

Use INRs as datapoints (function)

Key concepts \Rightarrow INRs : $f_{\theta} : X \rightarrow \mathbb{I} \leftarrow \text{features } f \in \mathbb{I} \text{ (intensity / pixel value)}$
of INRs
parameters \uparrow coordinates $x \in X$ (pixel locations)

fitted by minimizing mean squared error over all coordinates locations

$$\min_{\theta} \mathcal{L}(f_{\theta}, \{x_i, f_i\}_{i \in \mathbb{I}}) = \min_{\theta} \sum_{i \in \mathbb{I}} \|f_{\theta}(x_i) - f_i\|_2^2$$

each f_{θ} corresponds to a single image. parameterized by a feedforward

"Why function" neural network (MLP)

Naive approach for representing function is to take the parameter vector of SIREN.

\hookrightarrow might have large number of parameters X NOT GOOD

\downarrow So we want --
Modulations come

uses a shared base network across data points to model common structure, with modulations modeling the variation specific to each data point.

★ \hookrightarrow Use modulations instead of parameters - typically much more low dimensional. \Rightarrow Then we get a latent vector and do downstream work based on it.

KEY IDEA.

\downarrow So what is modulations?

Usually represented as elementwise affine transformations (shift and scale)

applied to the activations of the neural network. In this paper they prove that only use shift can be as good as

Latent Modulated SIREN:

uses a latent modulation vector ϕ that is linearly mapped using bias to the shift modulation.

i th layer is parameterised as:

$$x \mapsto \sin(w_0 (w^{(i)} x + b^{(i)} + s^{(i)}))$$

$$s = W' \phi + b'$$

We store this latent vector to represent any given data point.

When creating the funclist we only fit the modulation of each data point with the shared base network fixed.

Inner loop:

update the modulations

Outer loop:

update the base network weights.

Modulation structure