

Gantry Operations

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Useful links:

Github for labview programs: <https://github.com/TTUHGCAL/GantryPrograms>

TTU gantry slides: [googleSlides](#)

CMU github: <https://github.com/jparshook/UCSB-Gantry-master-main>

CMU programming slides: [CMU_Labview](#)

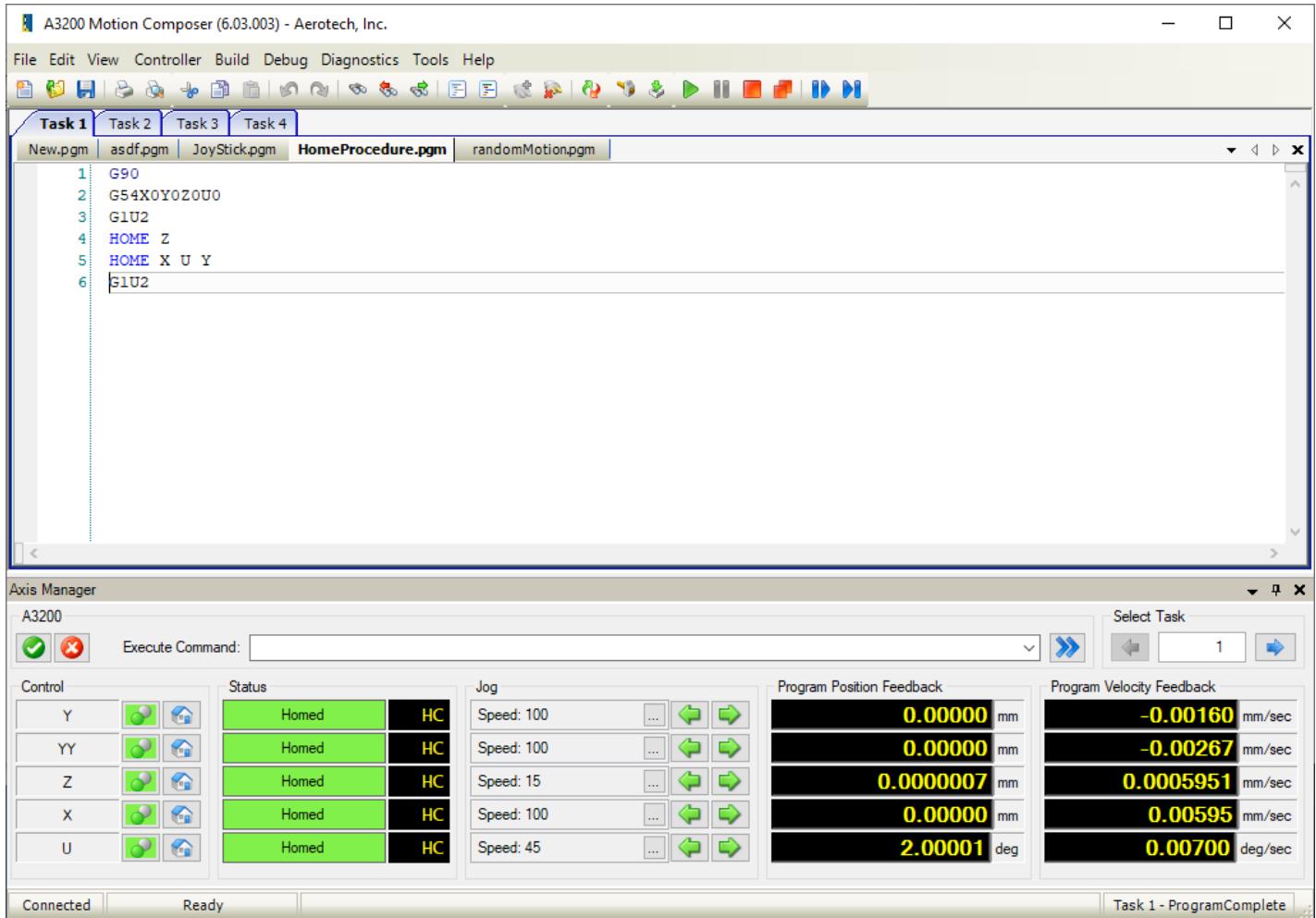
Gantry movement:

Moving the gantry using composer.

Home procedure:

Open A3200 motion composer → Use “HomeProcedure.pgm” and home the gantry. Make sure all controls are enabled.

Never click on home icons, always run “HomeProcedure.pgm”. Always start using the gantry with “HomeProcedure” and home it when you are done.



JoyStick:

Click on “JoyStick.pgm” for joystick program. The contents are:

JOYSTICK 2D RESET

JOYSTICK 2D AXISGROUP 1 Y X

JOYSTICK 2D AXISGROUP 2 Y Z

JOYSTICK 2D ON

Random motion:

Use “randomMotaion.pgm” to move the gantry using Gcode.

Closing:

Home the gantry and disable all the controls and close the A3200 composer program.

Labview programs:

Details about labview programs for assembly are described below.

VacuumSwitchTest.vi

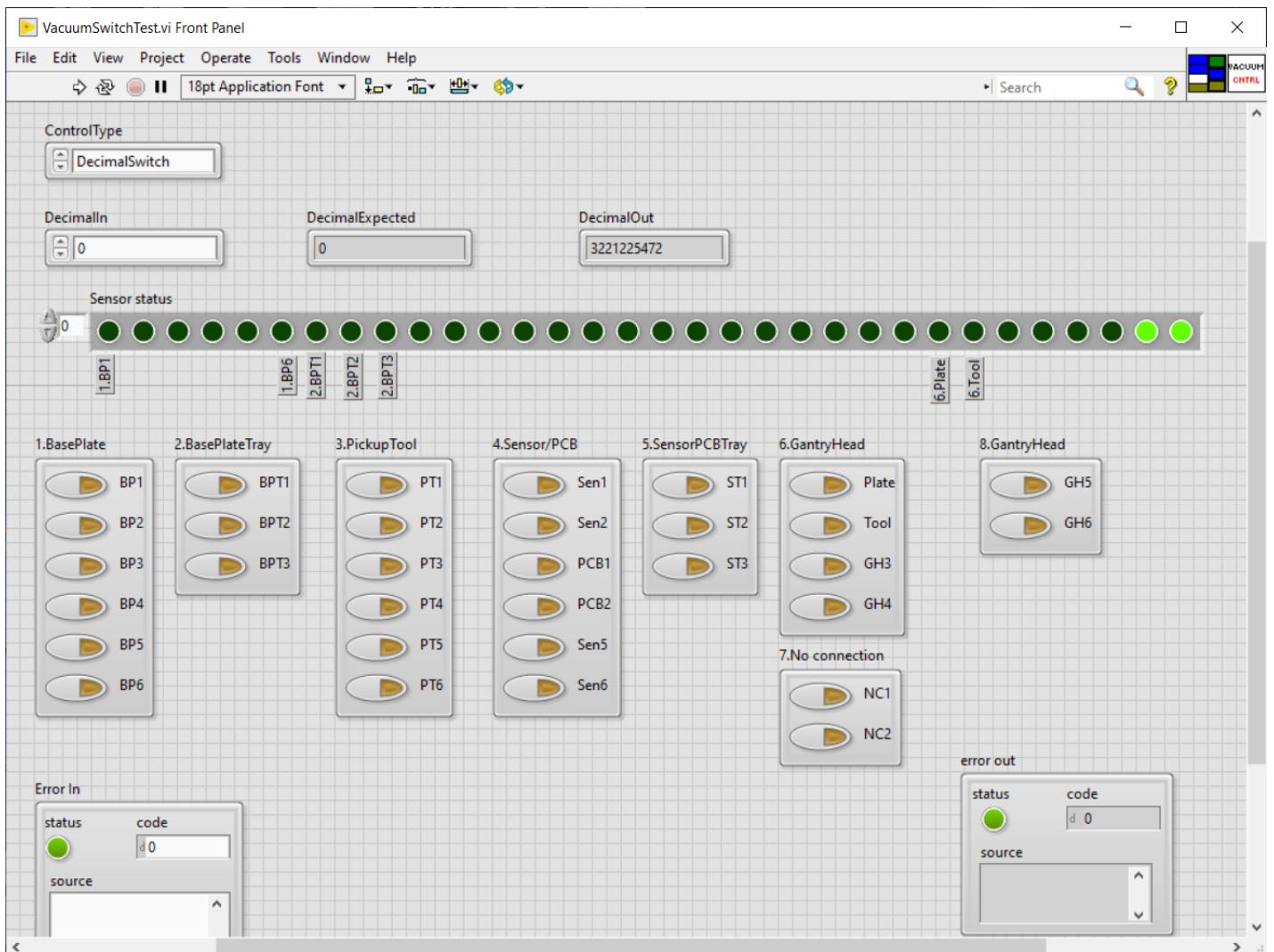
| | |
|---------------|---|
| File location | "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\VacuumSwitchTest.vi" |
| Operation | ON/OFF vacuum switches and read status of vacuum and gantry microswitches. |
| SubVIs | None |
| Main inputs | ControlType, DecimalIn |
| Main outputs | DecimalExpected, DecimalOut |
| Other I/Os | ErrorIn, error out |
| Hardwares | cDAQ1Mod1-NI9476(Spring) → vacuum on/off, cDAQ1Mod5-NI9403 → Read vacuum and gantry micro switches |
| VI descriptor | file:///C:/Users/TTUHEP/Documents/LabVIEW/GantryPrograms/VI_descriptions/VacuumSwitchTest.html |

Overview: control the vacuum switches either using toggle buttons or a decimal equivalent of the switch states. Can also be used for reading the state of vacuum and gantry micro switches.

Procedure::

1. Select "ControlType": DecimalSwitch, BinarySwitch or Conversion.
2. For DecimalSwitch (ignores binary switches):
 - a. Enter a value for "DecimalIn". When you run the program, this number is converted to 30 bit binary and those bit combinations are used to control vacuum switches.
 - b. If the vacuum switches are working and no leak, you should get DecimalIn = DecimalExpected
 - c. Switch status shows the status of vacuums and gantry microswitch.
3. For BinarySwitch:
 - a. Use the 32 binary toggle switches as input. Turn on/off required switches.
 - b. When the program is run, vacuums are turned on/off and "Switch status" indicates the status of vacuums.

- c. “DecimalIn” is ignored. “DecimalExpected” gives the decimal number corresponding to 30 vacuum switches (other 2 switches are for gantry). You can use this number in the other programs with “DecimalSwitch” as the “ControlType”.
4. For Conversion:
- Very similar to BinarySwitch, except that the vacuum are not physically turned on/off.
 - This is useful if you want to only read the status of vacuum or to know the decimal number corresponding to a certain binary switch combination.



Connection details:

| NI9476 (Spring) | | NI 9403 Mod5 | | |
|-----------------|-----------|-------------------|----------------------|------------|
| Line no. | Valve no. | Line no. (Sensor) | Vac Tubes Connection | Connected? |

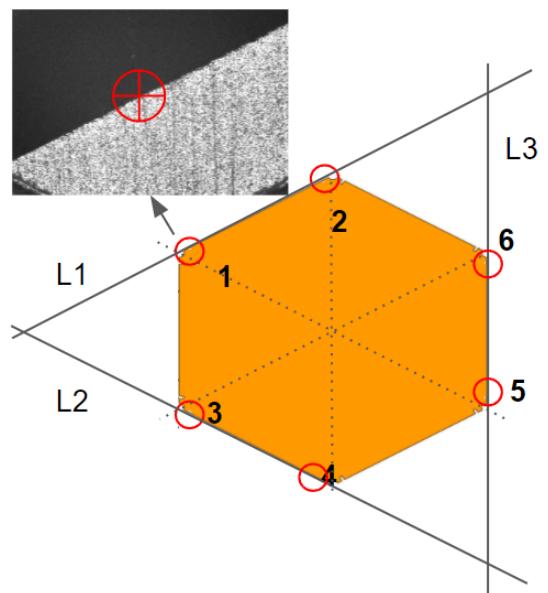
| | | | | |
|----|----|----|------------------------|------------------|
| 0 | 1 | 0 | Vac Base Plate 1 | Yes, direct wall |
| 1 | 2 | 1 | Vac Base Plate 2 | Yes, direct wall |
| 2 | 3 | 2 | Vac Base Plate 3 | |
| 3 | 4 | 3 | Vac Base Plate 4 | |
| 4 | 5 | 4 | Vac Base Plate 5 | |
| 5 | 6 | 5 | Vac Base Plate 6 | |
| 6 | 7 | 6 | Vac Base Plate Tray 1 | Yes |
| 7 | 8 | 7 | Vac Base Plate Tray 2 | |
| 8 | 11 | 10 | Vac Base Plate Tray 3 | |
| 9 | 12 | 11 | Vac Pickup Tool 1 | Yes |
| 10 | 13 | 12 | Vac Pickup Tool 2 | Yes |
| 11 | 14 | 13 | Vac Pickup Tool 3 | |
| 12 | 15 | 14 | Vac Pickup Tool 4 | |
| 13 | 16 | 15 | Vac Pickup Tool 5 | |
| 14 | 17 | 16 | Vac Pickup Tool 6 | |
| 15 | 18 | 17 | Vac Sensor 1 | Yes |
| 16 | 21 | 18 | Vac Sensor 2 | Yes |
| 17 | 22 | 19 | Vac Sensor 3 | Yes as PCB |
| 18 | 23 | 20 | Vac Sensor 4 | Yes as PCB |
| 19 | 24 | 21 | Vac Sensor 5 | |
| 20 | 25 | 22 | Vac Sensor 6 | |
| 21 | 26 | 23 | Vac Sensor Tray 1 | Yes |
| 22 | 27 | 24 | Vac Sensor Tray 2 | Yes as PCB |
| 23 | 28 | 25 | Vac Sensor Tray 3 | |
| 24 | 9 | 8 | Vac Gantry Head Tool 1 | Yes |
| 25 | 10 | 9 | Vac Gantry Head Tool 2 | Yes |
| 26 | 19 | | Vac Gantry Head Tool 1 | |
| 27 | 20 | | Vac Gantry Head Tool 2 | |
| 28 | | | | |
| 29 | | | | |
| 30 | 31 | | Vac Gantry Head Tool 1 | |
| 31 | 32 | | Vac Gantry Head Tool 2 | |

BaseplateCenterFinder.vi:

| | |
|---------------|---|
| File location | "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\BaseplateCenterFinder.vi" |
| Operation | Find the center of baseplate and its orientation using 6 Cu cutouts |
| SubVIs | GetArrayFmTxtFile.vi, CaptureImage.vi, GetGantryPosition.vi, GetPixelToGantryRelPosition.vi, CameraXYusingGantryHeadXY.vi |
| Main inputs | VisibilityInCamera, BaseplateCorners |
| Main outputs | Output XYZU, CameraGcode, XYZU in "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\BaseplatePositions.txt" |
| Other I/Os | AdjustCamera (for ClickMove option of VisibilityCamera), UsedCoordinates, Image, ErrorIn, error out |
| Hardwares | Camera (cam0), gantry |
| VI descriptor | file:///C:/Users/TTUHEP/Documents/LabVIEW/GantryPrograms/VI_descriptions/BaseplateCenterFinder.html |

Overview:

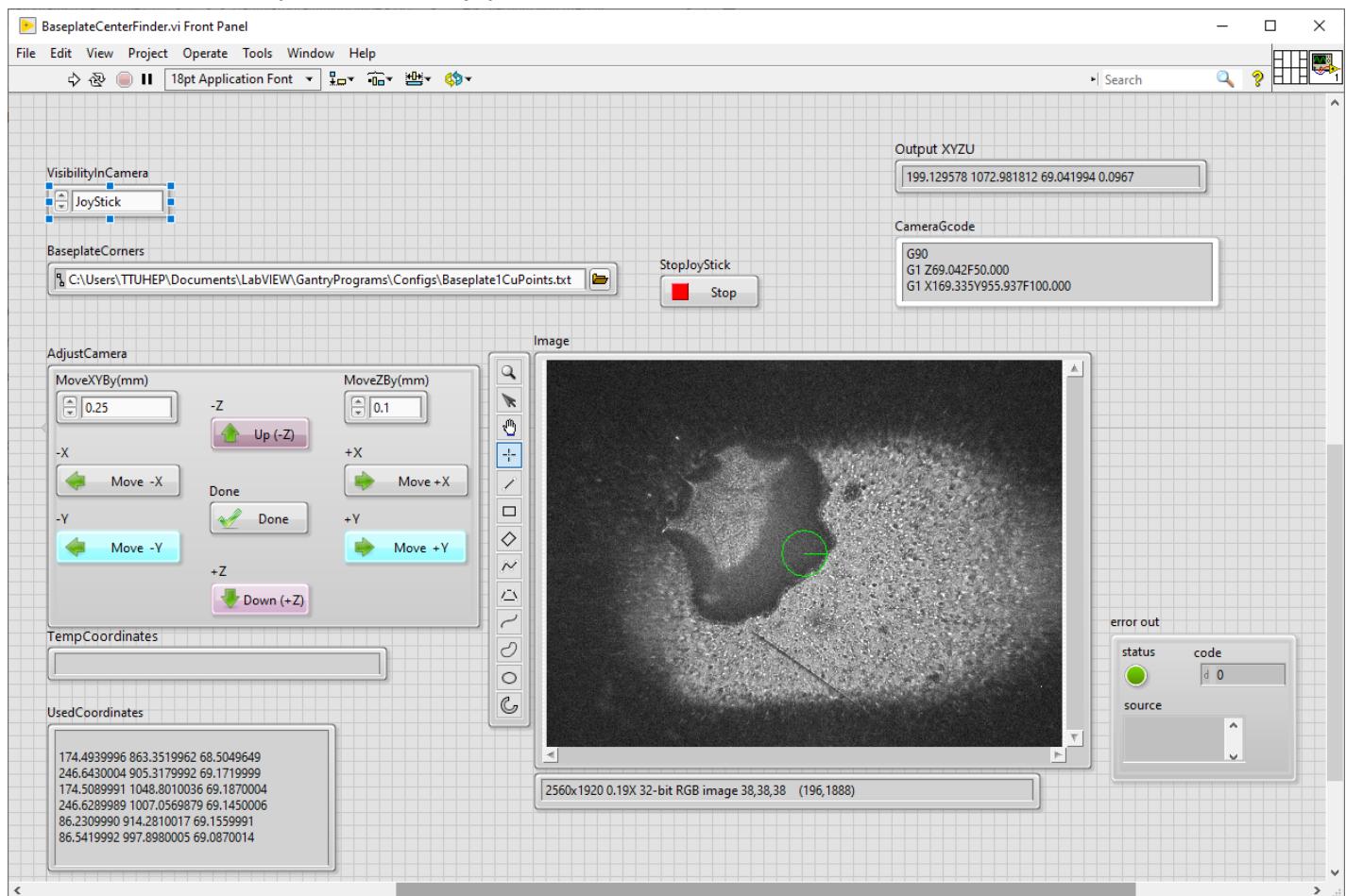
Find the center of the baseplate and its orientation using 6 Cu cutouts and picking a point on each of them.



Procedure:

1. Select an option in “VisibilityInCamera”.
 - a. JoyStick: you will use the joystick for final adjustments since the camera does not see the fiducials clearly.

- b. ClickToMove: Here too, camera cannot see the fiducials clearly. You will use “AdjustCamera” panel to make adjustments instead of joystick.
 - c. AllVisible: The coordinates specified in “BaseplateCorners” is good and you don’t need any adjustments.
2. Once you run the gantry goes to point 1 and you may/may not adjust the gantry depending on the option you chose in step 1 above. Then you will be asked to pick a point. Pick a point which is on the edge as shown in Figure above.
 3. Repeat step 2 for all other 5 points (total 6 points).
 4. At the end you will be asked if you want to write XYZU to a text file. If you think the procedure was good click Yes and the program will write (**overwrite**) the coordinates to a text file ““C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\BaseplatePositions.txt”” and the gantry moved so that the camera is looking at the center. A circle at the center of the image is drawn with a 50um radius. If you don’t want to write the XYZU, click No and gantry will not move and nothing is written to the text file. You can see the XYZU in “Output XYZU” and “CameraGcode” can be used to move the gantry to see the center.
 5. You can also adjust the input 6 coordinates for future use by looking at “UsedCoordinates”. Note that this is relevant if you have used joystick or clickToMove option.



SiRealCenterFinder.vi:

| | |
|---------------|---|
| File location | "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\SiRealCenterFinder.vi" |
| Operation | Find the center of sensor and its orientation using 2 circular fiducials |
| SubVIs | GetArrayFmTxtFile.vi, CaptureImage.vi, CircleFinderAI.vi, GetGantryPosition.vi, GetPixelToGantryRelPosition.vi, CameraXYusingGantryHeadXY.vi |
| Main inputs | VisibilityInCamera, SiFiducials or SiOnBPFiducials |
| Main outputs | Output XYZU, CameraGcode, XYZU in "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\SensorPositions.txt" OR "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\BaseplatePositions.txt" |
| Other I/Os | AdjustCamera (for ClickMove option of VisibilityCamera), UsedCoordinates, Image, ErrorIn, error out |
| Hardwares | Camera (cam0), gantry |
| VI descriptor | file:///C:/Users/TTUHEP/Documents/LabVIEW/GantryPrograms/VI_descriptions/SiRealCenterFinder.html |

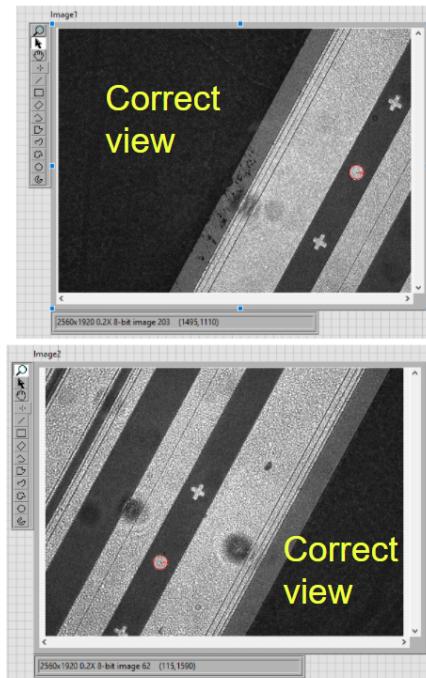
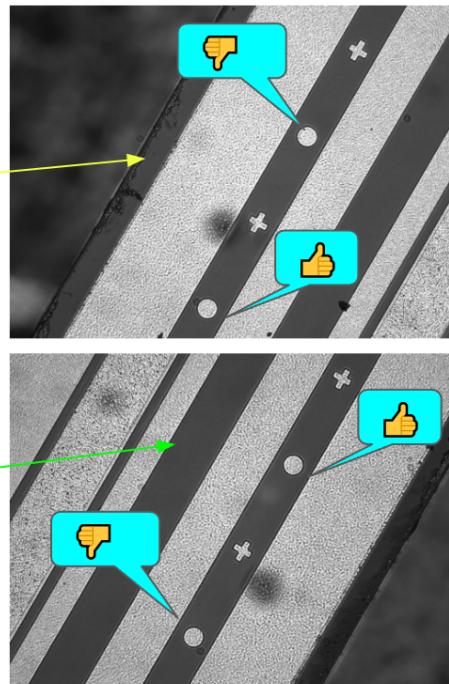
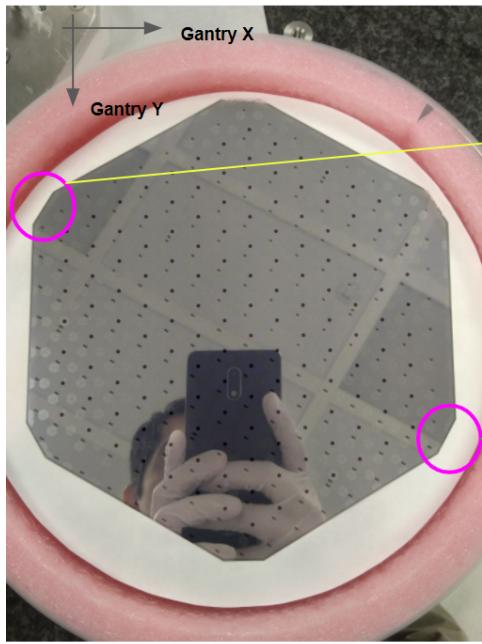
Overview:

The sensor has many fiducials which can be used to accurately find the center. We make use of 2 circles which are at the 2 sides shown in magenta below. Note that you should not make both circles visible. Correct view is shown in the top right and bottom right pictures. Once the fiducials are visible, the program finds the center using circle recognition.

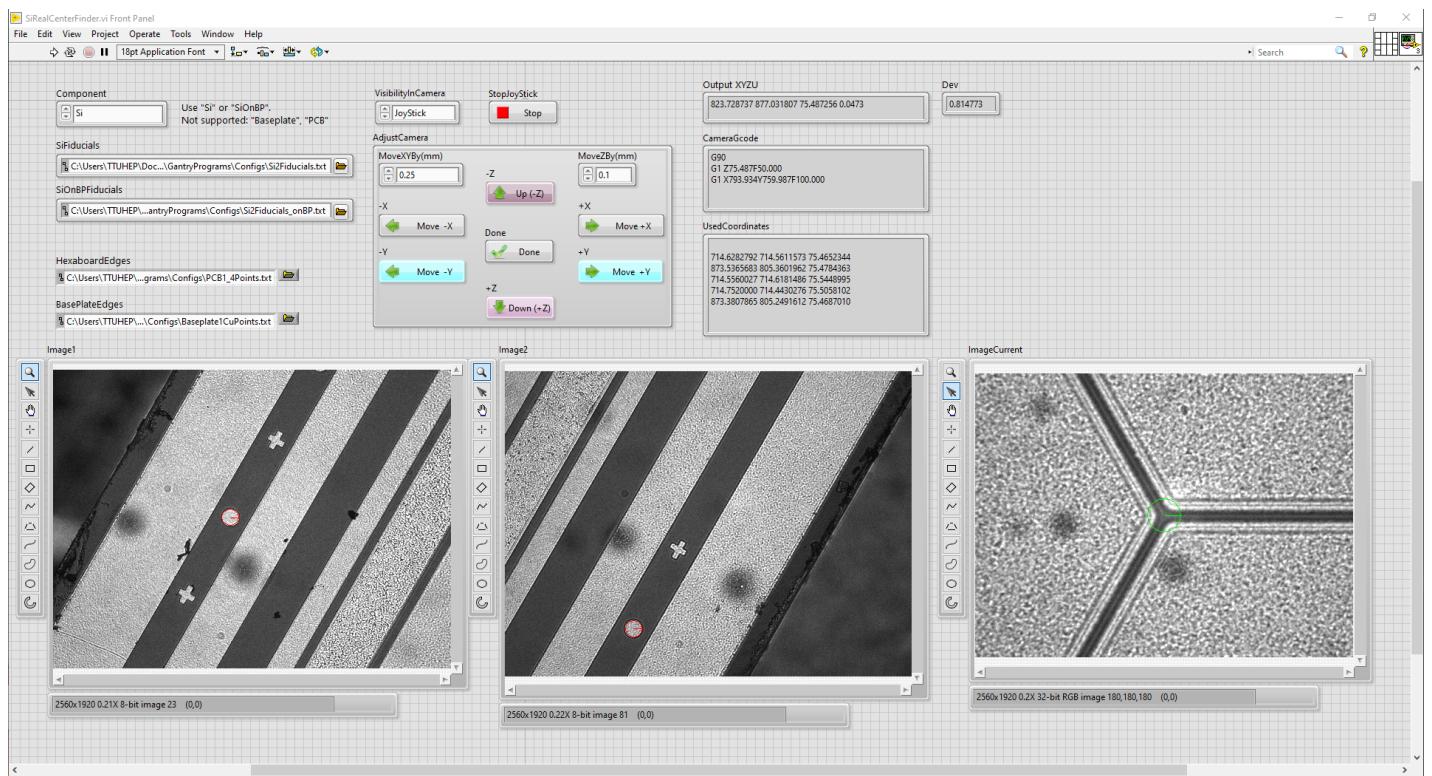
Procedure:

1. Select “Component” Si or SiOnBP depending on the type of assembly.
2. Select “VisibilityInCamera” as “AllVisible” or “ClickToMove” or “JoyStick”. This step is similar to baseplate.
3. Make sure you get a clear and correct picture as shown in the pictures below.

4. The program automatically finds the center and at the end it will ask if you would like to write the center and orientation. If you click yes, then it will write the info and the gantry goes to the center and you can see the center in camera. If you have the center correctly, you will see an intersection of 3 lines at the center as in figure.



5. The cell corresponding to the center is “88” and it is below the number “88”.



PCBdummySiCenterFinder.vi:

| | |
|---------------|---|
| File location | "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\PCBdummySiCenterFinder.vi" |
| Operation | Find the center and orientation of dummy sensor w/o patterns or PCB hexaboard. |
| SubVIs | GetArrayFmTxtFile.vi, CaptureImage.vi, GetGantryPosition.vi, GetPixelToGantryRelPosition.vi, CameraXYusingGantryHeadXY.vi |
| Main inputs | VisibilityInCamera, SiDummy 4 corners or PCB 4 corners |
| Main outputs | Output XYZU, CameraGcode, XYZU in C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\SensorPositions.txt OR C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\Configs\PCBPositions.txt |
| Other I/Os | AdjustCamera (for ClickMove option of VisibilityCamera), UsedCoordinates, Image, ErrorIn, error out |
| Hardwares | Camera (cam0), gantry |
| VI descriptor | file:///C:/Users/TTUHEP/Documents/LabVIEW/GantryPrograms/VI_descriptions/PCBdummySiCenterFinder.html |

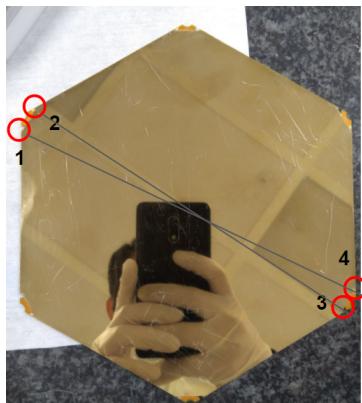
Overview:

For finding the center of dummy Si w/o patterns, use 4 corners.

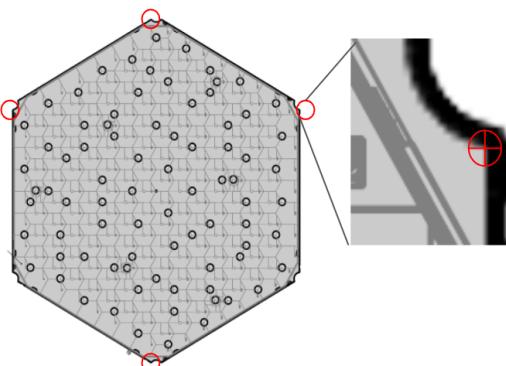
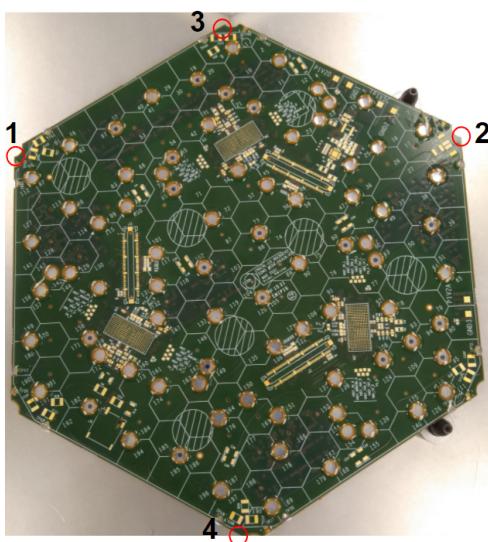
For finding the center of PCB, use 4 circular cutouts at the edges.

Procedure:

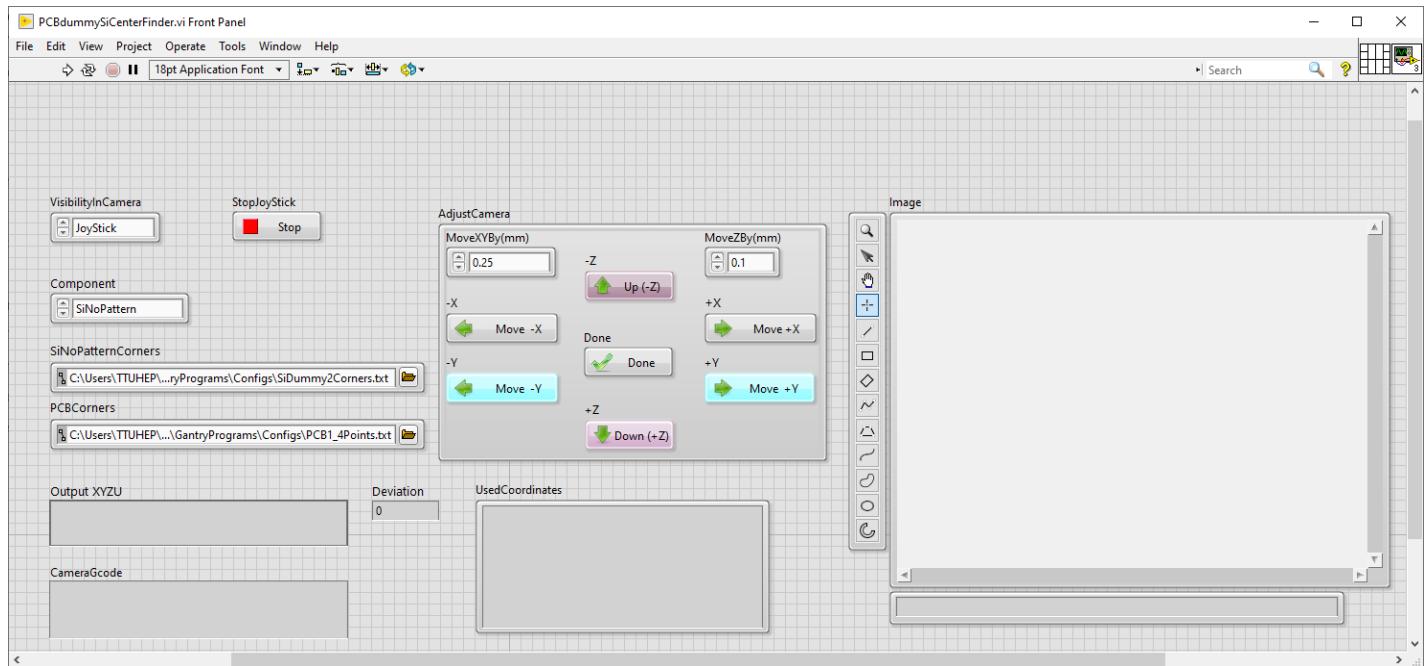
1. The steps to run the program are very similar to baseplate center finder except that we use 4 points instead of 6 points.



Dummy sensor center finder



PCB center finder



AssembleSiPCB.vi:

| | |
|---------------|--|
| File location | "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\AssembleSiPCB.vi" |
| Operation | Assemble Si or PCB |
| SubVIs | GetArrayFmTxtFile.vi, Dispenser_v2.vi, RotateGH_U.vi, PickDropVacCtrlId.vi |
| Main inputs | Initialize, AssmbType, Syringe XYZ, Glue pressure settings, Glue pattern and set of operations (Glue, GoToTool, PickTool etc). |
| Main outputs | Assemble Si/PCB and write log files to "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\LogFiles\" |
| Other I/Os | Position of baseplate, Si/PCB, PUT position, Vacuum switch states, ErrorIn, error out |
| Hardwares | Gantry, Vacuum & micro switches, Dispenser |
| VI descriptor | file:///C:/Users/TTUHEP/Documents/LabVIEW/GantryPrograms/VI_descriptions/AssembleSiPCB.html |

Overview:

Dispense glue using glue pattern, pick and place Si/PCB on baseplate/Si. This is the main program for assembly. It makes use of calibrations values determined from previous steps.

At present we use Position1 for baseplate, position2 for sensor and Position1 for PCB. Position of pickup tool (PUT) is fixed at position1 irrespective of Si or PCB assembly.

Procedure:

1. Do manual calibration of X,Y and Z of syringe and put those values into SyringeX/Y/Z input boxes.
2. Check the pressure and glue patterns as 30,30,15,0 for Si assembly and 15,14,8,0 for PCB assembly.
3. Fill the details in Initialize. For ModuleName, do not use any special characters or space.
4. Choose "AssmbType" as Sensor/PCB.
5. Click on all the steps, Glue, GoToTool..... Home. When they are activated, they are orange, if not they are gray.
6. You don't need to change anything else if it is a normal assembly.

7. After gluing, the program pauses and waits for your confirmation about the syringe being taken out or not. After removing the syringe, click yes in the popup window.
8. After pick and place, you will be asked if you want to write the log. Click yes. If you don't want to write, click No. Even if the log files are not written, the log is shown in "LogFileString" at the bottom of the front panel. You can copy and put the info into a text file. Log files are named as <ModuleName>_Assembly_<Sensor/PCB>_log.txt. For example, LiveModule1_Assembly_PCB_log.txt in "C:\Users\TTUHEP\Documents\LabVIEW\GantryPrograms\LogFiles\" directory.
9. **Never stop glue dispensing in the middle. If it is really needed try to stop when the dispenser is not pumping air. If you stopped glue dispensing in the middle, take out the syringe and "Home" the gantry using "Composer", not using the labview program.**

