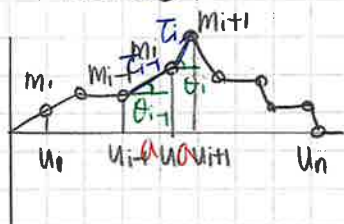


7. Lagrangian formalism in the continuum

① Example: 1-d string

(A) Discrete model



$$(i) \quad m_i \ddot{u}_i = \tau_i \sin \theta_i - \tau_{i-1} \sin \theta_{i-1} \quad (\text{for } i=1, 2, \dots, n)$$

$$u_0 = u_{n+1} = 0$$

$$(ii) \quad \text{assume } |\theta| \ll 1.$$

$$m_i \ddot{u}_i = \tau_i \tan \theta_i - \tau_{i-1} \tan \theta_{i-1} = \tau_i \frac{u_{i+1} - u_i}{a} - \tau_{i-1} \frac{u_i - u_{i-1}}{a}$$

$$(iii) \quad L = \sum_{i=1}^n \left[\frac{1}{2} m_i \dot{u}_i^2 - \frac{1}{2} \frac{\tau_i}{a} (u_{i+1} - u_i)^2 \right]$$

$$\frac{dL}{du_i} = \sum_{i=1}^n \frac{\tau_i}{a} (u_{i+1} - u_i), \quad \frac{d}{dt} \left(\frac{dL}{d\dot{u}_i} \right) = \sum_{i=1}^n m_i \ddot{u}_i$$

(B) Continuum limit

$$\left(\begin{array}{l} \text{limit: } a \rightarrow 0, n \rightarrow \infty \\ \text{constraint: } l = (n+1)a \end{array} \right) \rightarrow \text{변수} \quad x = ia \quad \left(\begin{array}{l} u_i(t) = u(ia, t) = u(x, t) \\ \tau_i(t) = \tau(ia, t) = \tau(x, t) \\ m_i/a = \lambda(ia) = \lambda(x) \end{array} \right)$$

$$(\text{경계조건: } u(0, t) = u(l, t) = 0)$$

$$\frac{m_i \ddot{u}_i}{a} = \frac{1}{a} \left[\tau_i \frac{u_{i+1} - u_i}{a} - \tau_{i-1} \frac{u_i - u_{i-1}}{a} \right] \rightarrow \lambda(x) \frac{\partial^2 u}{\partial t^2} = \frac{\partial}{\partial x} \left[\tau(x) \frac{\partial u}{\partial x} \right]$$

$$\text{for constant } \lambda \text{ and } \tau, \quad \frac{\partial^2 u}{\partial t^2} = \frac{\tau}{\lambda} \frac{\partial^2 u}{\partial x^2} = c_s^2 \frac{\partial^2 u}{\partial x^2} \rightarrow u_n^\pm(x, t) = \sin\left(\frac{2\pi x}{\ell}\right) e^{\pm i\omega_n t}$$

$$(\omega_n = \frac{n\pi c_s}{\ell})$$

• Lagrangian density

$$L = \sum_{i=1}^n a \left[\frac{1}{2} \frac{m_i}{a} \dot{u}_i^2 - \tau_i \left(\frac{u_{i+1} - u_i}{a} \right)^2 \right] \rightarrow \int_0^l dx \left[\frac{1}{2} \lambda(x) \left(\frac{du}{dt} \right)^2 - \tau(x) \left(\frac{du}{dx} \right)^2 \right]$$

$\mathcal{L}(u, \frac{du}{dt}, \frac{du}{dx}; x, t)$: Lagrangian density
(변수, 변인, 변인) 이 포함

② Hamilton's principle in the continuum

(A) Hamilton's principle

- $(x_\nu) = (x_0, x_1, \dots, x_d) = (t, \underline{x})$, u_1, u_2, \dots : $(u_p) = p^{\text{th}}$ field
(treating time and space equally)

notation $u_{p,\nu} \equiv du_p/dx_\nu$ (p^{th} field을 ν 방향으로 미분)

- Hamilton's principle : $\oint_{\Omega} d^{d+1}x \mathcal{L}(u_p, u_{p,\nu}; x_\nu) = 0$ (시공간 적분)

for variations, with $\delta u_p(x_\nu) = 0$ at $x_\nu \in \partial\Omega$
($u_p(x_\nu) \rightarrow u_p(x_\nu) + \delta u_p(x_\nu)$)

(B) Derivation of Lagrange's equations

$$\oint_{\Omega} d^{d+1}x \mathcal{L}(u_p, u_{p,\nu}; x_\nu) = \int_{\Omega} d^{d+1}x \left(\frac{d\mathcal{L}}{du_p} \cdot \delta u_p + \frac{d\mathcal{L}}{du_{p,\nu}} \delta u_{p,\nu} \right)$$

$$= \int_{\Omega} d^{d+1}x \left(\frac{d\mathcal{L}}{du_p} + \frac{d}{dx_\nu} \left(\frac{d\mathcal{L}}{du_{p,\nu}} \right) \right) \delta u_p = 0$$

$$\therefore \boxed{\frac{d\mathcal{L}}{du_p} - \frac{d}{dx_\nu} \left(\frac{d\mathcal{L}}{du_{p,\nu}} \right) = 0} \quad * \text{note: } \frac{d}{dx_\nu} \text{ 할 때, } x_\nu \text{ 에 의존적인 } u \text{ 들은 그대로 고려해야 함}$$

Application for $\mathcal{L} = \frac{1}{2} \lambda(x) \left(\frac{du}{dt} \right)^2 - \frac{1}{2} \tau(x) \left(\frac{du}{dx} \right)^2$

$$\frac{d\mathcal{L}}{du} - \frac{d}{dt} \left(\frac{d\mathcal{L}}{d(du/dt)} \right) - \frac{d}{dx} \left(\frac{d\mathcal{L}}{d(du/dx)} \right) = -\frac{d}{dt} \left(\lambda(x) \frac{du}{dt} \right) - \frac{d}{dx} \left(-\tau(x) \frac{du}{dx} \right) = 0$$

$$\Rightarrow \lambda(x) \frac{d^2 u}{dt^2} - \frac{d}{dx} \left(\tau(x) \frac{du}{dx} \right) = 0 \quad \leftarrow 1D \text{ string eqn}$$

③ Symmetries and conservation laws

(A) Noether's theorem

• infinitesimal coordinate and field transformation

$$x_\mu \rightarrow x'_\mu = x_\mu + \delta x_\mu, \quad u_p(x_\mu) \rightarrow u'_p(x'_\mu) = u_p(x_\mu) + \delta u_p(x_\mu)$$

• symmetry condition

$$\int_{\Omega'} d^4x' L(u'_p, u'_{p,\mu}; x'_\mu) = \int_{\Omega} d^4x L(u_p, u_{p,\mu}; x_\mu) + \frac{d}{dx_\nu} \delta \Lambda_\nu$$

(만약 transformation이 action의 위치를 바꾸면, 시스템의 역학은 transformation에 대해 cyclic/invariant 하다)

• Derivation of the conservation law

$$\begin{aligned} \int_{\Omega'} d^4x' L(u'_p, u'_{p,\mu}; x'_\mu) &= \int_{\Omega} d^4x L(u'_p, u'_{p,\mu}; x_\mu) + \int_{\partial\Omega} dS_\nu \delta x_\nu L(u_p, u_{p,\nu}; x_\mu) \\ (\text{발산정리}) \Rightarrow &= \int_{\Omega} d^4x L(u'_p, u'_{p,\mu}; x_\mu) + \frac{d}{dx_\nu} \delta x_\nu L(u_p, u_{p,\nu}; x_\mu) \end{aligned}$$

* Writing $u'_p(x_\mu) = u_p(x_\mu) + \bar{\delta} u_p(x_\mu)$ [$\bar{\delta} u_p \neq \delta u_p$]

$$\begin{aligned} L(u'_p, u'_{p,\nu}; x_\mu) &= L(u_p, u_{p,\nu}; x_\mu) + \frac{\partial L}{\partial u_p} \bar{\delta} u_p + \frac{\partial L}{\partial u_{p,\nu}} \bar{\delta} u_{p,\nu} \\ &= L(u_p, u_{p,\nu}; x_\mu) + \frac{d}{dx_\nu} \left(\frac{\partial L}{\partial u_{p,\nu}} \cdot \bar{\delta} u_p \right) \end{aligned}$$

$$\therefore \int_{\Omega} d^4x \frac{d}{dx_\nu} \left(\frac{\partial L}{\partial u_{p,\nu}} \cdot \bar{\delta} u_p + L \delta x_\nu - \delta \Lambda_\nu \right) = 0$$

$$\Rightarrow \boxed{\frac{d}{dx_\nu} \left(\frac{\partial L}{\partial u_{p,\nu}} \cdot \bar{\delta} u_p + L \delta x_\nu - \delta \Lambda_\nu \right) = 0}$$

parametrization of infinitesimal transformation

$$\delta x_\mu = \epsilon_r X_{r\mu}, \quad \delta u_p = \epsilon_r U_{rp}, \quad \delta \Lambda_\mu = \epsilon_r G_{r\mu} \quad (\epsilon_r, r=1,2,\dots,R)$$

* note: $\left(\underline{\delta u_p} = u_p'(x'_\mu) - u_p(x_\mu) = u_p'(x'_\mu) - u_p'(x_\mu) + \bar{\delta u_p} \approx \underline{\delta x_\mu u_{p,\mu}} + \bar{\delta u_p} \right)$

$$\bar{\delta u_p} = \epsilon_r (U_{rp} - u_{p,\mu} X_{r\mu})$$

$$\therefore \frac{d}{dx_\nu} \left[\left(L_{\delta u_\nu} - \frac{\partial L}{\partial u_{p,\nu}} u_{p,\mu} \right) X_{r\mu} + \frac{\partial L}{\partial u_{p,\nu}} U_{rp} - G_{r\nu} \right] = 0$$

$$\begin{aligned} \frac{d}{dt} \left(L X_{r0} - \frac{\partial L}{\partial u_{p,0}} u_{p,\mu} X_{r\mu} + \frac{\partial L}{\partial u_{p,0}} U_{rp} - G_{r0} \right) \\ = - \sum_{i=1}^d \frac{d}{dx_i} \left[\left(L_{\delta u_i} - \frac{\partial L}{\partial u_{p,i}} u_{p,\mu} \right) X_{r\mu} + \frac{\partial L}{\partial u_{p,i}} U_{rp} - G_{ri} \right] \end{aligned}$$

Noether charge is locally conserved.