A_Star(start, goal):

1. Open_Set = {start}

2. Came_From = empty map

3. For each node n:

   g(n) = ∞
   f(n) = ∞

4. g(start) = 0

5. f(start) = g(start) + h(start)

6. While Open_Set is not empty:

   a. Current = node in Open_Set with lowest f
   b. If Current == goal:
      Return Reconstruct_Path(Came_From, C
   c. Remove Current from Open_Set
   d. for each of Current:
      i. Tentative_g = g(Current) + d(Current, neighbo
      ii. if Tentative_g < g(neighbor):
         Came_From[neighbor] = Current
         g(neighbor) = Tentative_g
         f(neighbor) = g(neighbor) + h(neighbor)
         If neighbor not in Open_Set:
            Add neighbor to Open_Set

7. Return failure (no path found)

Tabu Search

1. Choose an initial solution S

2. Set Best_Solution = S

3. Initial Tabu_List as empty

4. Repeat until Stopping Condition met.

   a. Gen Neighborhood(S)
   b. From neighbors, select best candidate S' not in List
   c. if Cost(S') < Cost(Best_Solution):
      Best_Solution = S'

   d. Update Tabu_List with move from S to S'

   e. If Tabu_List exceeds sizeLimit:

      RM oldest entry

   f. Set S = S'

5. Return Best_Solution

Q1: what is the difference between bagging and boosting?

Answer:

Bagging: Reduces variance by training models in parallel (eg, Random forest)

Boosting: Reduces bias by training models sequentially, each focusing on correcting the errors of the previous one. (eg XGBoost).

Q2: Explain the concept of overfitting and how to prevent it.

Answer:

overfitting: occurs when a model learns the traing data too well, including noise and outliers, and fails to generlize to new data.
prevention methods include cross validation, prunning, dropout, regularization, and more data collecting