

Appendix 7: North American Aerodynamic Derivative Notation

Table A7.1 Longitudinal Normalised Derivatives

Dimensionless Coefficient	Multiplier	Dimensional
$C_{x_u} = -(M_0 C_{D_M} + 2C_D)$	$\rho V_0 S / 2m$	X_u
$C_{x_u}^* = -(M_0 C_{D_M} + 2C_D) + M_0 C_{\tau_M} \cos \kappa$	$\rho V_0 S / 2m$	X_u^*
$C_{x_{\dot{w}}} = C_{x_{\dot{\alpha}}}$	$\rho S \bar{c} / 4m$	$X_{\dot{w}}$
$C_{x_w} = C_L - C_{D_{\alpha}}$	$\rho V_0 S / 2m$	X_w
C_{x_q}	$\rho V_0 S \bar{c} / 4m$	X_q
$C_{x_{\delta}}$	$\rho V_0^2 S / 2m$	X_{δ}
$C_{z_u} = -(M_0 C_{L_M} + 2C_L)$	$\rho V_0 S / 2m$	Z_u
$C_{z_u}^* = -(M_0 C_{L_M} + 2C_L) - M_0 C_{\tau_M} \sin \kappa$	$\rho V_0 S / 2m$	Z_u^*
$C_{z_{\dot{w}}} = C_{z_{\dot{\alpha}}}$	$\rho S \bar{c} / 4m$	$Z_{\dot{w}}$
$C_{z_w} = -(C_D + C_{L_{\alpha}})$	$\rho V_0 S / 2m$	Z_w
C_{z_q}	$\rho V_0 S \bar{c} / 4m$	Z_q
$C_{z_{\delta}}$	$\rho V_0^2 S / 2m$	Z_{δ}
$C_{m_u} = M_0 C_{m_M}$	$\rho V_0 S \bar{c} / 2I_y$	M_u
$C_{m_u}^* = M_0 C_{m_M} + M_0 \frac{z_{\tau}}{\bar{c}} C_{\tau_M} \cos \kappa$	$\rho V_0 S \bar{c} / 2I_y$	M_u^*
$C_{m_{\dot{w}}} = C_{m_{\dot{\alpha}}}$	$\rho S \bar{c}^2 / 4I_y$	$M_{\dot{w}}$
$C_{m_w} = C_{m_{\alpha}}$	$\rho V_0 S \bar{c} / 2I_y$	M_w
C_{m_q}	$\rho V_0 S \bar{c}^2 / 4I_y$	M_q
$C_{m_{\delta}}$	$\rho V_0^2 S \bar{c} / 2I_y$	M_{δ}

Notes: Thrust coefficient is defined as $C_{\tau} = \tau / \frac{1}{2} \rho V_0^2 S$. In the notational style, $C_{\tau_M} = \partial C_{\tau} / \partial M$; κ is the (upward) inclination of the thrust line with respect to the x axis; z_{τ} is the normal offset of the thrust line from the cg. It is assumed that x_{τ} , the axial offset of the thrust line from the cg, is negligibly small.

Table A7.2 Longitudinal Dimensionless Derivative Equivalents

American	British	American	British
C_{x_u}		$C_{z_{\alpha}}$	Z_w
$C_{x_u}^*$	X_u	C_{z_q}	$2Z_q$
$C_{x_{\dot{\alpha}}}$	$2X_{\dot{w}}$	$C_{z_{\delta}}$	$Z_{\eta \tau}$
$C_{x_{\alpha}}$	X_w	C_{m_u}	
C_{x_q}	$2X_q$	$C_{m_u}^*$	M_u

(Continued)

Table A7.2 (Continued)

American	British	American	British
$C_{x_{\delta}}$	$X_{\eta^* \tau}$	$C_{m_{\dot{\alpha}}}$	$2M_{\dot{w}}$
C_{z_u}		$C_{m_{\dot{\alpha}}}$	$M_{\dot{w}}$
$C_{z_u}^*$	Z_u	C_{m_q}	$2M_q$
$C_{z_{\dot{\alpha}}}$	$2Z_{\dot{w}}$	$C_{m_{\delta}}$	$M_{\eta^* \tau}$

Table A7.3 Lateral-Directional Normalised Derivatives

Dimensionless Coefficient	Multiplier	Dimensional
C_{y_v}	$\rho V_0 S / 2m$	Y_v
$C_{y_{\beta}}$	$\rho V_0^2 S / 2m$	Y_{β}
C_{y_p}	$\rho V_0 S b / 4m$	Y_p
C_{y_r}	$\rho V_0 S b / 4m$	Y_r
$C_{y_{\delta}}$	$\rho V_0^2 S / 2m$	Y_{δ}
C_{l_v}	$\rho V_0 S b / 2I_x$	L_v
$C_{l_{\beta}}$	$\rho V_0^2 S b / 2I_x$	L_{β}
C_{l_p}	$\rho V_0 S b^2 / 4I_x$	L_p
C_{l_r}	$\rho V_0 S b^2 / 4I_x$	L_r
$C_{l_{\delta}}$	$\rho V_0^2 S b / 2I_x$	L_{δ}
C_{n_v}	$\rho V_0 S b / 2I_z$	N_v
$C_{n_{\beta}}$	$\rho V_0^2 S b / 2I_z$	N_{β}
C_{n_p}	$\rho V_0 S b^2 / 4I_z$	N_p
C_{n_r}	$\rho V_0 S b^2 / 4I_z$	N_r
$C_{n_{\delta}}$	$\rho V_0^2 S b / 2I_z$	N_{δ}

Table A7.4 Lateral-Directional Dimensionless Derivative Equivalents

American	British	American	British
C_{y_v}	Y_v	C_{l_r}	$2L_r$
$C_{y_{\beta}}$		$C_{l_{\delta}}$	$L_{\xi, \zeta}$
C_{y_p}	$2Y_p$	C_{n_v}	N_v
C_{y_r}	$2Y_r$	$C_{n_{\beta}}$	
$C_{y_{\delta}}$	$Y_{\xi, \zeta}$	C_{n_p}	$2N_p$
C_{l_v}	L_v	C_{n_r}	$2N_r$
$C_{l_{\beta}}$		$C_{n_{\delta}}$	$N_{\xi, \zeta}$
C_{l_p}	$2L_p$		