# EPICS Serial Howto

#### 2015-07-14

### 1 Brief notes

Based on http://www.aps.anl.gov/epics/modules/soft/asyn/R4-1/HowToDoSerial/tutorial.html NOTE: \$TOP is ~/project/EPICS/project/Metrolab in this case
Code can be found in ~/project/EPICS/project/docs/code/Metrolab

# 1.1 Support module. This is the "driver"

- 1. Make the skeleton
  - Make a folder and build the skeleton code

devGpib type is best for serial communivations

• Make some changes to configure/RELEASE

```
SNCSEQ=/data/EPICS/synApps/support/seq-2-2-1
ASYN = /home/longland/project/EPICS/synApps/support/asyn-4-26/
EPICS_BASE=/data/EPICS/base-3.15.2
```

• Make some changes to configure/CONFIG (uncomment  $CROSS_{COMPILERTARGETARCHS}$  and set it blank)

```
CROSS_COMPILER_TARGET_ARCHS =
```

- 2. Edit support code
  - Edit file MetrolabSup/devMetrolab.c

 Comment out unneeded DSET definitions (DSET<sub>AI</sub> must always be included) Note: "in" is "into EPICS". Out is "write out to device"

```
#define DSET_AI
                   devAiMetrolab
                                   // analog in
                                                  - into EPICS
                                  // analog out - out to device
#define DSET_AO
                   devAoMetrolab
#define DSET_BI
                   devBiMetrolab
                                  // binary in
#define DSET_BO
                   devBoMetrolab
                                  // binary out
#define DSET_SI
                   devSiMetrolab
                                  // string in
#define DSET_SO
                   devSoMetrolab
                                  // string out
#define DSET_LI
                   devLiMetrolab
                                  // long in
#define DSET_LO
                   devLoMetrolab
                                   // long out
```

• Define some strings to translate BI and BO numbers

```
static char *offOnList[] = { "Off","On" };
static struct devGpibNames offOn = { 2,offOnList,0,1 };

static char *remoteList[] = { "Remote","Remote" };
static struct devGpibNames remote = { 2,remoteList,0,1 };

static char *localList[] = { "Local","Local" };
static struct devGpibNames local = { 2,localList,0,1 };
```

- Comment out other unused string things (I uncommented intExtSsBmStopList stuff used by MBBI and MBBO)
- Same for EFAST strings (comment out userOffOn)
- Now is the important part. The command array. Each element in here is an individual command (see http://www.aps.anl.gov/epics/modules/soft/asyn/R4-1/devGpib.html#CreateInstrumentSupport)

```
/* Param 0 -- Read the displayed value */
{&DSET_SI,
                // DSET of command (read a string from the device)
GPIBREAD,
               // Type (read)
IB_Q_HIGH,
               // Priority (high)
"\x05",
               // Format string to send to device
               //
                              (ASCII HEX O5 - <ENQ>)
"%s",
               // String to interpret message
0, 200,
               // Error message length, return message length
NULL,
               // Conversion
0, 0, NULL,
               // P1, P2, and P3 used in conversion
               // Name strings
NULL,
```

```
NULL
                  // Input end-of-string
 },
  /* Param 1 - Remote control */
  {&DSET_BO, GPIBCMD, IB_Q_HIGH, "R", NULL, O, O,
       NULL, O, O, NULL, &remote, NULL},
  /* Param 2 - Local control */
  {&DSET_BO, GPIBCMD, IB_Q_HIGH, "L", NULL, O, O,
       NULL, O, O, NULL, &local, NULL},
  /* Param 3 -- Read and convert the displayed value */
                  \ensuremath{//} DSET of command (read a string from the device)
  {&DSET_SI,
  GPIBREAD,
                  // Type (read)
                  // Priority (high)
  IB_Q_HIGH,
                  // Format string to send to device (ASCII HEX 05 - <ENQ>)
   "\x05",
                  // String to interpret message (ignore a character then 9 cha
   "%*c%9s",
  0, 200,
                  // Error message length, return message length
                  // Conversion
  NULL,
  O, O, NULL,
                  // P1, P2, and P3 used in conversion
  NULL,
                  // Name strings
  NULL
                  // Input end-of-string
 },
• Modify the Metrolab/devMetrolab.dbd to include only the de-
 fined DSET definitions (you can comment out things using '#')
                    GPIB_IO, devAiMetrolab,
                                                 "Metrolab")
 device(ai,
 device(ao,
                    GPIB_IO, devAoMetrolab,
                                                 "Metrolab")
 device(bi,
                    GPIB_IO, devBiMetrolab,
                                                 "Metrolab")
                    GPIB_IO, devBoMetrolab,
 device(bo,
                                                 "Metrolab")
 device(stringin, GPIB_IO, devSiMetrolab,
                                                 "Metrolab")
 device(stringout, GPIB_IO, devSoMetrolab,
                                                 "Metrolab")
                    GPIB_IO, devLiMetrolab,
 device(longin,
                                                 "Metrolab")
                    GPIB_IO, devLoMetrolab,
                                                 "Metrolab")
 device(longout,
```

- include "asyn.dbd"
- Edit the support module database file
  - (a) Read the displayed value
  - (b) Put in remote control

```
(c) Put in local control
```

(d) Read the field (in Tesla) - this record auto updates

```
record(stringin, "$(P)$(R)NMR")
    field(DESC, "NMR Display Value")
    field(DTYP, "Metrolab")
    field(INP, "#L$(L) A$(A) @O")
    field(PINI, "YES")
}
record(bo, "$(P)$(R)Remote")
    field(DESC, "Remote mode")
    field(DTYP, "Metrolab")
    field(OUT, "#L$(L) A$(A) @1")
}
record(bo, "$(P)$(R)Local")
    field(DESC, "Local mode")
    field(DTYP, "Metrolab")
    field(OUT, "#L$(L) A$(A) @2")
    field(PINI, "YES")
    field(VAL, "1")
}
record(stringin, "$(P)$(R)Field")
    field(DESC, "Get the field value")
    field(DTYP, "Metrolab")
    field(PINI, "YES")
    field(SCAN, ".2 second")
    field(EGU, "Tesla")
    field(INP, "#L$(L) A$(A) @3")
}
```

• Edit the Makefile in (MetrolabSup/Makefile) to change the location of db file

```
DB_INSTALLS += ../devMetrolab.db
```

• Compile

```
cd MetrolabSup
make
```

- Check for libdevMetrolab.so in \$TOP/lib reminder that here, \$TOP=~/project/EPICS/project/Metrolab
- Check for devMetrolab.dbd in \$TOP/dbd
- Check for devMetrolab.db in \$TOP/db

## 1.2 Application. This is the code that runs

- 1. Make the application
  - Go to the \$TOP directory
     cd ~/project/EPICS/project/Metrolab
  - Make the base application and ioc boot directories

```
makeBaseApp.pl -t ioc Metrolab
makeBaseApp.pl -i -t ioc Metrolab
<Enter>
```

• Edit the Makefile in \$TOP/MetrolabApp/src/ to include the dbd created previously and the asyn driver

```
# Include dbd files from all support applications:
Metrolab_DBD += devMetrolab.dbd
Metrolab_DBD += drvAsynSerialPort.dbd
```

• Do the same for the libs (before Metrolab\_LIBS += \$(EPICS\_BASE\_IOC\_LIBS))

```
# Add all the support libraries needed by this IOC
Metrolab_LIBS += devMetrolab
Metrolab_LIBS += asyn
```

- Edit the Makefile in \$TOP/iocBoot/iocMetrolab include \$(EPICS\_BASE)/configure/RULES.ioc
- Compile

```
cd ~/project/EPICS/project/Metrolab
make
```

• Make sure it exists (there should be a Metrolab executable)

```
ls bin/linux-x86_64/
```

- 2. Make the startup script work!
  - Find the startup script
     cd iocBoot/iocMetrolab
  - Edit st.cmd
  - The records need to be loaded

```
## Load record instances
dbLoadRecords("db/devMetrolab.db","P=Metrolab:,R=,L=0,A=0")
```

• Get the serial port running

```
## Serial port
drvAsynSerialPortConfigure("L0","/dev/ttyUSB0",0,0,0)
asynSetOption("L0", -1, "baud", "19200")
asynSetOption("L0", -1, "bits", "8")
asynSetOption("L0", -1, "parity", "none")
asynSetOption("L0", -1, "stop", "1")
asynSetOption("L0", -1, "clocal", "Y")
asynSetOption("L0", -1, "crtscts", "N")
```

• Turn on debugging

```
## Debugging
asynSetTraceMask("L0",-1,0x9)
asynSetTraceIOMask("L0",-1,0x2)
```

• Make it executable chmod 755 st.cmd

• run!

./st.cmd