

# CONVEX OPTIMISATION ASSIGNMENT

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## Question 1

(a)

Problem (1) is convex. (Positive sum of norm functions is convex)  
Problem (2) is convex. (Norm is convex and Norm ball is convex)  
Problem (3) is convex. (Positive sum of norm function is convex)  
Problem (4) is convex. (Norm is convex and Norm ball is convex)

(b)

$$\begin{aligned}\nabla \text{Objective} &= \left( \frac{\partial \bar{x}^T (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I}) \bar{x} - \bar{y}^T \mathbf{A} \bar{x} + \bar{y}^T \bar{y}}{\partial \bar{x}} \right)^T \\ \implies \nabla \text{Objective} &= 2(\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I}) \bar{x} - 2\bar{y}^T \mathbf{A}\end{aligned}$$

(c)

$$\begin{aligned}\Delta \text{Objective} &= 0 \\ \implies \bar{x}^* &= (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y}\end{aligned}$$

(d)

Given,  $\|(\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y}\|_2 \leq 1$

$$\begin{aligned}\mathbf{A}^T (\bar{y} - \mathbf{A} \bar{x}_1^*) &= \mathbf{A}^T (\bar{y} - \mathbf{A} (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y}) = \mathbf{A}^T \bar{y} - (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I}) (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y} + \alpha (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y} \\ \implies \mathbf{A}^T (\bar{y} - \mathbf{A} \bar{x}_1^*) &= \alpha (\mathbf{A}^T \mathbf{A} + \alpha \mathbf{I})^{-1} \mathbf{A}^T \bar{y} \implies \|\mathbf{A}^T (\bar{y} - \mathbf{A} \bar{x}_1^*)\|_2 \leq \alpha\end{aligned}$$

Thus  $\bar{x}_1^*$  is a feasible point in Problem (2). Therefore the cost with this point will always be less than optimal cost,  $\implies \|\bar{x}_2^*\|_2 \leq \|\bar{x}_1^*\|_2$

(e)

## Question 2

$$f_2(\bar{x}) = \sum_i \|\mathbf{A}_i \bar{x} - \bar{b}\|_2$$

Apply epigraph trick on the objective,

$$\begin{aligned} & \|\mathbf{A}_i \bar{x} - \bar{b}\|_2 \leq t_i \\ \min \quad & \bar{\mathbf{1}}^T \bar{t} \\ \text{s.t.} \quad & \|\mathbf{A}_i \bar{x} - \bar{b}\|_2 \leq t_i \end{aligned}$$

The above is in form of *SOCP*.

$$f_1(\bar{x}) = \sum_i \|\mathbf{A}_i \bar{x} - \bar{b}\|_1$$

$$\begin{aligned} & \|\mathbf{A}_i \bar{x} - \bar{b}\|_1 \leq \bar{\mathbf{1}}^T \bar{t}_i \\ \implies \quad & \mathbf{A}_i \bar{x} - \bar{b} \leq \bar{t}_i; \mathbf{A}_i \bar{x} - \bar{b} \geq -\bar{t}_i \\ \min \quad & \sum_i \bar{\mathbf{1}}^T \bar{t}_i \equiv T\bar{\mathbf{1}} \\ \text{s.t.} \quad & \mathbf{A}_i \bar{x} - \bar{b} \leq \bar{t}_i \\ & \mathbf{A}_i \bar{x} - \bar{b} \geq -\bar{t}_i \end{aligned}$$

The above formulation is a *LP*.

$$f_\infty(\bar{x}) = \sum_i \|\mathbf{A}_i \bar{x} - \bar{b}\|_\infty$$

$$\begin{aligned} & \|\mathbf{A}_i \bar{x} - \bar{b}\|_\infty \leq t_i \\ \implies \quad & \mathbf{A}_i \bar{x} - \bar{b} \leq \bar{\mathbf{1}} t_i; \mathbf{A}_i \bar{x} - \bar{b} \geq -\bar{\mathbf{1}} t_i \\ \min \quad & \bar{\mathbf{1}}^T \bar{t} \\ \text{s.t.} \quad & \mathbf{A}_i \bar{x} - \bar{b} \leq \bar{t}_i \\ & \mathbf{A}_i \bar{x} - \bar{b} \geq -\bar{t}_i \end{aligned}$$

The above formulation is a *LP*.

## Question 3

(a)

To prove that the objective function is quasi-concave we need to show that all  $\alpha$  level supersets are convex.

$$\begin{aligned} & \frac{\bar{\mu}^T \bar{x}}{\|\mathbf{V} \bar{x}\|_2} \geq \alpha \\ \implies \quad & \|\mathbf{V} \bar{x}\|_2 \leq \frac{1}{\alpha} \bar{\mu}^T \bar{x} \end{aligned}$$

Given that  $\mathbf{V}$  is symmetric which means quadratic part is convex and the above constraints look like SOCP constraints thus it is convex.

(b)

$$\begin{aligned}
\bar{z} &= \frac{\bar{x}}{\bar{\mu}^T \bar{x}} \\
\Rightarrow \frac{\bar{z}}{\bar{1}^T \bar{z}} &= \frac{\frac{\bar{x}}{\bar{\mu}^T \bar{x}}}{\frac{\bar{1}^T \bar{x}}{\bar{\mu}^T \bar{x}}} \\
\Rightarrow \boxed{\bar{x} = \frac{\bar{z}}{\bar{1}^T \bar{z}}} \\
\frac{\bar{\mu}^T \bar{x}}{\|\mathbf{V}\bar{x}\|_2} &= \frac{\bar{\mu}^T \frac{\bar{z}}{\bar{1}^T \bar{z}}}{\|\mathbf{V} \frac{\bar{z}}{\bar{1}^T \bar{z}}\|_2} = \frac{\text{sgn}(\bar{1}^T \bar{z})}{\|\mathbf{V}\bar{z}\|_2}
\end{aligned}$$

Given  $\bar{\mu}^T \bar{x} \geq 0$  and  $\bar{1}^T \bar{x} = 1$  which means  $\bar{1}^T \bar{z} = \frac{1}{\bar{\mu}^T \bar{x}} > 0$ .

$$\begin{aligned}
\Rightarrow \boxed{\frac{\bar{\mu}^T \bar{x}}{\|\mathbf{V}\bar{x}\|_2} = \frac{1}{\|\mathbf{V}\bar{z}\|_2}} \\
\|\bar{x}\|_1 \leq L \Rightarrow \left\| \frac{\bar{z}}{\bar{1}^T \bar{z}} \right\|_1 \leq L \\
\|\bar{z}\|_1 \leq L \bar{1}^T \bar{z}
\end{aligned}$$

Now transformed problem is,

$$\begin{aligned}
\min \quad & \|\mathbf{V}\bar{z}\|_2 \\
\text{s.t.} \quad & \|\bar{z}\|_1 \leq L \bar{1}^T \bar{z} \\
& \bar{1}^T \bar{z} \geq 0
\end{aligned}$$

The above transformed problem has both convex objective and constraints thus it is convex optimisation problem.

## Question 4

(a)

*Lemma:*  $(\mathbf{A} + \mathbf{B})^{-1} = \mathbf{A}^{-1} - (I + \mathbf{A}^{-1}\mathbf{B})^{-1}\mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}$ .

If  $g(x)$  is convex then so is  $\bar{a}^T g(x) \bar{a}$  because the map linear with respect to  $g(x)$ .

Now it is sufficient to prove the convexity of  $\mathbf{X}^{-1}$ . We do this by contradiction assume that the function is not convex which means,

$$\begin{aligned}
(\alpha \mathbf{A})^{-1} + ((1 - \alpha) \mathbf{B})^{-1} &< (\alpha \mathbf{A} + (1 - \alpha) \mathbf{B})^{-1} \\
\frac{1}{\alpha} \mathbf{A}^{-1} + \frac{1}{1 - \alpha} \mathbf{B}^{-1} &< \alpha \mathbf{A}^{-1} - \frac{1 - \alpha}{\alpha^2} (I + \frac{1 - \alpha}{\alpha} \mathbf{A}^{-1} \mathbf{B})^{-1} \mathbf{A}^{-1} \mathbf{B} \mathbf{A}^{-1}
\end{aligned}$$

Since the matrices are positive semi-definite multiplication on inequality will not change the sign.

$$\begin{aligned}
\frac{1}{1 - \alpha} \mathbf{B}^{-1} &< -\frac{1 - \alpha}{\alpha^2} (I + \frac{1 - \alpha}{\alpha} \mathbf{A}^{-1} \mathbf{B})^{-1} \mathbf{A}^{-1} \mathbf{B} \mathbf{A}^{-1} \\
\Rightarrow \left( \frac{1 - \alpha}{\alpha} \mathbf{A}^{-1} \mathbf{B} \right)^2 &+ \left( \frac{1 - \alpha}{\alpha} \mathbf{A}^{-1} \mathbf{B} \right) + I < 0
\end{aligned}$$

Since  $\mathbf{A} \geq 0$  and  $\mathbf{B} \geq 0$  so is  $\mathbf{A}^{-1} \mathbf{B} \geq 0 \Rightarrow \frac{1 - \alpha}{\alpha} \mathbf{A}^{-1} \mathbf{B} \geq 0$ . Therefore the above obtained sum is just sum of positive semi definite matrices which is positive semi definite but we got negative definite which is a contradiction. Thus our assumption is wrong. Therefore  $\mathbf{X}^{-1}$  is convex and so is  $\bar{a}^T \mathbf{X}^{-1} \bar{a}$ .

(b)

Let  $\bar{a}_i$  be  $i$ th column of identity matrix then from previous results  $\bar{a}_i^T \mathbf{X}^{-1} \bar{a}_i$  is convex, this function just picks  $(i, i)$  element of  $\mathbf{X}^{-1}$  which is a diagonal element. Thus diagonal elements are convex combination of  $\mathbf{X}$ .

(c)

$\text{trace}(\mathbf{X}^{-1})$  is just sum of diagonal elements of  $\mathbf{X}^{-1}$  which are individually convex, since sum of convex functions are convex.  $\text{trace}(\mathbf{X}^{-1})$  is convex.

(d)

Let transform this problem in epigraph problem.

$$\begin{aligned} \min_{t, \mathbf{X}} \quad & t \\ \text{s.t} \quad & t \geq \bar{a}^T \mathbf{X}^{-1} \bar{a} \equiv \begin{bmatrix} t & \bar{a}^T \\ \bar{a} & \mathbf{X} \end{bmatrix} \geq 0 \\ & \mathbf{A}\mathbf{X} = \mathbf{B} \\ & \mathbf{X} \geq 0 \end{aligned}$$

Now we say  $\mathbf{Z} = \begin{bmatrix} \mathbf{X} \\ \bar{u}^T \end{bmatrix}$ ,  $\bar{u} = \begin{bmatrix} t \\ 0 \\ \cdot \\ 0 \end{bmatrix}$

$$\begin{aligned} \begin{bmatrix} t & \bar{a}^T \\ \bar{a} & \mathbf{X} \end{bmatrix} \geq 0 &\implies \mathbf{U}\mathbf{Z} + \mathbf{V} \geq 0 \\ \mathbf{U} &= \begin{bmatrix} 0 & 0 & 0 & \cdot & \cdot & \cdot & 1 \\ 1 & 1 & 1 & \cdot & \cdot & \cdot & 0 \end{bmatrix} \\ \mathbf{V} &= \begin{bmatrix} 0 & \bar{a}^T \\ \bar{a} & \mathbf{0} \end{bmatrix} \\ \mathbf{A}\mathbf{X} = \mathbf{B} &\implies \mathbf{W}\mathbf{Z} = \mathbf{B} \\ \mathbf{W} &= [\mathbf{A} \quad \mathbf{0}] \\ \mathbf{X} \geq 0 &\implies \mathbf{Y}\mathbf{Z} \geq 0 \\ \mathbf{Y} &= [I \quad \mathbf{0}] \end{aligned}$$

Final SDP problem is,

$$\begin{aligned} \min_{t, \mathbf{X}} \quad & \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \mathbf{Z} \\ \text{s.t} \quad & \begin{bmatrix} \mathbf{U} \\ \mathbf{W} \\ -\mathbf{W} \\ \mathbf{Y} \end{bmatrix} \mathbf{Z} \geq - \begin{bmatrix} \mathbf{V} \\ \mathbf{B} \\ -\mathbf{B} \\ \mathbf{0} \end{bmatrix} \end{aligned}$$

(e)

This reformulation is similar to previous one we can rewrite trace as written in (c).

$$\text{trace}(\mathbf{X}^{-1}) = \sum_i \bar{a}_i^T \mathbf{X}^{-1} \bar{a}_i$$

Where  $\bar{a}_i$  is ith column of Identity matrix. Now we apply the same epigraph trick,

$$\begin{aligned} \bar{a}_i^T \mathbf{X}^{-1} \bar{a}_i &\leq t_i \\ \begin{bmatrix} t_i & \bar{a}_i^T \\ \bar{a}_i & \mathbf{X} \end{bmatrix} &\geq 0 \end{aligned}$$

$$\begin{aligned} \min_{t, \mathbf{X}} \quad & \begin{bmatrix} \bar{0}^T & 1 \end{bmatrix} \mathbf{Z} \bar{1} \\ \text{s.t} \quad & \begin{bmatrix} \mathbf{U}_1 \\ \mathbf{U}_2 \\ \mathbf{U}_3 \\ \cdot \\ \mathbf{U}_n \\ \mathbf{W} \\ -\mathbf{W} \\ \mathbf{Y} \end{bmatrix} \mathbf{Z} \geq - \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \\ \mathbf{V}_3 \\ \cdot \\ \mathbf{V}_n \\ \mathbf{B} \\ -\mathbf{B} \\ \mathbf{0} \end{bmatrix} \end{aligned}$$

Where,  $\mathbf{Z} = \begin{bmatrix} \mathbf{X} \\ \bar{t}^T \end{bmatrix}$

## Question 5

## Question 6

Primal is

$$\begin{aligned} \bar{x} &= \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ \min \quad & \bar{x}^T \begin{bmatrix} 1 & -0.5 \\ -0.5 & 2 \end{bmatrix} \bar{x} + [-1 \quad 0] \bar{x} \\ \text{s.t} \quad & \begin{bmatrix} 1 & -2 \\ 1 & 4 \\ 5 & -76 \end{bmatrix} \bar{x} \leq \begin{bmatrix} u_1 \\ u_2 \\ 1 \end{bmatrix} \end{aligned}$$

Dual is

(a)

The above objective is in quadratic form and eigen decomposition of the hessian is

$$\begin{bmatrix} 1 & -0.5 \\ -0.5 & 2 \end{bmatrix} = \begin{bmatrix} -0.92387953 & 0.38268343 \\ -0.38268343 & -0.92387953 \end{bmatrix} \begin{bmatrix} 0.79289322 & 0 \\ 0 & 2.20710678 \end{bmatrix} \begin{bmatrix} -0.92387953 & -0.38268343 \\ 0.38268343 & -0.92387953 \end{bmatrix}$$

Here both eigen values are positive, which implies that hessian is positive semidefnite. With linear constraints, The problem is convex and is a QP.

(b)

After solving the problem with *CVXPY* we get,

$$\begin{aligned} x_1^* &= -3; x_2^* = 0 \\ \lambda_1^* &= 5.167; \lambda_2^* = 1.834; \lambda_3^* = 0 \end{aligned}$$

(c)

**KKT Conditions**

1.  $f_i(x^*) \leq 0$ , Satisfied.

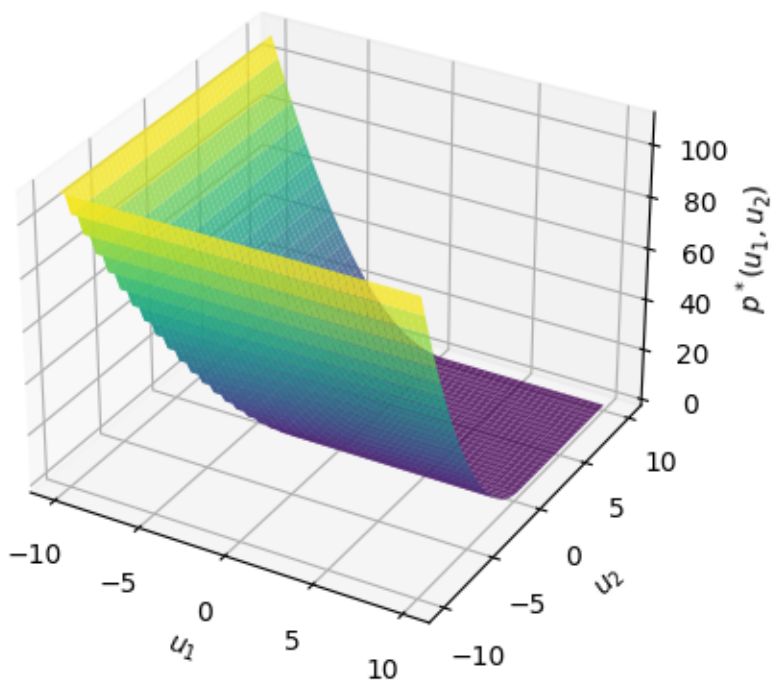
$$\begin{bmatrix} 1 & -2 \\ 1 & 4 \\ 5 & -76 \end{bmatrix} \begin{bmatrix} -3 \\ 0 \end{bmatrix} \leq \begin{bmatrix} -2 \\ -3 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} -3 \\ -3 \\ -15 \end{bmatrix} \leq \begin{bmatrix} -2 \\ -3 \\ 1 \end{bmatrix}$$

2.  $\lambda_i^* \geq 0$ , Satisfied.

3.  $\lambda_i^* f_i(x^*) = 0$ , Satisfied.

$$\begin{bmatrix} 5.167 & 1.834 & 0 \end{bmatrix} \left( \begin{bmatrix} -3 \\ -3 \\ -15 \end{bmatrix} - \begin{bmatrix} -2 \\ -3 \\ 1 \end{bmatrix} \right) = 0$$

(d)



(e)

From above graph it seems like  $p^*(u_1, u_2)$  is a convex function.

(f)

Numerically derivated at the given point is 0.

