

OBJECTIVE

I am a machine learning and computer vision researcher passionate about fine-grained video recognition and learning from simulation. My research contains two alternative directions for building robust vision solutions for real world problems. I care about top-down models that leverage compositionality to address the issue of complexity. I also build bottom-up data driven models trained using data generated by simulation engines. My research is applied to video surveillance and surgical data science. I thrive under a team environment and value diverse perspectives.

EDUCATION

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| Johns Hopkins University
Ph.D. in Computer Science, Advisor: Dr. Gregory D. Hager
– Thesis topic: “Towards Compositional Analysis of Fine-grained Activities” | Baltimore, MD
2015–Expected 2021 |
| Johns Hopkins University
M.S. in Computer Science, Advisor: Dr. Russell Taylor and Dr. Austin Reiter
– Thesis: “3D Reconstruction System using a Flexible Endoscope and a Laser” | Baltimore, MD
2014–2015 |
| Johns Hopkins University
B.S.E in Computer Science
– Graduated with general honors
– Minor: Robotics | Baltimore, MD
2010–2014 |

RESEARCH EXPERIENCE

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| Johns Hopkins University
Graduate Research Assistant
– The Deep Intermodal Video Analytics (DIVA) project by funded by IARPA
– The DIVA program is a US government funded multi-institutional research program that aims to develop a robust automated activity detection system for multi-camera video surveillance applications.
– As a senior Ph.D student of the JHU DIVA team, I assumed a leadership role in the team’s research, development and deployment of system deliverables to the program.
– I developed a zero-shot action recognition system that requires no labeled training examples of the test activities. (See publications: [1], [4])
– I developed a simulation software for synthesizing human activities from economic motion capture systems. We use the generated dataset to train activity recognition systems. (See publications: [2], [7]) | Baltimore, MD
2018-Current |
| Johns Hopkins University
Graduate Research Assistant
– Language of Surgery project funded by the Johns Hopkins Wilmer Eye Institute
– In collaboration with the surgeons from the Johns Hopkins Wilmer Eye Institute, the project aimed to build intelligent tools to automatically analyze videos of cataract surgery. | Baltimore, MD
2016-2018 |

- The goal is to build an intelligent system that provides actionable feedback to trainees by reviewing their surgical performance from video recordings.
- I showed that videos of cataract surgery can be annotated accurately at scale using crowd-sourced workers. (See publication: [6])
- As a machine learning and computer vision lead in the team, I developed deep learning algorithms to automatically recognize surgical phases from videos. (See publications: [5])
- I developed a deep learning model that provides objective assessment of surgical technical skill from cataract surgery videos. (See publication: [3])

Johns Hopkins University

Baltimore, MD

Masters Thesis Research

2014-2015

– System for stereo reconstruction from monoscopic endoscope images

- In collaboration with the department of head and neck surgery of the Johns Hopkins hospital, the project aimed to develop an economic solution for an endoscope capable of accurate 3D reconstruction of organs.
- I developed an active stereo vision system using a pattern generating laser inserted into a working channel of an endoscope.
- With a solution costing under a 100 dollars added to the endoscope, I developed a system capable of accurate 3D reconstruction using monoscopic endoscope images. (See patent: [10])

PROFESSIONAL EXPERIENCE

Siemens Healthineers (Siemens Corporate Research)

Princeton, NJ

Graduate Research Intern: hosted by Dr. Shaohua Kevin Zhou

Summer 2016

– Bone Removal Project

- The Bone Removal project developed deep learning algorithms to remove voxels representing bones in a computed tomography angiography volume.
- As an integrated software for immediate deployment in products, the bone removal software was required to be highly precise, efficient and fast.
- As a graduate research intern, I developed a novel 3D convolutional neural network architecture with separable convolutions for bone removal.
- My approach increased accuracy and precision while decreasing memory usage and inference time. The developed bone removal model was successfully deployed to commercial products. (See patents: [8], [9]).

Hyundai Heavy Industries, Medical Systems Department

Seoul, Korea

Undergraduate Research Intern

Summer 2012

– Medical Robotics Project

- The project aimed to build a minimally invasive surgical robot to remove malignant masses from breast cancer patients.
- As part of the computer vision team, I developed an algorithm for recognizing malignant/benign masses and cysts from breast ultrasound images. My main task involved data curation and implementation of state of the art machine learning algorithms.

TEACHING

- **Head Teaching Assistant** at Johns Hopkins University Fall 2015, 2016
Computer vision (Dr. Austin Reiter)
- **Head Teaching Assistant** at Johns Hopkins University Spring 2016
Augmented Reality (Dr. Nasir Navab)
- **Head Teaching Assistant** at Johns Hopkins University Summer 2015

SKILLS

- **Machine Learning/Computer Vision:** Python, Pytorch, Keras, Tensorflow, Opencv, Matlab
- **Simulation:** UnrealEngine, UnrealCV, Axis-Neuron, ROS
- **Other:** Html, Php, Javascript, Java, SQL, Android-Studio

LANGUAGES

- **Korean:** Native
- **English:** Bilingual

SERVICE

- **President** of Korean Graduate Students Association at JHU 2018–2019
As an elected leader of the Korean graduate student body, I served to provide constructive support, opportunities as well as entertainment to members of the Korean community at JHU.
- **Vice president** of Korean Graduate Students Association at JHU 2017–2018
As a VP of the largest Korean student group at JHU, my main responsibility involved networking with industry representatives for on-campus recruitment events and information sessions for Korean graduate students at JHU.
- **Reviewer** 2015–current
for CVPR, ICCV, ECCV, AAAI, MICCAI, IPCAI, TMI

PUBLICATIONS

- [1] **T.S. KIM***, J. Jones*, M. Peven*, Z. Xiao, J. Bai, Y. Zhang, W. Qiu, A. Yuille, and G. D. Hager, “Daszl: Dynamic action signatures for zero-shot learning”, in *AAAI*, 2021.
- [2] **T.S. KIM**, Michael, W. Qiu, A. Yuille, and G. D. Hager, “Synthesizing attributes with unreal engine for fine-grained activity analysis”, in *WACV-W*, 2019.
- [3] **T.S. KIM**, M. O’Brien, S. Zafar, A. Malpani, G. D. Hager, S. Sikder, and S. Vedula, “Objective assessment of intraoperative technical skill in capsulorhexis using videos of cataract surgery”, in *IJCARS*, 2019.
- [4] **T.S. KIM**, Y. Zhang, Z. Xiao, M. Peven, W. Qiu, J. Bai, A. Yuille, and G. D. Hager, “Safer: Fine-grained activity detection by compositional hypothesis testing”, in *arxiv*, 2019.
- [5] **T.S. KIM***, F. Yu*, G. S. Croso*, Z. Song, F. Parker, G. D. Hager, A. Reiter, S. Vedula, H. Ali, and S. Sikder, “Assessment of automated identification of phases in videos of cataract surgery using machine learning and deep learning techniques”, in *Jama Network Open*, 2019.
- [6] **T.S. KIM**, A. Malpani, A. Reiter, G. D. Hager, S. Sikder, and S. Vedula, “Crowdsourcing annotation of surgical instruments in videos of cataract surgery”, in *MICCAI-W*, 2018.
- [7] W. Qiu, F. Zhong, Y. Zhang, S. Qiao, Z. Xiao, **T.S. KIM**, Y. Wang, and A. Yuille, “Unrealcv: Virtual worlds for computer vision”, in *ACM-MM*, 2017.
- [8] S. K. Zhou, M. Chen, H. Ding, B. Georgescu, M. A. Gulsun, **T.S. Kim**, A. P. Kiraly, X. Lu, J.-h. Park, P. Sharma, S. Sun, D. Xu, Z. Xi, and Y. Zheng, “Method and system for artificial intelligence based medical image segmentation”, in *US Patent Application Number 62/414,913*, 2017.
- [9] M. Chen, **T.S. Kim**, J. Kretschmer, S. Seifert, S. K. Zhou, M. Schobinger, D. Liu, Z. Xu, S. Grbic, and H. Zhang, “Deep learning based bone removal in computed tomography angiography”, in *US Patent 10,852,907*, 2019.

- [10] K. C. Olds, **T.S. KIM**, R. H. Taylor, and A. Reiter, “System for stereo reconstruction from monoscopic endoscope images”, in *US Patent 10,368,720*, 2019.