# **Yipeng PAN**

yppan@hku.hk https://yp779.github.io/ (+852) 5622-7242 Hong Kong SAR, China

# **EDUCATION**

# China University of Mining and Technology (211) B.Eng in Electronic Engineering

Sep 2015 – Jul 2019 Xuzhou, China

• **GPA**: 85/100

(Top 15%, Recommended Admission to Postgraduate)

Major courses: Visual C++ Programming (96), Circuit Theory (90), Engineering Mathematics (96), Linear Algebra (98), Principle of Automatic Control (89), Information Theory (98), Image processing (89), Engineering Graphics (92), Digital Electronics Technology (89), General Physics (89), Microcomputer Principle & Application (95), Integrated Design of Electronic Technology (95), Embedded System Principle & Application (83), Network Programming (90), etc.

### WORK EXPERIENCE

# Chinese Academy of Sciences (CAS) Intern Student, Robot and Intelligent Equipment Center of SIAT Supervisor: Prof. Quijang Lei (UCAS)

Apr 2020 – Aug 2020 Guangzhou, China

- Developed software for counting the number of pipes with Qt and OpenCV, which has been deployed in a factory in Foshan
- Developed metal pipe grasping system for Yumi robot

# Hong Kong University of Science and Technology (HKUST) Research Assistant, HKCRC

Dec 2021 – Oct 2022 Hong Kong, China

Director: Prof. Zexiang Li

- Developed three prototypes of scanning devices, one of which will be shown on ICRA2022
- Designed a sensor-fusion synchronization control board, which shows better performance on existing SLAM algorithms than its counterparts in labs of HKU or HKUST

# The University of Hong Kong (HKU) Research Assistant, iLab Supervisor: Prof. Wilson Lu (Associate Dean)

Apr 2021 – Nov 2021 Nov 2022 – TBC. Hong Kong, China

Prof. Anthony Yeh (Academician, Chinese Academy of Sciences)

- Developed new i-Core for "BIM Square" project (ITF, ITC, HKSAR) (ITP/029/20LP, 10.36M HKD), and finally will be installed on Modular Integrated Construction of HKU Wong Chuk Hang Campus. This project also won an ICT Gold Award
- Developed a human-robot collaborative grasping system with the combination of HoloLens (AR) and UR5 robot arm

## **SKILLS**

- Coding: C / C++ / Java / Python
- GUI: Qt (C++), Android (Java), IOS (Objective C)
- Cooperation: Git
- Computer Vision: OpenCV, Halcon
- Robotics: Linux Shell, ROS
- Mechanics: AutoCAD, SolidWorks
- Electronics: Verilog HDL (FPGA), STM32 (HAL, STD), Arduino, PCB Layout (SMT)
- Word: LaTeX, Markdown

# **HONORS & AWARDS**

| • | Gold Award, Hong Kong ICT Awards (Smart Logistics)                | 2022 |
|---|---|------|
| • | 2 <sup>nd</sup> Prize, National Electronic Design Competition     | 2017 |
| • | National Encouragement Scholarship, Ministry of Education         | 2018 |
| • | Honorable Mentions, Mathematical Contest in Modeling              | 2018 |
| • | 1 <sup>st</sup> Prize, Provincial Electronic Design Competition   | 2017 |
| • | 2 <sup>nd</sup> Prize, Provincial Electronic Design Competition   | 2018 |
| • | 2 <sup>nd</sup> Prize, Postgraduate Electronic Design Competition | 2019 |
| • | School Excellent Graduation Design                                | 2019 |
| • | 1 <sup>st</sup> Prize, School Electronic Design Competition       | 2019 |
| • | Second Class Scholarship  | 2017 |
|   |   |      |

# **PROJECTS & DESIGNS**

My entire Portfolio and Video Presentation ——<u>http://pyp1024.cf/</u> Selected are as follows:

## Tracking Drone (Second Prize in National Competition)

Functions: The drone can take off, hover and land automatically, and follow the remote control car automatically when flying (it can learn to follow differently colored targets)

## New i-Core (Funded by ITF2020 (ITP/029/20LP))

Functions: The data collected by IMU, GPS, UWB and other sensors will be packed up in specific format and then uploaded to the universal platform which implies BIM, Blockchain and other technologies, aiming to manage the building flow and supply chain better

#### Lidar SLAM Device Synchronization Board

Functions: This board can trigger peripheral sensors such as multi-line Lidar, IMU, camera and motor encoder, to achieve a better time synchronization performance

### **EXTRACURRICULAR ACTIVITIES**

#### Office Director, School Electronics Association

Jun 2017 – Jul 2018

 Awarded the honor of 'Excellent Cadre', and the association was nominated and selected as the Top-10 associations

#### Lab Manager, Electronics Design Laboratory

Jun 2018 - Jul 2019

- Authorized to host the School Electronic Design Competition
- Be appointed to manage all routine work of the Lab

### **PUBLICATIONS**

[Conference] Yonglin Fu, Junjie Chen, Yipeng Pan and Weisheng Lu, An integrated visualization framework to enhance human-robot collaboration in facility management, CRIOCM.

[Under Review] Junjie Chen, Weisheng Lu, Yonglin Fu, Yipeng Pan and Frank Ato Ghansah, Digital twin-enabled human-robot collaborative teaming for facility management, Computers in Industry.