

# Simin Liu

siminliu@andrew.cmu.edu

[www.siminl.com](http://www.siminl.com)

<i>Interests</i>	My research topics are control and planning for robotics and machine learning.
<i>Education</i>	<p><b>Ph.D. in Robotics, Carnegie Mellon University</b> 2019-2025 (expected) Advisors (2021 –present): John Dolan, Changliu Liu, safe and adaptive robotics Advisor (2019 –2020): David Woodruff, mathematics and machine learning Coursework: nonlinear and adaptive control, RL, modeling and estimation for robotics, ML, statistics, convex and nonlinear optimization</p> <p><b>B.S. with High Honors in EECS and Mathematics, University of California, Berkeley</b> 2015-2019 Advisor: Sergey Levine, deep reinforcement learning for robotics Coursework: linear systems control (grad level), AI, mathematics for control and robotics (linear algebra, analysis, abstract algebra, probability)</p>
<i>Publications</i>	<p><b>S. Liu</b>, J. Dolan, and C. Liu, “Safe Control Under Input Limits with Neural Control Barrier Functions”, in 6th Annual Conference on Robot Learning, 2022.</p> <p>W. Zhao, T. He, T. Wei, <b>S. Liu</b>, and C. Liu, “Safety Index Synthesis via Sum-of-Squares Programming”, arXiv preprint arXiv:2209.09134, 2022. Under submission at 2023 American Controls Conference.</p> <p>Y. Li, H. Lin, <b>S. Liu</b>, A. Vakilian, and D. Woodruff, “Learning the Positions in CountSketch”. Under submission at 2023 International Conference on Learning Representations.</p> <p><b>S. Liu</b>, T. Liu, A. Vakilian, Y. Wan, and D. Woodruff, “Learning the Positions in CountSketch”, arXiv preprint arXiv:2007.09890, 2020.</p> <p>A. Nagabandi*, I. Clavera*, <b>S. Liu</b>, R. S. Fearing, P. Abbeel, S. Levine, and C. Finn, “Learning to Adapt in Dynamic, Real-World Environments Through Meta-Reinforcement Learning”, in International Conference on Learning Representations, 2018.</p>
<i>Awards</i>	<p>UC Berkeley undergraduate research honors 2019 Selected for Combinatorics, Algorithms, and AI for Real Problems program: prestigious undergrad research program at University of Maryland 2018 Computing Research Association GHC research scholarship 2018 Microsoft GHC scholarship 2017</p>

Top 10% of teaching assistants in UC Berkeley EECS 2017–2018  
Inducted to Tau Beta Pi, Eta Kappa Nu, and Phi Beta Kappa:  
national engineering, computer science, and liberal arts honor societies 2016  
UC Berkeley College of Engineering Dean’s List 2016–2019  
William M. Olson/Warren E. Taylor Science and Engineering scholarship 2015  
ACES-NM Young Asian-American Student Award 2015  
Jane Street Unboxed scholarship 2015

### *Talks*

“Safe Control Under Input Limits with Neural Control Barrier Functions”  
October 2022, Safe Autonomous Systems Lab, UCSD  
July 2022, PhD Speaking Qualifier, Robotics Institute, CMU  
  
“Dealing with sample inefficiency in deep reinforcement learning for robotics”  
July 2020, Session for Women in Machine Learning workshop at ICML

### *Teaching*

**Graduate Student Instructor, CMU**  
2021–2022  
(1) modeling, estimation, and control for robotics, (2) mathematics for robotics  
  
**Undergraduate Student Instructor, UC Berkeley**  
2016–2019, top 10% instructor by student ratings  
(1) intro to artificial intelligence, (2) algorithms in computer science, (3) intro to electrical engineering

### *Skills*

Operating systems: Linux (daily use), macOS (daily use)  
Programming languages: Python (daily use), C++ (learned in courses)  
Tools: PyTorch (proficient), TensorFlow (proficient), ROS (proficient)

### *Industry*

**Software Engineering Intern, Microsoft**  
Summer 2017  
Worked on natural language processing at Cortana, applying ML tools like gradient boosting to classify the intent of Cortana queries.  
  
**Software Engineering Intern, Microsoft**  
Summer 2016  
Prototyped a chatbot assistant for meeting scheduling. This successful demonstration preceded the serious adoption of chatbots in Teams, Microsoft’s workplace messaging platform.