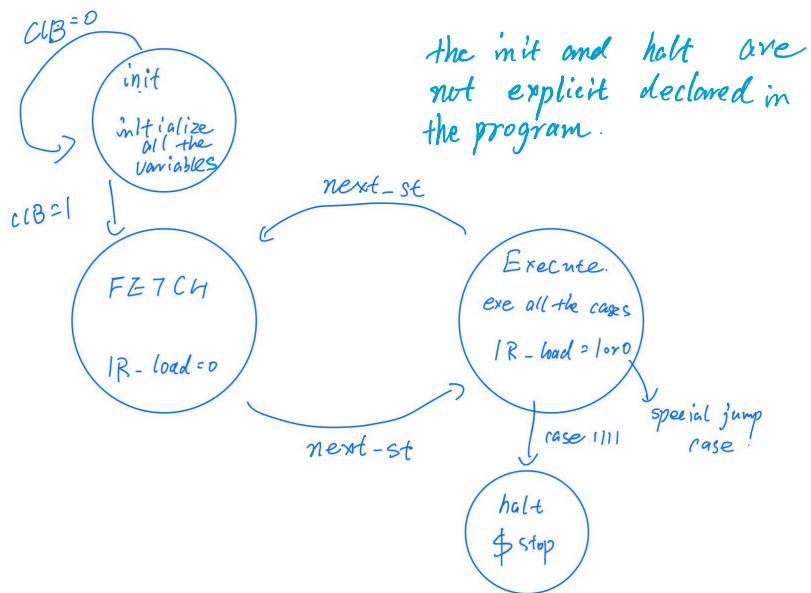


CSE664 Intro System-on-Chip Design

Project 1 part 2

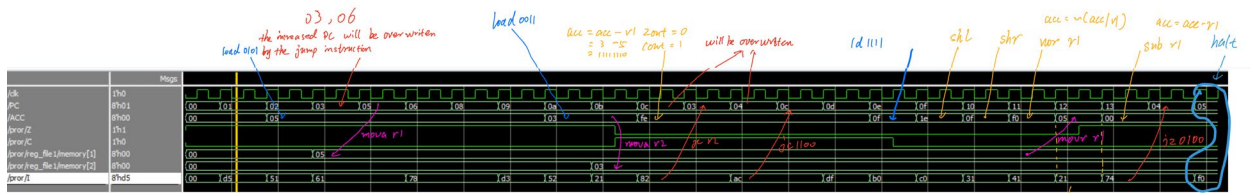
1. FSM of controller



2. Assembly code

| | |
|---------|----|
| ld 0101 | d5 |
| movb r1 | 51 |
| jz r1 | 61 |
| jc 1100 | AC |
| halt | f0 |
| jz 1000 | 78 |
| nop | 00 |
| nop | 00 |
| ld 0011 | d3 |
| movb r2 | 52 |
| sub r1 | 21 |
| jc r2 | 82 |
| ld 1111 | df |
| shl | b0 |
| shr | c0 |
| nor r1 | 31 |
| movb r1 | 41 |
| sub r1 | 21 |
| jz 0100 | 74 |
| nop | 00 |

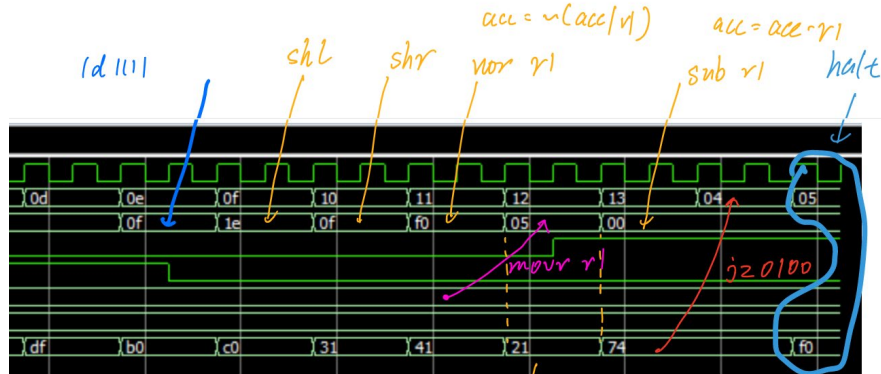
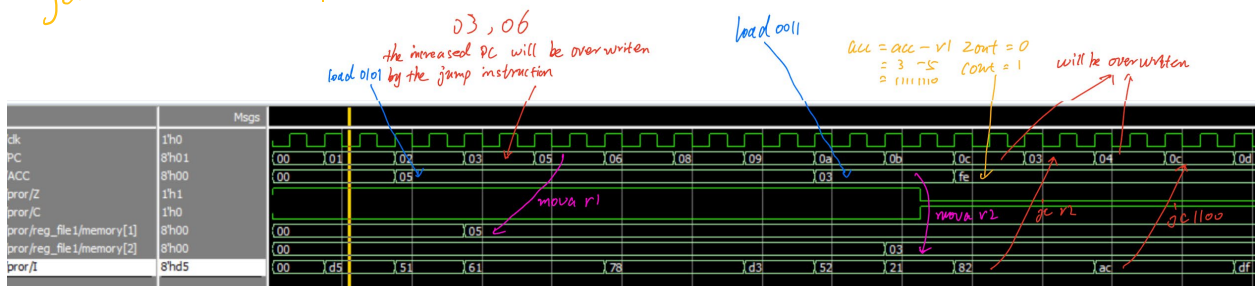
3. Waveform



red is jump operation
blue is load operation
purple is mov/r operation
yellow is ALU operation

Figure 1 The whole waveform

the program has a CPI = 2
the first half is the load instruction
the second half is the execute
So count will be 1 when
the execute phase.



the program has a CPI = 2
the first half is the load instruction
the second half is the execute
So count will be 1 when
the execute phase.

Figure 2&3 Same waveform but cropped for better view

4. PC issue
 - a. The start of the PC is different from the sample program.
 - b. The program counter will increase by 1 even if jump happens, but PC will later be overwritten by the jump target PC. So, this won't affect how the program works but will make the PC different from the sample program.

Both of the issue won't affect how the program works but will make expected ACC and expected PC different from the sample program.