# Garbage Collection

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# Garbage Collection

### outline

### Reference counting

deallocate records with count 0

### Mark & sweep

- mark reachable records
- sweep unmarked records

### Copying collection

copy reachable records

#### Generational collection

collect only in young generations of records



# Memory Safety & Management



# Memory Safety

A program execution is memory safe if

- It only creates valid pointers through standard means
- Only uses a pointer to access memory that belongs to that pointer

Combines temporal safety and spatial safety



# Spatial Safety

### Access only to memory that pointer owns

### View pointer as triple (p, b, e)

- p is the actual pointer
- b is the based of the memory region it may access
- e is the extent (bounds of that region)

#### Access allowed iff

 $b \le p \le e - sizeof(typeof(p))$ 

### Allowed operations

- Pointer arithmetic increments p, leaves b and e alone
- Using &: e determined by size of original type



### Temporal Safety

### No access to undefined memory

Temporal safety violation: trying to access undefined memory

- Spatial safety assures it was to a legal region
- Temporal safety assures that region is still in play

Memory region is defined or undefined

### Undefined memory is

- unallocated
- uninitialized
- deallocated (dangling pointers)



### Memory Management

### safety guarantees

#### Manual memory management

- malloc, free in C
- Easy to accidentally free memory that is still in use
- Pointer arithmetic is unsafe

### Automated memory management

- Spatial safety: references are opaque (no pointer arithmetic)
- (+ array bounds checking)
- Temporal safety: no dangling pointers (only free unreachable memory)



# Garbage Collector

### Terminology

- objects that are referenced are live
- objects that are not referenced are **dead (garbage)**
- objects are allocated on the **heap**

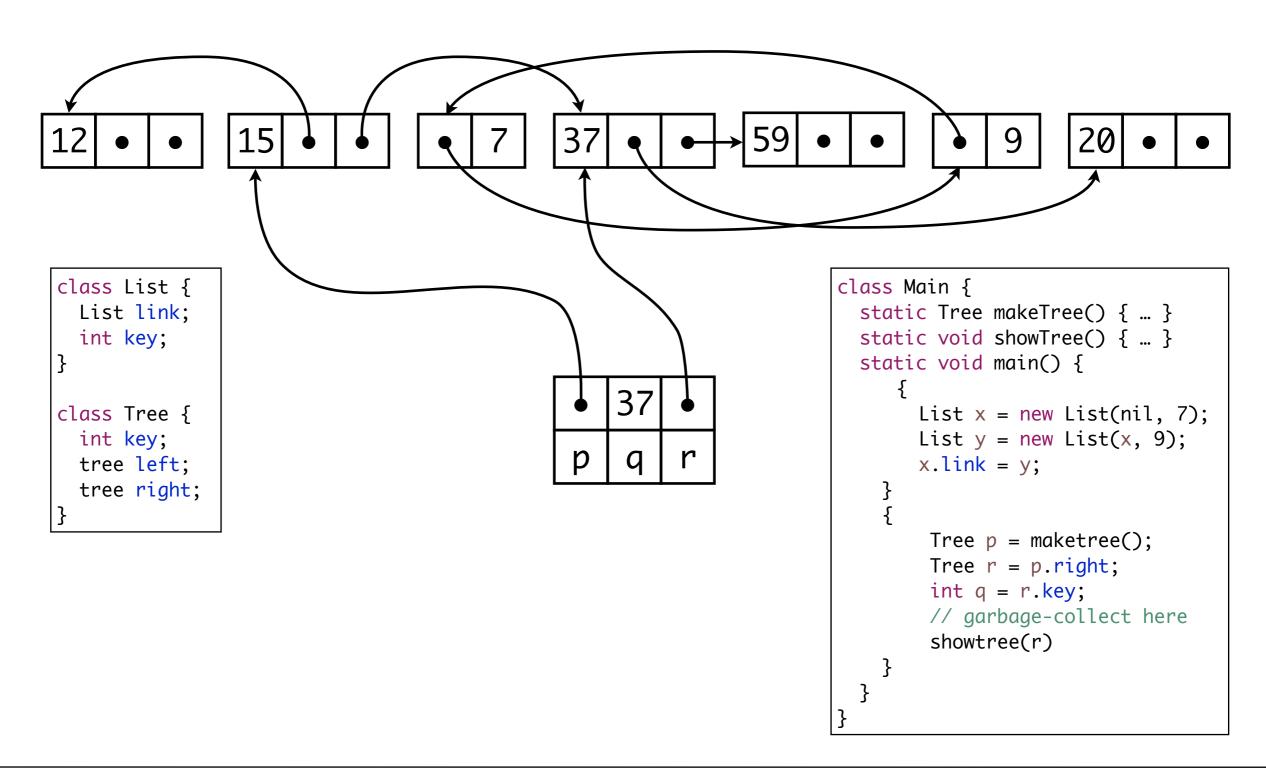
### Responsibilities

- allocating memory
- ensuring live objects remain in memory
- garbage collection: recovering memory from dead objects



```
class List {
 List link;
 int key;
class Tree {
 int key;
 tree left;
 tree right;
```

```
class Main {
  static Tree makeTree() { ... }
  static void showTree() { ... }
  static void main() {
     List x = new List(nil, 7);
     List y = new List(x, 9);
     x.link = y;
      Tree p = maketree();
      Tree r = p.right;
      int q = r.key;
      // garbage-collect here
      showtree(p)
```







### idea

#### Counts

- how many pointers point to each record?
- store with each record

### Counting

extra instructions

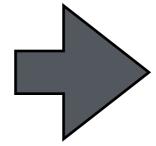
#### **Deallocate**

- put on freelist
- recursive deallocation on allocation



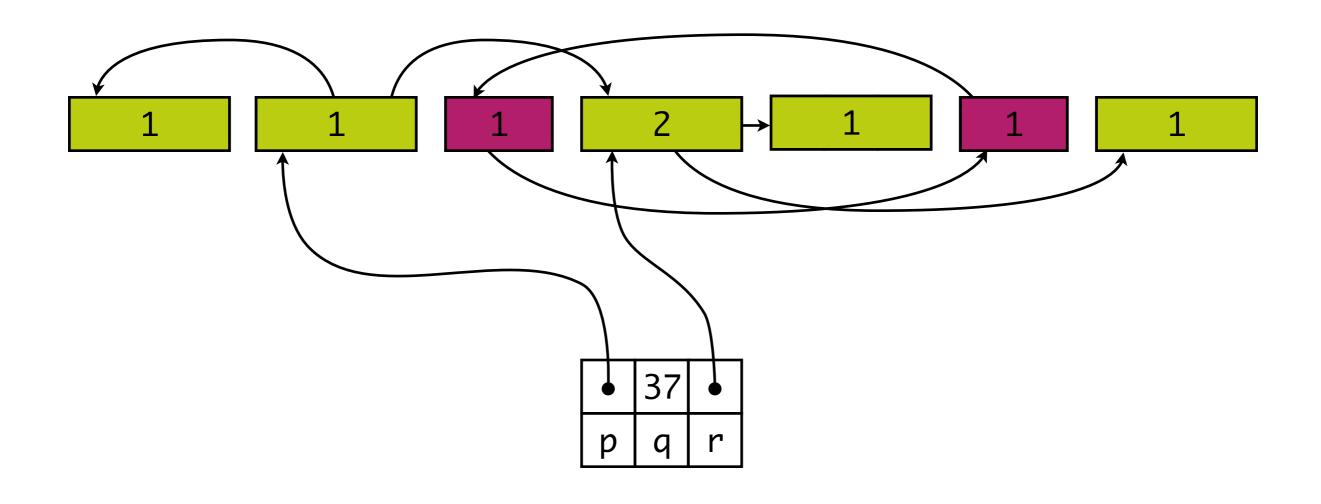
compiler instrumentation

$$x.f := p$$



```
:= x.f
      := z.count
  := c - 1
z.count := c
if (c == 0) put z on free list
x.f
 := p.count
  := c + 1
p.count := c
```

example





### notes

### Cycles

- memory leaks
- break cycles explicitly
- occasional mark & sweep collection

### Expensive

- fetch, decrease, store old reference counter
- possible deallocation
- fetch, increase, store new reference counter



### programming languages

### Languages with automatic reference counting

Objective-C, Swift

### Dealing with cycles

- strong reference: counts as a reference
- weak reference: can be nil, does not count
- unowned references: cannot be nil, does not count





### idea

#### Mark

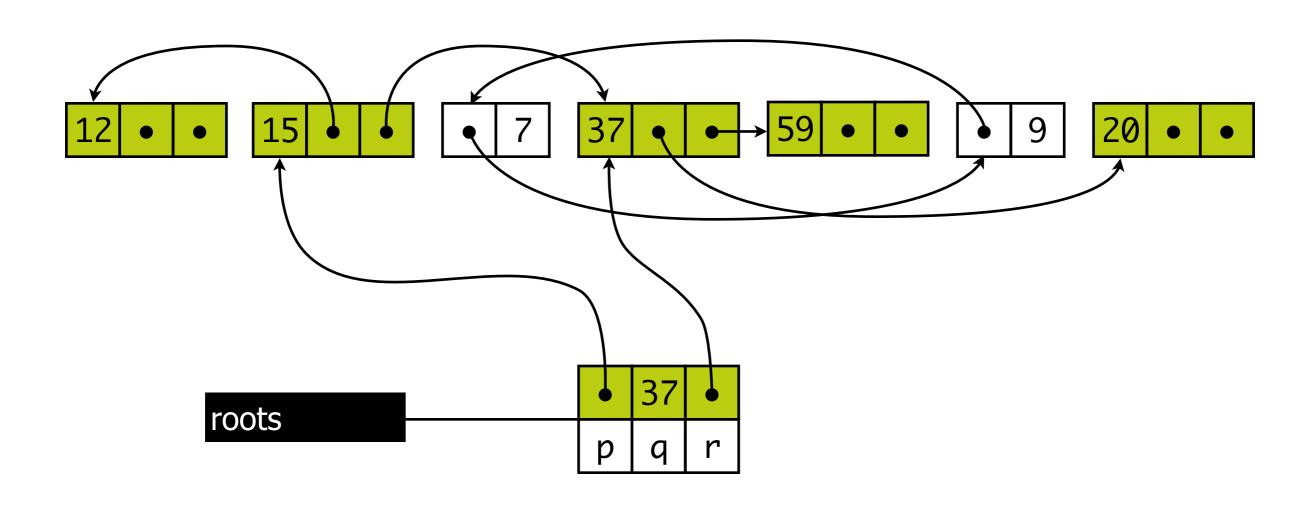
- mark reachable records
- start at variables (roots)
- follow references

### Sweep

- marked records: unmark
- unmarked records: deallocate
- linked list of free records

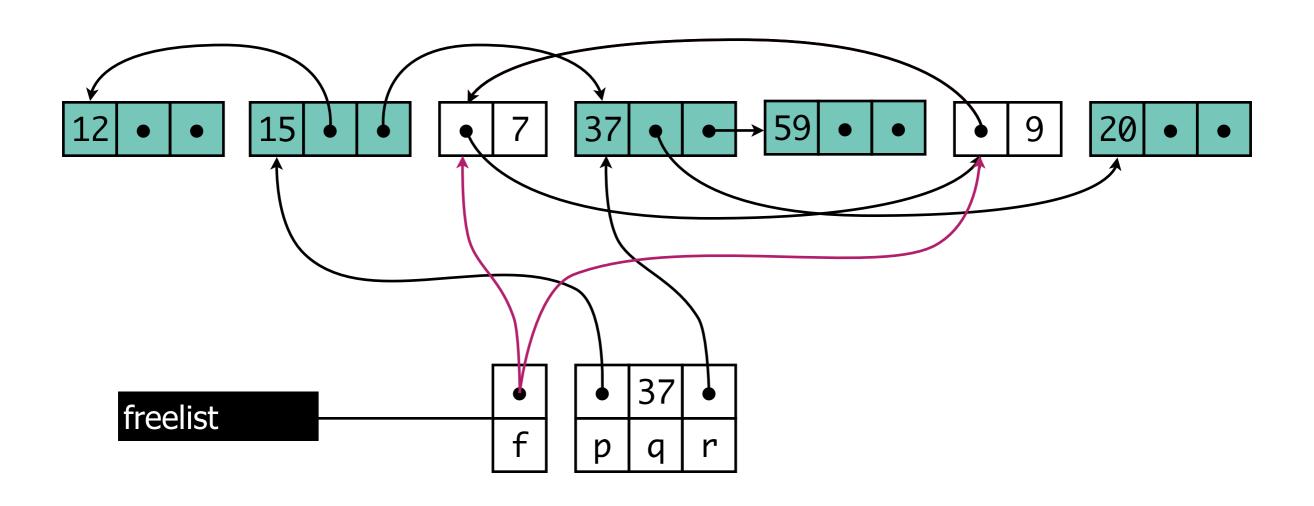


# Marking example





# Sweeping example





### algorithms

```
Mark phase:

foreach r in roots

DFS(r)
```

```
function DFS(x)

if pointer(x) & !x.marked

    x.marked := true

    foreach f in fields(x)

    DFS(f)
```

```
Sweep phase:
 p := first address in heap
 while p < last address in heap</pre>
    if p.marked
      p.marked := false
    else
      f1 := first field in p
      p.f1 := freelist
      free list := p
    p := p + sizeof(p)
```



### costs

#### **Instructions**

- R reachable words in heap of size H
- Mark: c1 \* R
- Sweep: c2 \* H
- Reclaimed: H R words
- Instructions per word reclaimed:

$$(c1 * R + c2 * H) / (H - R)$$

if (H >> R) cost per allocated word ~ c2

### costs

### Memory

- DFS is recursive
- maximum depth: longest path in graph of reachable data
- worst case: H
- | stack of activation records | > H

#### Measures

- explicit stack
- pointer reversal



# Marking: DFS with Explicit Stack

### algorithms

```
function DFS(x)
 if pointer(x) & !x.marked
    x.marked = true
    foreach f in fields(x)
      DFS(f)
```

```
function DFS(x)
 if pointer(x) & !x.marked
   x.marked = true
   t = 1; stack[t] = x
   while t > 0
     x = stack[t]; t = t - 1
      foreach f in fields(x)
       if pointer(f) & !f.marked
         f.marked = true
          t = t + 1; stack[t] = f
```



# Marking: DFS with Pointer Reversal

marking without memory overhead

```
function DFS(x)
  if pointer(x) & x.done < 0</pre>
    x.done = 0; t = nil
    while true
      if x.done < x.fields.size
        y = x.fields[x.done]
        if pointer(y) & y.done < 0</pre>
          x.fields[x.done] = t ; t = x ; x = y ; x.done = 0
        else
          x.done = x.done + 1
      else
        y = x; x = t
        if t = nil then return
        t = x.fields[x.done]; x.fields[x.done] = y
        x.done = x.done + 1
```



### notes

### Sweeping

- independent of marking algorithm
- several freelists (per record size)
- split free records for allocation

### Fragmentation

- external: many free records of small size
- internal: too-large record with unused memory inside





### idea

### Spaces

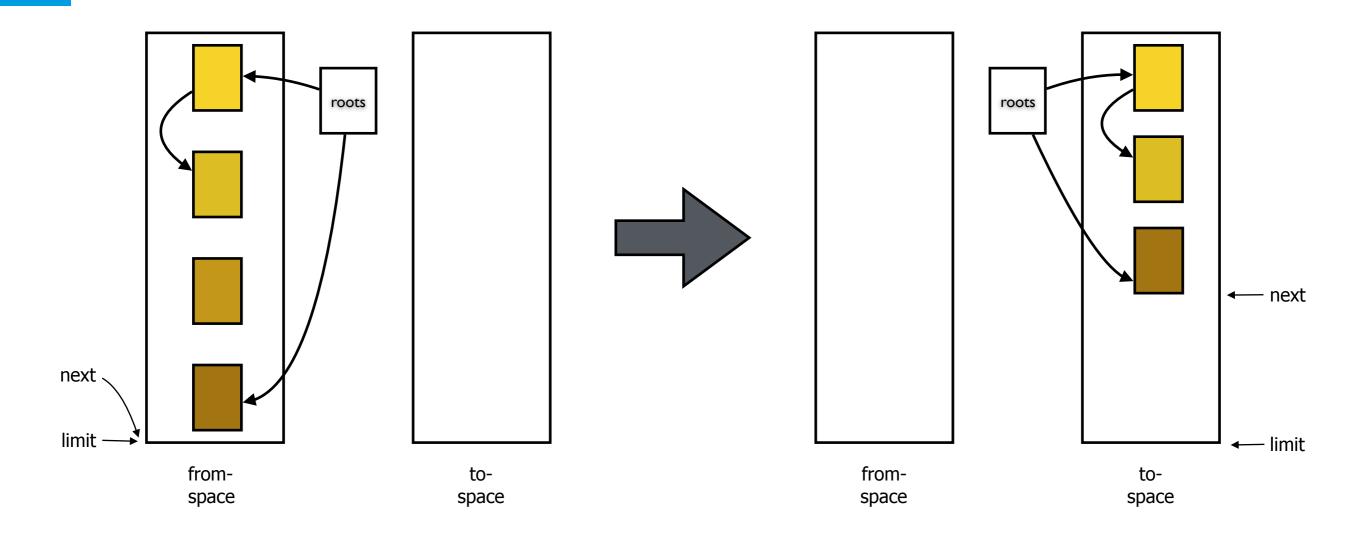
- fromspace & tospace
- switch roles after copy

### Copy

- traverse reachability graph
- copy from fromspace to tospace
- fromspace unreachable, free memory
- tospace compact, no fragmentation



idea





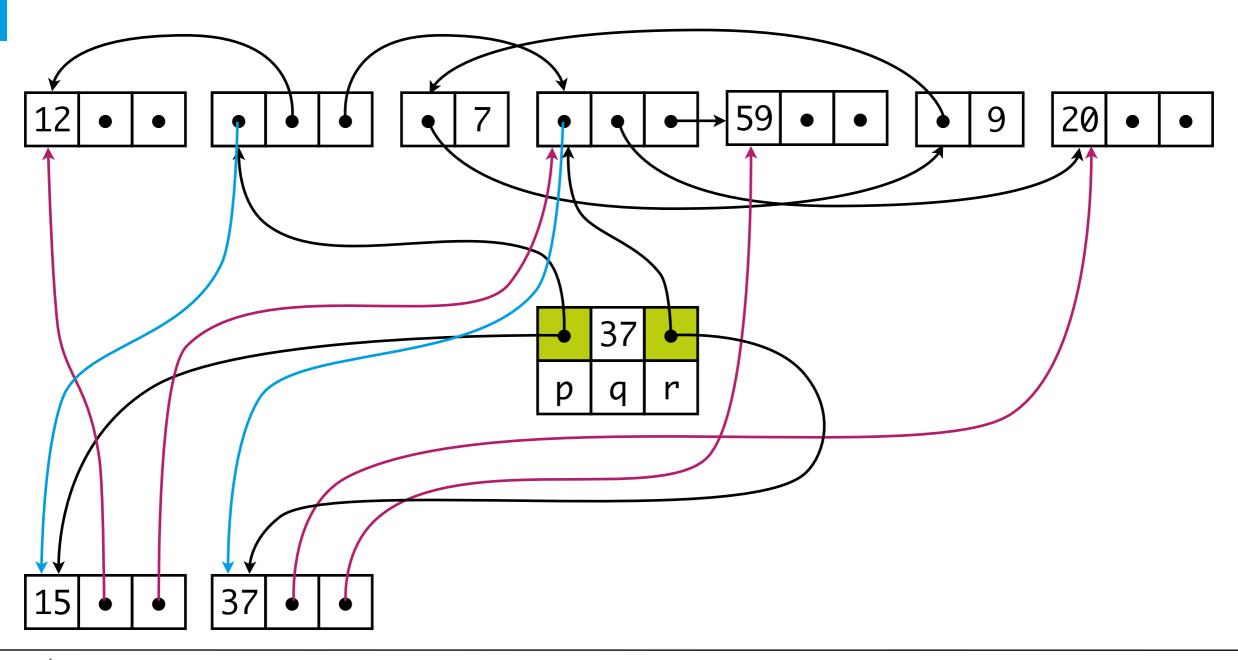
### Copying Collection algorithms

```
function Forward(p)
  if p in fromspace
    if p.f1 in tospace
      return p.f1
    else
      foreach f in fields of p
        next.f := p.f
      p.f1 := next
      next := next + sizeof(p)
      return p.f1
  else return p
```

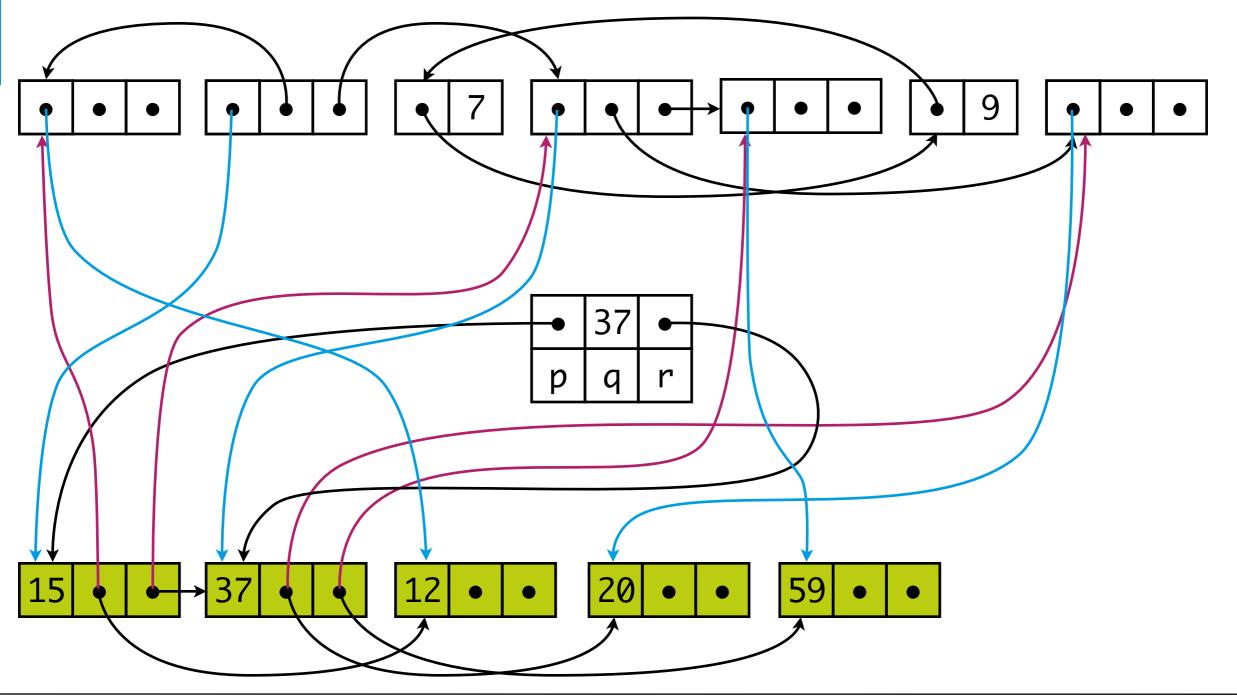
```
function BFS()
 next := scan := start(tospace)
 foreach r in roots
    r = Forward(r)
 while scan < next
    foreach f in fields of scan
      scan.f = Forward(scan.f)
    scan = scan + sizeof(scan)
```



example









### Copying Collection locality

### Adjacent records

likely to be unrelated

#### Pointers to records in records

- likely to be accessed
- likely to be far apart

#### Solution

- depth-first copy: slow pointer reversals
- hybrid copy algorithm



### costs

#### **Instructions**

- R reachable words in heap of size H
- BFS: c3 \* R
- No sweep
- Reclaimed: H/2 R words
- Instructions per word reclaimed: (c3 \* R) / (H/2 R)
- If (H >> R): cost per allocated word => 0
- If (H = 4R): c3 instructions per word allocated
- Solution: reduce portion of R to inspect => generational collection





### idea

#### Generations

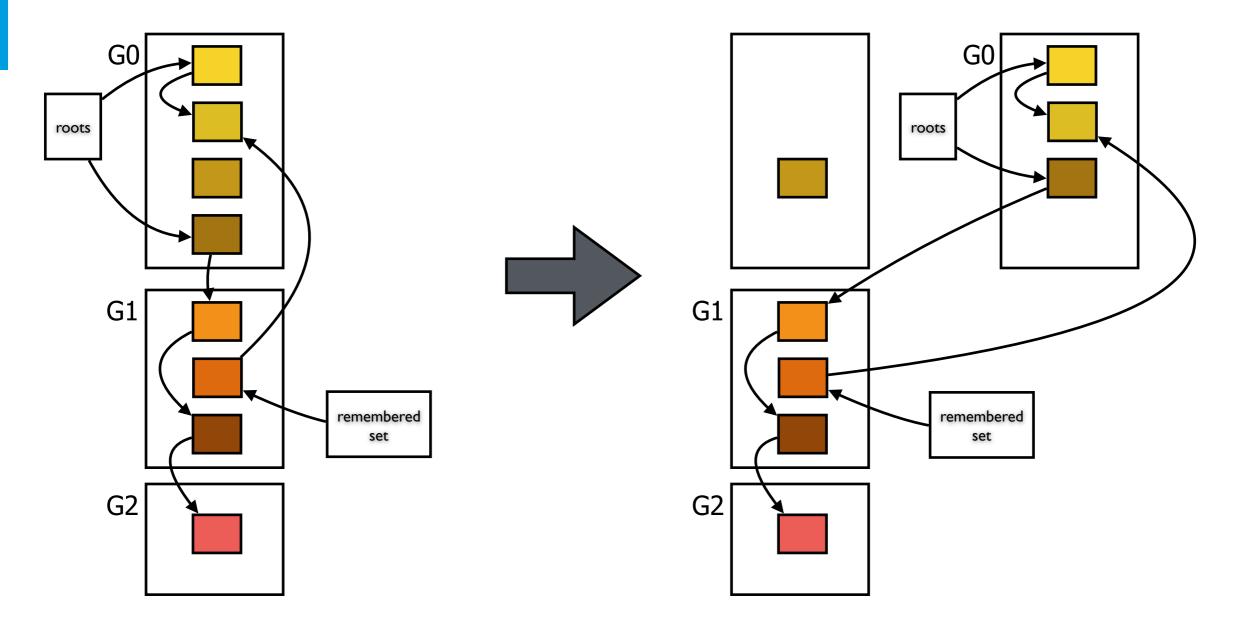
- young data: likely to die soon
- old data: likely to survive for more collections
- divide heap, collect younger generations more frequently

#### Collection

- roots: variables & pointers from older to younger generations
- preserve pointers to old generations
- promote objects to older generations



### idea





### costs

#### **Instructions**

- R reachable words in heap of size H
- BFS: c3 \* R
- No sweep
- 10% of youngest generation is live: H/R = 10
- Instructions per word reclaimed:  $(c3 * R) / (H - R) = (c3 * R) / (10R - R) \sim = c3/10$
- Adding to remembered set: 10 instructions per update



### Incremental Collection

### idea

#### Interrupt by garbage collector undesirable

interactive, real-time programs

#### Incremental / concurrent garbage collection

- interleave collector and mutator (program)
- incremental: per request of mutator
- concurrent: in between mutator operations

#### Tricolor marking

White: not visited

Grey: visited (marked or copied), children not visited

Black: object and children marked



# 

Summary



### Algorithms summary

How can we collect unreachable records on the heap?

- reference counts
- mark reachable records, sweep unreachable records
- copy reachable records

How can we reduce heap space needed for garbage collection?

- pointer-reversal
- breadth-first search
- hybrid algorithms



# Design Choices

### summary

#### Serial vs Parallel

garbage collection as sequential or parallel process

### Concurrent vs Stop-the-World

concurrently with application or stop application

### Compacting vs Non-compacting vs Copying

- compact collected space
- free list contains non-compacted chunks
- copy live objects to new space; from-space is non-fragmented



### Performance Metrics

### summary

### Throughput

percentage of time not spent in garbage collection

#### GC overhead

percentage of time spent in garbage collection

#### Pause time

length of time execution is stopped during garbage collection

### Frequency of collection

how often collection occurs

#### Footprint

measure of (heap) size



### Garbage Collection in Java HotSpot VM practice

#### Serial collector

- young generation: copying collection
- old generation: mark-sweep-compact collection

#### Parallel collector

- young generation: stop-the-world copying collection in parallel
- old generation: same as serial

### Parallel compacting collector

- young generation: same as parallel
- old generation: roots divided in threads, marking live objects in parallel, ...

### Concurrent Mark-Sweep (CMS) collector

- stop-the-world initial marking and re-marking
- concurrent marking and sweeping



### Literature

### learn more

Andrew W. Appel, Jens Palsberg. Modern Compiler Implementation in Java, 2nd edition, 2002.

Sun Microsystems. Memory Management in the Java HotSpotTM Virtual Machine, April 2006.



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