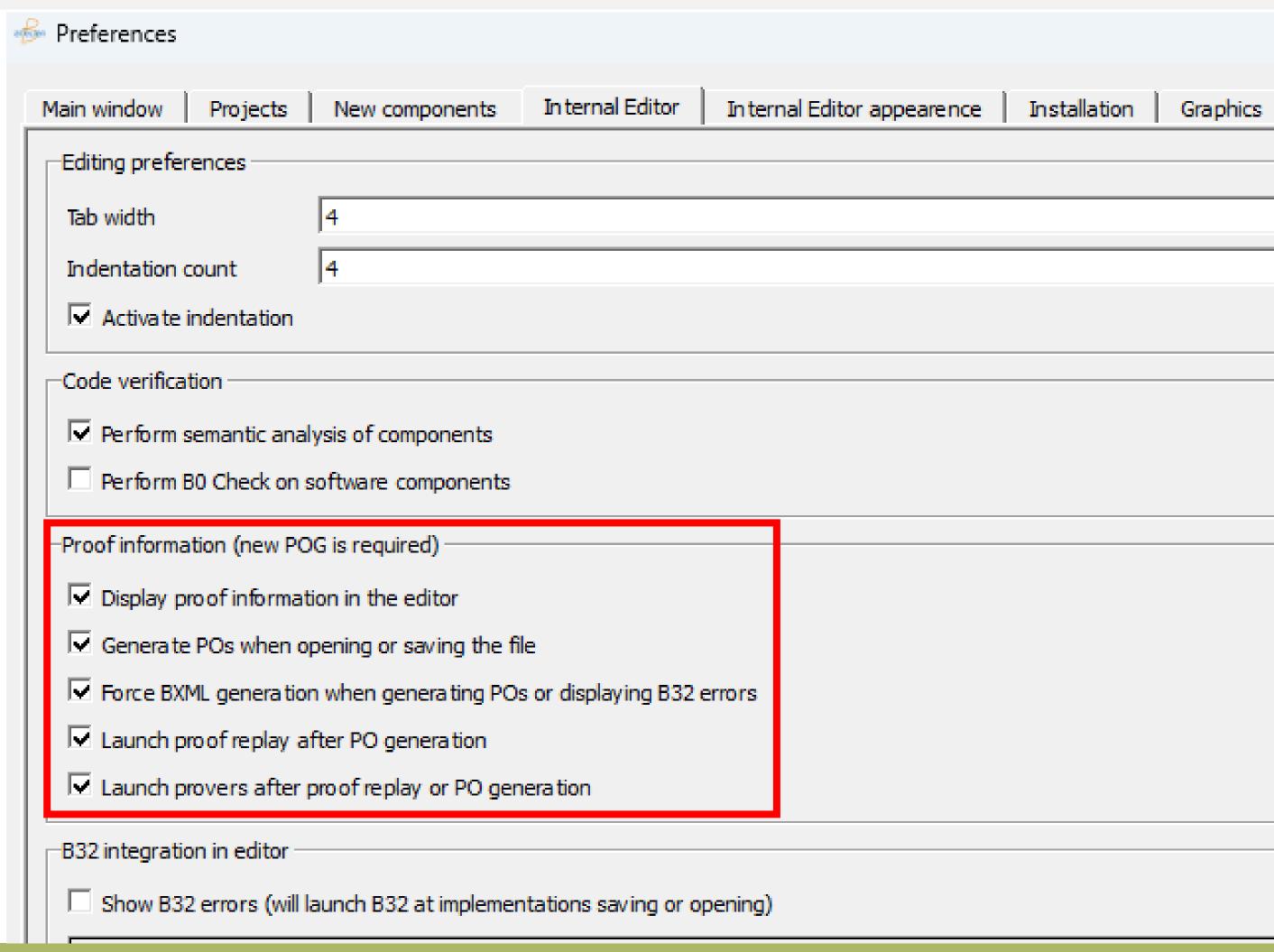
- The view
- 2 components to modify





Checking Setup 1/2

- Open menu Atelier B / Preferences
- Select Internal Editor
- Ensure that Proof Information is fully checked



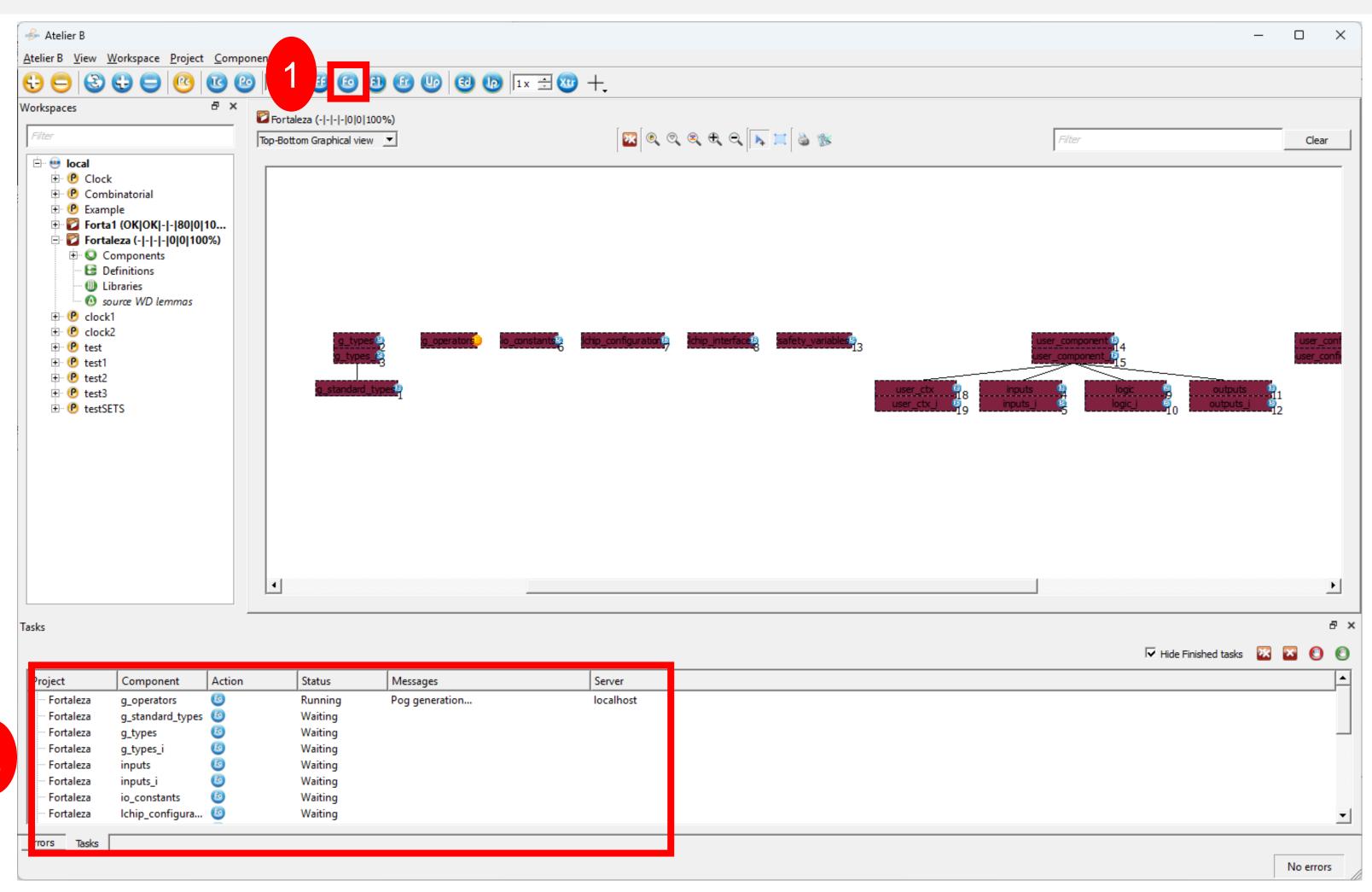
Checking Setup 2/2

- Open your project
- Open menu Project / Properties
- Select Software Development
- Ensure that New Generation is checked in Proof Obligation Generator

Properti	es for project Forta1
project	software development krt resource file
Type Checker	
Enable extended SEES	
Proof Obligation Generator	
Genera tor : Legacy (<4.2)	
	New Generation
Generate Overflow Proof Obligations	
POG NG	
Generate Well Definedness Proof Obligations	
Enable external provers	
	nable traceability in proof obligations

To be sure Your Environment is Operational ... 1/5

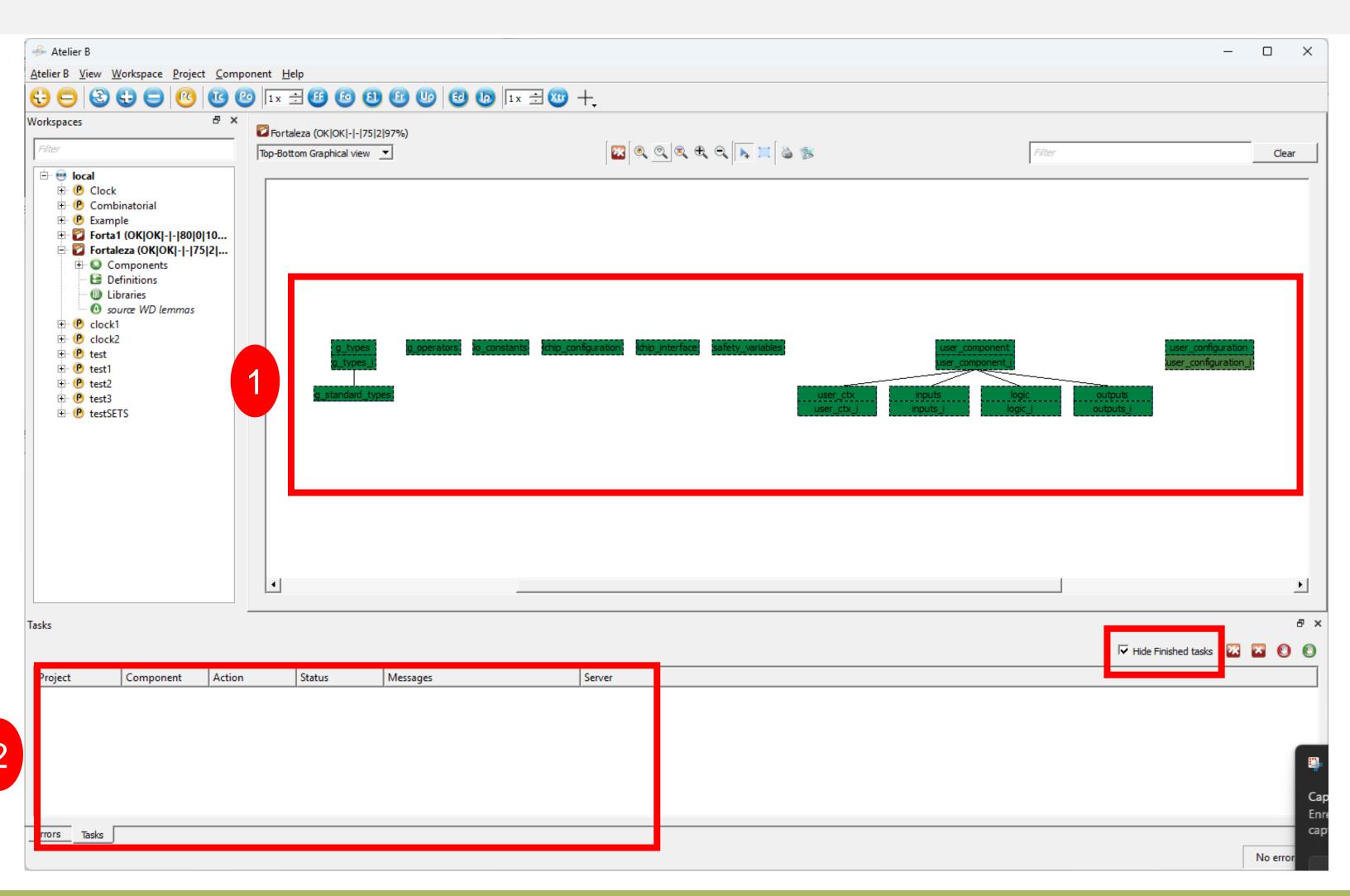
- Select all the components with Ctrl+A
- Start Proof Force 0 (or Ctrl-0)
- Wait for proof to complete



To be sure Your Environment is Operational ... 2/5

All components green

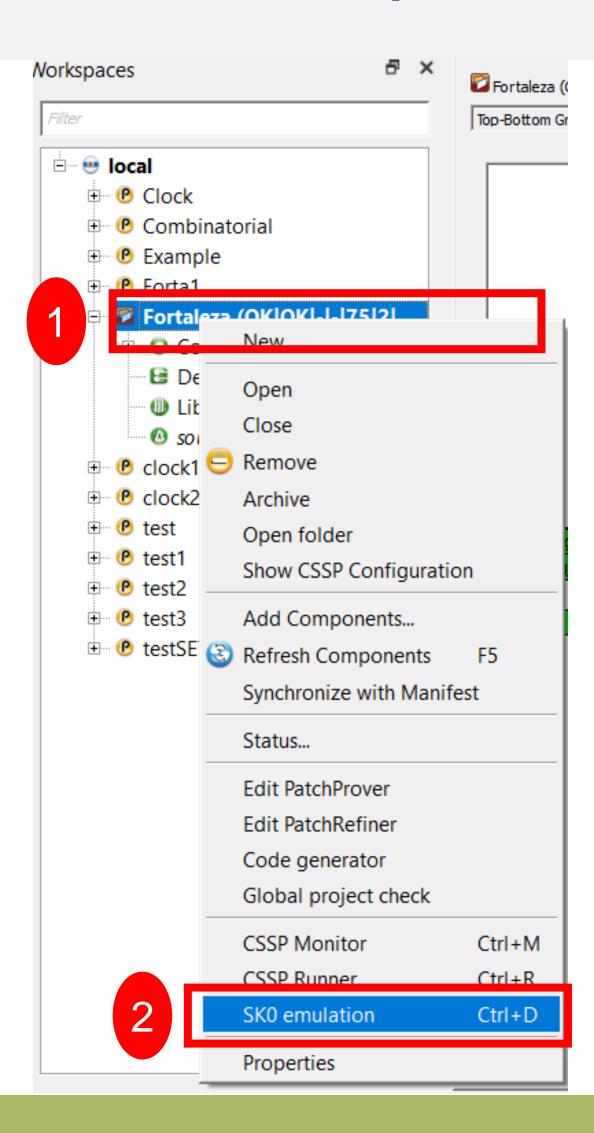
All tasks completed (select "Hide finished tasks")



To be sure Your Environment is Operational ... 3/5

Right click on the project

Select "SK0 emulation" or Ctrl-D



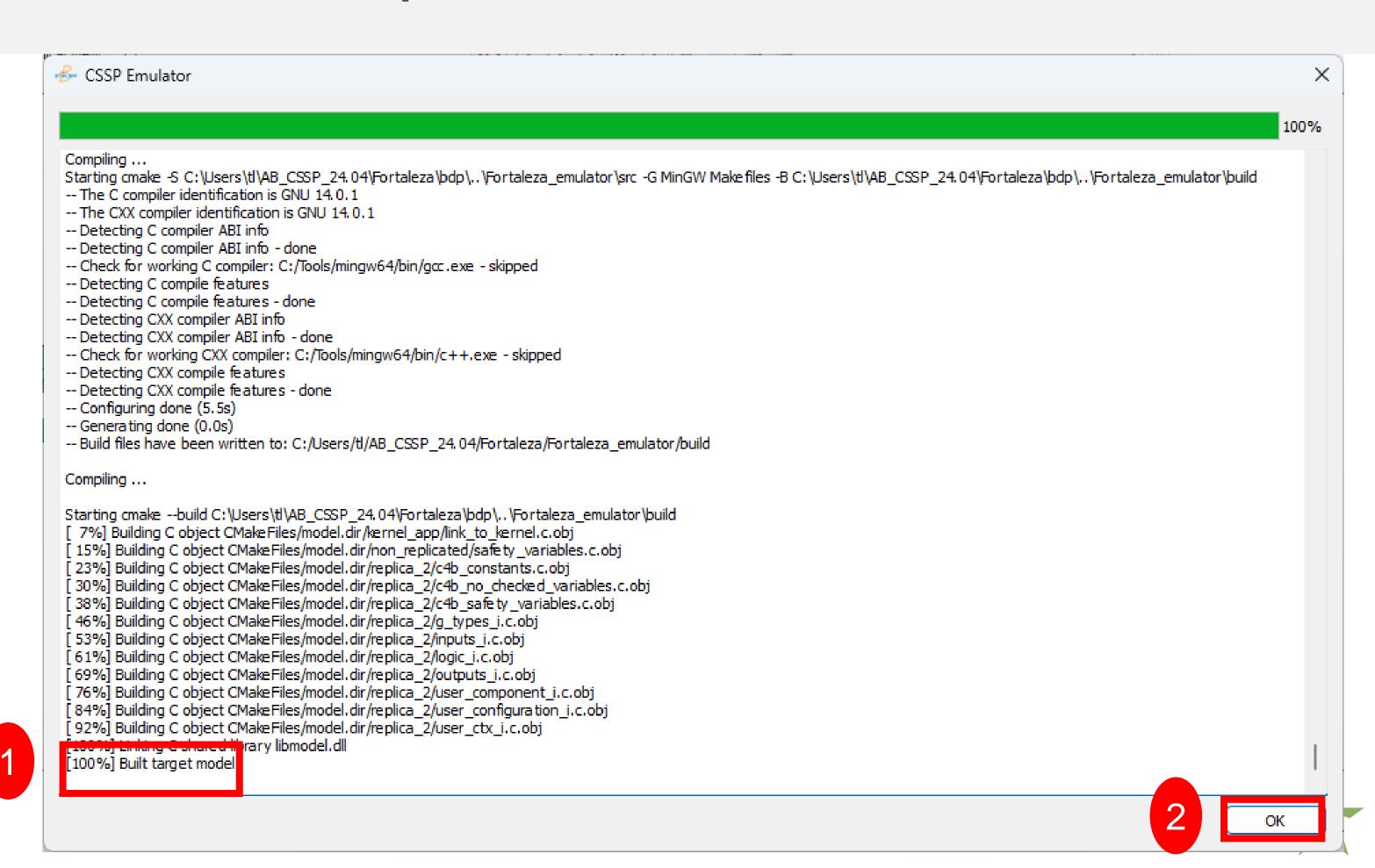


To be sure Your Environment is Operational ... 4/5

After several seconds and verbose messages ...

The process terminates with [100%] Built target model

Click on OK

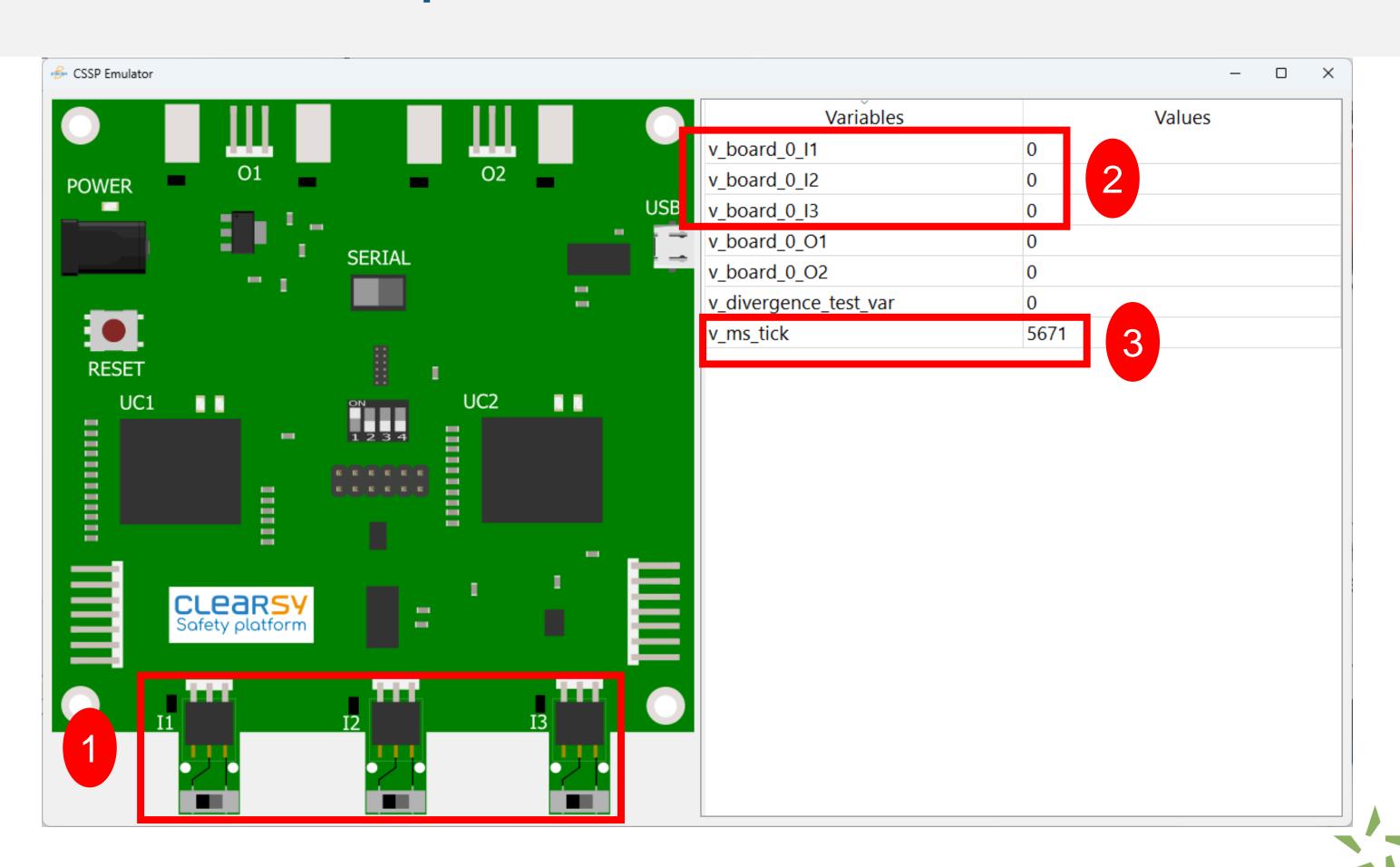


If stops before 100%, cmake / gcc installation is probably incomplete

ROBOSTAR

To be sure Your Environment is Operational ... 5/5

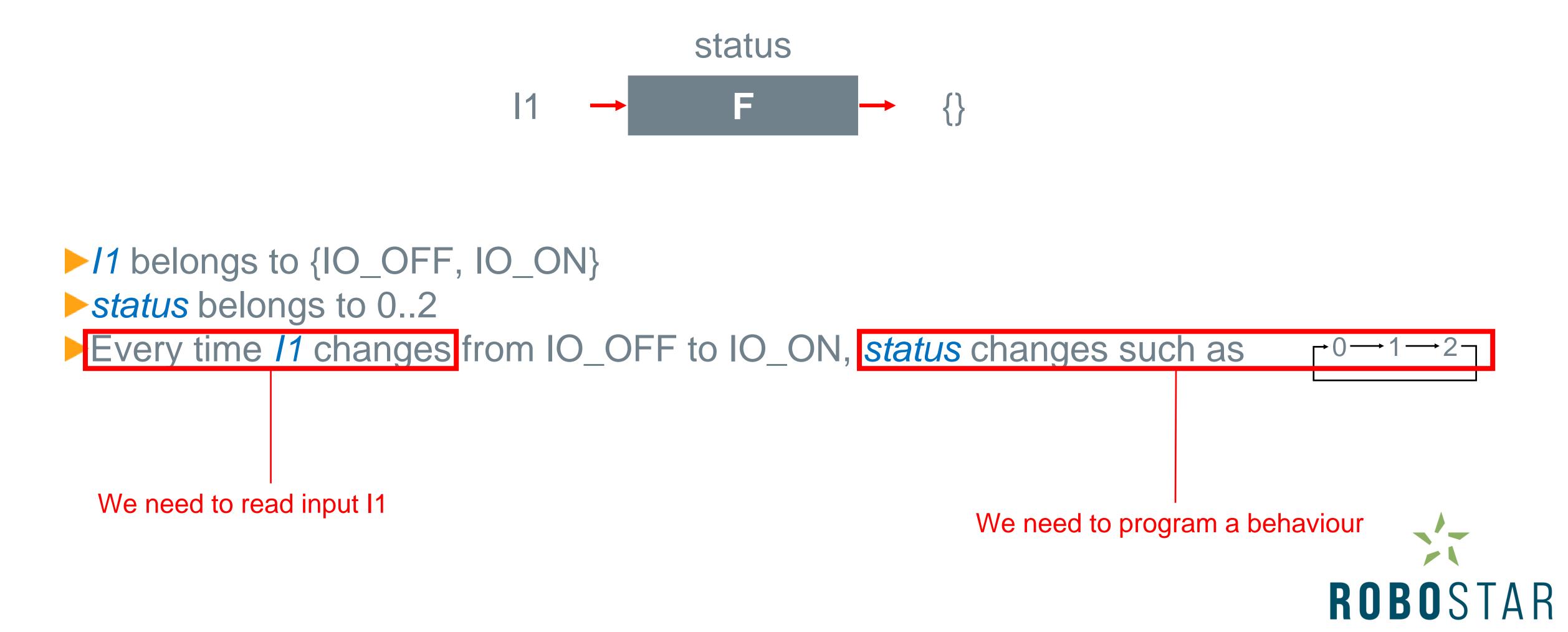
- The simulator starts
- If you click on I1, I2 or I3, the v_board_0_lx variables change
- The time flies



ROBOSTAR

Developping a Combinatorial Function

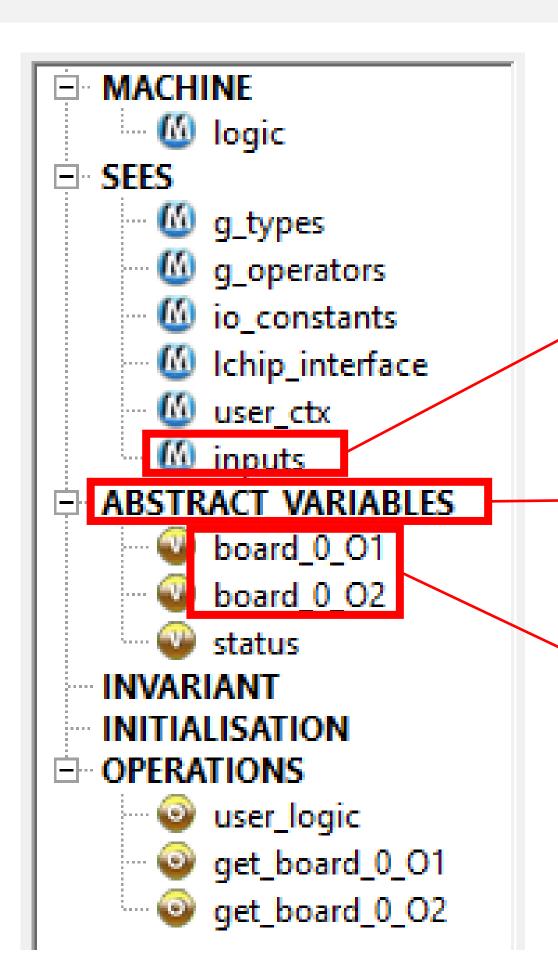




Specification component

double-click to open

logic logic_



Inputs are not variables of this model. They are read and accessed from the inputs component

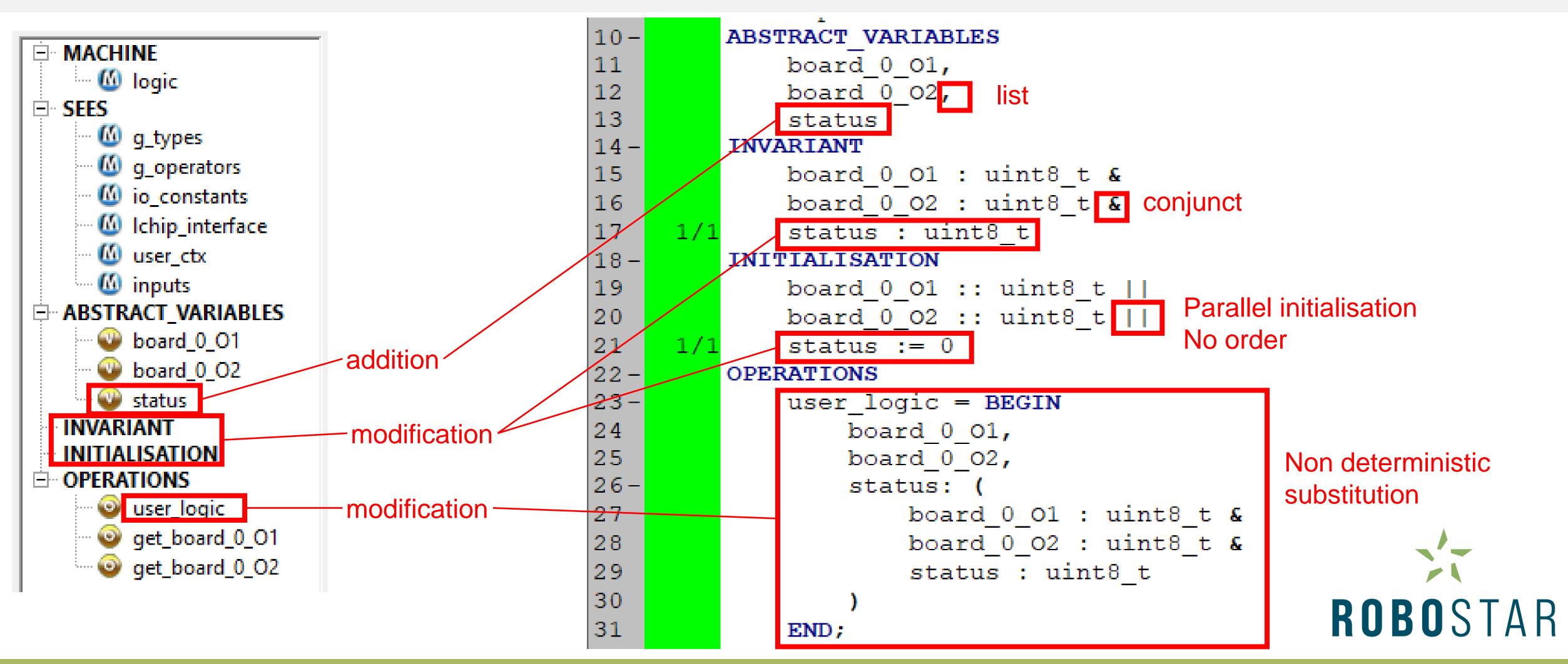
Abstract variables are not necessarily implemented. They could appear only in specification for « reasoning »

Outputs are variables of this component. They are modified in this component. In B, variables are modified in a single component



Specification component





Specification component



```
ABSTRACT VARIABLES
                                           10-
                                                         board 0 01,
                                           11
                                           12
                                                         board 0 02,
                                           13
                                                         status
                                           14 -
                                                     INVARIANT
                                           15
                                                         board_0_01 : uint8 t &
                                                         board 0 02 : uint8 t &
                                           16
                                                         status : uint8 t
                                                                                       The 3 variables are going to
                                           18-
                                                     INITIALISATION
                                                                                       evolve according to their type
                                           19
                                                         board 0 01 :: uint8 t ||
                                                                                       and could keep the same value
                                           20
                                                         board_0_02 :: uint8_t ||
                                                         status := 0
                                           22 -
                                                     OPERATIONS
                                                         user_logic = BEGIN
                                           23-
                                           24
                                                             board 0 01,
                            xx: (xx: T(xx))
                                                              board 0 02,
                                           26-
                                                              status: (
                                           27
                                                                  board 0 01 : uint8 t &
                                  means.
                                                                  board 0 02 : uint8 t &
                                           28
                                                                  status : uint8_t
                                           29
« xx becomes such that xx belongs to its type »
                                           30
                                                                                                ROBOSTAR
                                           31
                                                         END;
```

Specification component

double-click to open

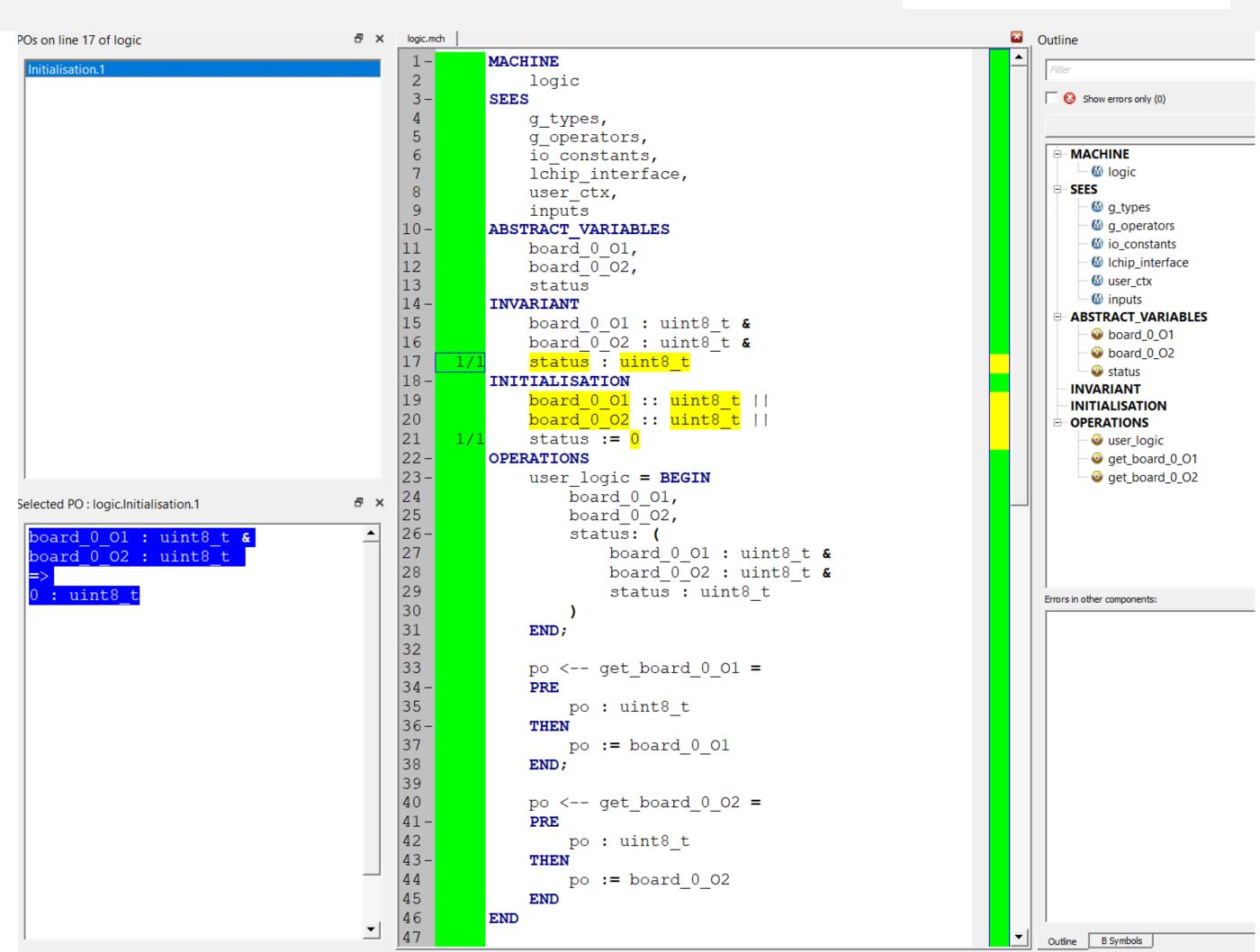


Once the editing is completed

Type Ctrl-S to save

Proof is automatically initiated

You should get a fully green (proved) component

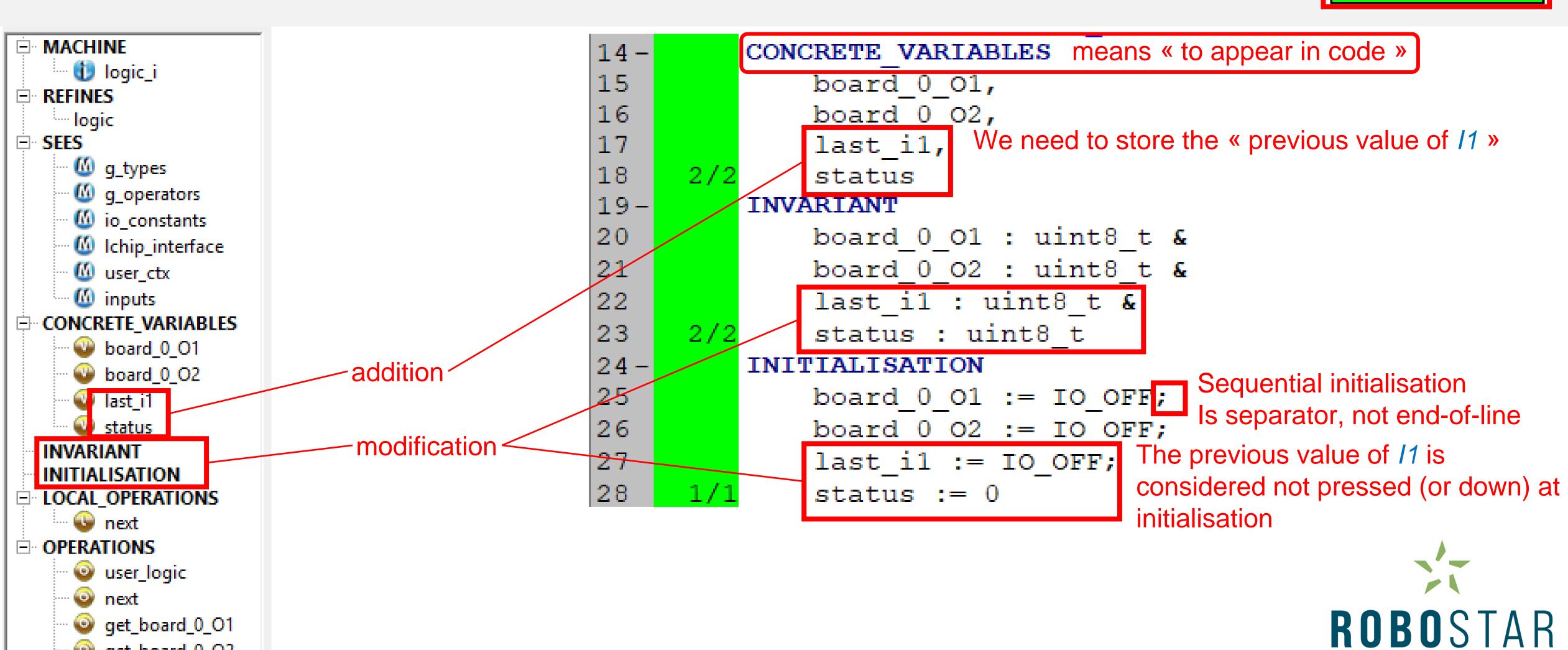


get_board_0_01

get_board_0_02

Implementation component

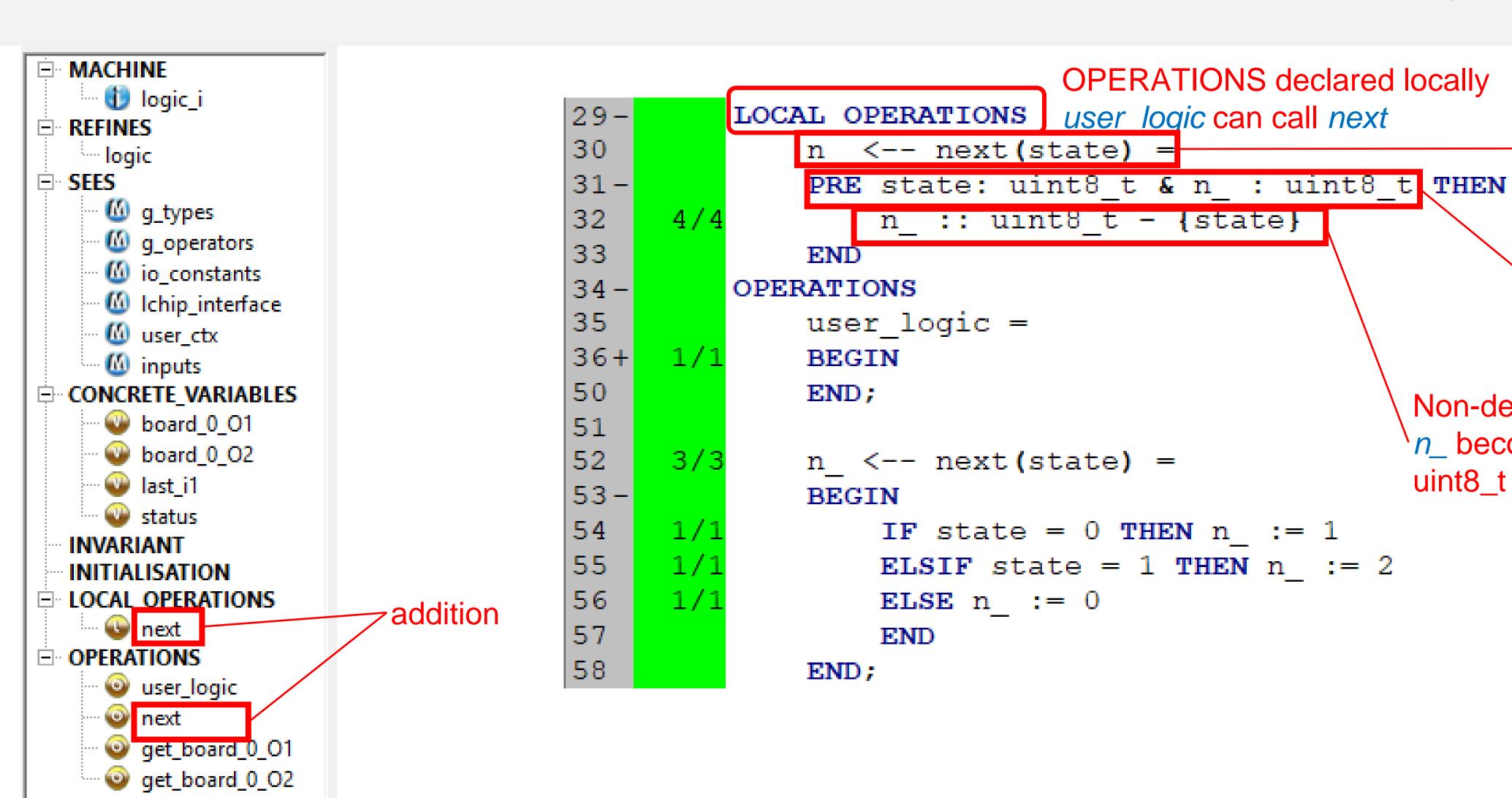




Implementation component

double-click to open





Operation *next* with one parameter *state* returning *n*_

Precondition used to indicate types for parameter and return value

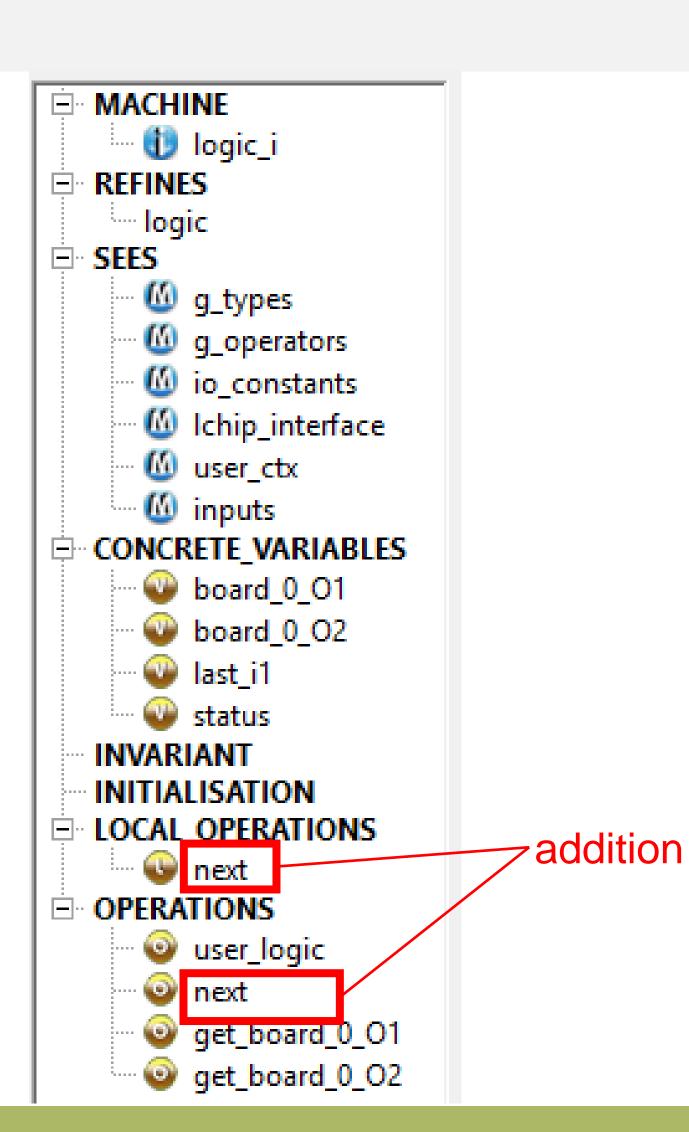
Non-deterministic substitution:

n_ becomes equal to any
uint8_t except the value of state



Implementation component



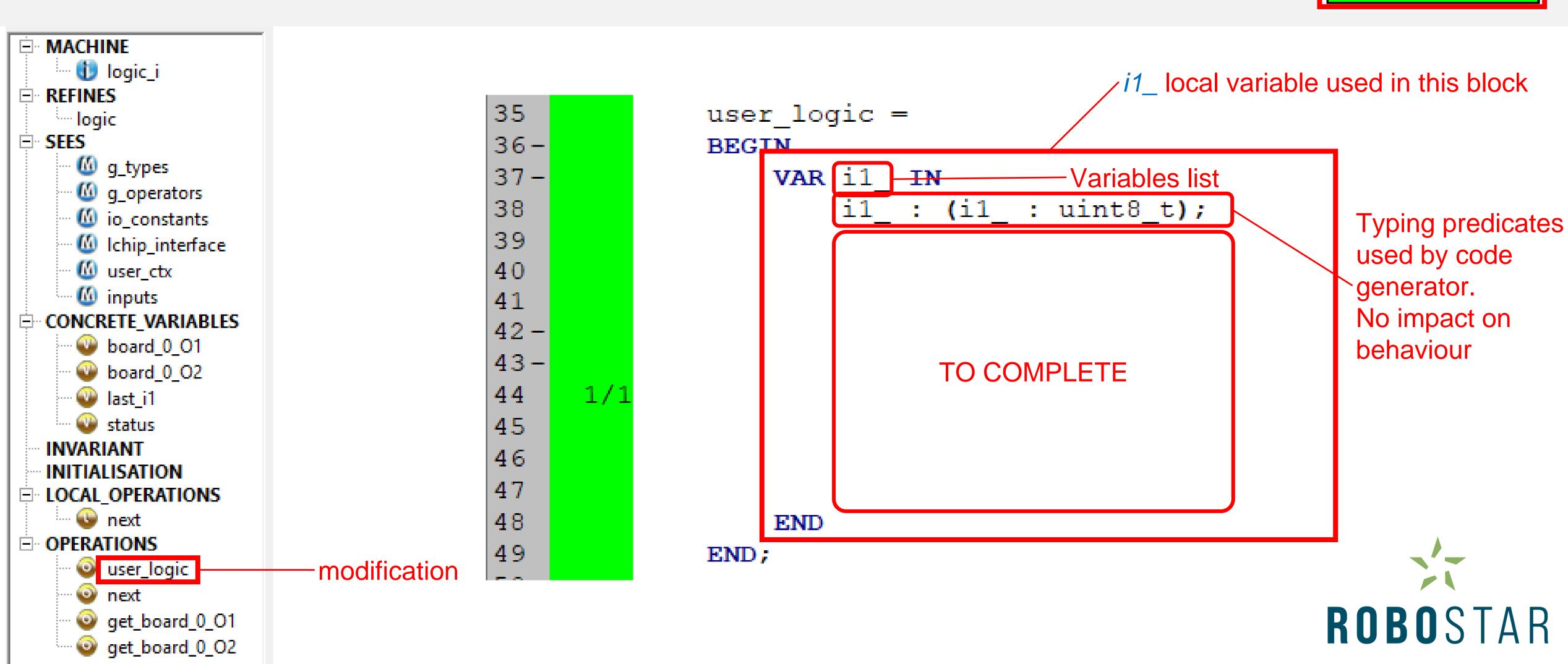


```
29-
30
31-
32
      4/4
33
34 -
35
36+
      1/1
50
51
      3/3
53-
      1/1
54
      1/1
      1/1
56
58
```

```
LOCAL OPERATIONS
    n <-- next(state) =
    PRE state: uint8 t & n : uint8 t THEN
        n :: uint8 t - {state}
    END
OPERATIONS
    user logic =
    BEGIN
    END;
                                 Same signature
                                 Types are kept from
       <-- next(state)
                                 LOCAL_OPERATIONS precondition
    BEGIN
        IF state = 0 THEN n := 1
        ELSIF state = 1 THEN n := 2
                                         Algorithm implemented with
        ELSE n := 0
                                         IF THEN ELSE
        END
    END;
            Assignment
                                               ROBOSTAR
```

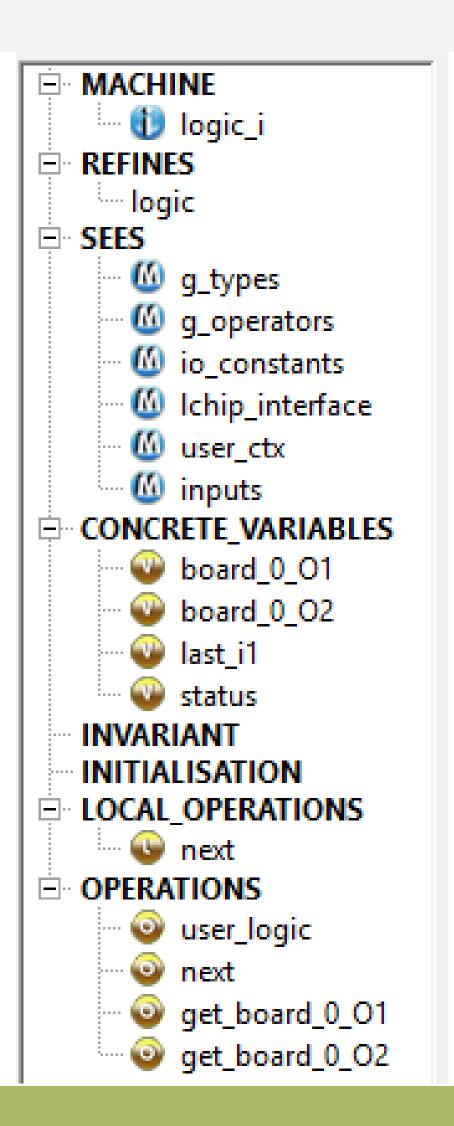
Implementation component





Implementation component





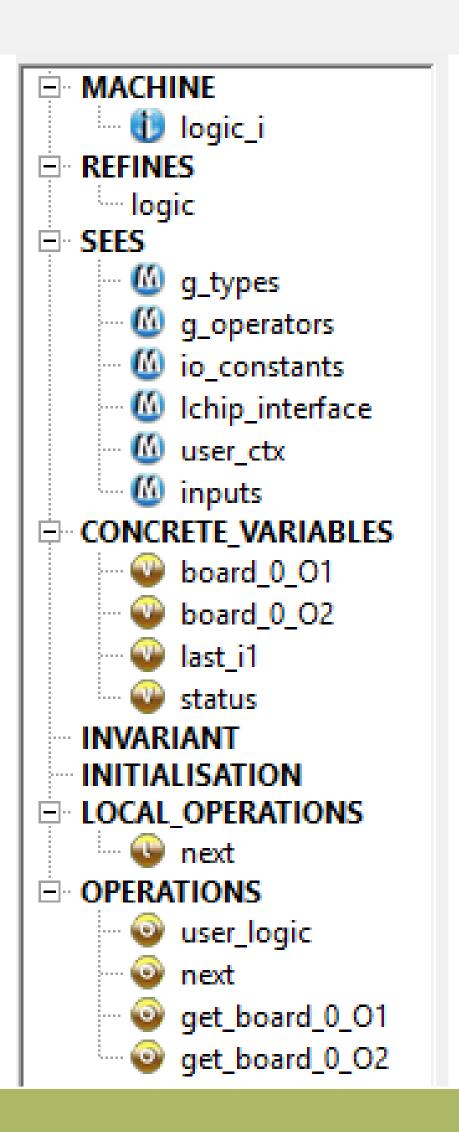
```
35
                user logic =
36-
                BEGIN
37 -
                     VAR il IN
38
                          i1 : (i1 : uint8 t);
39
40
41
                            If I1 has a raising edge then
42 -
                           change status to its next value.
43-
      1/1
44
                             Update the last value of 11
45
46
47
48
                     END
49
                END;
```

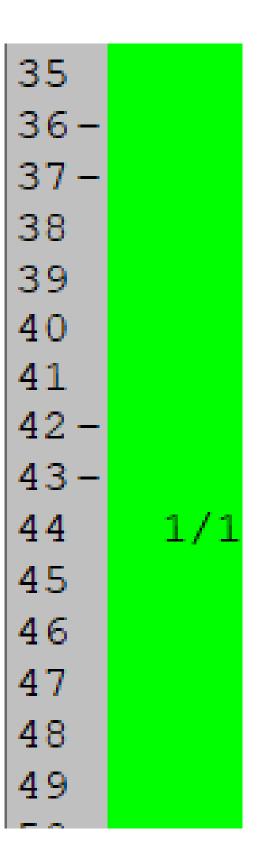


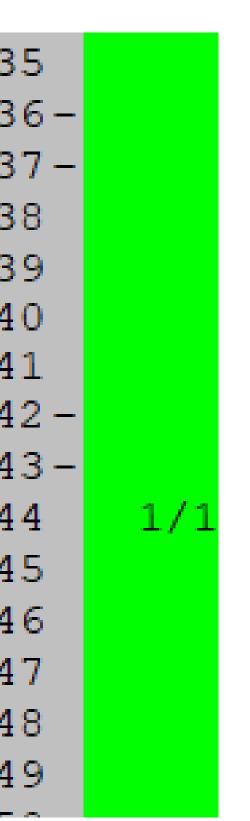
Implementation component

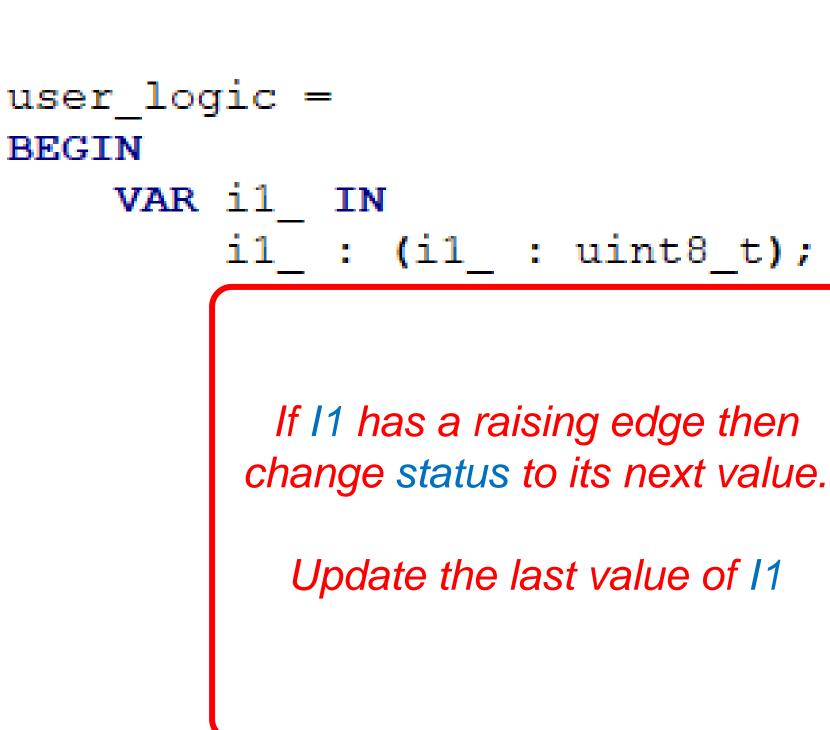
double-click to open











END

END;

HINT1

Operation call syntax: vv <-- ff(pp)

HINT2

The operation to read *I1* is in the *inputs* component

HINT3

To assign a variable vv: vv := value

CONSTRAINT

Only one condition per IF



Combinatorial Function: your turn

Implementation component

double-click to open



Edit logic and logic_i components

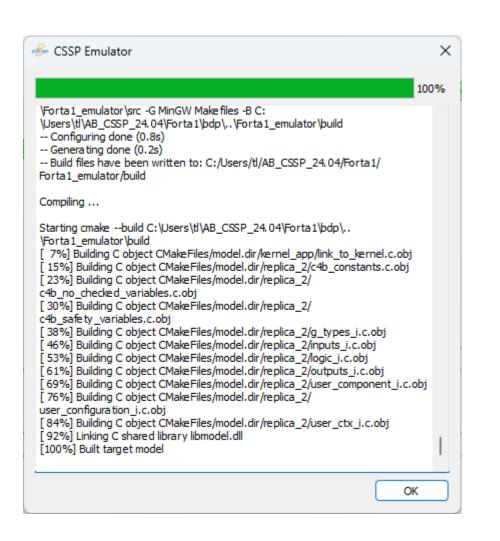
Ctrl-S to save and prove

Models should be « all green »

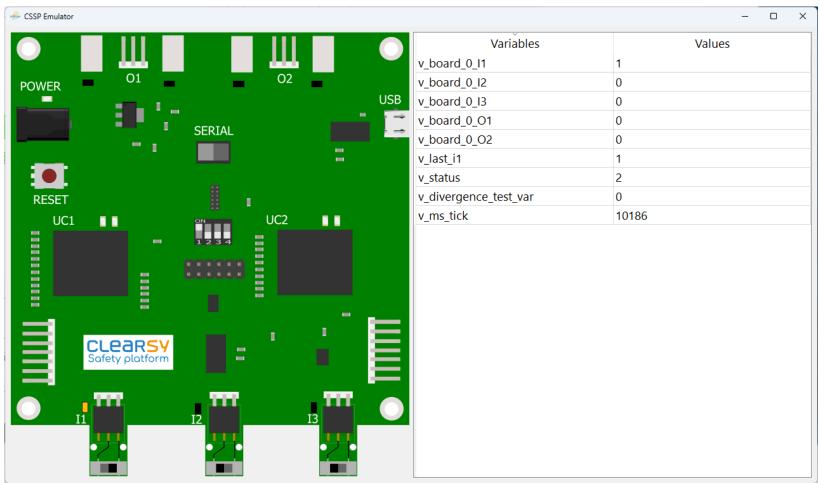
Ctrl-D to start the emulator
Reach « 100% built target model »
Press OK

```
MACHINE
               logic
               g operators,
               io constants,
               lchip_interface,
               user_ctx,
               inputs
          ABSTRACT VARIABLES
               board 0 01,
               board 0 02,
               status
          INVARIANT
               board_0_01 : uint8_t &
               board 0 02 : uint8 t &
18 -
19
20
21
22 -
23 -
24
25
26 -
27
                               logic
                         board 0 01 : uint8 t &
                        board 0 02 : uint8 t &
                        status : uint8 t
               END;
               po <-- get_board_0_01 =
                    po : uint8 t
36-
37
38
39
40
                    po := board_0_01
               po <-- get_board_0_02 =
41-
                    ~~ · · · · · · · + · · · +
```

```
logic_i.imp | logic.mch |
 1 -
2
3 -
4
5 -
6
7
              logic_i
          REFINES
              logic
              g_operators,
              io constants,
              lchip_interface,
              user_ctx,
11
              inputs
12
13
              // pragma SAFETY VARS
          CONCRETE VARIABLES
14-
              board_0_01,
              hoard 0 02
19-
20
21
22
23
24-
25
26
              board_0_02 := IO_OFF;
27
              last_i1 := IO_OFF;
              status := 0
          LOCAL OPERATIONS
              n <-- next(state) =
31 -
              PRE state: uint8 t & n : uint8 t THEN
32
                  n_ :: uint8_t - {state}
34 -
          OPERATIONS
              user logic =
37 -
38
39
40
41
                  VAR i1_, n_ IN
                      i1_ : (i1_ : uint8_t);
                      n_ : (n_ : uint8_t);
                       i1_ <-- get_board_0_I1;
```



Click on I1 several times and observe the behaviour of *status*





Combinatorial Function: your turn

Hard Work On Going!

Spoiler Alert: Solution on the next slide!

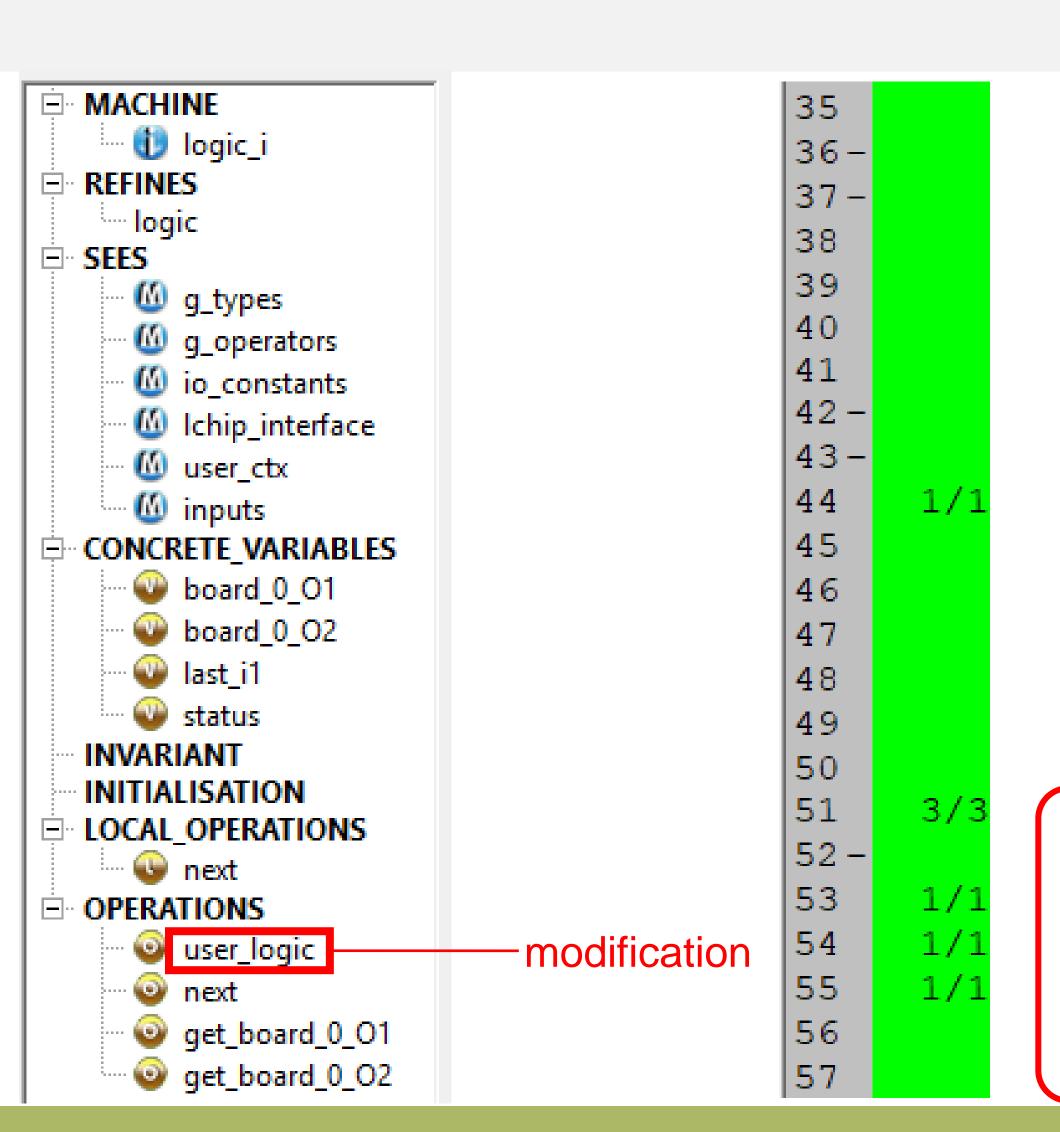


Combinatorial Function: the solution

Implementation component

double-click to open





```
user logic =
BEGIN
    VAR il IN
        i1_ : (i1_ : uint8_t);
                                  We call the predefined operation
                                  get_board_0_I1 to get the value of I1
        il <-- get board 0 I1;
                                  and store it in i1_
        IF last i1 = IO OFF THEN
            IF i1 = IO ON THEN
                 status <-- next(status)
            END
        END;
        last i1 := i1
    END
END;
n <-- next(state) =
BEGIN
    IF state = 0 THEN n := 1
    ELSIF state = 1 THEN n :=
    ELSE n := 0
    END
END;
```

We call *next* to get the new value of status



Developping a Synchronous Function

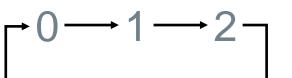




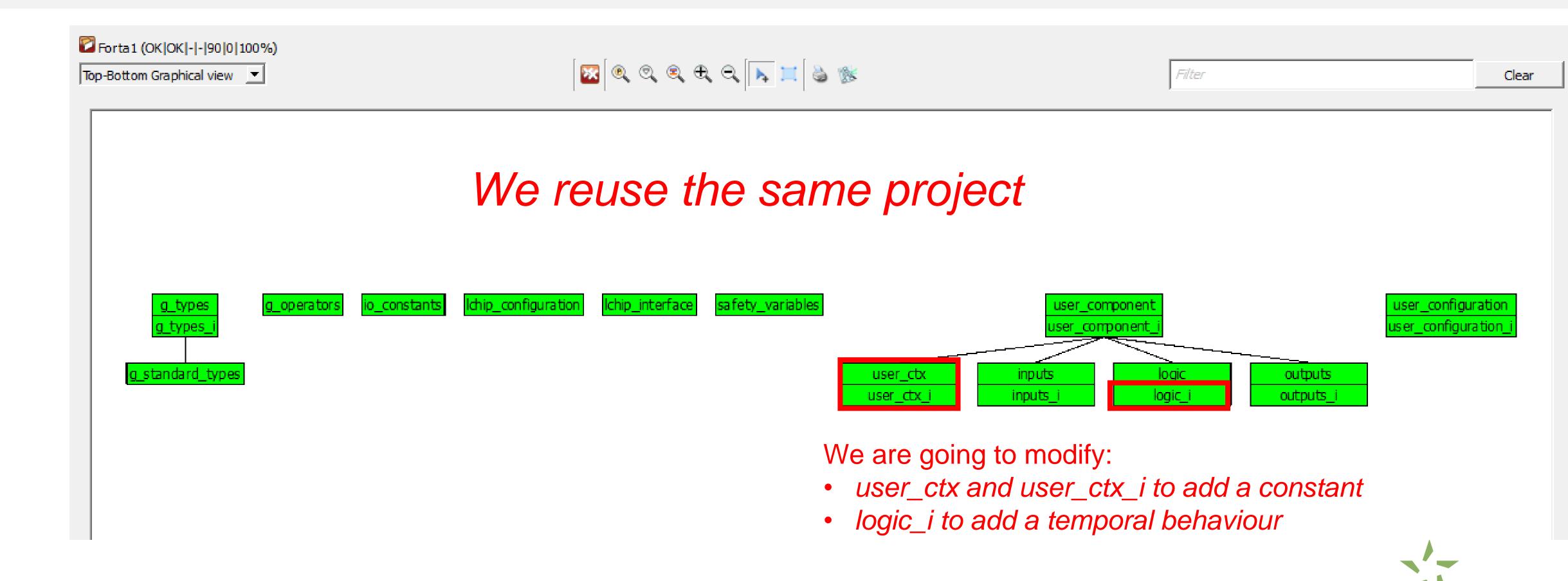
We need to specify a timer

- ►I1 belongs to {IO_OFF, IO_ON}
- status belongs to 0..2
- Every time I1 changes from 10_OFF to IO_ON, status changes such as
- If status = 2 during 2 s or more then sets O1 to IO_ON
- Otherwise sets O1 to IO_OFF

We need to command output O1

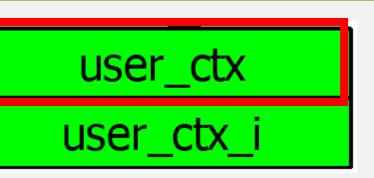


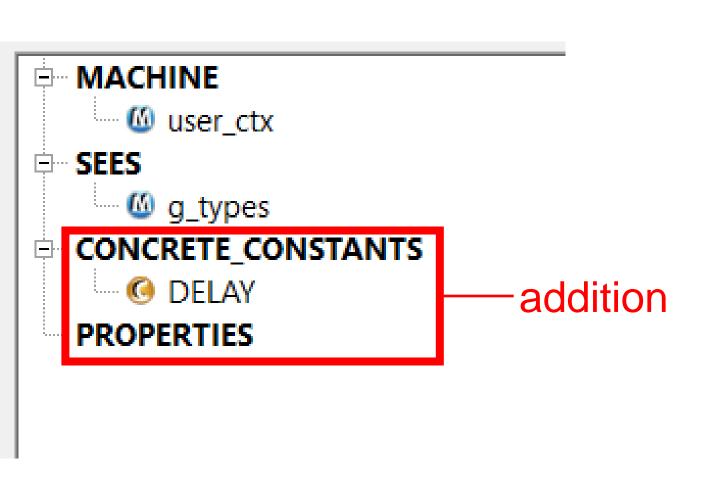


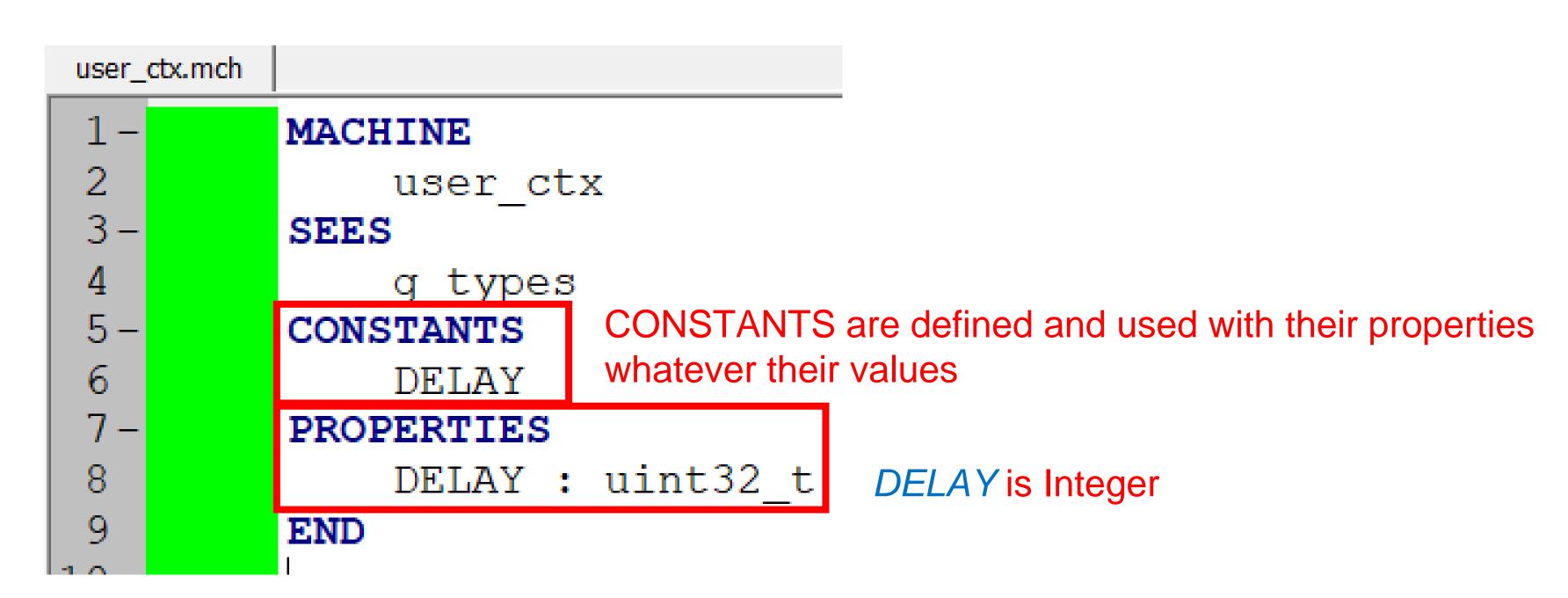


ROBOSTAR

Specification component



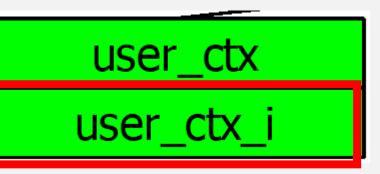


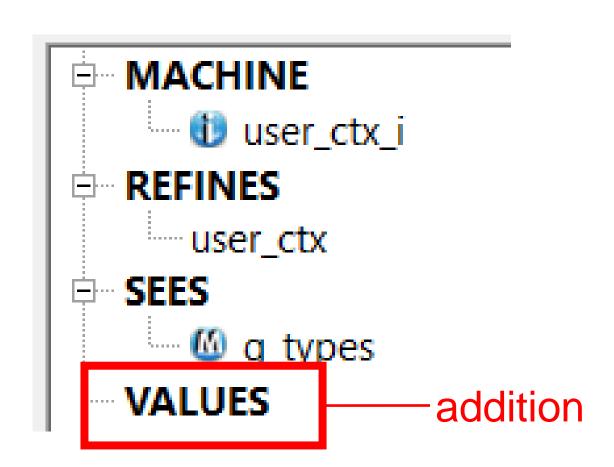


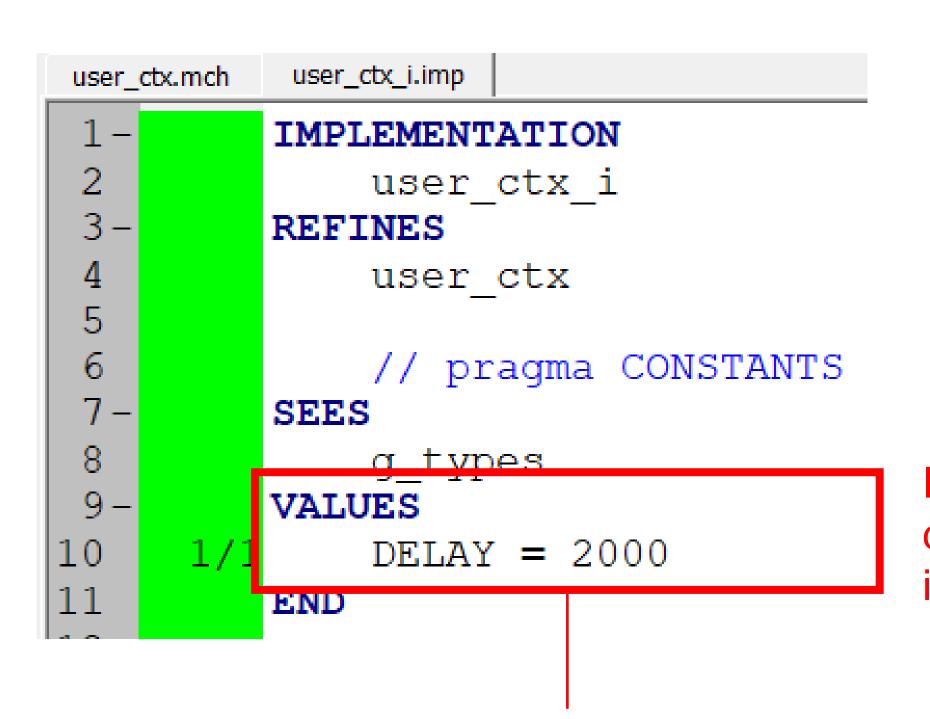


Implementation component

double-click to open







In

DELAY: uint32_t &

DELAY > 10 &

DELAY < 2

It is not possible to value

DELAY: it is a miracle

Each CONSTANT should be valued to demonstrate it is not a miracle i.e. 2000 belongs to uint32_t

Time returned by get_ms_tick OPERATION is in ms
Hence 2s == 2000 ms



Specification component

double-click to open



```
■ MACHINE
   └ logic
  SEES
    @ g_types
    @ g_operators
    io_constants
    Ichip_interface
    user_ctx
    inputs
                       No change!
  ABSTRACT_VARIABLES
    board_0_01
    board_0_02
    status
  INVARIANT
  INITIALISATION
user_logic
```

get_board_0_O1

get_board_0_02

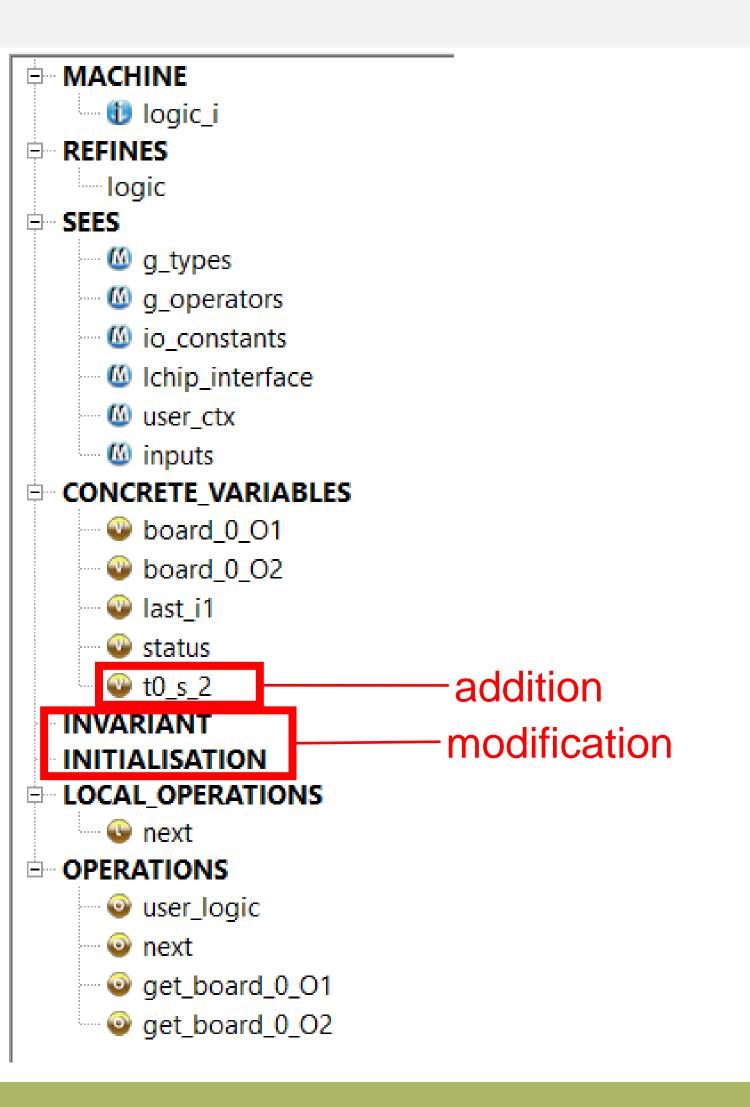
```
logic_i.imp
        logic.mch
         MACHINE
             logic
         SEES
             g_types,
             g operators,
             io constants,
             lchip_interface,
             user ctx,
             inputs
         ABSTRACT VARIABLES
             board_0_01,
             board 0 02,
             status
         INVARIANT
             board_0_01 : uint8_t &
             board_0_02 : uint8_t &
             status : uint8 t
         INITIALISATION
             board_0_01 :: uint8_t ||
             board 0 02 :: uint8 t ||
             status := 0
         OPERATIONS
             user logic = BEGIN
                 board 0 01,
                 board 0 02,
                  status: (
                      board 0 01 : uint8 t &
                      board_0_02 : uint8_t &
                      status : uint8 t
30
31
             END;
```



Implementation component

double-click to open





```
logic_i.imp
14-
         CONCRETE VARIABLES
15
             board 0 01,
16
             board 0 02,
             last il,
18
     4/4
             status,
             t0 s 2
19
     4/4
20-
         INVARIANT
21
             board 0 01 : uint8 t &
             board 0 02 : uint8 t &
23
             last i1 : uint8 t &
24
     4/4
             status : uint8 t &
25
             t0 s 2 : uint32 t
26-
         INITIALISATION
27
             board 0 O1 := IO OFF;
28
             board 0 02 := IO OFF;
             last i1 := IO OFF;
29
30
     1/1
             status := 0;
31
             t0 s 2 := 0
```

We need to store the last time *status* changed to the value 2

Timing information returned by the board is uint32_t

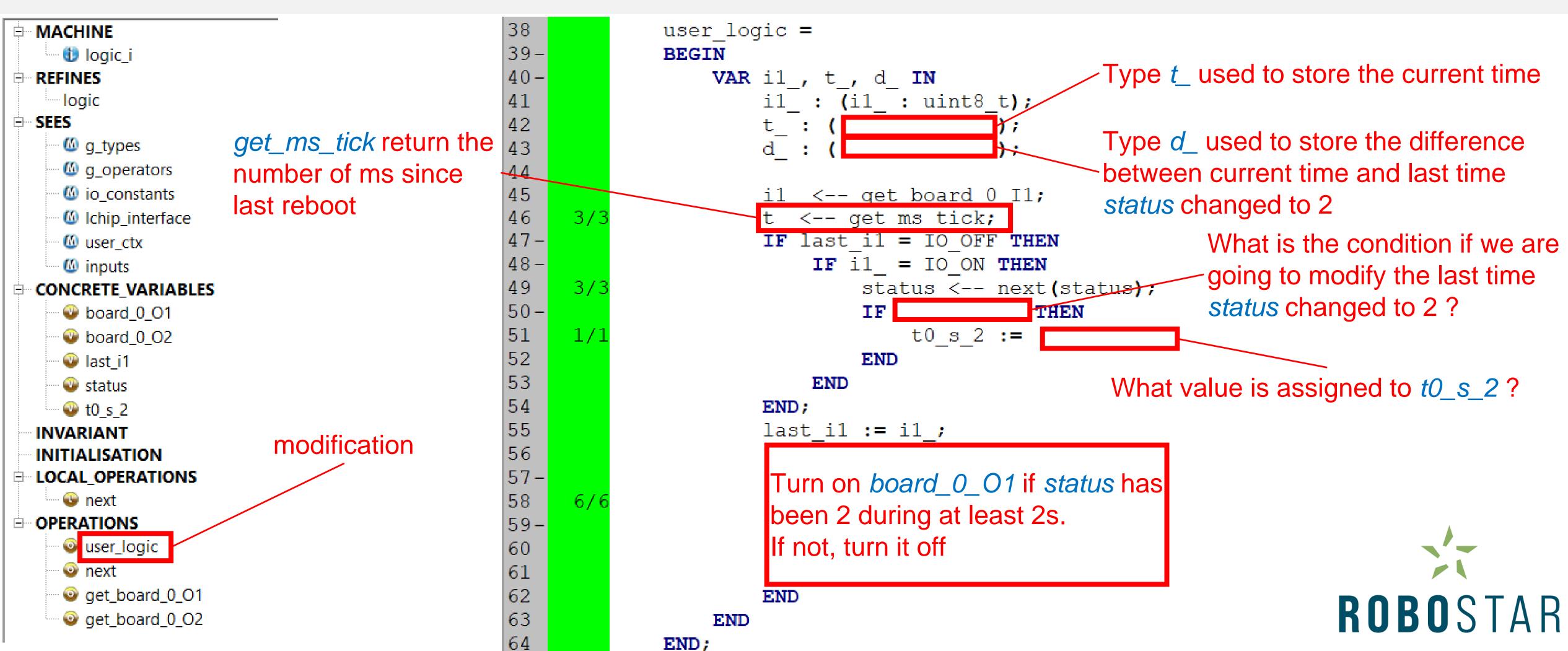
The initial value is 0, even if *status* is different from 2



ROBOSTAR

Implementation component

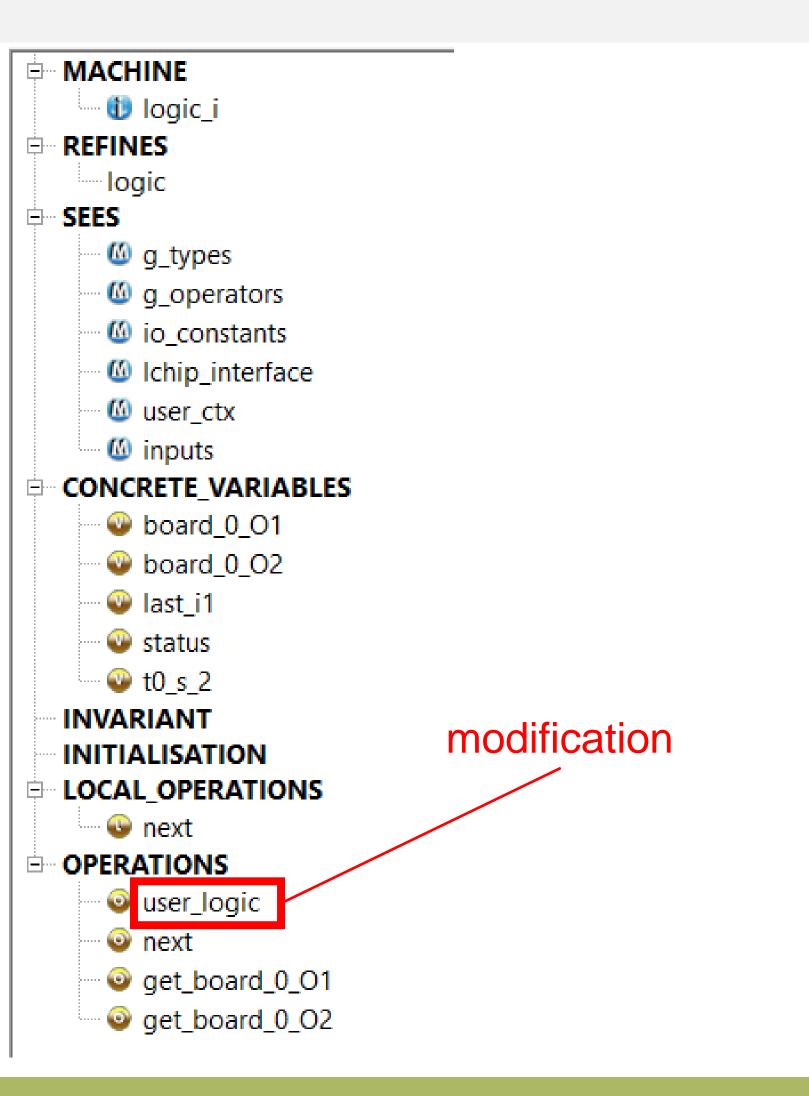




Implementation component

double-click to open





```
38
39-
40-
41
42
43
44
45
46
      3/3
47 –
48-
49
      3/3
50-
51
      1/1
52
53
54
55
56
57-
58
      6/6
59-
60
61
62
63
64
```

END;

```
user_logic =
BEGIN
    VAR i1 _, t_, d_ IN
        il_ : (il_ : uint8_t);
        il <-- get board 0 I1;
        t <-- get ms tick;
        IF last i1 = IO_OFF THEN
            IF i1 = IO ON THEN
                status <-- next(status);
                IF
                               THEN
                    t0_s_2 :=
                END
            END
        END;
        last i1 := i1 ;
         Turn on board_0_01 if status has
        been 2 during at least 2s.
        If not turn off 01
        END
    END
```

HINT1

To turn on an ouput OO

 $OO := IO_ON$

To turn it off

00 := IO_OFF

HINT2

Substraction of two uint32_t with *sub_uint32*

Ex: $vv := sub_uint32(aa,bb)$

CONSTRAINT1

Condition only with values, no calculation

CONSTRAINT2

Only < or <= , no > or >= for condition

ROBOSTAR

Synchronous / Timed Function: your turn

Implementation component

double-click to open



Edit logic and logic_i components

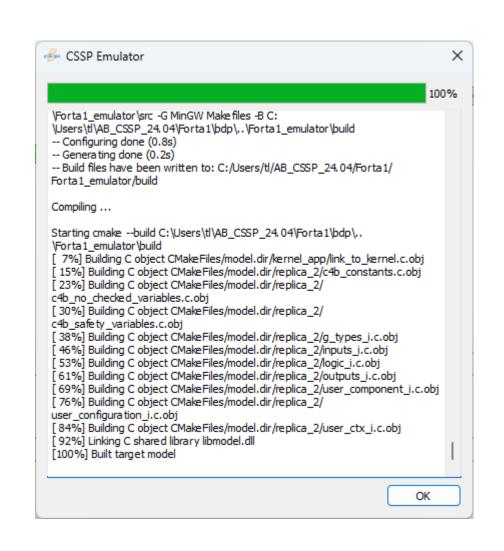
Ctrl-S to save and prove

Models should be « all green »

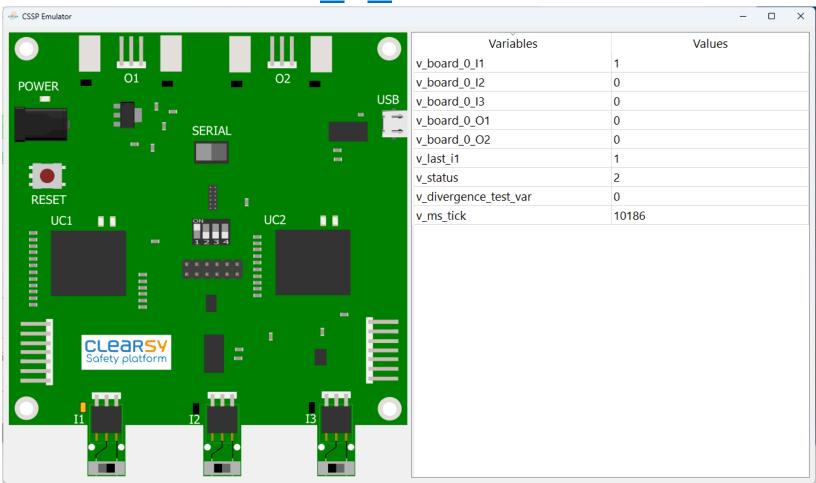
Ctrl-D to start the emulator
Reach « 100% built target model »
Press OK

```
MACHINE
               logic
               g operators,
               io constants,
               lchip interface,
               user_ctx,
               inputs
          ABSTRACT VARIABLES
               board 0 01,
               board 0 02,
               status
          INVARIANT
               board_0_01 : uint8_t &
               board 0 02 : uint8 t &
18 -
19
20
21
22 -
23 -
24
25
26 -
27
                               logic
                         board 0 01 : uint8 t &
                        board 0 02 : uint8 t &
                         status : uint8 t
               po <-- get_board_0_01 =
                   po : uint8 t
36-
37
38
39
40
                   po := board_0_01
               po <-- get_board_0_02 =
41-
                   ~~ · · · · · · · + · · · +
```

```
logic_i.imp | logic.mch |
 1 -
2
3 -
4
5 -
6
7
              logic_i
          REFINES
              logic
              g_operators,
              io constants,
              lchip_interface,
              user_ctx,
11
              inputs
12
13
              // pragma SAFETY VARS
          CONCRETE VARIABLES
14 -
              board_0_01,
              hoard 0 02
19-
20
21
22
23
24-
25
26
              board_0_02 := IO_OFF;
27
              last_i1 := IO_OFF;
              status := 0
          LOCAL OPERATIONS
              n <-- next(state) =
31 -
              PRE state: uint8 t & n : uint8 t THEN
32
                  n_ :: uint8_t - {state}
34 -
          OPERATIONS
              user logic =
37 -
38
39
40
41
                  VAR i1_, n_ IN
                      i1_ : (i1_ : uint8_t);
                      n : (n : uint8 t);
                       il <-- get board 0 I1;
```



Click on I1 several times and observe the behaviour of *status* and *board_0_01*





Synchronous / Timed Function: your turn

Hard Work On Going!

Spoiler Alert: Solution on the next slide!



Synchronous / Timed Function: the solution Implementation component double-click to open



```
user logic =
■ MACHINE
                                            39-
                                                           BEGIN
    · 👣 logic_i
                                            40-
                                                               VAR i1_, t_, d_ IN
□ REFINES
                                            41
    --logic
                                                                       : (i1 : uint8 t);
□ SEES
                                            42
                                                                       : (t_ : uint32_t);
                                                                                                 Both t and d are unit32_t
    ⋅ 🐠 g_types
                                            43
                                                                          (d : uint32 t);
                                            44
    Ø g_operators
                                            45
    io_constants
                                                                    il <-- get board 0 I1;
                                            46
                                                                    t <-- get ms_tick;
                                                  3/3
    Ichip_interface
                                            47 –
                                                                    IF last i1 = IO OFF THEN
    W user_ctx
                                            48-
                                                                        IF i1 = IO ON THEN
    · 🐠 inputs
                                            49
                                                  3/3
                                                                             status <-- next(status);
 CONCRETE_VARIABLES
                                            50-
                                                                             IF status = 2 THEN
                                                                                                      status has just changed to 2.
    board_0_01
                                            51
                                                  1/1
                                                                                 t0 s 2 := t
    board_0_02
                                                                                                      It is the right time to store the current
                                            52
                                                                             END
    last_i1
                                                                                                      time
                                            53
                                                                        END
    status
                                            54
                                                                    END;
    🐠 t0_s_2
                                                                    last i1 := i1 ;
 INVARIANT
                                            56
                                                                   board 0 01 := IO OFF;
  INITIALISATION
                                            57 –
                                                                    IF status = 2 THEN
 LOCAL_OPERATIONS
                                            58
    · 🕒 next
                                                  6/6
                                                                        d_{:=} sub_uint32(t_{,} t0_s_2);
                                                                                                           d_ is meaningful only if status is 2
                                            59.
                                                                        IF DELAY <= d_ THEN</pre>

    □ OPERATIONS

                                                                             board 0 01 := IO ON
     user_logic
                          modification
                                                                        END
                                            62
    get_board_0_01
                                                                    END
                                                                                                                          ROBOSTAR
                                            63
                                                               END
    get_board_0_02
                                            64
                                                           END;
```

Exercise to Go Further



- ► 11 {IO_OFF, IO_ON}
- ►I1 is noisy, changing value up to thousands times per second
- ►Only I1 constant during at least 100 ms have to be considered and are repeated on O1 and O2 has to be IO_ON
- ►If no constant behavior is observed, then O2 has to be IO_OFF in this case, the status of O1 is not considered (could be any value)
- Summary:
- O2 is IO_ON when I1 has been constant during at least 100 ms and O1 has the status of the observed I1
- O2 is IO_OFF when I1 has not been constant during the last 100 ms

ROBOSTAR

Next

From RoboSim To The CLEARSY Safety Platform

Paulo Bezerra

