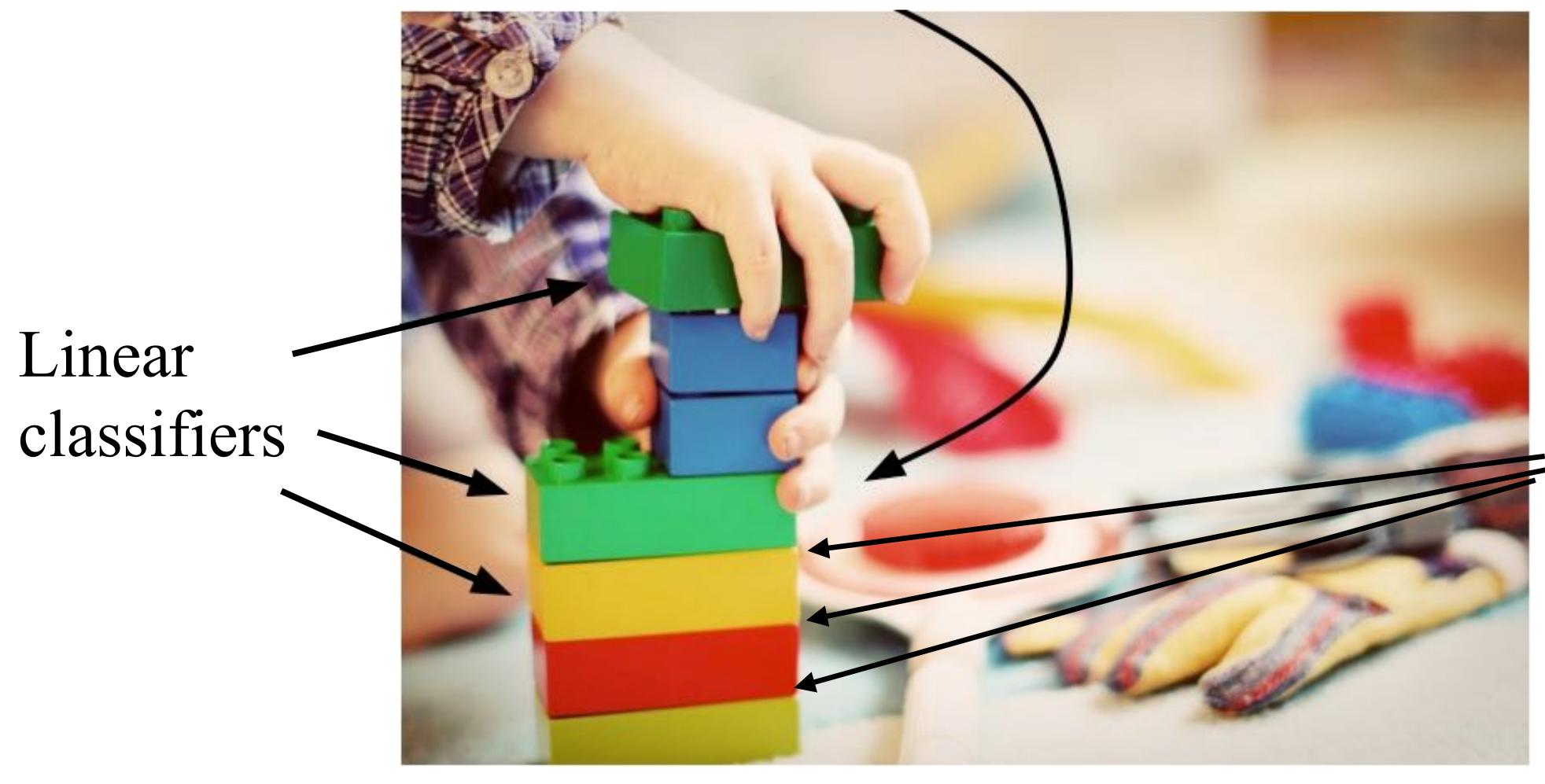
Deep Learning

Lecture 6

Neural Network



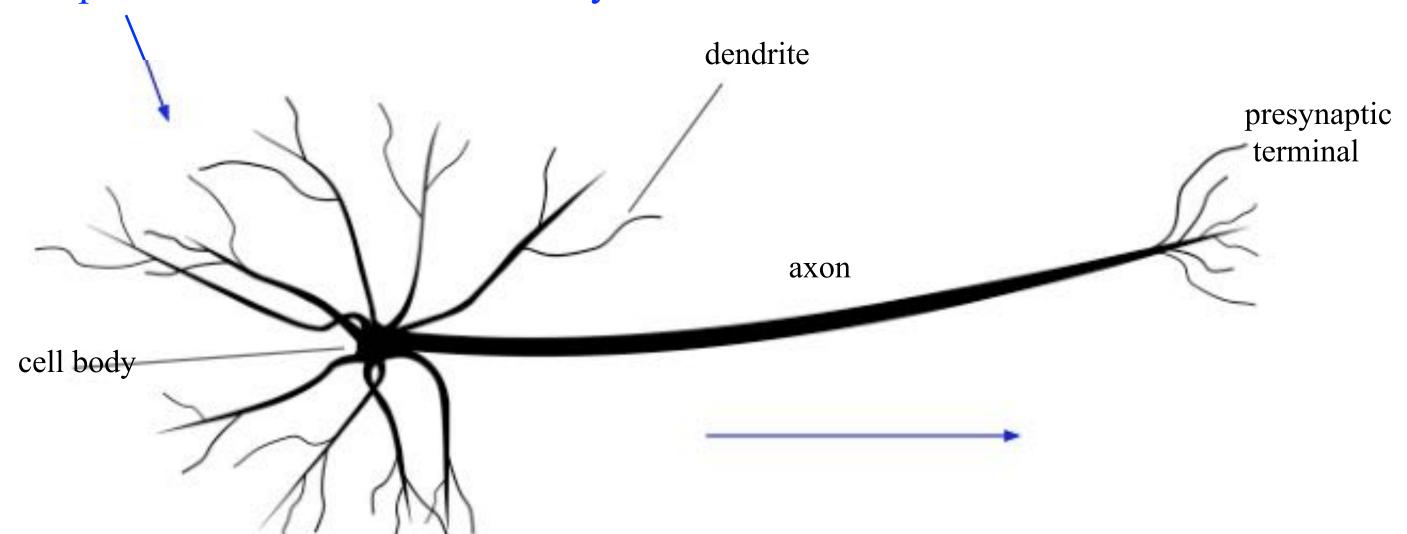
Activation Functions

This image is CC0 1.0 public domain

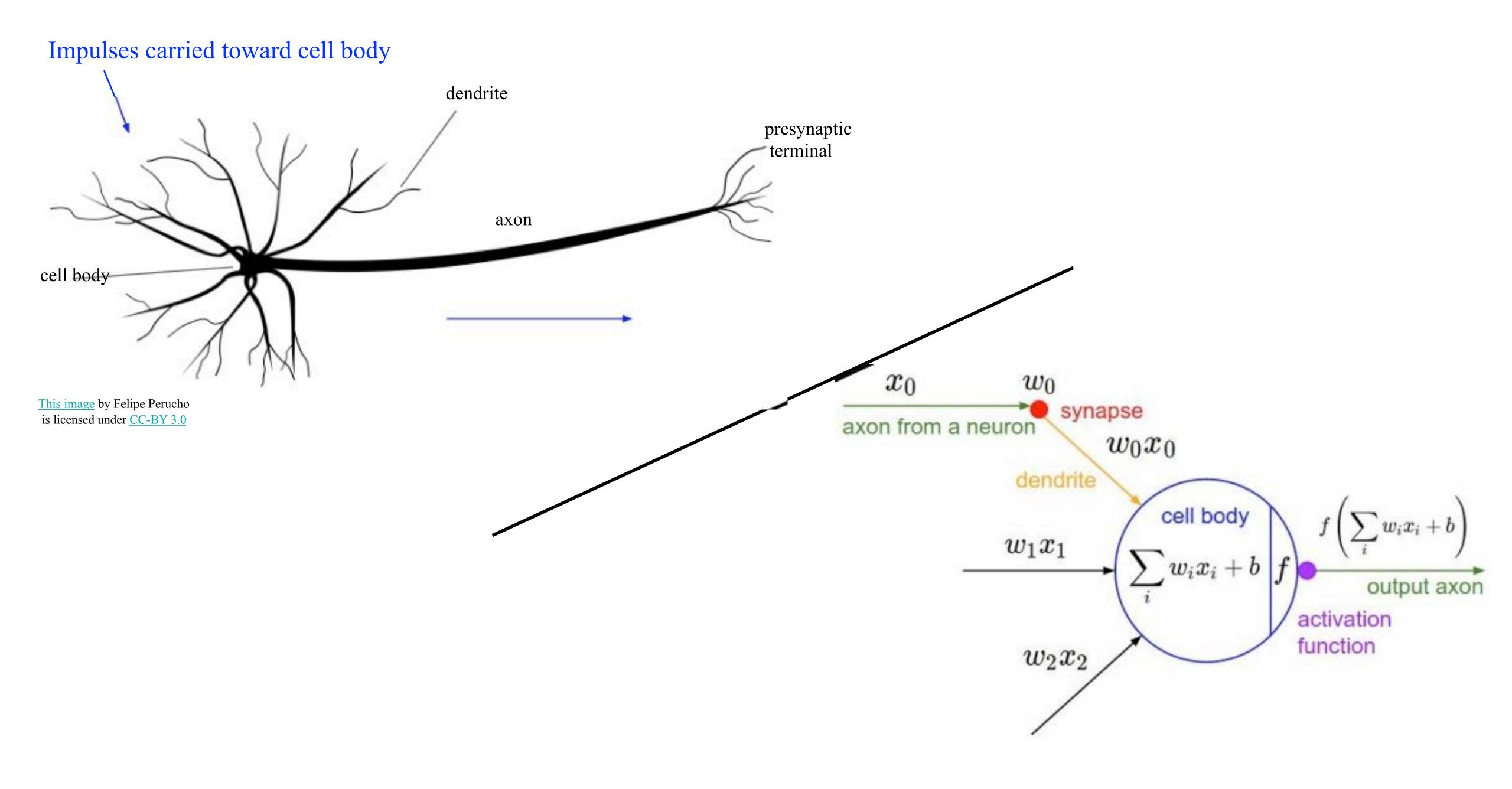


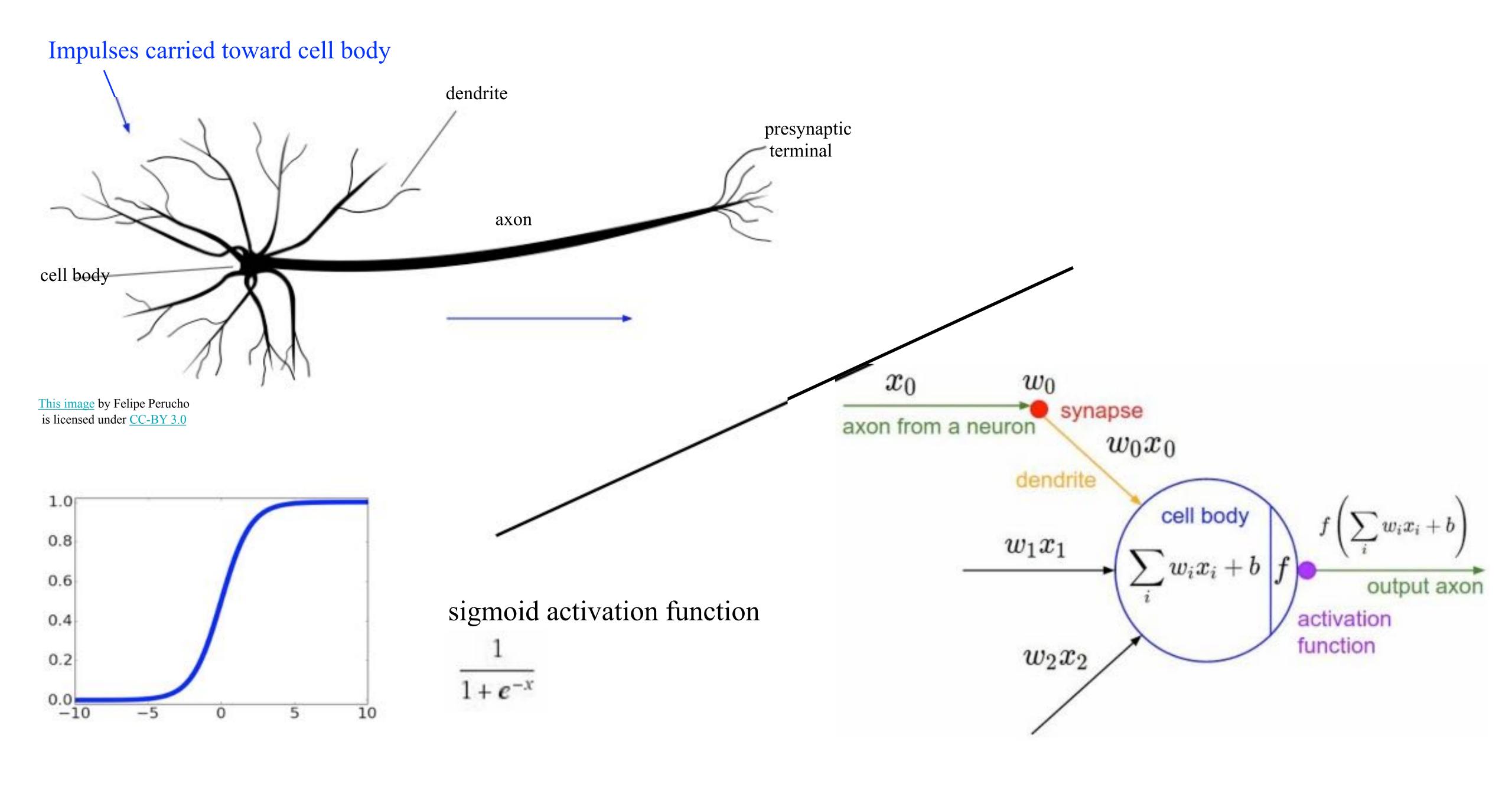
This image by Fotis Bobolas is licensed under CC-BY 2.0

Impulses carried toward cell body



This image by Felipe Perucho is licensed under CC-BY 3.0





Be very careful with your brain analogies!

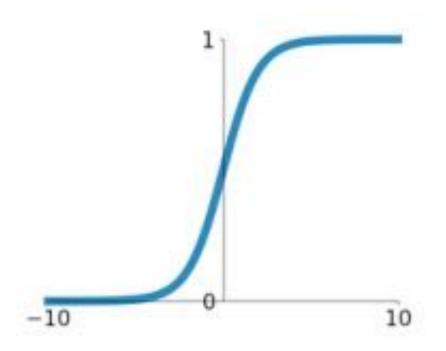
Biological Neurons:

- Many different types
- Dendrites can perform complex non-linear computations
- Synapses are not a single weight but a complex non-linear dynamical system
- Rate code may not be adequate

[Dendritic Computation. London and Hausser]

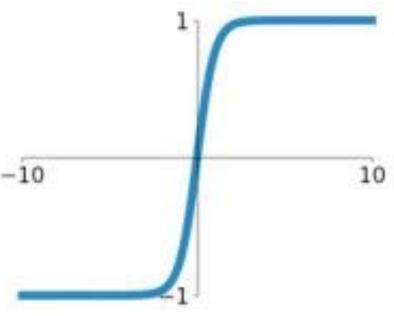
Sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



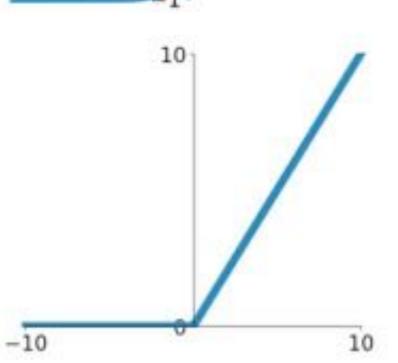
tanh

tanh(x)



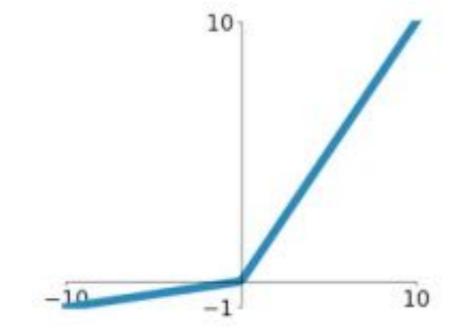
ReLU

 $\max(0,x)$



Leaky ReLU

 $\max(0.1x, x)$

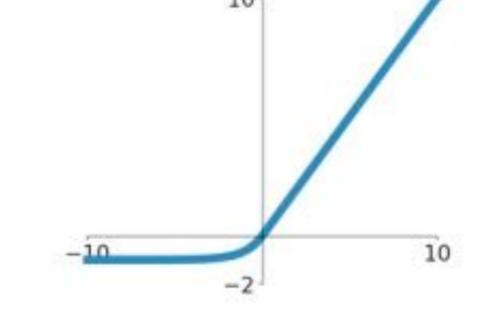


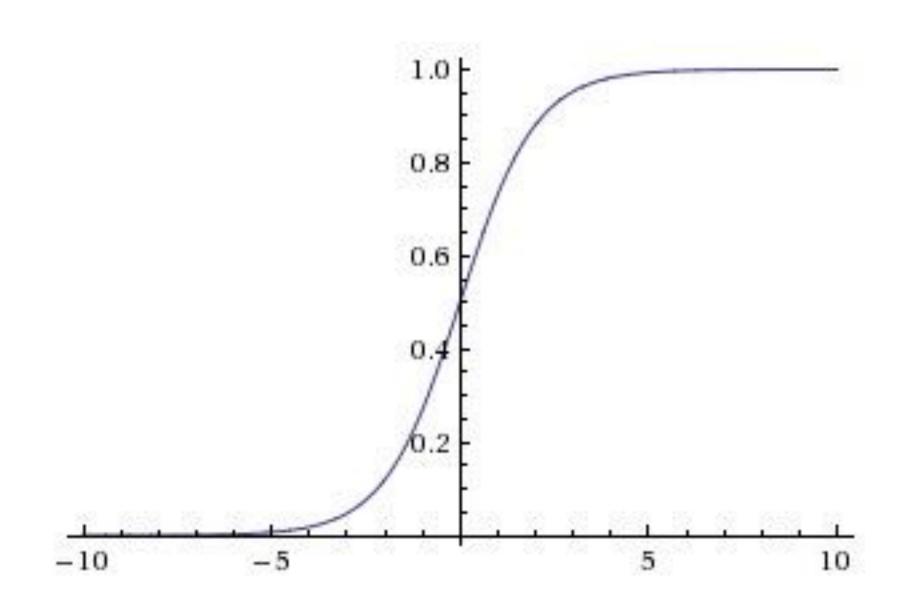
Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

ELU

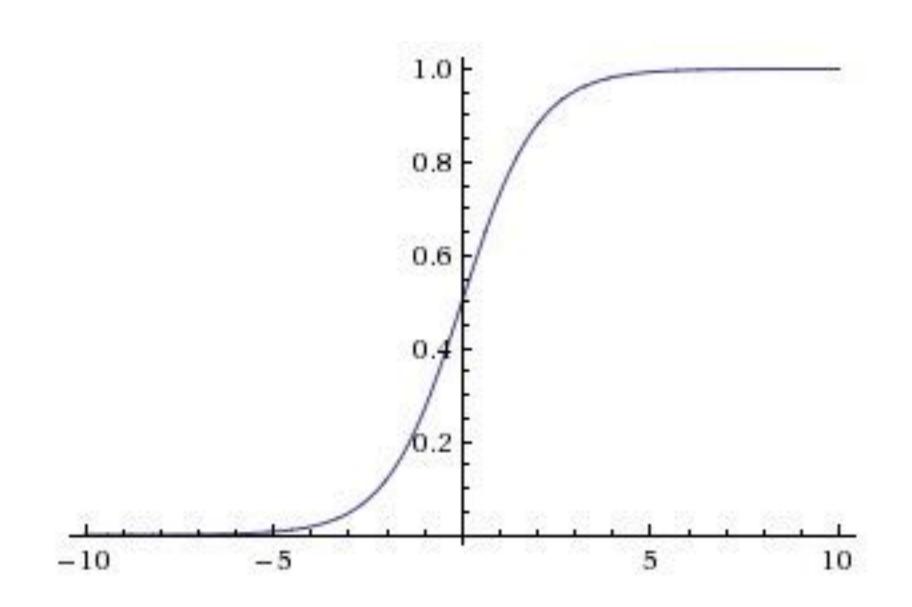
$$\begin{cases} x & x \ge 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$





$$\sigma(x) = 1/(1 + e^{-x})$$

- Squashes numbers to range [0,1]
- Historically popular since they have nice interpretation as a saturating "firing rate" of a neuron



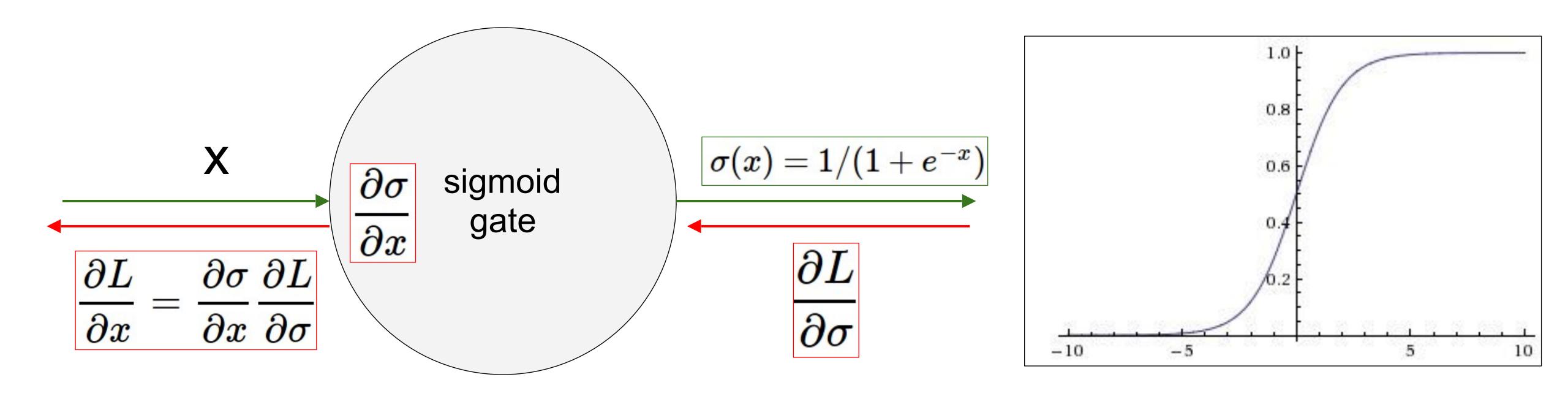
Sigmoid

$$\sigma(x) = 1/(1 + e^{-x})$$

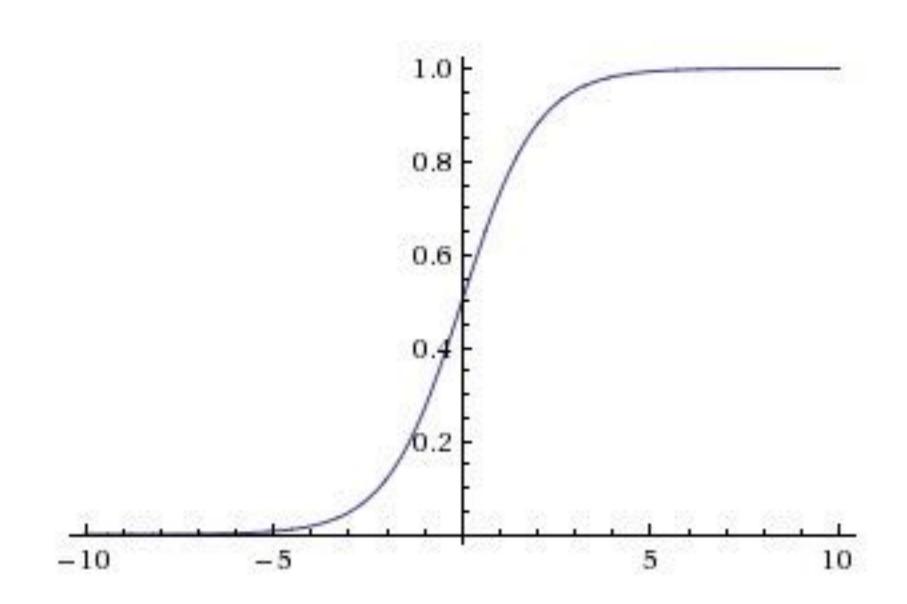
- Squashes numbers to range [0,1]
- Historically popular since they have nice interpretation as a saturating "firing rate" of a neuron

3 problems:

1. Saturated neurons "kill" the gradients



What happens when x = -10? What happens when x = 0? What happens when x = 10?



Sigmoid

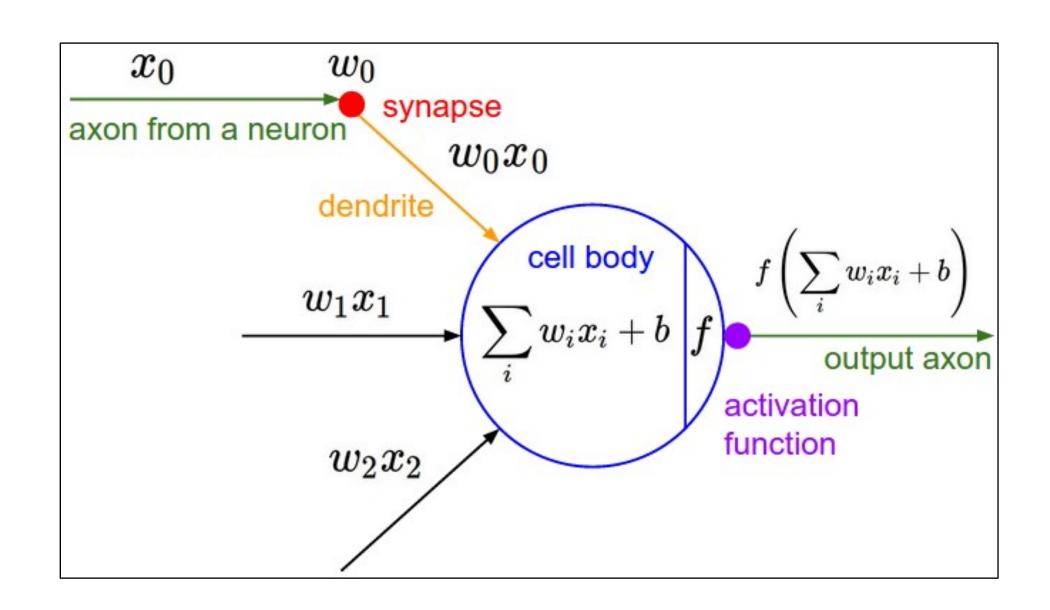
$$\sigma(x) = 1/(1 + e^{-x})$$

- Squashes numbers to range [0,1]
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3 problems:

- 1. Saturated neurons "kill" the gradients
- 2. Sigmoid outputs are not zerocentered

Consider what happens when the input to a neuron (x) is always positive:



$$f\left(\sum_{\pmb{i}} w_{\pmb{i}} x_{\pmb{i}} + b\right)$$

What can we say about the gradients on w?

Consider what happens when the input to a neuron is always positive...

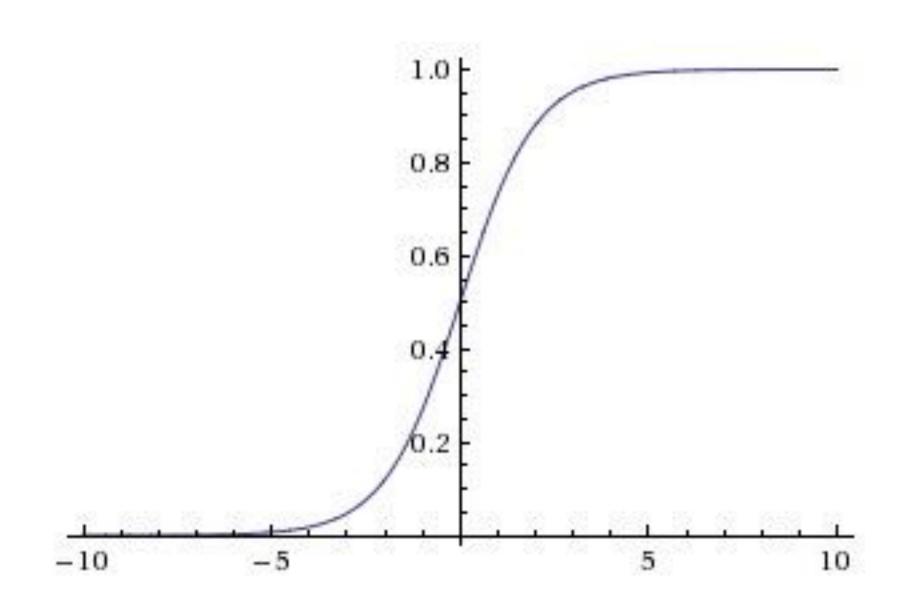
$$f\left(\sum_{i}w_{i}x_{i}+b\right)$$

on w?

data!)

allowed gradient update directions zig zag path allowed gradient update directions hypothetical optimal w vector

What can we say about the gradients on w? Always all positive or all negative :((this is also why you want zero-mean data!)



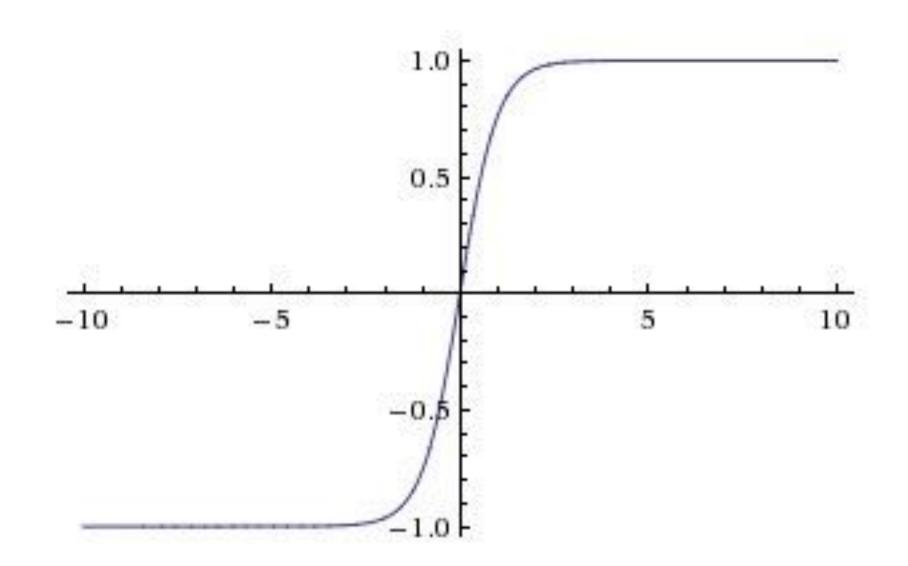
Sigmoid

$$\sigma(x) = 1/(1 + e^{-x})$$

- Squashes numbers to range [0,1]
- Historically popular since they have nice interpretation as a saturating "firing rate" of a neuron

3 problems:

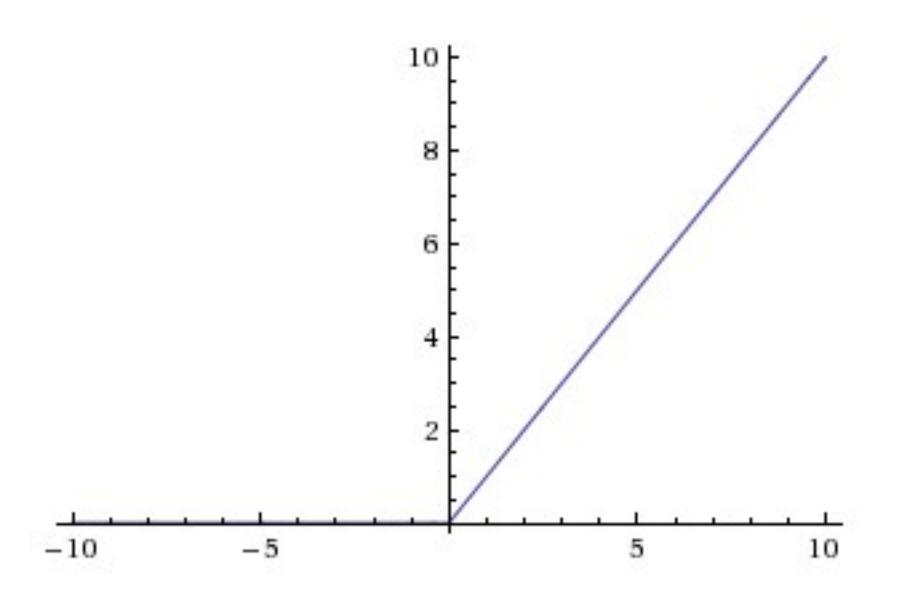
- 1. Saturated neurons "kill" the gradients
- 2. Sigmoid outputs are not zerocentered
- 3. exp() is a bit compute expensive



tanh(x)

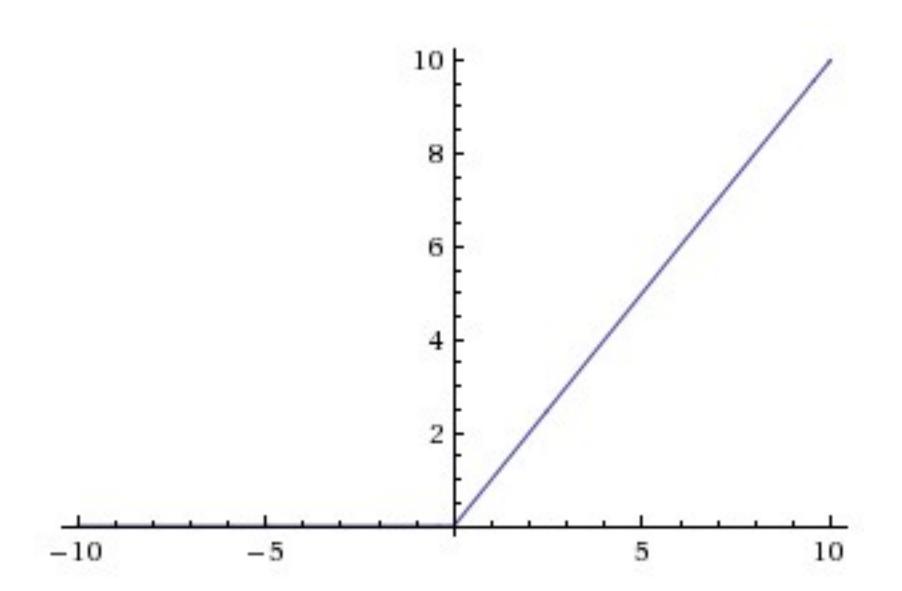
- Squashes numbers to range [-1,1]
- zero centered (nice)
- still kills gradients when saturated :(

[LeCun et al., 1991]



ReLU (Rectified Linear Unit)

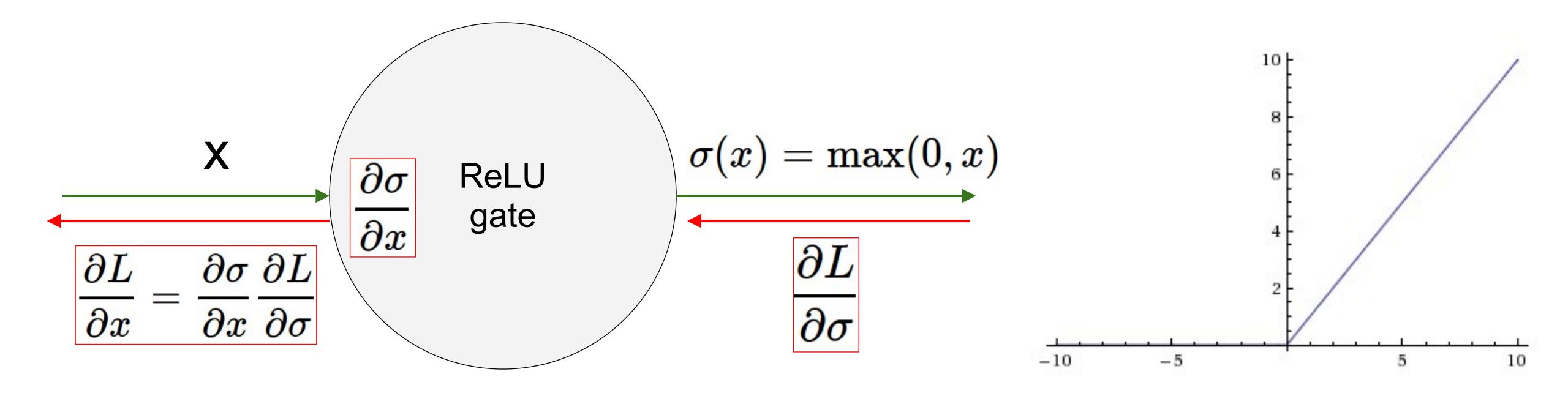
- Computes f(x) = max(0,x)
- Does not saturate (in +region)
- Very computationally efficient
- Converges much faster than sigmoid/tanh in practice (e.g. 6x)



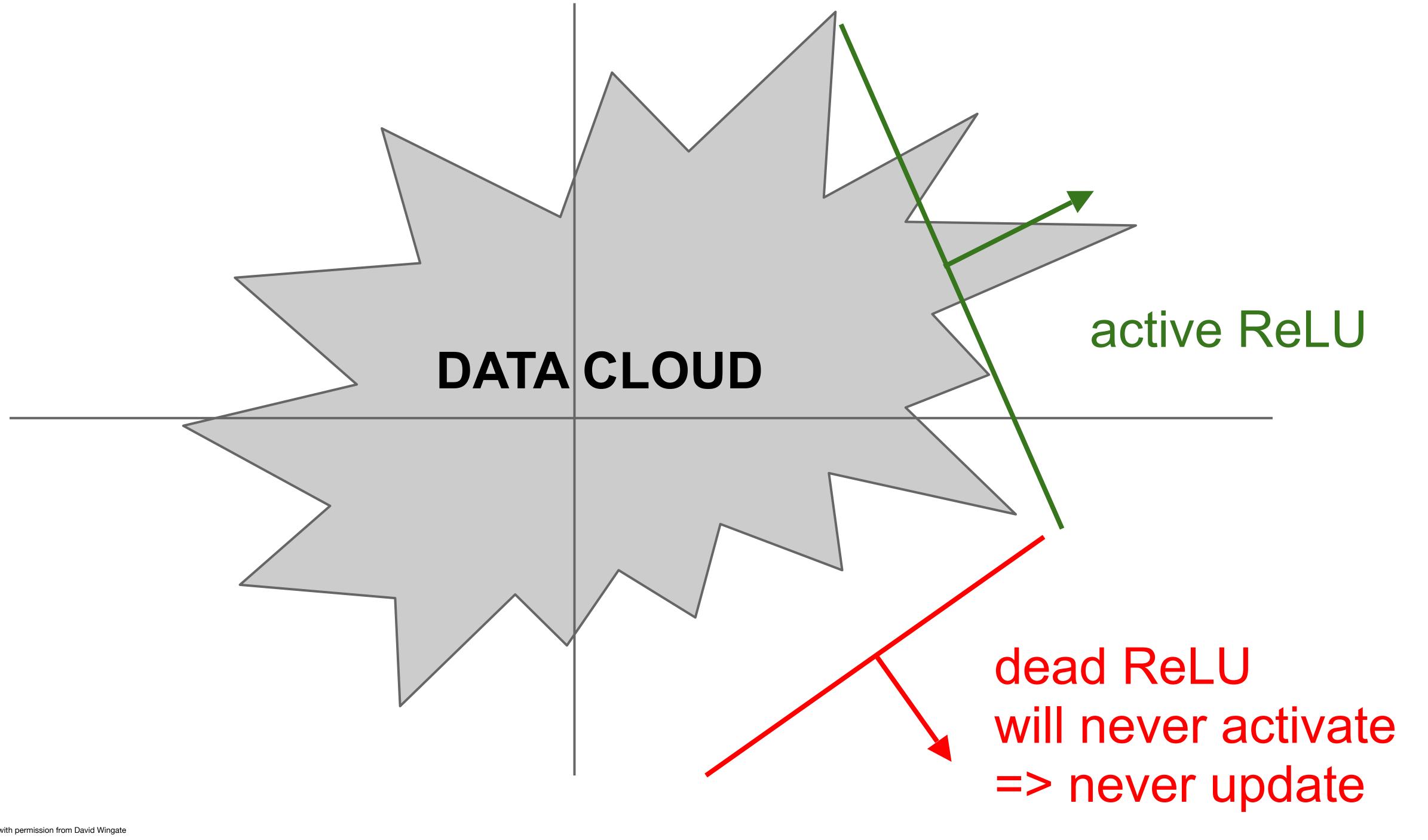
ReLU (Rectified Linear Unit)

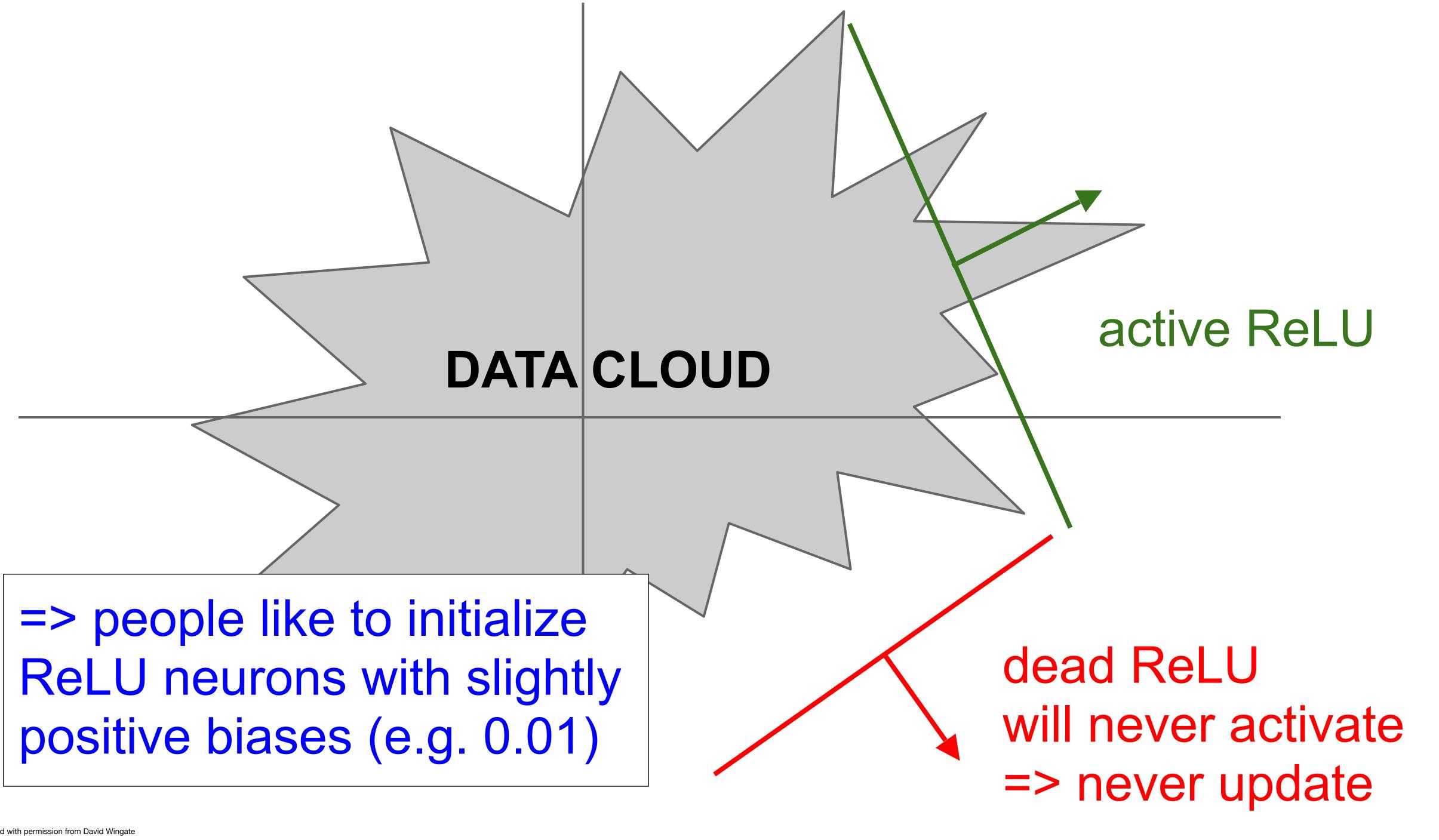
- Computes f(x) = max(0,x)
- Does not saturate (in +region)
- Very computationally efficient
- Converges much faster than sigmoid/tanh in practice (e.g. 6x)
- Not zero-centered output
- An annoyance:

hint: what is the gradient when x < 0?

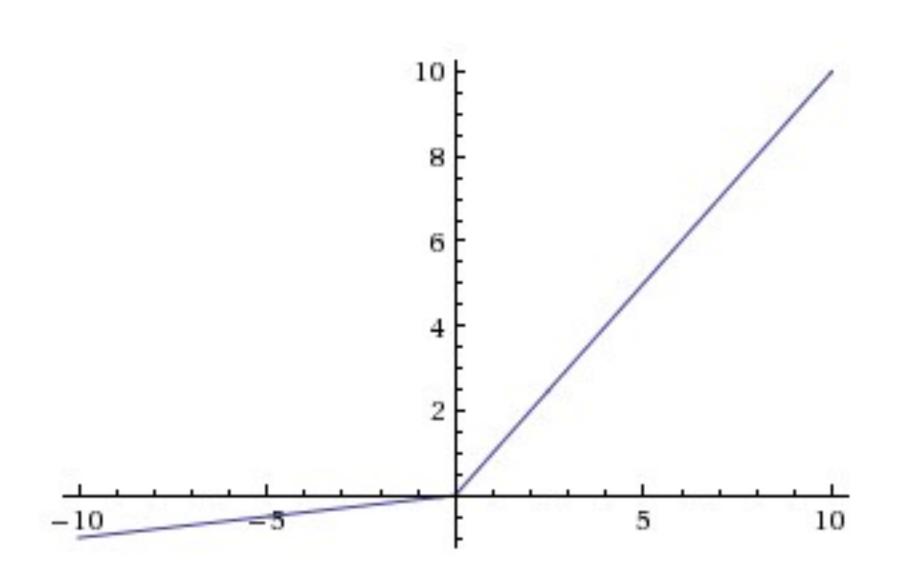


What happens when x = -10? What happens when x = 0? What happens when x = 10?





[Mass et al., 2013] [He et al., 2015]

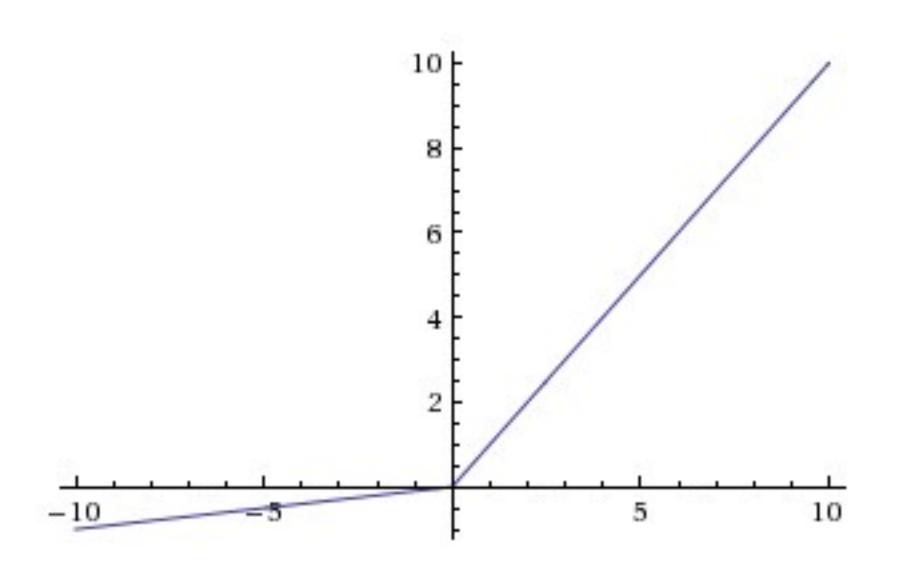


- Does not saturate
- Computationally efficient
- Converges much faster than sigmoid/tanh in practice! (e.g. 6x)
- will not "die".

Leaky ReLU

$$f(x) = \max(0.01x, x)$$

[Mass et al., 2013] [He et al., 2015]



Leaky ReLU

$$f(x) = \max(0.01x, x)$$

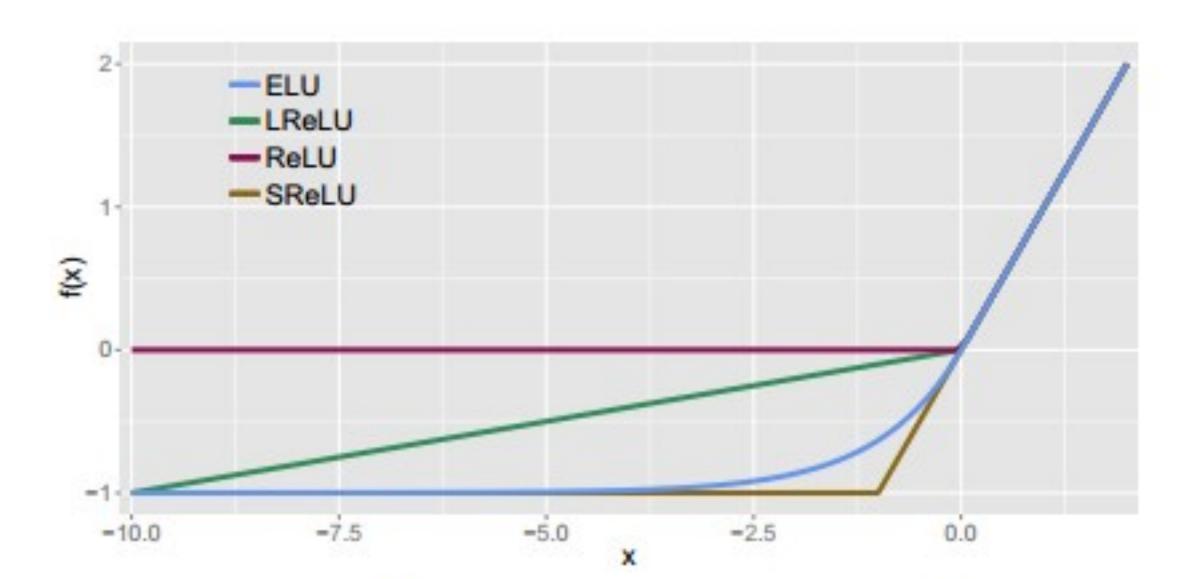
- Does not saturate
- Computationally efficient
- Converges much faster than sigmoid/tanh in practice! (e.g. 6x)
- will not "die".

Parametric Rectifier (PReLU)

$$f(x) = \max(\alpha x, x)$$

backprop into \alpha (parameter)

Exponential Linear Units (ELU)



$$f(x) = \begin{cases} x & \text{if } x > 0 \\ \alpha (\exp(x) - 1) & \text{if } x \le 0 \end{cases}$$

- All benefits of ReLU
- Does not die
- Closer to zero mean outputs
- Computation requires exp()

Maxout "neuron"

[Goodfellow et al., 2013]

- Does not have the basic form of dot product -> nonlinearity
- Generalizes ReLU and Leaky ReLU
- Linear Regime! Does not saturate! Does not die!

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

Problem: doubles the number of parameters/neuron:(

TLDR: In practice, you should

- Use ReLU. Be careful with your learning rates
- Try out Leaky ReLU / Maxout / ELU
- Try out tanh but don't expect much
- Don't use sigmoid

Fully-connected Neural Networks

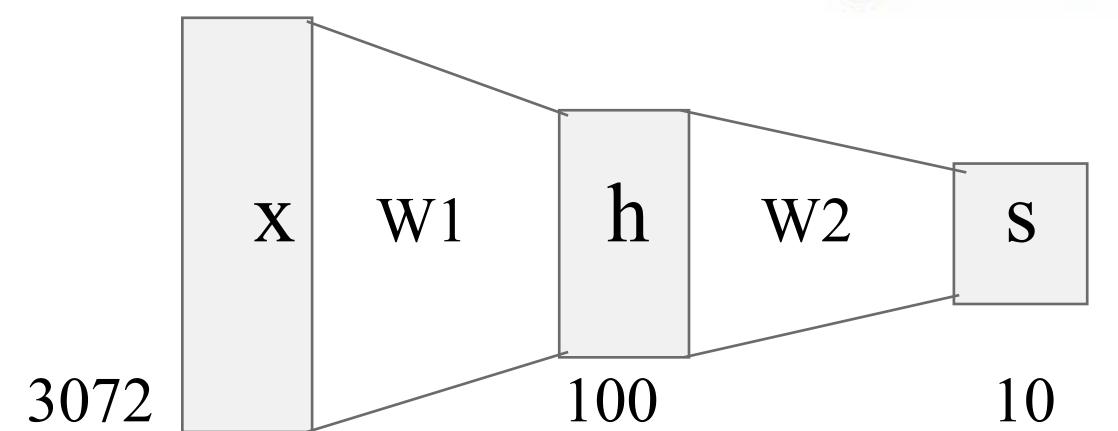
(Before) Linear score function: f = Wx

(**Before**) Linear score function: f=Wx (**Now**) 2-layer Neural Network $f=W_2\max(0,W_1x)$

(Before) Linear score function:

$$f = Wx$$

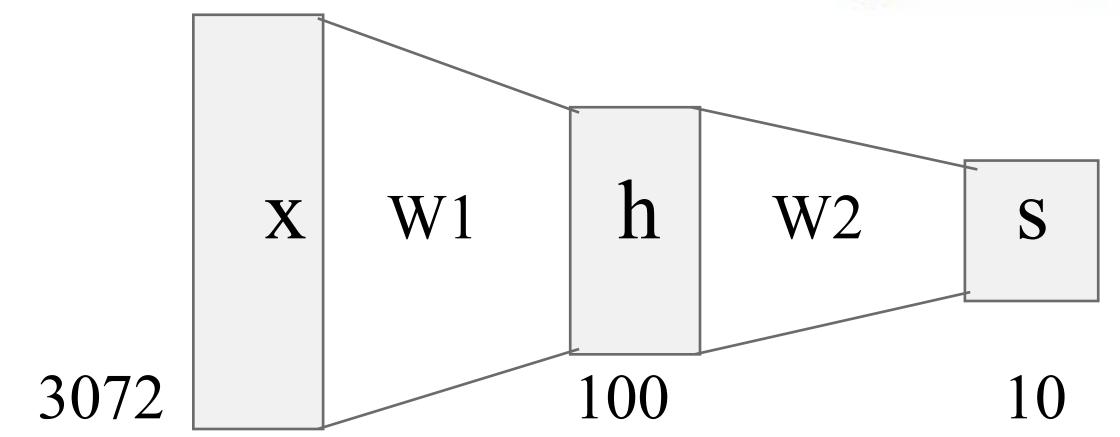
(Now) 2-layer Neural Network
$$f = W_2 \max(0, W_1 x)$$

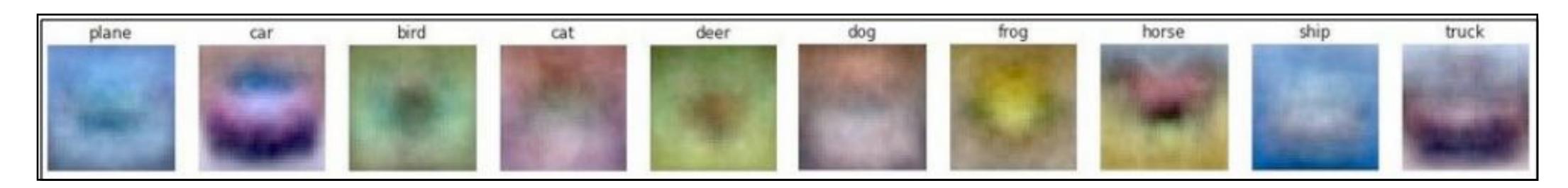


(Before) Linear score function:

$$f = Wx$$

(Now) 2-layer Neural Network
$$f = W_2 \max(0, W_1 x)$$





(**Before**) Linear score function:
$$f=Wx$$
 (**Now**) 2-layer Neural Network $f=W_2\max(0,W_1x)$ or 3-layer Neural Network $f=W_3\max(0,W_2\max(0,W_1x))$

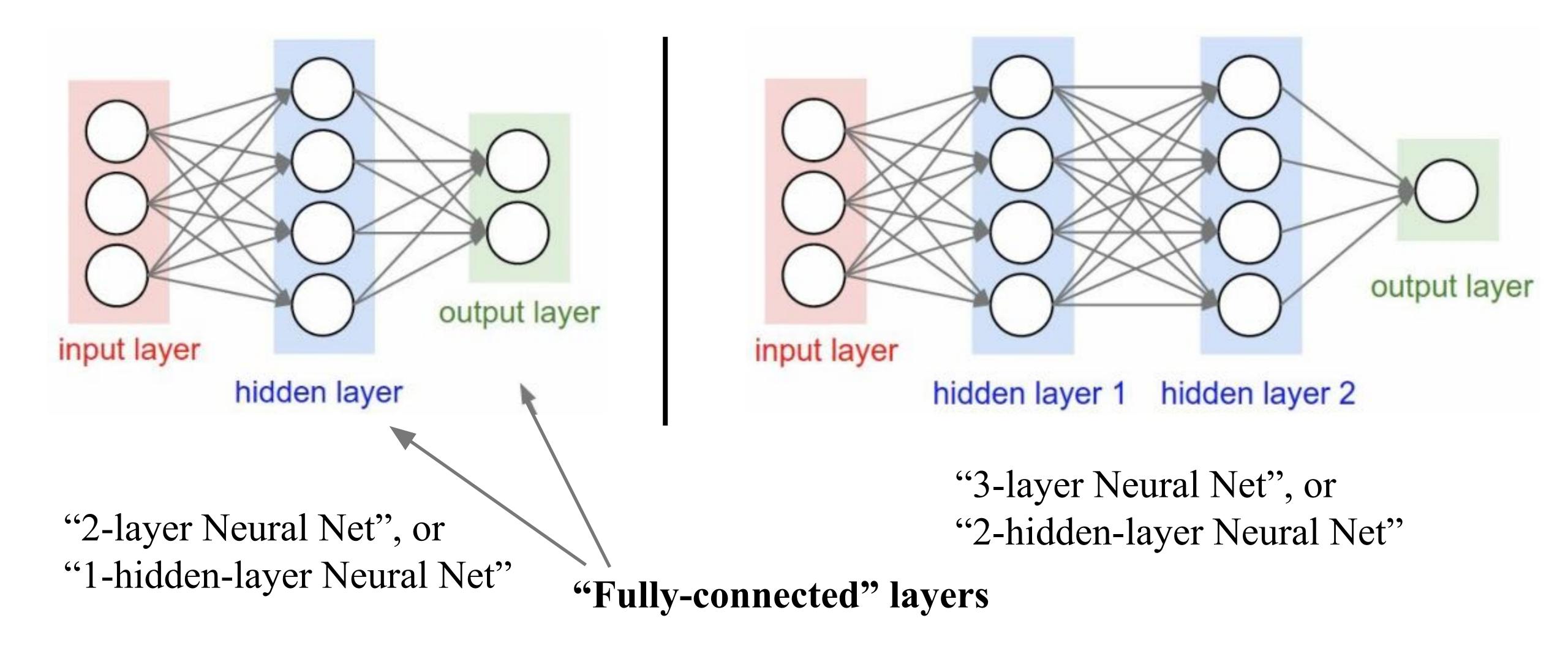
Full implementation of training a 2-layer Neural Network needs ~20 lines:

```
import numpy as np
    from numpy.random import randn
    N, D_{in}, H, D_{out} = 64, 1000, 100, 10
    x, y = randn(N, D_in), randn(N, D_out)
    w1, w2 = randn(D_in, H), randn(H, D_out)
     for t in range(2000):
      h = 1 / (1 + np.exp(-x.dot(w1)))
      y_pred = h.dot(w2)
10
       loss = np.square(y_pred - y).sum()
11
       print(t, loss)
12
13
      grad_y_pred = 2.0 * (y_pred - y)
14
15
       grad_w2 = h.T.dot(grad_y_pred)
      grad_h = grad_y_pred.dot(w2.T)
16
      grad_w1 = x.T.dot(grad_h * h * (1 - h))
17
18
      w1 -= 1e-4 * grad_w1
19
20
      w2 -= 1e-4 * grad_w2
```

In HW: Writing a 2-layer net

```
# receive W1, W2, b1, b2 (weights/biases), X (data)
# forward pass:
h1 = \#... function of X,W1,b1
scores = #... function of h1,W2,b2
loss = #... (several lines of code to evaluate Softmax loss)
# backward pass:
dscores = #...
dh1, dW2, db2 = #...
dW1, db1 = #...
```

Neural networks: Architectures

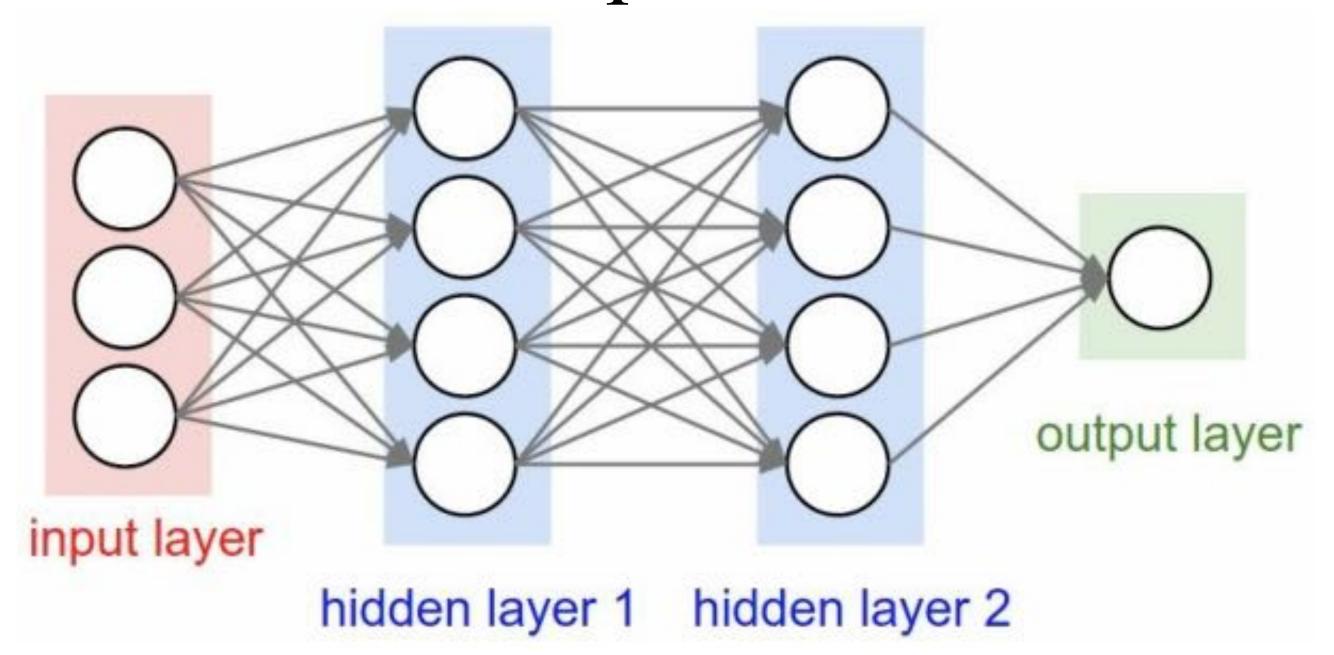


Example feed-forward computation of a neural network

```
class Neuron:
    # ...
    def neuron_tick(inputs):
        """ assume inputs and weights are 1-D numpy arrays and bias is a number """
        cell_body_sum = np.sum(inputs * self.weights) + self.bias
        firing_rate = 1.0 / (1.0 + math.exp(-cell_body_sum)) # sigmoid activation function
        return firing_rate
```

We can efficiently evaluate an entire layer of neurons.

Example feed-forward computation of a neural network

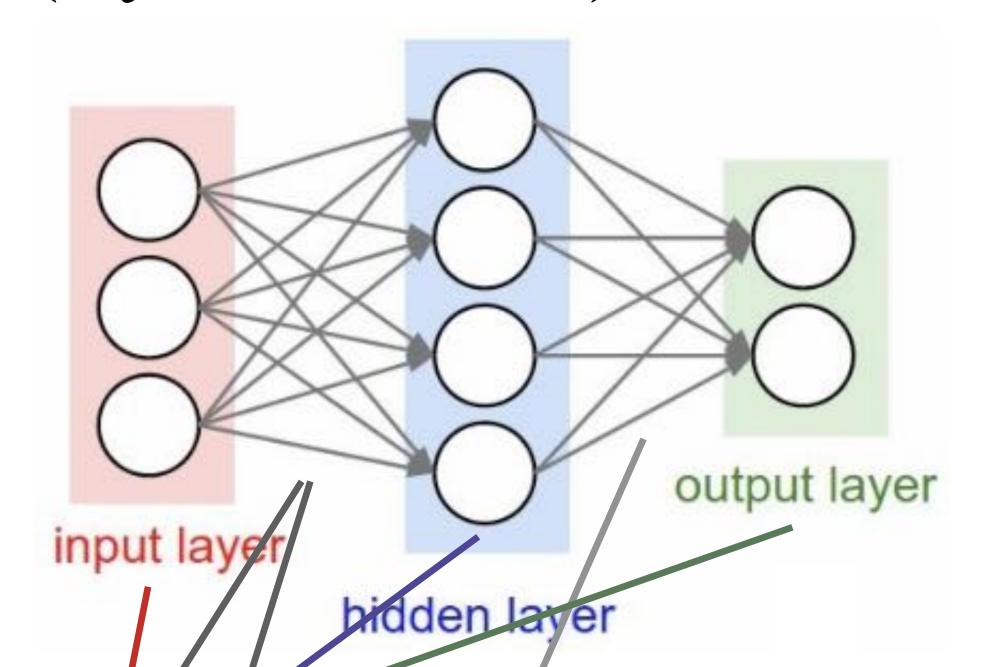


```
# forward-pass of a 3-layer neural network: f = lambda \ x: \ 1.0/(1.0 + np.exp(-x)) \ \# \ activation \ function \ (use \ sigmoid) \\ x = np.random.randn(3, 1) \ \# \ random \ input \ vector \ of \ three \ numbers \ (3x1) \\ h1 = f(np.dot(W1, x) + b1) \ \# \ calculate \ first \ hidden \ layer \ activations \ (4x1) \\ h2 = f(np.dot(W2, h1) + b2) \ \# \ calculate \ second \ hidden \ layer \ activations \ (4x1) \\ out = np.dot(W3, h2) + b3 \ \# \ output \ neuron \ (1x1)
```

Universal approximation theorem (Cybenko 1989)

Definition. We say that σ is sigmoidal if

$$\sigma(t) \to \begin{cases} 1 & \text{as } t \to +\infty, \\ 0 & \text{as } t \to -\infty. \end{cases}$$



Theorem 2. Let σ be any continuous sigmoidal function. Then finite sums of the form

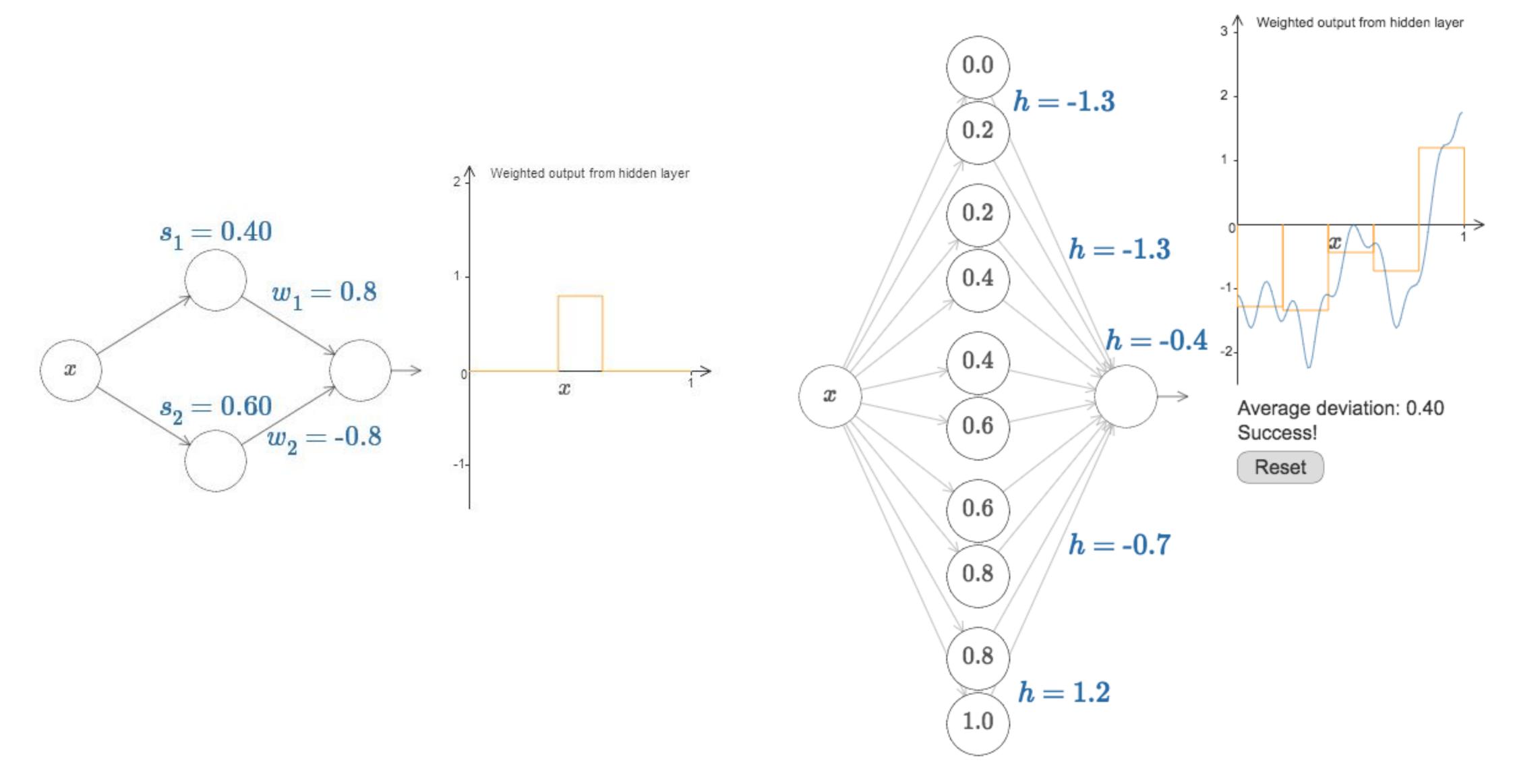
$$G(x) = \sum_{j=1}^{N} \alpha_j \sigma(y_j^T x + \theta_j)$$

are dense in $C(I_n)$. In other words, given any $f \in C(I_n)$ and $\varepsilon > 0$, there is a sum, G(x), of the above form, for which

$$|G(x) - f(x)| < \varepsilon$$
 for all $x \in I_n$.

Not every function, but a lot!

Universal approximation theorem (Cybenko 1989)

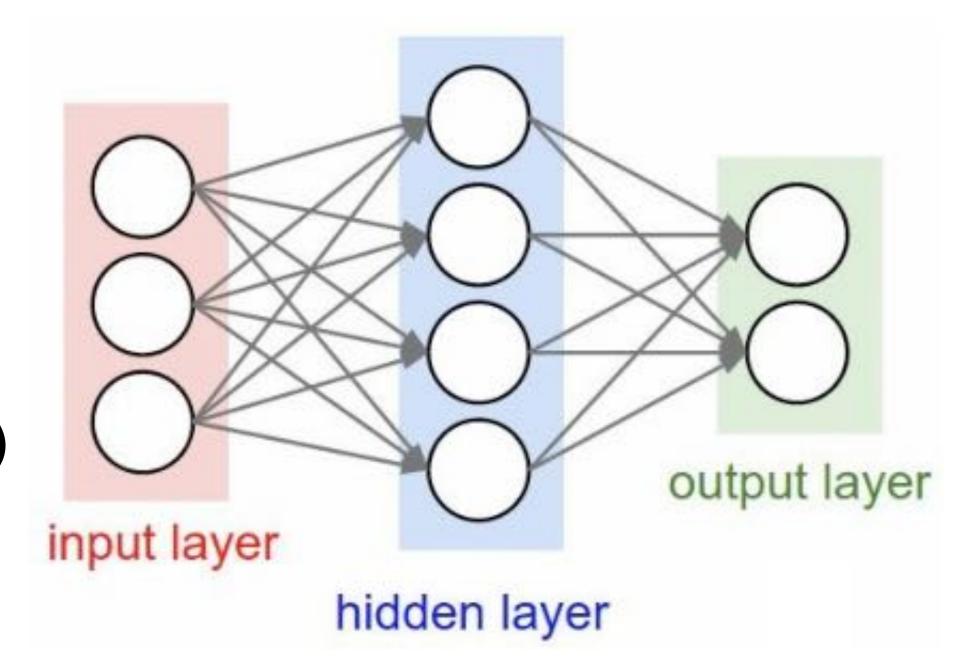


Universal approximation theorem (Cybenko 1989)

Exciting result right?

Not really...requires one neuron for every small volume of the space (so number of neurons grows exponentially with dimension!)

Overcome this with depth!



Theorem 2. Let σ be any continuous sigmoidal function. Then finite sums of the form

$$G(x) = \sum_{j=1}^{N} \alpha_j \sigma(y_j^{\mathrm{T}} x + \theta_j)$$

are dense in $C(I_n)$. In other words, given any $f \in C(I_n)$ and $\varepsilon > 0$, there is a sum, G(x), of the above form, for which

$$|G(x) - f(x)| < \varepsilon$$
 for all $x \in I_n$.

Tensorflow Playground

Summary

- We arrange neurons into fully-connected layers
- The abstraction of a **layer** has the nice property that it allows us to use efficient vectorized code (e.g. matrix multiplies)
- Neural networks are not really neural
- Fully-connected neural networks are universal (but inefficient)
- Overcome inefficiency with depth!