CS 445: Computational Photography

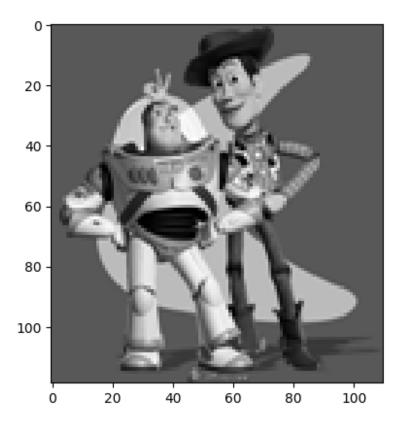
Programming Project #3: Gradient Domain Fusion

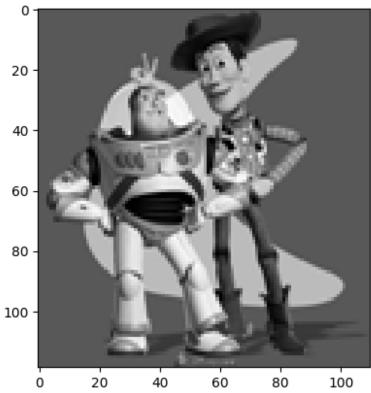
```
import cv2
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
import os
from random import random
import time
import scipy
import scipy.sparse.linalg
import utils
```

Part 1 Toy Problem (20 pts)

```
def toy_reconstruct(img):
    The implementation for gradient domain processing is not
complicated, but it is easy to make a mistake, so let's start with a
toy example. Reconstruct this image from its gradient values, plus one
pixel intensity. Denote the intensity of the source image at (x, y) as
s(x,y) and the value to solve for as v(x,y). For each pixel, then, we
have two objectives:
    1. minimize (v(x+1,y)-v(x,y) - (s(x+1,y)-s(x,y)))^2
    2. minimize (v(x,y+1)-v(x,y) - (s(x,y+1)-s(x,y)))^2
    Note that these could be solved while adding any constant value to
v. so we will add one more objective:
    3. minimize (v(1,1)-s(1,1))^2
    :param toy img: numpy.ndarray
    # Initialization
    H, W = imq.shape
    im2var = np.arange(H*W).reshape(H, W)
    total = 2*(H-1)*(W-1)+W+H-1
    A = np.zeros((total, H*W))
    b = np.zeros(total)
    e = 0
    # object 3
    A[e][im2var[0][0]] = 1
    b[e] = imq[0][0]
    e += 1
```

```
for x in range(W):
        for y in range(H):
            # object 1
            if x < W - 1:
                A[e][im2var[y][x+1]] = 1
                A[e][im2var[y][x]] = -1
                b[e] = img[y][x+1] - img[y][x]
                e += 1
            # object 2
            if y < H - 1:
                A[e][im2var[y+1][x]] = 1
                A[e][im2var[y][x]] = -1
                b[e] = img[y+1][x] - img[y][x]
                e += 1
    v = scipy.sparse.linalg.lsgr(A, b, atol=1e-14, btol=1e-14)[0]
    return v.reshape(H, W)
toy_img = cv2.cvtColor(cv2.imread('samples/toy_problem.png'),
cv2.COLOR_BGR2GRAY).astype('double') / 255.0
plt.imshow(toy img, cmap="gray")
plt.show()
im out = toy reconstruct(toy img)
plt.imshow(im_out, cmap="gray")
plt.show()
print("Max error is: ", np.sqrt(((im out - toy img)**2).max()))
```



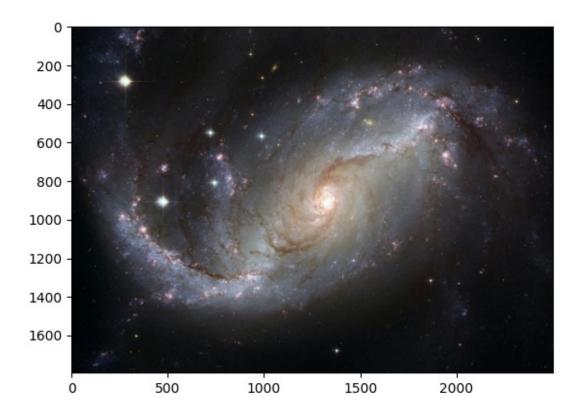


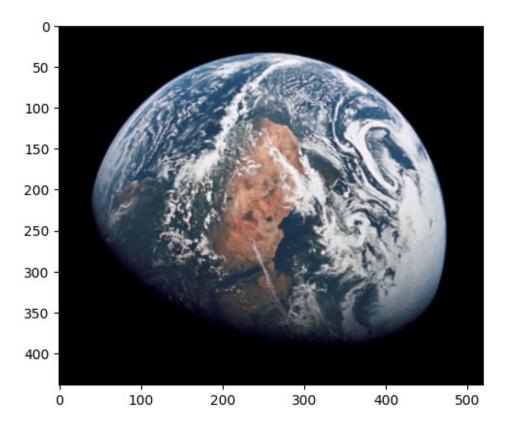
Max error is: 7.420508651989621e-12

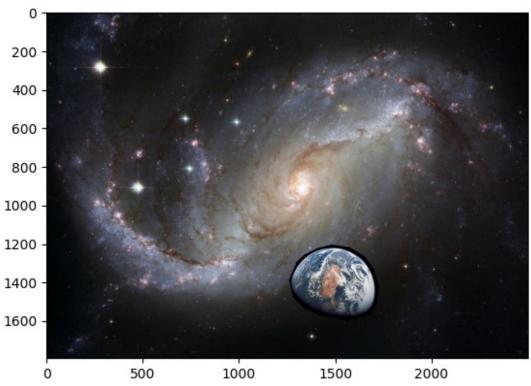
Part 2 Poisson Blending (50 pts)

Preparation

```
background img = cv2.cvtColor(cv2.imread('samples/universe.jpg'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
# background img = cv2.cvtColor(cv2.imread('samples/horizon.jpg'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
plt.figure()
plt.imshow(background img)
plt.show()
object img = cv2.cvtColor(cv2.imread('samples/earth.png'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
# object_img = cv2.cvtColor(cv2.imread('samples/dophin2.png'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
# object img = cv2.cvtColor(cv2.imread('samples/dophin.png'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
plt.imshow(object img)
plt.show()
use interface = False # set to true if you want to use the interface
to choose points (might not work in Colab)
if not use interface:
    # result 1
    xs = (174, 110, 67, 29, 50, 102, 189, 329, 450, 482, 495, 470,
424, 342, 247)
    vs = (35, 66, 106, 200, 290, 343, 383, 411, 383, 332, 232, 144,
78, 29, 15)
    bottom center = (1500, 1600) \# (x, y)
    # result 2
    \# xs = (62, 36, 8, 10, 41, 57, 84, 116, 175, 186, 210, 213, 222,
188, 160, 163, 150, 117, 89)
    \# ys = (7, 21, 30, 43, 56, 77, 81, 80, 99, 126, 130, 108, 77, 74,
58, 38, 19, 6, 4)
    \# bottom center = (150, 530) \# (x,y)
    # result 3
    \# xs = (60, 46, 27, 19, 4, 4, 25, 53, 60, 81, 97, 128, 130, 118,
113, 104, 101, 107, 127, 114, 124, 140, 136, 117, 89)
   \# ys = (8, 21, 47, 59, 72, 85, 97, 130, 151, 164, 176, 175, 166,
161, 143, 115, 98, 79, 78, 51, 38, 25, 9, 5, 2)
    \# bottom center = (700, 530) \# (x,v)
    object mask = utils.get mask(ys, xs, object img)
    object img, object mask = utils.crop object img(object img,
object mask)
    bg_ul = utils.upper_left_background_rc(object_mask, bottom_center)
    combined img = utils.get combined img(background_img, object_img,
object_mask, bg_ul)
```







Poisson Blending

```
def poisson blend(object img, object mask, bg img, bg ul):
    Returns a Poisson blended image with masked object img over the
bg img at position specified by bg ul.
    Can be implemented to operate on a single channel or multiple
channels
    :param object img: the image containing the foreground object
    :param object mask: the mask of the foreground object in
object img
    :param background_img: the background image
    :param bg ul: position (row, col) in background image
corresponding to (0,0) of object img
    # get all nonzeros indices
    rows, cols = np.nonzero(object mask)
    # construct im2var
    im2var = np.full(object mask.shape, -1, dtype=int)
    for i, (r, c) in enumerate(zip(rows, cols)):
        im2var[r][c] = i
    data, row ind, col ind = [], [], []
    b = np.zeros(4*len(rows))
    e = 0
    increments = [(-1,0), (1,0), (0,-1), (0,1)]
    for r, c in zip(rows, cols):
        for inc in increments:
            nr, nc = r+inc[0], c+inc[1]
            row ind.append(e)
            col ind.append(im2var[r][c])
            data.append(1)
            if object mask[nr][nc]:
                row ind.append(e)
                col ind.append(im2var[nr][nc])
                data.append(-1)
                b[e] = object_img[r][c] - object_img[nr][nc]
            else:
                tnr, tnc = bg ul[0]+nr-1, bg ul[1]+nc-1
                b[e] = bg img[tnr][tnc] + object img[r][c] -
object img[nr][nc]
            e += 1
    A = scipy.sparse.csr matrix((data, (row ind, col ind)), shape=(e,
len(rows)))
```

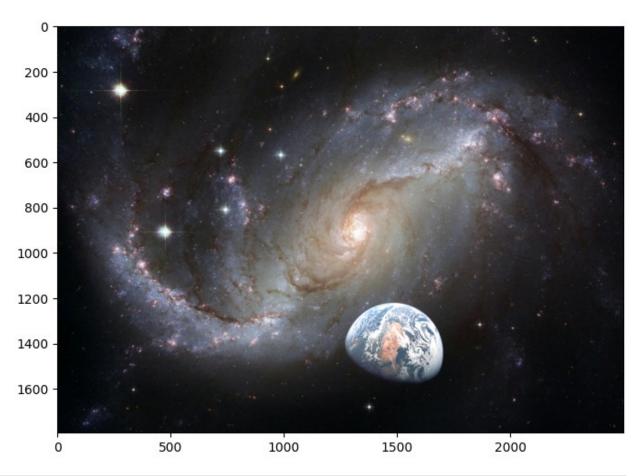
```
v = scipy.sparse.linalg.lsqr(A, b, atol=1e-14, btol=1e-14)[0]
v = np.clip(v, 0.0, 1.0)

# paste to background image
for i, (r, c) in enumerate(zip(rows, cols)):
    tr, tc = bg_ul[0]+r-1, bg_ul[1]+c-1
    bg_img[tr][tc] = v[i]

return bg_img

im_blend = np.zeros(background_img.shape)
for b in np.arange(3):
    im_blend[:,:,b] = poisson_blend(object_img[:,:,b], object_mask, background_img[:,:,b].copy(), bg_ul)

plt.figure(figsize=(8,8))
plt.imshow(im_blend)
<matplotlib.image.AxesImage at 0x762e2bb25d80>
```

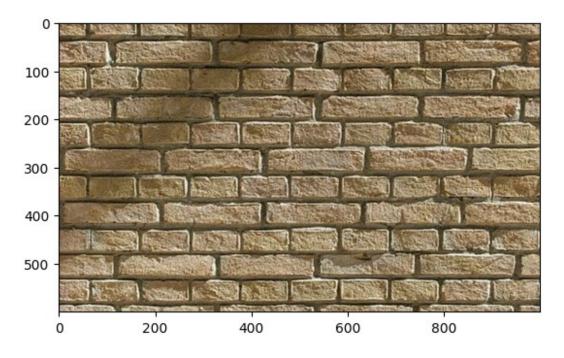


plt.imsave("./results/part2_result1.png", im_blend)

Part 3 Mixed Gradients (20 pts)

Preparation

```
background img = cv2.cvtColor(cv2.imread('samples/wall.jpg'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
plt.figure()
plt.imshow(background img)
plt.show()
object img = cv2.cvtColor(cv2.imread('samples/writing.png'),
cv2.COLOR BGR2RGB).astype('double') / 255.0
plt.imshow(object img)
plt.show()
use interface = False # set to true if you want to use the interface
to choose points (might not work in Colab)
if not use interface:
    # result 1
    xs = (135, 80, 42, 33, 16, 21, 35, 86, 129, 146, 196, 227, 331,
363, 405, 415, 436, 419, 371, 333, 230)
   ys = (7, 77, 113, 180, 313, 410, 454, 464, 407, 348, 346, 379,
374, 434, 401, 336, 260, 167, 136, 37, 11)
    bottom_center = (500, 530) \# (x,y)
    object mask = utils.get mask(ys, xs, object img)
    object_img, object_mask = utils.crop_object_img(object_img,
object mask)
    bg ul = utils.upper left background rc(object mask, bottom center)
    combined img = utils.get combined img(background img, object img,
object mask, bg ul)
    plt.imshow(combined img)
    plt.imsave("./results/part3 simple result.png", combined img)
```



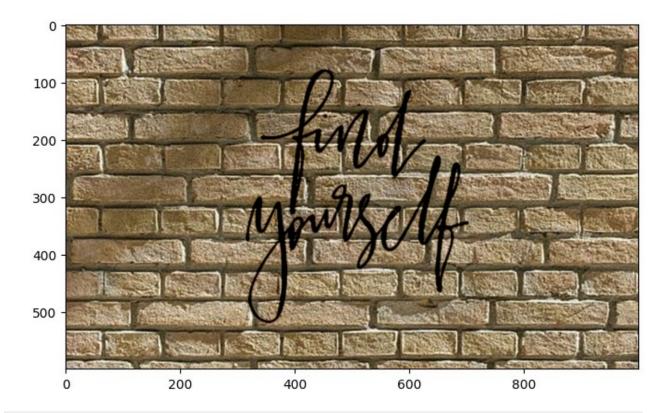




Mixed Gradients Blending

```
def mixed blend(object img, object mask, bg img, bg ul):
    Returns a mixed gradient blended image with masked object img over
the bg img at position specified by bg ul.
    Can be implemented to operate on a single channel or multiple
channels
    :param object img: the image containing the foreground object
    :param object mask: the mask of the foreground object in
object img
    :param background img: the background image
    :param bg_ul: position (row, col) in background image
corresponding to (0,0) of object img
    def get grad(r, c, nr, nc):
        s grad = object_img[r][c] - object_img[nr][nc]
        tr, tc = bg_ul[0]+r-1, bg_ul[1]+c-1
        tnr, tnc = \log ul[0]+nr-1, \log ul[1]+nc-1
        t_grad = bg_img[tr][tc] - bg_img[tnr][tnc]
        return s grad if abs(s grad) > abs(t grad) else t grad
    # get all nonzeros indices
    rows, cols = np.nonzero(object mask)
    # construct im2var
    im2var = np.full(object mask.shape, -1, dtype=int)
    for i, (r, c) in enumerate(zip(rows, cols)):
```

```
im2var[r][c] = i
    data, row ind, col ind = [], [], []
    b = np.zeros(4*len(rows))
    e = 0
    increments = [(-1,0), (1,0), (0,-1), (0,1)]
    for r, c in zip(rows, cols):
        for inc in increments:
            nr, nc = r+inc[0], c+inc[1]
            row ind.append(e)
            col ind.append(im2var[r][c])
            data.append(1)
            grad = get grad(r, c, nr, nc)
            if object mask[nr][nc]:
                row ind.append(e)
                col ind.append(im2var[nr][nc])
                data.append(-1)
                b[e] = qrad
            else:
                tnr, tnc = \log ul[0]+nr-1, \log ul[1]+nc-1
                b[e] = bg img[tnr][tnc] + grad
            e += 1
    A = scipy.sparse.csr matrix((data, (row ind, col ind)), shape=(e,
len(rows)))
    v = scipy.sparse.linalg.lsqr(A, b, atol=1e-14, btol=1e-14)[0]
    v = np.clip(v, 0.0, 1.0)
    # paste to background image
    for i, (r, c) in enumerate(zip(rows, cols)):
        tr, tc = bg ul[0]+r-1, bg ul[1]+c-1
        bg_img[tr][tc] = v[i]
    return bg img
im mix = np.zeros(background img.shape)
for b in np.arange(3):
    im mix[:,:,b] = mixed blend(object img[:,:,b], object mask,
background img[:,:,b].copy(), bg ul)
plt.figure(figsize=(8,8))
plt.imshow(im mix)
<matplotlib.image.AxesImage at 0x762e85ebeda0>
```



plt.imsave("./results/part3_result.png", im_mix)

Bells & Whistles (Extra Points)

Color2Gray (20 pts)

```
def color2gray(img):
    pass
```

Laplacian pyramid blending (20 pts)

```
def laplacian_blend(object_img, object_mask, bg_img, bg_ul):
    # feel free to change input parameters
    pass
```

More gradient domain processing (up to 20 pts)