```
import required packages
import numpy as np
import cv2
import matplotlib.pyplot as plt
from sklearn.metrics import classification_report
from sklearn.linear_model import LogisticRegression
import time
import datetime
from sklearn.model_selection import train_test_split
```

## 1. Load the datasets

For the project, we provide a training set with 50000 images in the directory .../data/images/ with:

- noisy labels for all images provided in ../data/noisy\_label.csv;
- clean labels for the first 10000 images provided in ../data/clean\_labels.csv .

```
# [DO NOT MODIFY THIS CELL]

# Load the images
n_img = 50000
n_noisy = 40000
n_clean_noisy = n_img - n_noisy
imgs = np.empty((n_img,32,32,3))
for i in range(n_img):
    img_fn = f'../data/images/{i+1:05d}.png'
    imgs[i,:,::]=cv2.cvtColor(cv2.imread(img_fn),cv2.COLOR_BGR2RGB)

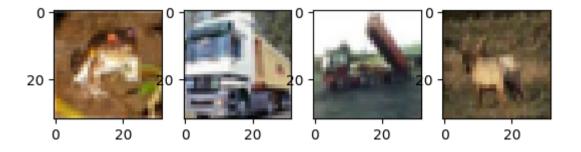
# Load the Labels
clean_labels = np.genfromtxt('../data/clean_labels.csv', delimiter=',', dtype="int8")
noisy_labels = np.genfromtxt('../data/noisy_labels.csv', delimiter=',', dtype="int8")
```

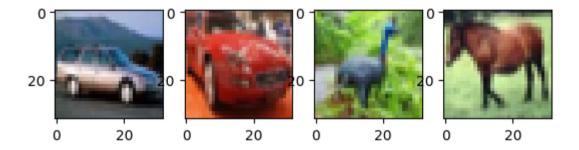
For illustration, we present a small subset (of size 8) of the images with their clean and noisy labels in clean\_noisy\_trainset . You are encouraged to explore more characteristics of the label noises on the whole dataset.

```
In [6]: # [DO NOT MODIFY THIS CELL]
fig = plt.figure()
```

```
ax1 = fig.add subplot(2,4,1)
ax1.imshow(imgs[0]/255)
ax2 = fig.add subplot(2,4,2)
ax2.imshow(imgs[1]/255)
ax3 = fig.add_subplot(2,4,3)
ax3.imshow(imgs[2]/255)
ax4 = fig.add_subplot(2,4,4)
ax4.imshow(imgs[3]/255)
ax1 = fig.add_subplot(2,4,5)
ax1.imshow(imgs[4]/255)
ax2 = fig.add_subplot(2,4,6)
ax2.imshow(imgs[5]/255)
ax3 = fig.add_subplot(2,4,7)
ax3.imshow(imgs[6]/255)
ax4 = fig.add_subplot(2,4,8)
ax4.imshow(imgs[7]/255)
# The class-label correspondence
classes = ('plane', 'car', 'bird', 'cat',
            'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
# print clean labels
print('Clean labels:')
print(' '.join('%5s' % classes[clean_labels[j]] for j in range(8)))
# print noisy labels
print('Noisy labels:')
print(' '.join('%5s' % classes[noisy labels[j]] for j in range(8)))
Clean labels:
```

# Clean labels: frog truck truck deer car car bird horse Noisy labels: cat dog truck frog dog ship bird deer





# 2. The predictive model

We consider a baseline model directly on the noisy dataset without any label corrections. RGB histogram features are extracted to fit a logistic regression model.

## 2.1. Baseline Model

```
In [7]: # [DO NOT MODIFY THIS CELL]
# RGB histogram dataset construction
no_bins = 6
bins = np.linspace(0,255,no_bins) # the range of the rgb histogram
target_vec = np.empty(n_img)
feature_mtx = np.empty((n_img,3*(len(bins)-1)))
i = 0
for i in range(n_img):
    # The target vector consists of noisy labels
target_vec[i] = noisy_labels[i]
```

```
# Use the numbers of pixels in each bin for all three channels as the features
feature1 = np.histogram(imgs[i][:,:,0],bins=bins)[0]
feature2 = np.histogram(imgs[i][:,:,1],bins=bins)[0]
feature3 = np.histogram(imgs[i][:,:,2],bins=bins)[0]

# Concatenate three features
feature_mtx[i,] = np.concatenate((feature1, feature2, feature3), axis=None)
i += 1
```

```
# [DO NOT MODIFY THIS CELL]
# Train a Logistic regression model
clf = LogisticRegression(random_state=0).fit(feature_mtx, target_vec)
```

For the convenience of evaluation, we write the following function predictive\_model that does the label prediction. For your predictive model, feel free to modify the function, but make sure the function takes an RGB image of numpy.array format with dimension  $32 \times 32 \times 3$  as input, and returns one single label as output.

#### 2.2. Model I

```
In [69]: #!pip install tensorflow

In [10]: import tensorflow as tf from tensorflow import keras
```

```
In [11]:
          # [BUILD A MORE SOPHISTICATED PREDICTIVE MODEL]
          # write your code here...
          def model I(image):
              This function should takes in the image of dimension 32*32*3 as input and returns a label prediction
              # write your code here...
              result = model1.predict(np.array([image/255,]))
              result = np.argmax(result,axis = 1)
              return result
In [12]:
          def create_model_I():
              model = tf.keras.models.Sequential([tf.keras.layers.BatchNormalization(),
                                                   tf.keras.layers.Conv2D(32, (3,3),strides=1,padding="same",
                                                                          activation='tanh', input_shape=(28, 28, 1)),
                                                   tf.keras.layers.MaxPooling2D((2, 2)),
                                                   tf.keras.layers.Conv2D(64, (3,3),strides=1,padding="same", activation='tanh'),
                                                   tf.keras.layers.MaxPooling2D((2, 2)),
                                                   tf.keras.layers.Flatten(),
                                                   tf.keras.layers.Dropout(0.8),
                                                   tf.keras.layers.Dense(30, activation='relu'),
                                                   tf.keras.layers.Dense(10, activation="softmax")])
              return model
In [13]:
          start time = time.time()
          model1 new = create_model_I()
          #compile model
          #model1 new.compile(loss='sparse categorical crossentropy'.optimizer=tf.keras.optimizers.Adam(0.0005).metrics=['accuracy'])
          model1 new.compile(optimizer='adam',
                        loss='sparse categorical crossentropy',
                        metrics=['accuracy'])
          #model fitting
          early stop = tf.keras.callbacks.EarlyStopping(patience=3)
```

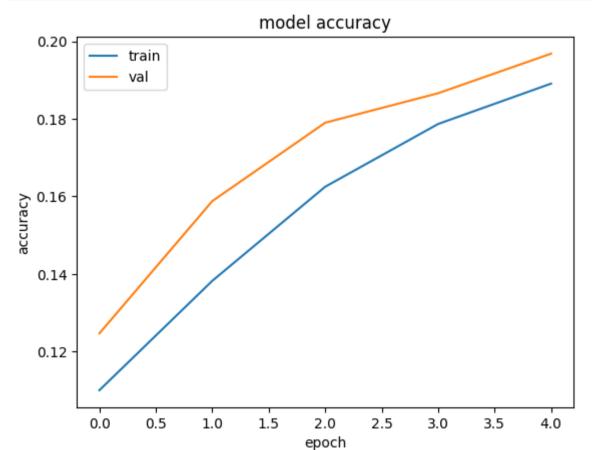
# model1.fit(imqs,noisy labels,epochs = 5, validation split =0.2,callbacks=[timer,early stop])

log dir = "logs/fit/" + datetime.datetime.now().strftime("%Y%m%d-%H%M%S")

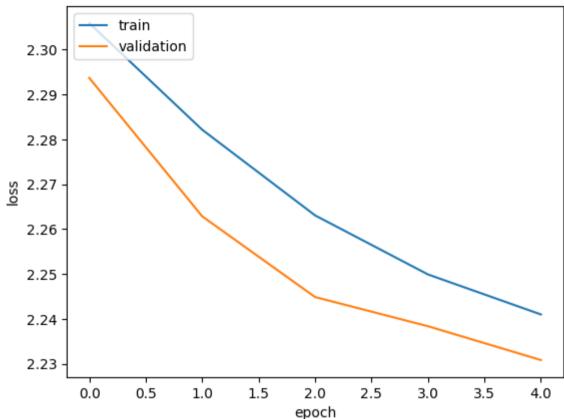
```
tensorboard callback = tf.keras.callbacks.TensorBoard(log dir=log dir, histogram freq=1)
      history=model1 new.fit(x=imgs,
            y=noisy labels,
            batch size=256,
            epochs=5,
            validation split =0.2,
            callbacks=[tensorboard callback])
      print('----Model1 run time: %s seconds----'%(time.time()-start time))
     Epoch 1/5
     247
     Epoch 2/5
     588
     Epoch 3/5
     790
     Epoch 4/5
     866
     Epoch 5/5
     968
     -----Model1 run time: 122.34153962135315 seconds-----
In [14]:
      #save trained model
      model1 new.save('model1')
     WARNING:absl:Found untraced functions such as jit compiled convolution op, jit compiled convolution op, update step xla while s
     aving (showing 3 of 3). These functions will not be directly callable after loading.
     INFO:tensorflow:Assets written to: model1\assets
     INFO:tensorflow:Assets written to: model1\assets
In [15]:
      import pandas as pd
In [24]:
      #### plot the acc and loss
      plt.plot(history.history['accuracy'])
      plt.plot(history.history['val accuracy'])
      plt.title('model accuracy')
      plt.ylabel('accuracy')
```

```
plt.xlabel('epoch')
plt.legend(['train', 'val'], loc='upper left')
plt.show()

##plot Loss
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'validation'], loc='upper left')
plt.show()
```





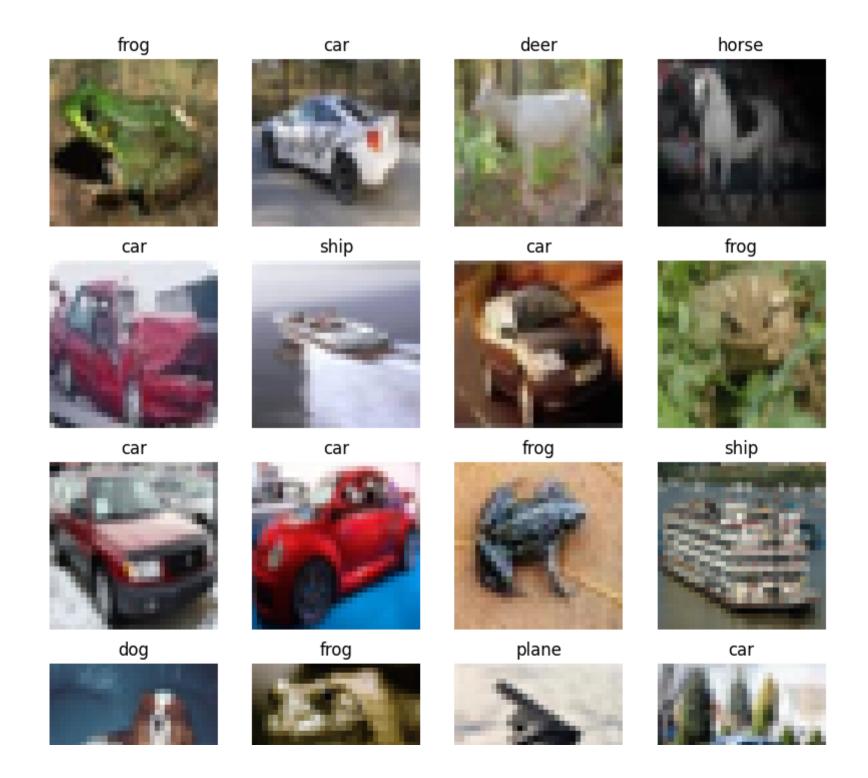


## 2.3. Model II

```
import matplotlib.pyplot as plt
imgs_c = imgs[:10000].reshape(-1,32,32,3)

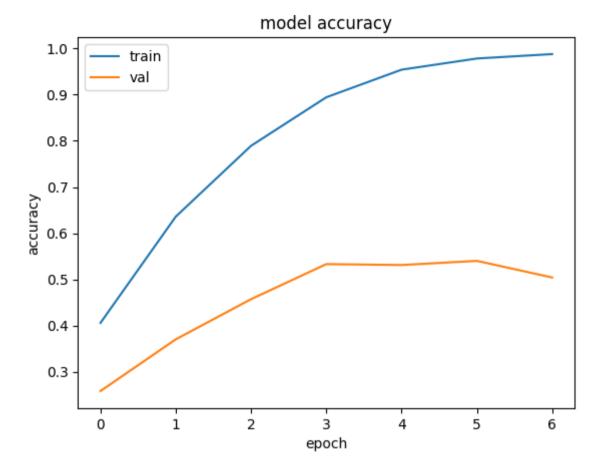
fig, ax = plt.subplots(4,4, figsize = (10,10))
for i in range(4):
    for j in range(4):
        n = int(np.random.randint(10000, size=1))
        ax[i,j].imshow(imgs_c[n]/255)
```

```
ax[i,j].title.set_text(classes[clean_labels[n]])
ax[i,j].axis("off")
```

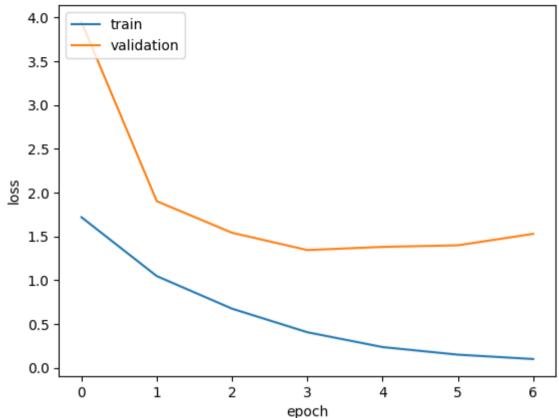


```
In [19]:
       import tensorflow as tf
       def label cor():
          model = tf.keras.Sequential([
           tf.keras.layers.Conv2D(128, (2, 2), activation='relu', input_shape=(32, 32, 3)),
           tf.keras.layers.Dropout(0.1),
           tf.keras.layers.BatchNormalization(),
           tf.keras.layers.Conv2D(64, (2, 2), activation='relu'),
           tf.keras.layers.Dropout(0.1),
           tf.keras.layers.BatchNormalization(),
           tf.keras.layers.Flatten(),
           tf.keras.layers.Dense(64, activation='relu'),
           tf.keras.layers.Dropout(0.1),
           tf.keras.layers.BatchNormalization(),
           tf.keras.layers.Dense(10, activation='softmax')
       1)
          return model
In [20]:
       #train based on clear data
       label corr = label cor()
       #compile model
       label corr.compile(loss='sparse categorical crossentropy', optimizer=tf.keras.optimizers.Nadam(),metrics=['accuracy'])
       #model fitting
       early stop =tf.keras.callbacks.EarlyStopping(patience=3)
       history21=label corr.fit(x=imgs c, y=clean labels, epochs=30,batch size=256,validation split =0.1,callbacks=[early stop])
       print('----label corr run time: %s seconds----'%(time.time()-start time))
       Epoch 1/30
       Epoch 2/30
       Epoch 3/30
```

```
Epoch 4/30
     Epoch 5/30
     Epoch 6/30
     Epoch 7/30
     ----label corr run time: 588.6727545261383 seconds----
In [35]:
     #### plot the acc and loss
     plt.plot(history21.history['accuracy'])
     plt.plot(history21.history['val accuracy'])
     plt.title('model accuracy')
     plt.ylabel('accuracy')
     plt.xlabel('epoch')
     plt.legend(['train', 'val'], loc='upper left')
     plt.show()
     ##plot loss
     plt.plot(history21.history['loss'])
     plt.plot(history21.history['val_loss'])
     plt.title('model loss')
     plt.ylabel('loss')
     plt.xlabel('epoch')
     plt.legend(['train', 'validation'], loc='upper left')
     plt.show()
```



## model loss



```
In [37]: # [ADD WEAKLY SUPERVISED LEARNING FEATURE TO MODEL I]

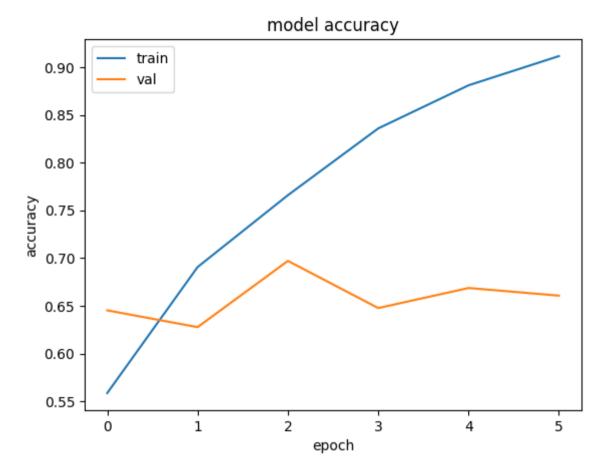
# write your code here...

def model_II(image):
    ...
    This function should takes in the image of dimension 32*32*3 as input and returns a label prediction
    ...
    # write your code here...
    result = model1.predict(np.array([image/255,]))
    result = np.argmax(result,axis = 1)
    return result
```

```
In [38]:
         #create training and testing set for model
         imgs c = imgs[:10000].reshape(-1,32,32,3)
         x tr, x te, y tr, y te = train test split(imgs c,clean labels,test size=0.2,random state=42)
In [39]:
          from sklearn.metrics import accuracy score, confusion matrix,precision score
In [40]:
         #create training and testing set for model
         imgs c = imgs[:10000].reshape(-1,32,32,3)
         noisy lab = (np.array(noisy labels[10000:])).reshape(-1,1)
          x_tr, x_te, y_tr, y_te = train_test_split(imgs c,noisy lab[:10000],test size=0.2,random state=42)
          x tr = tf.cast(x tr,dtype='float32')/255.0
         x te = tf.cast(x te,dtype='float32')/255.0
In [41]:
          #clean 40000 after pic
         imgs n = imgs[10000:].reshape(-1,32,32,3)
          new predictions = np.argmax(label corr.predict(imgs n),axis=1)
         In [42]:
          # #aet cleaned labels
          # imas n = imas[10000:].reshape(-1,32,32,3)
          # imas n = tf.cast(imas n.dtvpe='float32')/255.0
          # cleaned labels = np.argmax(label corr.predict(imgs n),axis=1)
         labels = np.append(clean labels, new predictions)
          #create training and testing set for modelII
          #x tr, x te, y tr, y te = train_test_split(imgs,labels,test_size=0.1,shuffle=False)
In [43]:
         def create model II():
              model = tf.keras.Sequential([
               tf.keras.layers.Conv2D(128, (2, 2), activation='relu', input shape=(32, 32, 3)),
               tf.keras.layers.Dropout(0.1),
               tf.keras.layers.BatchNormalization(),
               tf.keras.layers.Conv2D(64, (2, 2), activation='relu'),
               tf.keras.layers.Dropout(0.1),
```

```
tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Flatten(),
        tf.keras.layers.Dense(64, activation='relu'),
        tf.keras.layers.Dropout(0.1),
        tf.keras.layers.BatchNormalization(),
        tf.keras.layers.Dense(10, activation='softmax')
     1)
       return model
In [44]:
     model2= create model II()
In [45]:
     start time = time.time()
     #compile model
     model2.compile(loss='sparse categorical crossentropy',optimizer=tf.keras.optimizers.Nadam(),metrics=['accuracy'])
     #model fitting
     early stop = tf.keras.callbacks.EarlyStopping(patience=3)
     history2=model2.fit(x=imgs, y=labels, epochs=10, validation split =0.1,callbacks=[early stop])
     print('----Model1 run time: %s seconds----'%(time.time()-start time))
     Epoch 1/10
     0.6452
     Epoch 2/10
    0.6276
     Epoch 3/10
    0.6970
     Epoch 4/10
    0.6476
     Epoch 5/10
     0.6686
     Epoch 6/10
    0.6606
     -----Model1 run time: 1539.0410952568054 seconds-----
```

```
In [46]:
          #save trained model
          model2.save('model2')
         WARNING:absl:Found untraced functions such as _jit_compiled_convolution_op, _jit_compiled_convolution_op, _update_step_xla while s
         aving (showing 3 of 3). These functions will not be directly callable after loading.
         INFO:tensorflow:Assets written to: model2\assets
         INFO:tensorflow:Assets written to: model2\assets
In [47]:
          #### plot the acc and loss
          plt.plot(history2.history['accuracy'])
          plt.plot(history2.history['val accuracy'])
          plt.title('model accuracy')
          plt.ylabel('accuracy')
          plt.xlabel('epoch')
          plt.legend(['train', 'val'], loc='upper left')
          plt.show()
          ##plot loss
          plt.plot(history2.history['loss'])
          plt.plot(history2.history['val loss'])
          plt.title('model loss')
          plt.ylabel('loss')
          plt.xlabel('epoch')
          plt.legend(['train', 'validation'], loc='upper left')
          plt.show()
```





# 3. Evaluation

For assessment, we will evaluate your final model on a hidden test dataset with clean labels by the evaluation function defined as follows.

Although you will not have the access to the test set, the function would be useful for the model developments. For example, you can split the small training set, using one portion for weakly supervised learning and the other for validation purpose.

```
In [39]:
# [DO NOT MODIFY THIS CELL]
def evaluation(model, test_labels, test_imgs):
    y_true = test_labels
    y_pred = []
    for image in test_imgs:
```

```
y_pred.append(model(image))
print(classification_report(y_true, y_pred))
```

```
In []: # [DO NOT MODIFY THIS CELL]
# This is the code for evaluating the prediction performance on a testset
# You will get an error if running this cell, as you do not have the testset
# Nonetheless, you can create your own validation set to run the evaluation
n_test = 10000
test_labels = np.genfromtxt('../data/test_labels.csv', delimiter=',', dtype="int8")
test_imgs = np.empty((n_test,32,32,3))
for i in range(n_test):
    img_fn = f'../data/test_images/test{i+1:05d}.png'
    test_imgs[i,:,::]=cv2.cvtColor(cv2.imread(img_fn),cv2.COLOR_BGR2RGB)
evaluation(baseline_model, test_labels, test_imgs)
```

The overall accuracy is 0.24, which is better than random guess (which should have a accuracy around 0.10). For the project, you should try to improve the performance by the following strategies:

- Consider a better choice of model architectures, hyperparameters, or training scheme for the predictive model;
- Use both clean\_noisy\_trainset and noisy\_trainset for model training via **weakly supervised learning** methods. One possible solution is to train a "label-correction" model using the former, correct the labels in the latter, and train the final predictive model using the corrected dataset.
- Apply techniques such as k-fold cross validation to avoid overfitting;
- Any other reasonable strategies.

```
In []: # [DO NOT MODIFY THIS CELL]
# This is the code for evaluating the prediction performance on a testset
```

```
# You will get an error if running this cell, as you do not have the testset
# Nonetheless, you can create your own validation set to run the evlauation
n_test = 10000
test_labels = np.genfromtxt('../data/test_labels.csv', delimiter=',', dtype="int8")
test_imgs = np.empty((n_test,32,32,3))
for i in range(n_test):
    img_fn = f'../data/test_images/test{i+1:05d}.png'
    test_imgs[i,:,:,:]=cv2.cvtColor(cv2.imread(img_fn),cv2.COLOR_BGR2RGB)
evaluation(baseline_model, test_labels, test_imgs)
```

```
In [ ]:
        #generate classification report
         ##1. baseline
        feature mtx pred = np.empty((10000,3*(len(bins)-1)))
         for i in range(10000):
             # Use the numbers of pixels in each bin for all three channels as the features
            feature1 = np.histogram(test_imgs[i][:,:,0],bins=bins)[0]
             feature2 = np.histogram(test imgs[i][:,:,1],bins=bins)[0]
            feature3 = np.histogram(test imgs[i][:,:,2],bins=bins)[0]
             # Concatenate three features
             feature mtx pred[i,] = np.concatenate((feature1, feature2, feature3), axis=None)
            i += 1
         pred base = clf.predict(feature mtx pred)
         report base = classification report(test labels, pred base)
         print('-----baseline model classification report-----')
         print(report base)
         #model 1
        model1 pred = tf.keras.models.load model('model1')
         pred 1 = model1 pred.predict(test imgs)
         pred 1 = np.argmax(pred 1,axis=-1)
         report 1 = classification report(test labels, pred 1)
         print('-----')
         print(report 1)
         #model 2
         model2 pred = tf.keras.models.load model('model2')
         pred 2 = model2 pred.predict(test imgs)
```

```
pred 2 = np.argmax(pred 2,axis=-1)
        report 2 = classification report(test labels, pred 2)
         print('-----')
         print(report 2)
In [ ]:
        #generate prediction for models and export csv file
        output df = pd.DataFrame()
         #haseline
        feature mtx pred = np.empty((10000,3*(len(bins)-1)))
        for i in range(10000):
            # Use the numbers of pixels in each bin for all three channels as the features
            feature1 = np.histogram(test_imgs[i][:,:,0],bins=bins)[0]
            feature2 = np.histogram(test_imgs[i][:,:,1],bins=bins)[0]
            feature3 = np.histogram(test imgs[i][:,:,2],bins=bins)[0]
             # Concatenate three features
            feature mtx pred[i,] = np.concatenate((feature1, feature2, feature3), axis=None)
             i += 1
         pred base = clf.predict(feature mtx pred)
         pred base = clf.predict(feature mtx pred)
         #model1
         model1 pred = tf.keras.models.load model('model1')
         pred 1 = model1 pred.predict(test imgs)
         pred 1 = np.argmax(pred 1,axis=-1)
         #model 2
         model2 pred = tf.keras.models.load model('model2')
        pred 2 = model2 pred.predict(test imgs)
        pred 2 = np.argmax(pred 2,axis=-1)
         index vals = np.arange(10000)
        output df = pd.DataFrame(index=index vals)
         output df['baseline pred'] = pred base
        output df['modelI pred'] = pred 1
        output df['modelII pred'] = pred 2
         output df.to csv('label prediction.csv')
```

# 4. Report

Below is a brief report that summarizes the development of an image classification AI model to address the limitations of a client's existing approach.

#### 4.1 Problem statement

The objective of this project is to develop an image classification AI model that effectively addresses the limitations of the client's current practice, which relies on simple logistic regression and assumes clean labels. The new model must be sophisticated enough to handle the given dataset of 50,000 images with noisy labels and an additional 10,000 images with cleaned labels, while maintaining a balance between memory cost and running time cost. The model should be capable of learning from potentially untrustworthy sources and providing accurate classification results. The end goal is to deliver a robust, efficient, and scalable solution that surpasses the performance of the client's existing logistic regression-based approach for their image classification needs.

## 4.2 Baseline model (Client's model)

The client's baseline model employs logistic regression, a linear model that utilizes a single linear boundary to distinguish classes in the feature space, while treating noisy labels as clean labels. This simple and interpretable model is effective for clean, linearly separable datasets. However, logistic regression has inherent limitations in capturing complex relationships between input features and is potentially inadequate for handling datasets with noise and non-linear decision boundaries. Consequently, this approach may not yield optimal performance in the context of the client's mixed dataset, which includes noisy and cleaned labels.

### 4.3 Model I

We propose Model I, a Convolutional Neural Network (CNN), as an alternative to the logistic regression-based baseline model. Model I utilizes all 50k images and 50k noisy labels, treating them as clean data during training. The architecture includes a batch normalization layer, two CNN layers with Conv2D and MaxPooling2D, a Flatten layer, a Dropout layer, and two Dense layers with ReLU and softmax activations. The model is fitted using an 80% training and 20% validation split, with the Adam optimizer, sparse categorical cross-entropy loss function, and an early stopping callback to prevent overfitting.

In comparison to the baseline logistic regression model, Model I is a deep learning approach that can learn more complex representations of images, automatically extract features, and classify images more accurately. However, this model does not incorporate weakly supervised learning features and treats noisy data as clean data during training.

The performance of Model I shows a slight improvement in accuracy over the baseline model, with around 20% accuracy on both the training and validation sets. Despite this improvement, the classification results are still not ideal. The runtime for Model I is around 120 seconds, indicating its potential to be optimized further.

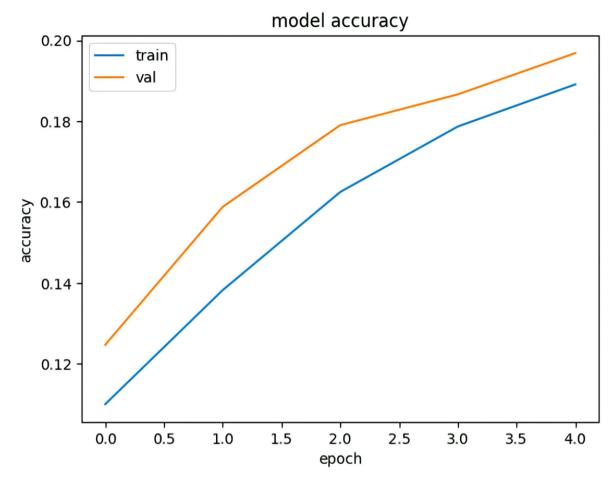


Figure 1: model trained with 50k noisy labels.

#### 4.4 Model II

Model II, an improved Convolutional Neural Network (CNN), is designed to address the limitations of the baseline model and Model I. The architecture consists of two CNN layers with 128(1) and 64(2) 2x2 filters, ReLU activation, 10% dropout, and batch normalization. It also includes a Flatten layer, a Dense layer with ReLU activation, another Dropout layer, a BatchNormalization layer, and a final Dense layer with softmax activation.

For training, Model II uses a weakly supervised learning approach, leveraging 50k images and 10k cleaned labels. Initially, the CNN is trained with the first 10k images and their corresponding clean labels. This model then predicts clean labels for the remaining 40k images with noisy labels. The model

is subsequently retrained using the original 10k clean labels and 40k corrected labels, with a 90% training and 10% validation split, Nadam optimizer, sparse categorical cross-entropy loss function, and an early stopping callback.

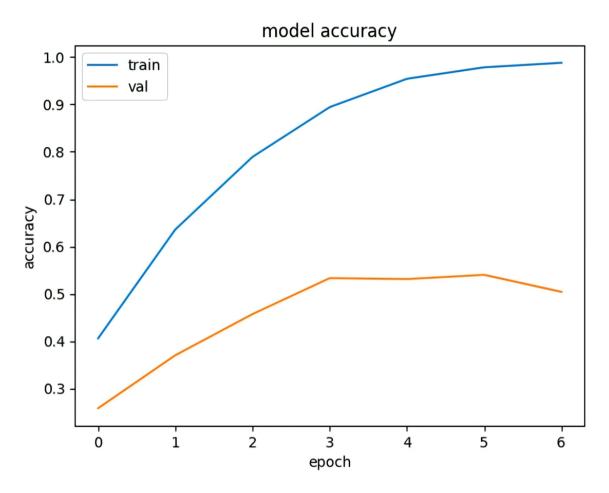


Figure 2: model trained with 10k clean labels.

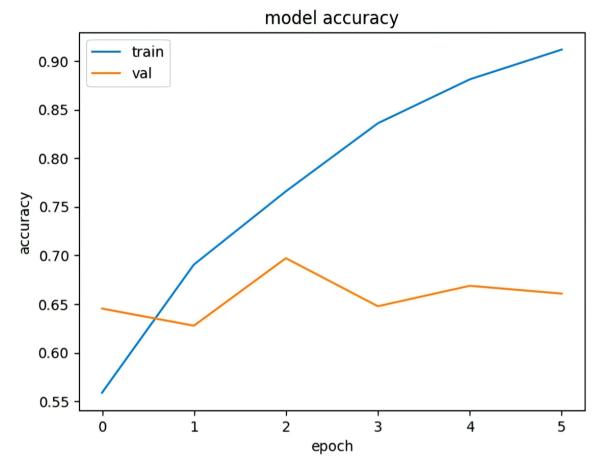


Figure 3: model trained with 10k clean labels and 40k corrected labels.

Model II demonstrates superior performance compared to the baseline model and Model I. When trained with 10k clean labels, it achieves 99% training accuracy and 50% validation accuracy. After retraining with the 10k clean labels and 40k corrected labels, the model's performance improves to 88% training accuracy and 65% validation accuracy, with a runtime of around 1200 seconds.

This improved model benefits from more accurate training data, a more complex architecture, and the use of regularization techniques such as dropout and batch normalization. These enhancements enable Model II to learn complex, non-linear relationships between input and output, leading to better overall performance.

#### 4.5 Conclusions and Recommendations

In conclusion, Model II, with its more complex CNN architecture, regularization techniques, and a combination of clean and predicted labels for training, has proven to be superior to both the baseline logistic regression model and the simpler CNN architecture of Model I in image classification tasks. Although Model II has a longer running time compared to Model I, it significantly outperforms Model I in terms of accuracy, striking a balance between running time cost and accuracy given the large volume of data.

For future improvements, we recommend exploring hyperparameter tuning through techniques such as grid-search to test different learning rates, batch sizes, and dropout rates, which can further optimize the model and enhance its performance. Additionally, ensemble learning, which combines multiple models (e.g., Model II with other CNN architectures), can be employed to improve the model's accuracy and robustness.