Theory for derivation of the expressions for Douglas-Gunn Alternating Direction Implicit (DG-ADI) method for solving the inhomogeneous heat diffusion equation on a rectangular cuboid finite element grid

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1 Heat equation

t is the time. The remaining quantities are considered functions of space: The volumetric heat capacity $c_{\rm VHC}$, with units of $\frac{\rm J}{\rm m^3 K}$, the temperature T with units of K, the rate of heat deposition per unit volume per unit time q with units of $\frac{\rm W}{\rm m^3 s}$ and the thermal conductivity k, with units of $\frac{\rm W}{\rm m \cdot K}$.

The heat diffusion equation is

$$c_{\text{VHC}} \frac{dT}{dt} = \nabla \cdot (k\nabla T) + q \tag{1}$$

2 Discretization in 1D

Let k_{x+} denote the effective thermal conductivity for heat flow between a voxel and its neighbor in the plus x direction: $k_{x+} = \frac{2k_i k_{i+1}}{k_i + k_{i+1}}$. Similarly, $k_{x-} = \frac{2k_{i-1} k_i}{k_{i-1} + k_i}$.

Writing the equation in 1D yields

$$c_{\text{VHC}}\frac{dT}{dt} = \frac{d}{dx}\left(k\frac{d}{dx}T\right) + q\tag{2}$$

Using the notation T^n to denote the temperature at time step n, we can discretize the above as

$$c_{\text{VHC}} \frac{\Delta T}{\Delta t} = \frac{\Delta_x}{\Delta x} \left(k \frac{\Delta_x}{2\Delta x} \left(T^n + T^{n+1} \right) \right) + q \tag{3}$$

where we have chosen to use the mean $\frac{1}{2}(T^n + T^{n+1})$ as the estimate of the temperature. We can expand this to get

$$c_{\text{VHC}} \frac{T^{n+1} - T^n}{\Delta t} = \frac{1}{2\Delta_x x^2} \Delta_x \left(k\Delta \left(T^n + T^{n+1} \right) \right) + q$$

$$= \frac{1}{2\Delta x^2} \left(k_{x_+} \left(T_{i+1}^n + T_{i+1}^{n+1} - T_i^n - T_i^{n+1} \right) - k_{x_-} \left(T_i^n + T_i^{n+1} - T_{i-1}^n - T_{i-1}^{n+1} \right) \right) + q \quad (4)$$

We multiply by $\frac{\Delta t}{c_{\text{VHC}}}$ and move the terms with time step n+1 to the left hand side:

$$-\frac{\Delta t k_{x_{+}}}{2 c_{\text{VHC}} \Delta x^{2}} T_{i+1}^{n+1} + \left(1 + \frac{\Delta t (k_{x_{+}} + k_{x_{-}})}{2 c_{\text{VHC}} \Delta x^{2}}\right) T_{i}^{n+1} - \frac{\Delta t k_{x_{-}}}{2 c_{\text{VHC}} \Delta x^{2}} T_{i-1}^{n+1}$$

$$= \frac{\Delta t k_{x_{+}}}{2 c_{\text{VHC}} \Delta x^{2}} T_{i+1}^{n} + \left(1 - \frac{\Delta t (k_{x_{+}} + k_{x_{-}})}{2 c_{\text{VHC}} \Delta x^{2}}\right) T_{i}^{n} + \frac{\Delta t k_{x_{-}}}{2 c_{\text{VHC}} \Delta x^{2}} T_{i-1}^{n} + \frac{\Delta t}{c_{\text{VHC}}} q$$
(5)

We see that it is convenient to introduce $\alpha_{x_{\pm}} = \frac{\Delta t k_{x_{\pm}}}{2c_{\text{VHC}}\Delta x^2}$ and $\beta = \frac{\Delta t}{c_{\text{VHC}}}q$ so we can write

$$-\alpha_{x_{+}}T_{i+1}^{n+1} + \left(1 + \alpha_{x_{+}} + \alpha_{x_{-}}\right)T_{i}^{n+1} - \alpha_{x_{-}}T_{i-1}^{n+1} = \alpha_{x_{-}}T_{i+1}^{n} + \left(1 - \alpha_{x_{+}} - \alpha_{x_{-}}\right)T_{i}^{n} + \alpha_{x_{-}}T_{i-1}^{n} + \beta$$

$$(6)$$

Representing the temperatures and the heat deposition rate as column vectors, we can write the equation in terms of tridiagonal matrix multiplication and column vector addition

$$M_{\rm LHS}T^{n+1} = M_{\rm RHS}T^n + \beta \tag{7}$$

where the matrices for insulating boundaries are (example shown for a 5-element grid)

$$M_{\text{LHS}} = \begin{bmatrix} 1 + \alpha_{x_{+}} & -\alpha_{x_{+}} & 0 & 0 & 0 & 0 \\ -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} & 0 & 0 & 0 \\ 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} & 0 & 0 \\ 0 & 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} \\ 0 & 0 & 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} \\ 0 & 0 & 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{-}} \end{bmatrix}$$
(8)
$$M_{\text{RHS}} = \begin{bmatrix} 1 - \alpha_{x_{+}} & \alpha_{x_{+}} & 0 & 0 & 0 & 0 \\ \alpha_{x_{-}} & 1 - \alpha_{x_{+}} - \alpha_{x_{-}} & \alpha_{x_{+}} & 0 & 0 \\ 0 & \alpha_{x_{-}} & 1 - \alpha_{x_{+}} - \alpha_{x_{-}} & \alpha_{x_{+}} & 0 \\ 0 & 0 & 0 & \alpha_{x_{-}} & 1 - \alpha_{x_{-}} - \alpha_{x_{-}} \\ 0 & 0 & 0 & \alpha_{x_{-}} & 1 - \alpha_{x_{-}} & \alpha_{x_{+}} \end{bmatrix}$$
(9)

in which the $\alpha_{x_{\pm}}$ parameters in the *i*'th row in both matrices are to be evaluated at the spatial position of the *i*'th pixel/voxel.

The matrices for heat sinked boundaries are

$$M_{\text{LHS}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} & 0 & 0 \\ 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} & 0 \\ 0 & 0 & -\alpha_{x_{-}} & 1 + \alpha_{x_{+}} + \alpha_{x_{-}} & -\alpha_{x_{+}} \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$
(10)
$$M_{\text{RHS}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ \alpha_{x_{-}} & 1 - \alpha_{x_{+}} - \alpha_{x_{-}} & \alpha_{x_{+}} & 0 & 0 \\ 0 & \alpha_{x_{-}} & 1 - \alpha_{x_{+}} - \alpha_{x_{-}} & \alpha_{x_{+}} & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$
(11)

where furthermore the edge values of β must be set to zero.

To calculate the temperature T^{n+1} , one can calculate first the right hand side of Eq. 7 by simple matrix multiplication and addition and then solve the remaining system of linear equations for T^{n+1} using, for example, the "matrix left division" of MATLAB.

3 Discretization in 2D

Similar to Eq. 2, we can write the equation in 2D

$$c_{\text{VHC}} \frac{dT}{dt} = \frac{d}{dx} \left(k \frac{d}{dx} T \right) + \frac{d}{dy} \left(k \frac{d}{dy} T \right) + q \tag{12}$$

We discretize and insert an intermediate time step, denoted by the superscript $n + \frac{1}{2}$, and we use the approach of Douglas and use different temperature estimates for the different operators in the two steps. Δt is the time difference between sub-steps, that is, the time difference between n and n + 1 is $2\Delta t$. The equation for the step from n to $n + \frac{1}{2}$ is

$$c_{\text{VHC}} \frac{\Delta T}{\Delta t} = \frac{\Delta_x}{\Delta x} \left(k \frac{\Delta_x}{2\Delta x} \left(T^n + T^{n + \frac{1}{2}} \right) \right) + \frac{\Delta_y}{\Delta y} \left(k \frac{\Delta_y}{\Delta y} T^n \right) + q \tag{13}$$

and the equation for the step from $n+\frac{1}{2}$ to n+1 is

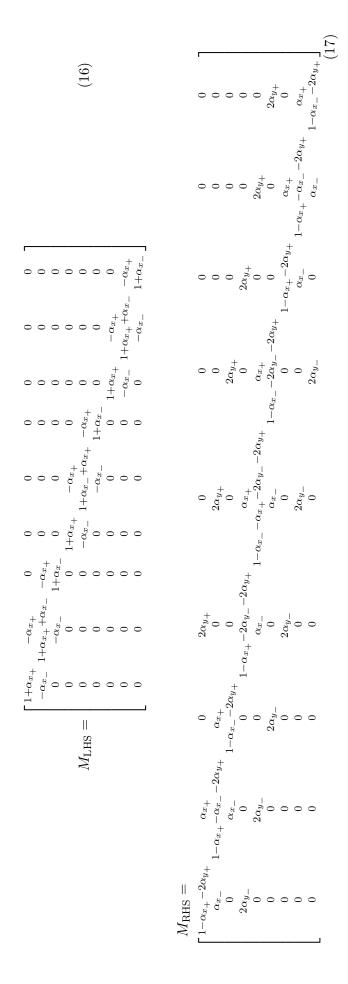
$$c_{\text{VHC}} \frac{\Delta T}{\Delta t} = \frac{\Delta_x}{\Delta x} \left(k \frac{\Delta_x}{2\Delta x} \left(T^n + T^{n+\frac{1}{2}} \right) \right) + \frac{\Delta_y}{\Delta y} \left(k \frac{\Delta_y}{2\Delta y} \left(T^n + T^{n+1} \right) \right) + q \tag{14}$$

Introducing α and β as in the 1D case, we get for the first step

$$-\alpha_{x_{+}}T_{i+1,j}^{n+\frac{1}{2}} + \left(1 + \alpha_{x_{+}} + \alpha_{x_{-}}\right)T_{i,j}^{n+\frac{1}{2}} - \alpha_{x_{-}}T_{i-1,j}^{n+\frac{1}{2}} = \alpha_{x_{+}}T_{i+1,j}^{n} + 2\alpha_{y_{+}}T_{i,j+1}^{n} + \left(1 - \alpha_{x_{+}} - \alpha_{x_{-}} - 2\alpha_{y_{+}} - 2\alpha_{y_{-}}\right)T_{i,j}^{n} + \alpha_{x_{-}}T_{i-1,j}^{n} + 2\alpha_{y_{-}}T_{i,j-1}^{n} + \beta$$

$$(15)$$

Writing this in matrix form we get (example shown for grid with size 3 in the x direction and size 3 in the y direction)



Before the second step, we transpose the grid (in practice rearranging the ordering of the data in the PCs memory representation), which I will show in the following by having the subscript j index (which still corresponds to the y direction) first and the i index last.

$$-\alpha_{y_{+}}T_{j+1,i}^{n+1} + \left(1 + \alpha_{y_{+}} + \alpha_{y_{-}}\right)T_{j,i}^{n+1} - \alpha_{y_{-}}T_{j-1,i}^{n+1} = \alpha_{x_{+}}T_{j,i+1}^{n} + \alpha_{y_{+}}T_{j+1,i}^{n} + \left(-\alpha_{x_{+}} - \alpha_{x_{-}} - \alpha_{y_{+}} - \alpha_{y_{-}}\right)T_{j,i}^{n} + \alpha_{x_{-}}T_{j,i-1}^{n} + \alpha_{y_{-}}T_{j-1,i}^{n} + \alpha_{x_{+}}T_{j,i+1}^{n+\frac{1}{2}} + \left(1 - \alpha_{x_{+}} - \alpha_{x_{-}}\right)T_{j,i}^{n+\frac{1}{2}} + \alpha_{x_{-}}T_{j,i-1}^{n+\frac{1}{2}} + \beta \quad (18)$$