## In The Name of God Computer Engineering Department of Amirkabir University of Technology

## Microprocessors Homework 7 -

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All of the delay times are calculated with the clock frequncy of 1Mhz. The delay for writing to EEPROM is 1 ms. Which I used a 1000 loop in order to create this delay.

And the delay for reading from EEPROM is in order of nano seconds which is lower than a single NOP. So I have used only one NOP.

Below are the timing tables for EEPROM 27c64 which I have used in order to use it as an EEPROM.

TABLE 1-3: READ OPERATION AC CHARACTERISTICS

	Outpu Input	it Load Rise a	Wavefold: Ind Fal Inperat	II Time	1 es: 10 C	VIH = 2.4V and VIL = 0.45V; VOH = 2.0V VOL = 0.8V 1 TTL Load + 100 pF 10 ns Commercial: Tamb = 0°C to +70°C Industrial: Tamb = -40°C to +85°C							
Parameter	Sym	27C64-12		27C64-15		27C64-17		27C64-20		27C64-25		Units	Conditions
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Units	Conditions
Address to Output Delay	tacc	_	120	_	150	_	170	_	200	1	250	ns	CE = OE = VIL
CE to Output Delay	tce	_	120	_	150	_	170	_	200	-	250	ns	OE = VIL
OE to Output Delay	toE	_	65	_	70	_	70	_	75	1	100	ns	CE = VIL
CE or OE to O/P High Impedance	toff	0	50	0	50	0	50	0	55	0	60	ns	
Output Hold from Address CE or OE, whichever occurs first	tон	0	_	0	-	0	_	0	_	0	_	ns	

**TABLE 1-5:** PROGRAMMING AC CHARACTERISTICS

for Program, Program Verify and Program Inhibit Modes  AC Testing Waveform: VIH=2.4V and VIL=0.45V; VOH=2.0V; VOL=0.8V Tamb=25°C ±5°C VCC= 6.5V ± 0.25V, VPP = VH = 13.0V ± 0.25V										
Parameter	Symbol	Min	Max	Units	Remarks					
Address Set-Up Time	tas	2	_	μs						
Data Set-Up Time	tos	2 _		μs						
Data Hold Time	tDH	2	_	μs						
Address Hold Time	tan	0	_	μs						
Float Delay (2)	tDF	0	130	ns						
Vcc Set-Up Time	tvcs	2	_	μs						
Program Pulse Width (1)	tpw	95	105	μs	100 μs typical					
CE Set-Up Time	tces	2	_	μs						
OE Set-Up Time	toes	2	_	μs						
VPP Set-Up Time	tvps	2	_	μs						
Data Valid from OE	toe	_	100	ns						

You can find the datasheet in the attached documents.

<sup>Note 1: For express algorithm, initial programming width tolerance is 100 μs ±5%.
2: This parameter is only sampled and not 100% tested. Output float is defined as the point where data is no longer driven (see timing diagram).</sup>