# Yipeng PAN

Email yppancs@connect.hku.hk (+852) 6733-3260

Page https://yppan.top/ Hong Kong SAR

**EDUCATION** 

China University of Mining and Technology (211) Sep 2015 – Jul 2019

**B.Eng. in Electronic Engineering** 

GPA: 85 / 100 (Top 15%, Recommended Admission to Postgraduate)

The University of Hong Kong Sep 2023 – TBC.

Ph.D. in Computer Science (Robotics)

Supervisor: <u>Dr. Jia Pan</u>

Prof. Anthony G.O. Yeh (Academician, Chinese Academy of Sciences)

**CAREER** 

HKUST <u>iLab</u>
Position: Research Assistant

Apr 2021 – Nov 2021

Director: Prof. Weisheng Lu

Nov 2022 – Mar 2023

HKUST HKCRC Dec 2021 – Oct 2022

Position: Research Assistant Director: Prof. Zexiang Li

HKU TransGP Apr 2023 – TBC.

Position: Research Assistant Director: Prof. Norman C. Tien

**SKILLS** 

Coding: C / C++ / Java / Python

GUI: Qt (C++), Android (Java), IOS (Objective - C)

Cooperation: Git

Computer Vision: OpenCV, Halcon

Robotics: Linux Shell, ROS

Mechanics: AutoCAD, SolidWorks, 3D Printing

**Electronics**: Verilog HDL (FPGA), STM32 (HAL, STD), Arduino, PCB Layout (SMT)

Word: LaTeX. Markdown

**AWARDS** 

Gold Award, Hong Kong ICT Awards (Smart Logistics)	2022
2 <sup>nd</sup> Prize, National Electronic Design Competition	2017
National Encouragement Scholarship, Ministry of Education	2018
Honorable Mentions, Mathematical Contest in Modeling	2018
1 <sup>st</sup> Prize, Provincial Electronic Design Competition	2017
2 <sup>nd</sup> Prize. Provincial Electronic Design Competition	2018

2 <sup>nd</sup> Prize, Postgraduate Electronic Design Competition	2019
School Excellent Graduation Design	2019
1 <sup>st</sup> Prize, School Electronic Design Competition	2019
Second Class Scholarship	2017

### **PROJECTS**

#### SELECTED:

◆ Tracking Drone (Second Prize winner in National Electronic Design Competition)

The drone can autonomously take off, hover and land. It can also automatically track and follow a remote-control car (by learning to follow targets of different colors).

### ♦ i-Core (Funded by ITF2020 (ITP/029/20LP)

With the goal of improving the management of building processes and supply chains, the system will organize data collected from IMU, GPS, UWB, and other sensors into a specific format. Subsequently, this data will be uploaded to a universal platform integrating BIM, Blockchain, etc.

### ◆ LiDAR SLAM Synchronization Board (Start-up Project)

This board is designed to synchronize peripheral sensors, including LiDAR, IMU, cameras, and motor encoders, Consequently, to improve the effectiveness of LiDAR SLAM.

**PS:** Entire Portfolio & Demos: <a href="https://yppan.top/Portfolio">https://yppan.top/Portfolio</a>

## **PUBLICATIONS**

[1] Chen, Junjie & Lu, Weisheng & Pan, Yipeng & Fu, Yonglin. (2024). Building "RoboAvatar": Industry Foundation Classes–Based Digital Representation of Robots in the Built Environment. Journal of Computing in Civil Engineering.

[2] Lu, Liang, Yinqiang Zhang, Peng Zhou, Jiaming Qi, Yipeng Pan, Changhong Fu, and Jia Pan. "Semantics-Aware Receding Horizon Planner for Object-Centric Active Mapping." *IEEE Robotics and Automation Letters* (2024).

[3] Chen, Junjie & Fu, Yonglin & Lu, Weisheng & Pan, Yipeng. (2023). Augmented reality-enabled human-robot collaboration to balance construction waste sorting efficiency and occupational safety and health. Journal of environmental management.

[4] Lu, Weisheng & Chen, Junjie & Fu, Yonglin & Pan, Yipeng & Ghansah, Frank. (2023). Digital twin-enabled human-robot collaborative teaming towards sustainable and healthy built environments. Journal of Cleaner Production.