Flattening Irregular Nested Parallelism

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Parallel Basic Blocks

Flattening Nested and Irregular Parallelism
Irregular Multi-Dimensional Array Representation
Flattening at A High-Level
Rules For Flattening
Flattening Quicksort
Flattening Prime-Number (Sieve) Computation

- zip : $[n]\alpha_1 \rightarrow [n]\alpha_2 \rightarrow [n](\alpha_1, \alpha_2)$
- zip $[a_1,...,a_n]$ $[b_1,...,b_n] \equiv [(a_1,b_1),...,(a_n,b_n)],$

```
■ zip : [n]\alpha_1 \to [n]\alpha_2 \to [n](\alpha_1, \alpha_2)

■ zip [a_1, ..., a_n] [b_1, ..., b_n] \equiv [(a_1, b_1), ..., (a_n, b_n)],

■ unzip : [n](\alpha_1, \alpha_2) \to ([n]\alpha_1, [n]\alpha_2)

■ unzip [(a_1, b_1), ..., (a_n, b_n)] \equiv ([a_1, ..., a_n], [b_1, ..., b_n]),
```

In some sense zip/unzip are syntactic sugar

- zip : $[n]\alpha_1 \rightarrow [n]\alpha_2 \rightarrow [n](\alpha_1, \alpha_2)$
- zip $[a_1,...,a_n]$ $[b_1,...,b_n] \equiv [(a_1,b_1),...,(a_n,b_n)],$
- \blacksquare unzip : $[n](\alpha_1,\alpha_2) \rightarrow ([n]\alpha_1,[n]\alpha_2)$
- unzip $[(a_1,b_1),...,(a_n,b_n)] \equiv ([a_1,...,a_n],[b_1,...,b_n]),$
- In some sense zip/unzip are syntactic sugar
- replicate : (n: int) $\rightarrow \alpha \rightarrow [n]\alpha$
- replicate n a \equiv [a, a,..., a],

```
■ zip : [n]\alpha_1 \to [n]\alpha_2 \to [n](\alpha_1, \alpha_2)

■ zip [a_1, ..., a_n] [b_1, ..., b_n] \equiv [(a_1, b_1), ..., (a_n, b_n)],

■ unzip : [n](\alpha_1, \alpha_2) \to ([n]\alpha_1, [n]\alpha_2)

■ unzip [(a_1, b_1), ..., (a_n, b_n)] \equiv ([a_1, ..., a_n], [b_1, ..., b_n]),
```

• replicate : (n: int) $\rightarrow \alpha \rightarrow \lceil n \rceil \alpha$

In some sense zip/unzip are syntactic sugar

- replicate n a \equiv [a, a,..., a],
- iota : $(n: int) \rightarrow [n]int$
- iota $n \equiv [0, 1, ..., n-1]$

Note: in Haskell zip does not expect same-length arrays; in Futhark it does!

Map, Reduce, and Scan Types and Semantics

- [n] α denotes the type of an array of n elements of type α .
- map : $(\alpha \to \beta) \to [n]\alpha \to [n]\beta$ map f $[x_1, ..., x_n] = [f x_1, ..., f x_n]$, i.e., $x_i : \alpha, \forall i$, and f : $\alpha \to \beta$.
- reduce : $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to \alpha$ reduce \odot e $[x_1, x_2, ..., x_n]$ = $e \odot x_1 \odot x_2 \odot ... \odot x_n$, i.e., e: α , x_i : α , $\forall i$, and \odot : $\alpha \to \alpha \to \alpha$.
- $\operatorname{scan}^{exc}$: $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to [n]\alpha$ $\operatorname{scan}^{exc} \odot \operatorname{e} [x_1, \dots, x_n] = [\operatorname{e}, \operatorname{e} \odot x_1, \dots, \operatorname{e} \odot x_1 \odot \dots x_{n-1}]$ i.e., $\operatorname{e} : \alpha$, $x_i : \alpha, \forall i$, and $\odot : \alpha \to \alpha \to \alpha$.
- $\operatorname{scan}^{inc}$: $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to [n]\alpha$ $\operatorname{scan}^{inc}$ ⊙ e $[x_1, \dots, x_n]$ = $[\operatorname{e} \odot x_1, \dots, \operatorname{e} \odot x_1 \odot \dots x_n]$ i.e., $\operatorname{e} : \alpha$, x_i : $\alpha, \forall i$, and \odot : $\alpha \to \alpha \to \alpha$.

Map2, Filter

- $\blacksquare map2: (\alpha_1 \to \alpha_2 \to \beta) \to [n]\alpha_1 \to [n]\alpha_2 \to [n]\beta$
- $\begin{array}{l} \blacksquare \ \mathsf{map2} \ \odot \ [\mathsf{a}_1,\ldots,\mathsf{a}_n] \ [\mathsf{b}_1,\ldots,\mathsf{b}_n] \ \equiv \\ [\mathsf{a}_1\odot\mathsf{b}_1,\ldots,\mathsf{a}_n\odot\mathsf{b}_n] \end{array}$
- map3 ...

Map2, Filter

- $\blacksquare map2: (\alpha_1 \to \alpha_2 \to \beta) \to [n]\alpha_1 \to [n]\alpha_2 \to [n]\beta$
- $\begin{array}{l} \blacksquare \ \mathsf{map2} \ \odot \ [\mathsf{a}_1,\ldots,\mathsf{a}_n] \ [\mathsf{b}_1,\ldots,\mathsf{b}_n] \ \equiv \\ [\mathsf{a}_1\odot\mathsf{b}_1,\ldots,\mathsf{a}_n\odot\mathsf{b}_n] \end{array}$
- map3 ...
- filter : $(\alpha \rightarrow \mathsf{Bool}) \rightarrow [\mathsf{n}]\alpha \rightarrow [\mathsf{m}]\alpha \ (\mathsf{m} \le \mathsf{n})$
- filter p $[a_1, \ldots, a_n] = [a_{k_1}, \ldots, a_{k_m}]$ such that $k_1 < k_2 < \ldots < k_m$, and denoting $\overline{k} = k_1, \ldots, k_m$, we have $(p \ a_j = = true) \ \forall j \in \overline{k}$, and $(p \ a_j = = false) \ \forall j \notin \overline{k}$.

Note: in Haskell map2, map3 do not expect same-length arrays; in Futhark they do!

Scatter: A Parallel Write Operator

Scatter updates in parallel a base array with a set of values at specified indices:

```
scatter: *[m]\alpha \to [n]int \to [n]\alpha \to *[m]\alpha
A (data vector) =[b0, b1, b2, b3]
I (index vector) =[2, 4, 1, -1]
X (input array) =[a0, a1, a2, a3, a4, a5]
scatter X I A =[a0, b2, b0, a3, b1, a5]
```

Scatter: A Parallel Write Operator

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X (input array) =[a0, a1, a2, a3, a4, a5]
scatter X I A =[a0, b2, b0, a3, b1, a5]
```

```
scatter has D(n) = \Theta(1) and W(n) = \Theta(n), i.e., requires n update operations (n is the size of I or A, not of X!).
```

- 1 Array X is consumed by scatter; following uses of X are illegal!
- 2 Similarly, X can alias neither I nor A!

In Futhark, scatter check and ignores the indices that are out of bounds (no update is performed on those). This is useful for padding the iteration space in order to obtain regular parallelism.

Partition2/Filter Implementation

```
partition2: (\alpha \rightarrow Bool) \rightarrow \lceil n \rceil \alpha \rightarrow (\lceil n \rceil i 32, \lceil n \rceil \alpha)
 In result, the elements satisfying the predicate occur before the
 others. Can be implemented by means of map, scan, scatter.
let partition 2 't [n] (dummy: t)
                                                   Assume X = [5,4,2,3,7,8], and
       (cond: t \rightarrow bool) (X: [n]t) :
                                                   cond is T(rue) for even nums.
                          (i32. [n]t) =
 let cs = map cond X
 let tfs = map (\setminus f\rightarrowif f then 1
                              else 0) cs
 let isT = scan (+) 0 tfs
 let i = isT[n-1]
 let ffs = map (f \rightarrow if f then 0
                             else 1) cs
 let is F = map(+i) < scan(+) 0 ffs
 let inds=map (\((c,iT,iF) \rightarrow
                      if c then iT-1
                            else iF-1
```

) (zip3 cs isT isF)

let tmp = replicate n dummy
in (i, scatter tmp inds X)

Partition2/Filter Implementation

```
partition2: (\alpha \to Bool) \to [n]\alpha \to ([n]i32,[n]\alpha)
In result, the elements satisfying the predicate occur before the others. Can be implemented by means of map, scan, scatter.
```

```
let partition 2 't [n] (dummy: t)
                                             Assume X = [5,4,2,3,7,8], and
      (cond: t \rightarrow bool) (X: [n]t) :
                                             cond is T(rue) for even nums.
                       (i32, [n]t) =
 let cs = map cond X
                                             cs = [F, T, T, F, F, T]
 let tfs = map (\setminus f\rightarrowif f then 1
                                             tfs = [0, 1, 1, 0, 0, 1]
                           else 0) cs
 let isT = scan (+) 0 tfs
                                             isT = [0, 1, 2, 2, 2, 3]
 let i = isT[n-1]
 let ffs = map (f \rightarrow if f then 0
                                             ffs = [1, 0, 0, 1, 1, 0]
                          else 1) cs
                                             isF = [4, 4, 4, 5, 6, 6]
 let is F = map(+i) < scan(+) 0 ffs
 let inds=map (\((c,iT,iF) \rightarrow
                                              inds= [3, 0, 1, 4, 5, 2]
                   if c then iT-1
                         else iF-1
               ) (zip3 cs isT isF)
                                             flags = [3, 0, 0, 3, 0, 0]
 let tmp = replicate n dummy
                                              Result = [4, 2, 8, 5, 3, 7]
 in (i, scatter tmp inds X)
```

Segmented Scan Is a Sort of Scan

Futhark Implementation:

```
let sgmscan 't \lceil n \rceil (op: t->t->t) (ne: t)
                (flq : \lceil n \rceil i 32) (arr : \lceil n \rceil t) : \lceil n \rceil t =
  let flqs vals =
    scan (\ (f1, x1) (f2,x2) ->
              let f = f1 \mid f2 in
              if f2 != 0 then (f, x2)
              else (f, op x1 x2) )
           (0,ne) (zip flq arr)
  let ( , vals) = unzip flqs vals
  in vals
```

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Shape-Based Representation

■ Two dimensional arrays: arr = [[1,2,3], [4], [], [5,6]]⇒ $S_{arr}^0 = [4]$ $S_{arr}^1 = [3, 1, 0, 2]$ $D_{arr} = [1, 2, 3, 4, 5, 6]$

Three dimensional arrays:

Shape-Based Representation

■ Two dimensional arrays: arr = [[1,2,3], [4], [], [5,6]] ⇒ S⁰_{arr} = [4] S¹_{arr} = [3, 1, 0, 2] D_{arr} = [1, 2, 3, 4, 5, 6]

Three dimensional arrays:
arr = [[], [[1, 2, 3], [4], [], [5, 6]], [[7], [], [8, 9, 10]]

```
S_{arr}^{0} = [3] 

S_{arr}^{1} = [0, 4, 3] 

S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3] 

flen_{arr} = 10 

D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Assume a n-dimensional array; The following invariant holds:

```
length S_{arr}^i = reduce (+) 0 S_{arr}^{i-1}, \forall 1 \leq i < n length D_{arr} = reduce (+) 0 S_{arr}^{n-1}
```

Flat Representation: Auxiliary Structures

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

• Offset Indices (B): segment-start offset in the flat data: $B_{arr}^1 = [0, 0, 6]$ $B_{arr}^2 = [0, 3, 4, 4, 6, 7, 7]$

■ Flag Array (F): start of a segment indicated by a value !=0 for example used for segmented scan operations: $F_{arr}^{1} = [1, 0, 0, 0, 0, 0, 1, 0, 0, 0]$ $F_{arr}^{2} = [1, 0, 0, 1, 1, 0, 1, 1, 0, 0]$

Segment and Inner indices (II):

Auxiliary structures are useful to optimize the replication of values.

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let rss = map2 (\ xs y → map (+y) xs ) xss ys

⇒
rss = [ map (+4) [1,2,3], map (+2) [], map (+1) [5,7] ]
rss = [ [5,6,7], [], [6,8] ]
```

Traditional flattening would replicate the values of x:

```
let (S_{yss}^1, D_{yss}) = \mathcal{F}(\text{map2 } (\xs y \rightarrow \text{replicate (length xs) y}) \text{ xss ys})
let D_{rss} = \text{map2 } (\xs y \rightarrow \text{x + y}) D_{xss} D_{yss}
\Rightarrow D_{xss} = [1, 2, 3, 5, 7] \\ + + + + + + + D_{yss} = [4, 4, 4, 1, 1] \\ = = = = = = D_{rss} = [5, 6, 7, 6, 8]
```

Auxiliary structures are useful to optimize the replication of values.

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let rss = map2 (\ xs y → map (+y) xs ) xss ys

⇒
rss = [ map (+4) [1,2,3], map (+2) [], map (+1) [5,7] ]
rss = [ [5,6,7], [], [6,8] ]
```

Using the auxiliary structures we indirectly access other arrays:

```
let D_{rss} = map2 (\ x sgmind → x + ys[sgmind]) D_{xss} ||1_{rss} ⇒ S_{rss}^1 = [3, 0, 2] ||1_{rss}^1 = [0, 0, 0, 2, 2] ||D_{xss} = [1, 2, 3, 5, 7] ||D_{rss} = [1+4, 2+4, 3+4, 5+1, 7+1] = [5, 6, 7, 6, 8]
```

But what have we gained? Creating II_{rss}^1 is as expensive as xss ...

Auxiliary structures are useful to optimize replication:

- they depend only on the shape of the result (created once)
- can indirectly access several lower-dimensional arrays, sharing parallel dimensions!

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let zs = [ 1, 2, 3 ]
let rss = map3 (\ xs y z → map (\x → x*y + z ) xs ) xss ys zs
⇒
rss = [ [5,9,13], [], [8,10] ]
```

Using the auxiliary structures we indirectly access other arrays:

```
let D_{rss} = map2 (\ y sgmind -> x*ys[sgmind] + zs[sgmind]) D_{xss} ||1_{rss} = |0, 0, 0, 2, 2| D_{xss} = [1, 2, 3, 5, 7] D_{rss} = [1*4+1, 2*4+1, 3*4+1, 5*1+3, 7*1+3] = [5, 9, 13, 8, 10]
```

We build II_{rss}^1 once and reuse it twice; also improves locality!

```
Nested-Execution Example:
let xss = [1,3], [2]
let yss = [2], [4,5]
let rss = map2 (\xspace xs ys \xspace xs map (\xspace xs ys \xspace xs map (\xspace xs ys \xspace xs ys \xspace xs map (\xspace xs ys \xspace xs ys \xspace xs map (\xspace xs ys \xspace xs ys \xspace xs ys \xspace xs map (\xspace xs ys \xspace xs ys \xspace xs \xspace
\Rightarrow
rss = [[3],[5]],[[6,7]]
Using the auxiliary structures we indirectly access other arrays:
let D_{rss} = map3(\ s1 \ s2 \ s3 \rightarrow let \ ind_x = B_{xss}^1[s1] + s2
                                                                                                                          let ind_y = B_{vss}^{1}[s1] + s3
                                                                                                                         in X[ind_x] + Y[ind_y]
                                                             | | |_{rss}^{1} |_{rss}^{2} | |_{rss}^{3} |
\Rightarrow
B_{vcc}^1 = [0, 2]
B_{vss}^2 = [0, 1]
\prod_{r=1}^{1} = [0, 0, 1, 1]
\prod_{r \in S}^{2} = [0, 1, 0, 0]
\prod_{r=1}^{3} = [0, 0, 0, 1]
D_{rss} = [D_{xss}[0+0]+D_{vss}[0+0], D_{xss}[0+1]+D_{vss}[0+0]
                           , D_{xss}[2+0]+D_{vss}[1+0], D_{xss}[2+0]+D_{vss}[1+1]
D_{rss} = [1+2, 3+2, 2+4, 2+5] = [3, 5, 6, 7]
```

Constructing the Offset Indices (B)

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Offset Indices (B): segment-start offset in the flat data:

```
B_{arr}^1 = [0, 0, 6]

B_{arr}^2 = [0, 3, 4, 4, 6, 7, 7]
```

How to construct Offset Indices (B)?

By using exclusive scan on the shape!

$$B_{arr}^2 = scan^{exc}$$
 (+) 0 S_{arr}^2 — [0, 3, 4, 4, 6, 7, 7]

$$B_{arr}^1 = scan^{exc}$$
 (+) 0 S_{arr}^1 — [0, 0, 4]
|> map (\i i -> B_{arr}^2 [i]) — [0, 0, 6]

Constructing the Flag Array

From now on, we discuss only TWO-dimensional irregular arrays!

```
mkFlagArray 't [m]
           (aoa_shp: [m]i32) (zero: t) — aoa_shp = [0,3,1,0,4,2,0]
           (aoa\_val: [m]t) : []i32 = --aoa\_val = [1,1,1,1,1,1,1]
 let shp_rot = map (i \rightarrow if i ==0 then zero—shp_rot = [0,0,3,1,0,4,2]
                        else aoa_shp[i-1]
                   ) (iota m)
 let shp_scn = scan (+) 0 shp_rot — shp_scn = [0,0,3,4,4,8,10]
 let aoa_len = shp_scn[m-1]+aoa_shp[m-1]—aoa_len = 10
 let shp_ind = map2 (\ shp_ind -> --shp_ind =
                      if shp==0 then -1 — [-1,0,3,-1,4,8,-1]
                      else ind —scatter
                    ) aoa_shp shp_scn — [0,0,0,0,0,0,0,0,0,0]
 in scatter (replicate aoa_len zero) — [-1,0,3,-1,4,8,-1]
            shp_ind aoa_val
                                 — [1,1,1,1,1,1,1]
                                     -- F = [1,0,0,1,1,0,0,0,1,0]
```

Why do we need aoa_val?

Constructing the Flag Array

From now on, we discuss only TWO-dimensional irregular arrays!

```
mkFlagArray 't [m]
           (aoa_shp: [m]i32) (zero: t) — aoa_shp = [0,3,1,0,4,2,0]
           (aoa\_val: [m]t) : []i32 = --aoa\_val = [1,1,1,1,1,1,1]
 let shp_rot = map (i \rightarrow if i ==0 then zero—shp_rot = [0,0,3,1,0,4,2]
                        else aoa_shp[i-1]
                   ) (iota m)
 let shp_scn = scan (+) 0 shp_rot — shp_scn = [0,0,3,4,4,8,10]
 let aoa_len = shp_scn[m-1]+aoa_shp[m-1]—aoa_len = 10
 let shp_ind = map2 (\ shp_ind -> --shp_ind =
                      if shp==0 then -1 — [-1,0,3,-1,4,8,-1]
                      else ind —scatter
                    ) aoa_shp shp_scn — [0,0,0,0,0,0,0,0,0,0]
 in scatter (replicate aoa_len zero) — [-1,0,3,-1,4,8,-1]
            shp_ind aoa_val
                                  — [1,1,1,1,1,1,1]
                                     -- F = [1,0,0,1,1,0,0,0,1,0]
```

Why do we need aoa_val?

Because there are many valid flag arrays, i.e., the start of the segment can be denoted by any value different than zero!

Constructing the Segment and Inner Indices

From now on, we discuss only TWO-dimensional irregular arrays!

```
arr = [1,2,3], [4], [], [5,6], [7], [], [8,9,10]
S_{arr}^{0} = [7]
S_{arr}^1 = [3, 1, 0, 2, 1, 0, 3]
flen_{arr} = reduce (+) 0 S_{arr}^1 = 10
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
Segment and Inner indices (II):
II_{arr}^{-} = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
||1|_{arr}^2 = [0, 1, 2, 0, 0, 1, 0, 0, 1, 2]
Constructing Segment and Inner indices (II):
F_{arr} = mkFlagArray S_{arr}^1 0 [1...length S_{arr}^1]
        — [1, 0, 0, 2, 4, 0, 5, 7, 0, 0]
II_{arr}^1 = \operatorname{sgmscan} (+) 0 F F |> \operatorname{map} (-1)
\Pi_{qrr}^2 = sqmscan (+) 0 F (replicate flen 1) |> map (-1)
```

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Flattening by Function Lifting: Basic Idea

Assume a simple function f:

```
let f(x: i32) : i32 = x + 1
```

f lifted, denoted f^L semantically corresponds to map f, where the arguments have been expanded to an extra array dimension, and the inner operators/functions have also been lifted:

```
let +^{L} [n] (as: [n]i32) (bs: [n]i32) : [n]i32 = map2 (+) as bs
```

```
let f^{L} [n] (xs: [n]i32) : [n]i32 = xs +<sup>L</sup> (replicate n 1)
```

Flattening by Function Lifting: Basic Idea

Assume a simple function f:

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```
let +^{L} [n] (as: [n]i32) (bs: [n]i32) : [n]i32 = map2 (+) as bs
```

```
let f^{L} [n] (xs: [n]i32) : [n]i32 = xs +<sup>L</sup> (replicate n 1)
```

- Locals such as $x \Rightarrow left$ alone
- Global such as $+ \Rightarrow$ lifted $(+^{L})$
- Constants such as $k \Rightarrow replicate$ (length xs) k
 - good for vectorization, bad for locality, asymptotics
 - for GPU better to indirectly index into a smaller array, rather than replicate.

Flattening by Function Lifting: Key Insight!

```
let f (xs: []i32) : []i32 = map g xs -- = g^L xs let f<sup>L</sup> (xss: [][]i32) : [][]i32 = (g^L)^L -- ???
```

How do we stop lifting? g and g^L are enough: no need for $(g^L)^L$!

Flattening by Function Lifting: Key Insight!

```
let f (xs: \lceil \rceil i32) : \lceil \rceil i32 = map g xs -- = q^L xs
let f^L (xss: \lceil \rceil \lceil \rceil i32) : \lceil \rceil \lceil \rceil i32 = (g^L)^L -- ???
How do we stop lifting? g and g^L are enough: no need for (g^L)^L!
let f (xs: \lceil \rceil i32) : \lceil \rceil i32 = map q xs -- = q^L xs
-- in nested parallel form
let f<sup>L</sup> (xss: [][]i32 =
     segment xss (q<sup>L</sup> (concat xss))
-- in flatten form
let f^{L} (S_{xss}^{1}: []i32, D_{xss}: []i32) : ([]i32, []i32) =
     (S_{xss}^1, q^L D_{xss})
```

In Haskell Notation:

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

Normalize the code:

```
map (\i -> let ip1 = i+1 in
            let iot = (iota i) in
            let ip1r= (replicate i ip1) in
            map2 (+) ip1r iot ) arr
```

Distribute the map over every instruction in the body (bottom-up if nest > 2), where $\mathcal F$ denotes the flattening transf, and modify the inputs (results) accordingly.

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

Normalize the code:

```
map (\i -> let ip1 = i+1 in
            let iot = (iota i) in
            let ip1r= (replicate i ip1) in
            map2 (+) ip1r iot ) arr
```

Distribute the map over every instruction in the body (bottom-up if nest > 2), where \mathcal{F} denotes the flattening transf, and modify the inputs (results) accordingly.

```
According to rule (4) iota nested inside a map (assuming arr = [1,2,3,4]):
```

According to rule (3) replicate nested inside a map (assuming arr = [1,2,3,4]):

```
3. let ip1rs= \mathcal{F}(\text{map2 }(\ i \ ip1 \ -> \ replicate \ i \ ip1) \ arr \ ip1s) \equiv vals = scatter (replicate size 0) inds ip1s -- [2,3,0,4,0,0,5,0,0,0] ip1rs= sgmScan<sup>inc</sup> (+) 0 flag vals -- [2,3,3,4,4,4,5,5,5,5]
```

According to rule (2) map nested inside a map

Parallel Basic Blocks

Flattening Nested and Irregular Parallelism

Irregular Multi-Dimensional Array Representation Flattening at A High-Level

Rules For Flattening

Flattening Quicksort Flattening Prime-Number (Sieve) Computation

Nested vs Flattened Parallelism: Scan inside a Map

(1) Scan inside a nested map:

```
res = map (\row->scan<sup>inc</sup> (+) 0 row) [[1,3], [2,4,6]] \equiv res = [ scan<sup>inc</sup> (+) 0 [1,3], scan<sup>inc</sup> (+) 0 [2,4,6] ] \equiv res = [ [ 1, 4], [2, 6, 12] ]
```

Nested vs Flattened Parallelism: Scan inside a Map

(1) Scan inside a nested map:

```
res = map (\row->scan<sup>inc</sup> (+) 0 row) [[1,3], [2,4,6]] \equiv res = [ scan<sup>inc</sup> (+) 0 [1,3], scan<sup>inc</sup> (+) 0 [2,4,6] ] \equiv res = [ [ 1, 4], [2, 6, 12] ]
```

becomes a segmented scan, which requires a flag array as arg:

```
sgmScan^{inc} (+) 0 [1, 0, 1, 0, 0] [1, 3, 2, 4, 6] \equiv [ 1, 4, 2, 6, 12 ]
```

Flattening a scan directly nested inside a map:

- the flat-data array is obtained by a segmented scan;
- the shape of the result array is the same as the input array.

```
\mathcal{F}(\text{res} = \text{map (\row -> scan } (\odot) \ \emptyset_{\odot} \text{ row) arr}) \Rightarrow S_{res}^{1} = S_{arr}^{1}
D_{res} = \text{sgmScan } (\odot) \ \emptyset_{\odot} \text{ F}_{arr} D_{arr}
```

Nested vs Flattened Parallelism: Map inside a Map

(2) Map nested inside a map:

```
res = map (\row->map f row) [[1,3], [2,4,6]]

res = [ map f [1, 3], map f [2, 4, 6] ]

res = [ [f(1),f(3)], [f(2),f(4),f(6)] ]
```

Nested vs Flattened Parallelism: Map inside a Map

(2) Map nested inside a map:

```
res = map (\row->map f row) [[1,3], [2,4,6]] 

= res = [ map f [1, 3], map f [2, 4, 6] ] 

= res = [ [f(1),f(3)], [f(2),f(4),f(6)] ]
```

Flattening a map directly nested inside a map:

- the flat-data array is obtained by a map on the flat input;
- the shape of the result array is the same as the input array.

```
\mathcal{F}(\text{res} = \text{map (\row -> map f row) arr}) \Rightarrow S_{res}^1 = S_{arr}^1

D_{res} = \text{map f } D_{arr}
```

Nested vs Flattened Parallelism: Replicate in a Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] \equiv res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] \equiv res = [ [7], [], [8,8,8], [9,9] ]
```

Nested vs Flattened Parallelism: Replicate in a Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] = res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] = res = [ [7], [], [8,8,8], [9,9] ]
```

becomes a composition of scans and scatter:

- 1. the shape of the result array is ns
- 2-3. builds the indices at which segment start (-1 for null shape)
 - 4. get the size of the flat array (summing ns)
- 5-6. write the ms and ns values at the start of their segments
 - 7. propagate the ms values throughout their segments.
 - Implementation shortcomings:

Nested vs Flattened Parallelism: Replicate in a Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] =
res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] =
res = [ [7], [], [8,8,8], [9,9] ]
```

becomes a composition of scans and scatter:

- 1. the shape of the result array is ns
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 - 4. get the size of the flat array (summing ns)
- 5-6. write the ms and ns values at the start of their segments
 - 7. propagate the ms values throughout their segments.
 - Implementation shortcomings: sgmScan^{inc} (+)?

5. vls = scatter (replicate size 0) inds ms — [7, 8, 0, 0, 9, 0]6. F_{arr} = scatter (replicate size 0) inds ns — [1, 3, 0, 0, 2, 0]6. F_{res} = sgmScan^{inc} (+) 0 F_{res} vls — [7, 8, 8, 8, 9, 9]

Nested vs Flattened Parallelism: Iota in a Map

(4) lota nested inside a map ((iota n) \equiv [0,...,n-1]):

```
res = map (\i -> iota i) [1,3,2] \equiv res = [ iota 1, iota 3, iota 2 ] \equiv [ [0], [0,1,2], [0,1] ]
```

Nested vs Flattened Parallelism: Iota in a Map

(4) lota nested inside a map ((iota n) \equiv [0,...,n-1]):

```
res = map (\i -> iota i) [1,3,2] \equiv
res = [ iota 1, iota 3, iota 2 ] \equiv [ [0], [0,1,2], [0,1] ]
```

boils down to a segmented scan applied to an array of ones:

- 1. by definition of iota, ns contains the size of each subarray, hence the shape of the result is ns;
- 2. the flag-array of the result, F_{res} , is constructed from ns;
- 3. the result is obtained by an exclusive segmented scan operation applied to an array of ones.

Note that iota $n \equiv scan^{exc}$ (+) 0 (replicate n 1).

Nested vs Flattened Parallelism: Reduce Inside Map

(5) Reduce Inside a Map or Segmented Reduce:

```
let arr = [[1, 3, 4], [6, 7]] in
let res = map (\x -> reduce (+) 0 x) arr
-- should result in [8, 13]
```

Nested vs Flattened Parallelism: Reduce Inside Map

(5) Reduce Inside a Map or Segmented Reduce:

```
let arr = [[1, 3, 4], [6, 7]] in
let res = map (\x -> reduce (+) 0 x) arr
-- should result in [8, 13]
```

translates to a scan-pack composition:

- 1. the length of res equals the number of subarrays of arr;
- the shape of arr is scanned: the result records the position of the last element in a segment plus one;
- 3. segmented scan is applied on the input array: the last elem in a segment holds the reduced value of the segment;
- 4. segment's last element is extracted by a map operation.

Treating a Scalar Variant to the Outer Map

(6) The inner construct uses a scalar variant to the outer map:

```
let res = map2 (\x ys -> map (+x) ys) [1,3] [[4,5,6], [9,7]] \equiv let res = [map (+1) [4,5,6], map (+3) [9,7]] let res = [ [5,6,7], [12,10] ]
```

Treating a Scalar Variant to the Outer Map

(6) The inner construct uses a scalar variant to the outer map:

```
let res = map2 (\x ys -> map (+x) ys) [1,3] [[4,5,6], [9,7]] =
let res = [map (+1) [4,5,6], map (+3) [9,7]]
let res = [ [5,6,7], [12,10] ]
```

Traditionally, this is handled by expanding (replicating) each \boldsymbol{x} across the whole segment

Instead, we use II_{arr}^1 to indirectly access in the xs array:

```
 F(\text{res} = \text{map2} (\x ys -> \text{map} (fx) ys) xs yss) \Rightarrow 
 -- xs = [1,3], S_{yss}^1 = [3,2], F_{yss} = [1,0,0,1,0], D_{yss} = [4,5,6,9,7] 
 1. S_{res}^1 = S_{yss}^1 
 2. D_{res} = \text{map2} (\y \text{sgmind} -> f(\text{xs[sgmind]}, y)) D_{yss} II_{yss}^1 
 -- II_{yss}^1 = [0,0,0,1,1], D_{res} = [5,6,7,12,10]
```

Treating Indexing Variant to the Outer Map

(7) Indexing Operations Variant to the Outer Map:

```
let res = map2 (\i xs -> xs[i]) [2,0] [[4,5,6], [9,7]] \equiv let res = [6, 9]
```

Treating Indexing Variant to the Outer Map

(7) Indexing Operations Variant to the Outer Map:

```
let res = map2 (\i xs -> xs[i]) [2,0] [[4,5,6], [9,7]] \equiv let res = [ 6, 9 ]
```

To corresponding flat index in D_{vss} is obtained by summing up

- the start offset of every segment, which we get from B_{yss}^1 , and
- the index inside the segment, which we get from is

```
\mathcal{F}(\text{res = map2} (\in xs -> xs[i]) \text{ is } xss) \Rightarrow
-- is = [2,0], S_{xss}^1 = [3,2], B_{yss}^1 = [0,3], D_{xss} = [4,5,6,9,7]
1. S_{res}^0 = S_{yss}^0 -- S_{is}^0 = [2]
2. D_{res} = \text{map2} (\ \text{off i} -> D_{yss}[\text{off+i}]) B_{yss}^1 \text{ is } -- D_{res} = [6,9]
```

Nested vs Flattened Parallelism: If Inside a Map 2D Case

(8) If-Then-Elese with inner parallelism nested inside a map:

```
bs = [F,T,F,T]
xss = [[1,2,3],[4,5,6,7],[8,9],[10]]
res = map(\b xs -> if b then map (+1) xs else map (*2) xs) bs xss
res = [ map(*2)[1,2,3], map(+1)[4,5,6,7], map(*2)[8,9], map(+1)[10] ]
res = [ [2,4,6], [5,6,7,8], [16,18], [11] ]
```

Nested vs Flattened Parallelism: If Inside a Map 2D Case

(8) If-Then-Elese with inner parallelism nested inside a map:

```
bs = [F,T,F,T]
xss = [[1,2,3],[4,5,6,7],[8,9],[10]]
res = map(\b xs -> if b then map (+1) xs else map (*2) xs) bs xss
res = [ map(*2)[1,2,3], map(+1)[4,5,6,7], map(*2)[8,9], map(+1)[10] ]
res = [ [2,4,6], [5,6,7,8], [16,18], [11] ]
```

translates to a scatter-map-gather composition. Intuition:

- 1. compute iinds, the permutation of segments w.r.t. bs;
- 2-3. partition the xss array based on bs;
- 4-5. flatten the code for the then and else branches;
 - 6. inverse permute the resulted segments according to iinds.

```
1. iinds = partition2 bs (iota (length b)) -- [1,3,0,2]
2. xss<sub>then</sub> = gatherThen iinds xss -- ([4,1], [4,5,6,7, 10])
3. xss<sub>else</sub> = gatherElse iinds xss -- ([3,2], [1,2,3, 8,9])
4. res<sub>then</sub> = map (+1) xss<sub>then</sub> -- ([4,1], [5,6,7,8, 11])
5. res<sub>else</sub> = map (*2) xss<sub>else</sub> -- ([3,2], [2,4,6,16,18])
6. res = inversePermute iinds (res<sub>then</sub>++res<sub>else</sub>)
-- ([3,4,2,1], [2,4,6, 5,6,7,8, 16,18, 11])
```

Nested vs Flattened Parallelism: If Inside a Map 2D Case

(8) If-Then-Elese with inner parallelism nested inside a map:

```
bs = [F,T,F,T], xss = [[1,2,3],[4,5,6,7],[8,9],[10]], S_{xc}^1 = [3,4,2,1], f=map (+1), g=map (*2)
\mathcal{F}(\text{res} = \text{map2} (\b xs \rightarrow \text{if b then } f xs \text{ else } q xs) \text{ bs } xss) \Rightarrow
(spl, iinds) = partition2 bs (iota (length bs)) - (2, [1,3,0,2])
(S_{XSS_{then}}^1, S_{XSS_{olco}}^1) = \text{split spl (map (\ii -> S_{XSS}^1[ii]) iinds)} - ([4,1],[3,2])
mask_{xss} = map (\setminus sgmind \rightarrow bs[sgmind]) II_{xss}^1 - [F,F,F,T,T,T,T,F,F,T]
(brk, D_{xss}^p) = partition 2 mask_{xss} D_{xss}
(D_{xss_{then}}, D_{xss_{else}}) = split brk D_{xss}^{p} - ([4,5,6,7,10],[1,2,3,8,9])
(S_{res_{then}}^1, D_{res_{then}}) = \mathcal{F}(map f) (S_{xss_{then}}^1, D_{xss_{then}}) - ([4,1], [5,6,7,8,11])
(S_{res_{olso}}^{1}, D_{res_{olso}}) = \mathcal{F}(map g) (S_{xss_{olso}}^{1}, D_{xss_{olso}}) - ([3,2], [2,4,6,16,18])
S_{res}^{1P} = S_{res_{then}}^{1} + + S_{res_{else}}^{1} - [4, 1, 3, 2]
S_{res}^1 = scatter (replicate (length bs) 0) iinds S_{res}^{1P} — [3,4,2,1]
B_{res}^1 = scan^{exc} (+) 0 S_{res}^1 - [0,3,7,9]
F_{res}^{p} = mkFlagArray S_{res}^{1p} 0 \text{ (map (+1) iinds)} - [2,0,0,0,4,1,0,0,3,0]
\prod_{res}^{1p} = \text{sgmscan} (+) 0 F_{res}^{p} F_{res}^{p} |> \text{map} (-1) - [1,1,1,1,3,0,0,0,2,2]
||_{res}^{2P} = ||_{res_{then}}^{2} + + ||_{res_{elce}}^{2} - [0,1,2,3,0,0,1,2,0,1]
sinds_{res} = map2 \ (\sq miin -> B_{res}^1[sgm] + iin) \ ||_{res}^{1P} \ ||_{res}^{2P}
-[3+0,3+1,3+2,3+3,9+0,0+0,0+1,0+2,7+0,7+1] = [3,4,5,6,9,0,1,2,7,8]
D_{res} = scatter (replicate flen<sub>res</sub> 0) sinds<sub>res</sub> (D_{res_{then}}++D_{res_{else}})
   - [2,4,6, 5,6,7,8, 16.18, 11]
(S_{res}^1, D_{res})
```

Nested vs Flattened Parallelism: Do Loop Inside a Map

(9) Flattening a Do Loop Nested Inside a Map:

- compute the maximal loop count n_{max}
- interchange the loop and the map:
 - loop count becomes n_{max}
 - ▶ the loop body is wrapped inside a if i<n condition, and
 - the new loop body is flattened!

```
\mathcal{F}(\text{res} = \text{map2} \ (\n xs \rightarrow \text{loop}(xs) \ \text{for} \ i < n \ \text{do} \ f \ xs) \ ns \ xss) \Rightarrow
1. \ n_{max} = \text{reduce max 0i32 ns}
2. \ g \ m \ arr = if \ i < m \ then \ f \ arr \ else \ arr
2. \ loop(S_{xss}^1, D_{xss}) \ \text{for} \ i < n_{max} \ \text{do}
3. \ \mathcal{F}(\text{map2} \ g) \ ns \ (S_{xss}^1, D_{xss})
4. \ - g^L \ ns \ (S_{yss}^1, D_{xss})
```

Parallel Basic Blocks

Flattening Nested and Irregular Parallelism

Irregular Multi-Dimensional Array Representation Flattening at A High-Level Rules For Flattening

Flattening Quicksort

Flattening Prime-Number (Sieve) Computation

Recounting Quicksort

Recount the classic nested-parallel definition:

```
let quicksort [n] (arr : [n]f32) : [n]f32 =
    if n < 2 then arr else
    let i = getRand (0, (length arr) - 1)
    let a = arr[i]
    let s1 = filter (< a ) arr
    let s2 = filter (== a) arr
    let s3 = filter (> a) arr
    in (quicksort s1) ++ s2 ++ (quicksort s3)
        -- can be re-written as:
        -- rs = map nestedQuicksort [s1, s3]
        -- in (rs[0]) ++ s2 ++ (rs[1])
```

Note: Futhark does not support recursive calls, hence not valid code!

Nested-Parallel Quicksort Simplified

For simplicity we will rewrite it in terms of partition2:

```
let isSorted [n] (as: [n]f32) : bool =
    map (\i i -> if i ==0 then true else as[i-1] < as[i]) (iota n)
    |> reduce (&&) true

let quicksort [n] (arr: [n]f32) : [n]f32 =
    if isSorted arr then arr else
    let i = getRand (0, (length arr) - 1)
    let a = arr[i]
    let bs = map (< a) arr
    let (q, arr') = partition2 bs 0.0f32 arr
    let (arr<, arr>) = split q arr'
    in concat <| map quicksort [arr<, arr>]
```

Note: Futhark does not support recursive calls, irregular map operation, or concat!

Partition2

Reorders the elements of an array such that those that correspond to a true mask come before those corresponding to false.

```
let partition2 [n] 't (conds: [n]bool) (dummy: t) (arr: [n]t)
        : (i32, [n]t) =
  let tflqs = map (\setminus c \rightarrow if c then 1 else 0) conds
  let fflgs = map (\ b \rightarrow 1 - b) tflgs
  let indsT = scan (+) 0 tflqs
  let tmp = scan (+) 0 fflgs
  let lst = if n > 0 then indsT[n-1] else -1
  let indsF = map (+lst) tmp
  let inds = map3 (\ c indT indF \rightarrow if c then indT-1 else indF-1)
                    conds indsT indsF
  let fltarr= scatter (replicate n dummy) inds arr
  in (lst, fltarr)
```

For example:

```
conds = [F,T,F,T,F,F,T]

xss = [1,2,3,4,5,6,7]

partition2 conds 0 xss => (3, [2,4,7,1,3,5,6])
```

Lifting Quicksort

Key Idea: write a function with the semantics of map nestedQuicksort, i.e., it operates on array of arrays.

Important observations:

- map quicksort \equiv quicsort^L
- the flat data of $[xs_{<}, xs_{>}] \equiv xs^{p}$, the result of partition2

Lifting Quicksort

Let us treat the last three lines from the previous implem:.

```
let quicksort<sup>L</sup> (S_{xss}^1:[]i32, D_{xss}:[]f32): ([]i32,[]f32) = (xss: [][]f32)
  let (S_{bss}^1, D_{bss}) = \mathcal{F} (
     map (\setminus xs \rightarrow
              if isSorted xs then xs else
              let i = getRand (0, (length xs) - 1)
              let a = xs[i]
              let bs = map (< a) xs
              in bs
           ) xss )
  let (ps, (S_{xss^p}^1, D_{xss^p})) = partition 2<sup>L</sup> D_{bss} 0.0 f 32 (S_{xss}^1, D_{xss})
  - Invariant: S_{xss}^1 == S_{hss}^1 == S_{xss}^1
  let S^1_{[xss]} = filter (!=0) <| flatten <|
           map2 (\lambda p s \rightarrow if s==0 then [0,0] else [p,s-p]) ps S_{xxx}^1
  in quicksort<sup>L</sup> (S^1_{[xss_<,xss_>]}, D_{xss^p})
```

- $S^1_{[xss_{< a},xss_{>a}]}$ is the shape of $[xs_{<}, xs_{\geq}]$
- (concat <| quicksort^L)^L xsss ≡ concat <| segment xsss <| quicksort (concat xsss) ≡ quicksort (concat xsss)</p>
- The function looks tail recursive now: let's replace it with a loop!

Lifting Quicksort: Final Implementation

```
let quicksort<sup>L</sup> [m][n] (S_{xss}^1:[m]i32, D_{xss}:[n]f32): [n]f32 =
  let (stop, count) = (isSorted D_{xss}, 0i32)
  let (_,res,_,_) =
     loop(S_{xss}^1, D_{xss}, stop, count) while (!stop) do
          — compute helper-representation structures
           let B_{yss}^1 = scan^{exc} (+) 0 S_{yss}^1
           let F_{xss}^1 = mkFlagArray S_{xss}^1 0i32 <| map (+1) <| iota m
           let \prod_{res}^{1} = sqmscan (+) 0 F_{res}^{1} < |
                     map (\f -> if f==0 then 0 else f-1) F_{xss}^1
          — flattening quicksort:
           let rL = map (\u -> randomInd (0,u-1) count) S_{yss}^1
           let aL = map3(\r l i\rightarrow if l <= 0 then 0.0 else D_{xss}[B_{vee}^{1}[i]+r]
                            ) rL S_{rss}^{1} (iota m)
           let D_{bss} = map2 \ (\ x \ sgmind \rightarrow aL[sgmind] > x \ ) \ D_{xss} \ II_{xss}^{1}
           let (ps, (S_{xss}^1, D_{xss}^{per})) = partition2<sup>L</sup> D_{bss} 0.0 f32 (S_{xss}^1, D_{xss})
           let S^1_{[xss < .xss > ]} = filter (!=0) <| flatten <|
                   map2 (\ p s \rightarrow if s==0 then [0,0] else [p,s-p]) ps S_{vss}^1
          in (S^1_{[xss < .xss >]}, D^{per}_{xss}, isSorted D^{per}_{xss}, count+1)
  in
        res
```

PFP Weekly 2 Exercise: Implement partition2^L

Parallel Basic Blocks

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Flattening Prime-Number (Sieve) Computation

How Does One Flattens Prime Numbers?

The important bit with nested parallelism:

How Does One Flattens Prime Numbers?

The important bit with nested parallelism:

Normalize the nested map:

Flattening PrimeOpt was part of PMPH's Weekly Assignment 1!