

[Review] DetectoRS: Detecting Objects with Recursive Feature Pyramid and Switchable Atrous Convolution



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Introduction

Contribution

Exploring a backbone for object detector that looks at the images twice or more.

- Recursive Feature Pyramid (RFP)
- Switchable Atrous Convolution (SAC)
- DetectoRS by combining RFP and SAC



Table: A glimpse of the improvements of the box and mask AP by DetectoRS on COCO test-dev.

Method	Backbone	AP_{box}	AP_{mask}	FPS
HTC [4]	ResNet-50	43.6	38.5	4.3
DetectoRS	ResNet-50	51.3	44.4	3.9

Feature Pyramid Network (FPN) [2]

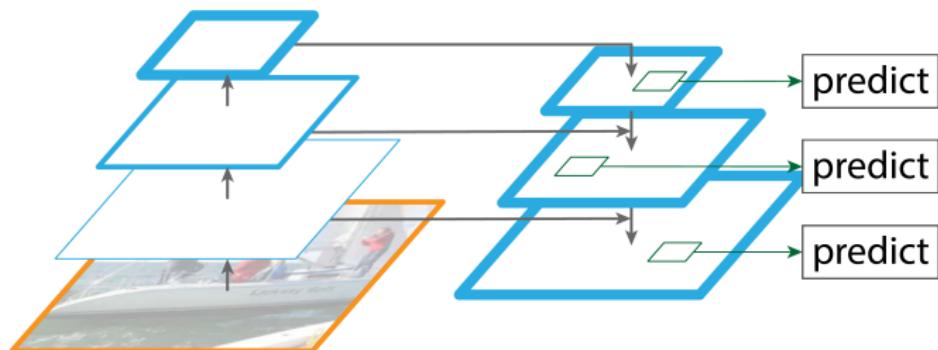


Figure: Feature pyramid network (FPN) [2].

Recursive formula for FPN

Let \mathbf{B}_i denote the i -th stage of the bottom-up backbone, and \mathbf{F}_i denote the i -th top-down FPN operation. The backbone equipped with FPN outputs a set of feature maps $\{\mathbf{f}_i | i = 1, \dots, S\}$, where S is the number of the stages.

$$\forall i = 1, \dots, S, \quad \mathbf{f}_i = \mathbf{F}_i(\mathbf{f}_{i+1}, \mathbf{x}_i) \quad \text{and} \quad \mathbf{x}_i = \mathbf{B}_i(\mathbf{x}_{i-1}).$$

Feature Pyramid Network (FPN) [2]

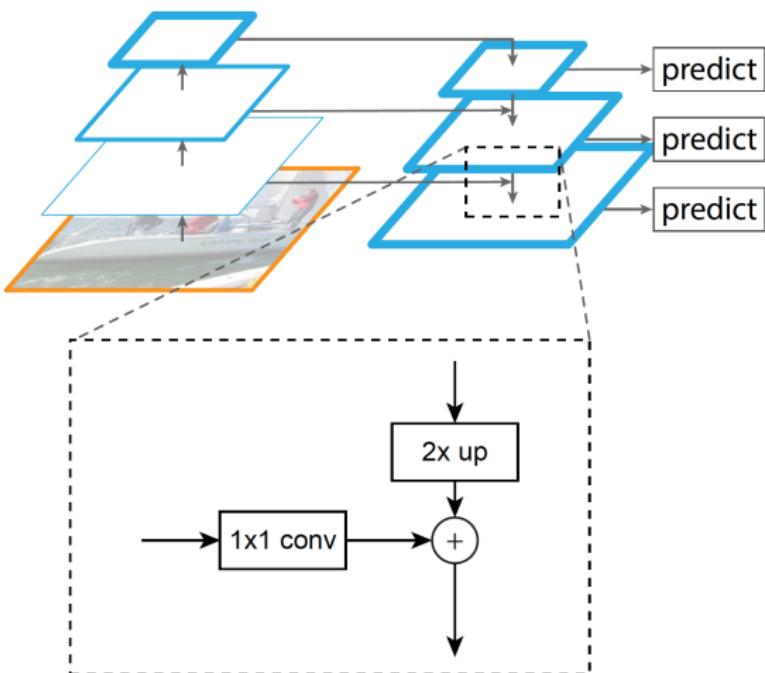


Figure: Feature pyramid network (FPN). A building block illustrating the lateral connection and the top-down pathway, merged by addition [2].

Atrous Convolution

Atrous Convolution

Consider one-dimensional case. The output $\mathbf{y}[i]$ of atrous convolution of a 1-D input $\mathbf{x}[i]$ with a filter $\mathbf{w}[k]$ of length K is defined as:

$$\mathbf{y}[i] = \sum_{k=1}^K \mathbf{x}[i + r \cdot k] \mathbf{w}[k],$$

where r is *atrous rate* parameter.

- Note that if the original kernel size is $k \times k$ and with the rate parameter r , the kernel of atrous convolution is $k + (k - 1)(r - 1)$.

Atrous Convolution

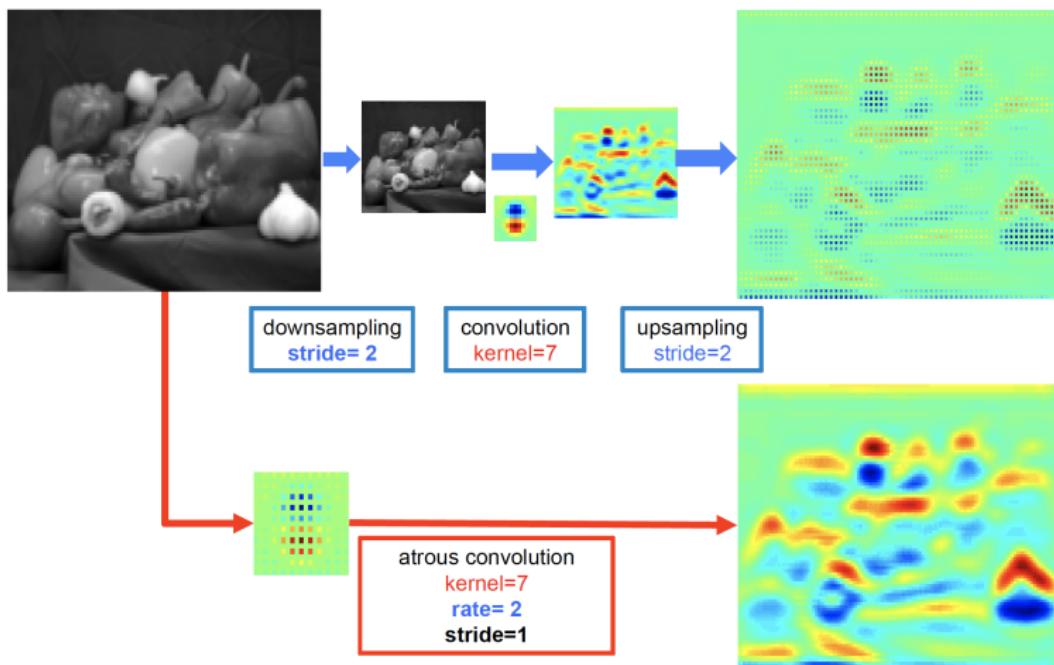


Figure: Illustration of Atrous Convolution in 2-D. The kernel here is the vertical Gaussian derivative [3].

Atrous Spatial Pyramid Pooling (ASPP) [3]

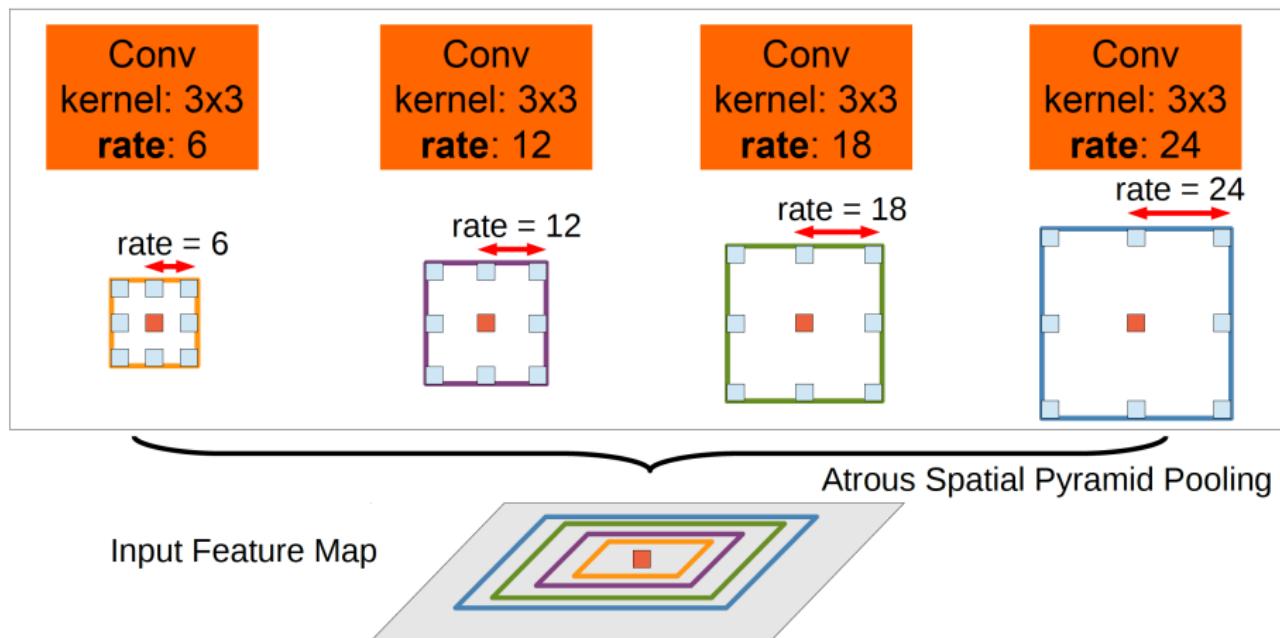


Figure: Illustration of ASPP in 2-D [3].

Recursive Feature Pyramid (RFP)

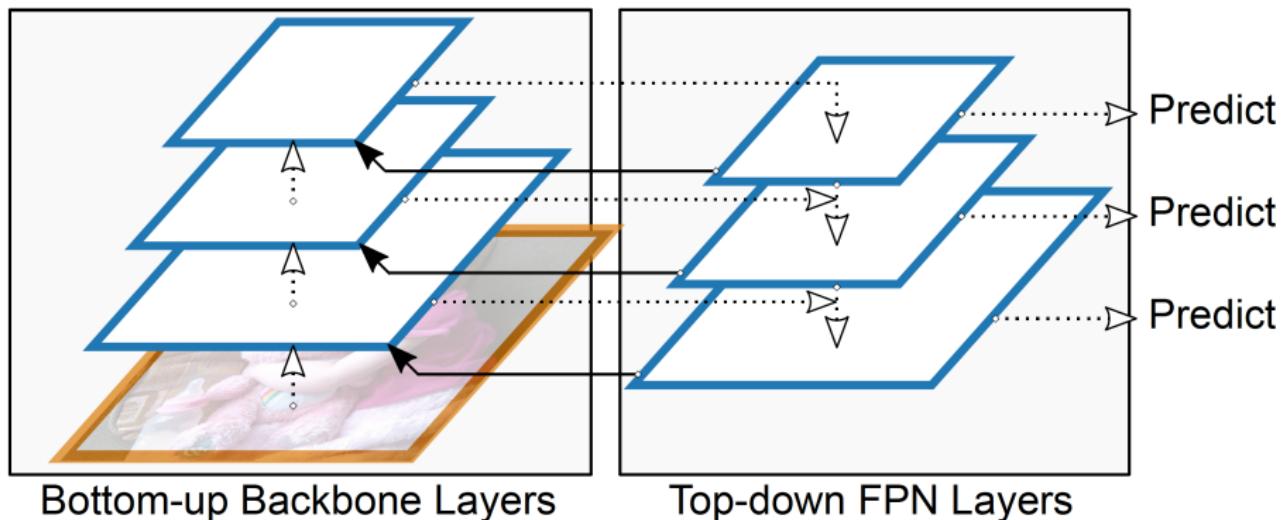


Figure: Recursive feature pyramid (RFP) which incorporates feedback connections into FPN.

Recursive Feature Pyramid (RFP)

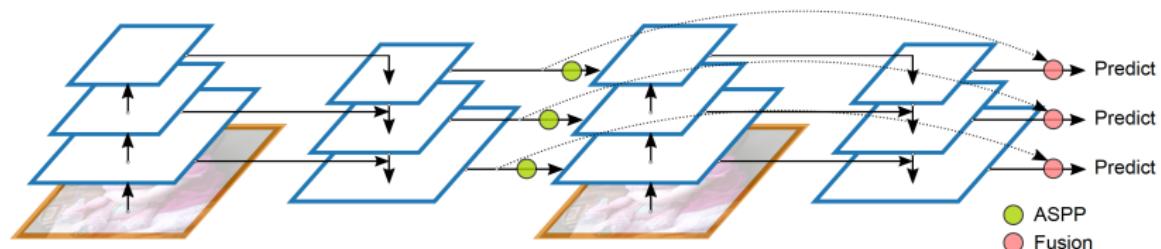


Figure: Recursive feature pyramid unrolled to a 2-step sequential network.

Recursive Formula for RFP

Let \mathbf{R}_i denote the feature transformers before connecting them back to the bottom-up backbone. Then $\forall i = 1, \dots, S, \forall t = 1, \dots, T,$

$$\mathbf{f}_i^t = \mathbf{F}_i^t(\mathbf{f}_{i+1}^t, \mathbf{x}_i^t), \quad \mathbf{x}_i^t = \mathbf{B}_i^t(\mathbf{x}_{i-1}^t, \mathbf{R}_i^t(\mathbf{f}_i^{t-1})),$$

where T is the number of unrolled iterations, and we use superscript t to denote operations and features at the step t .

Recursive Feature Pyramid (RFP)

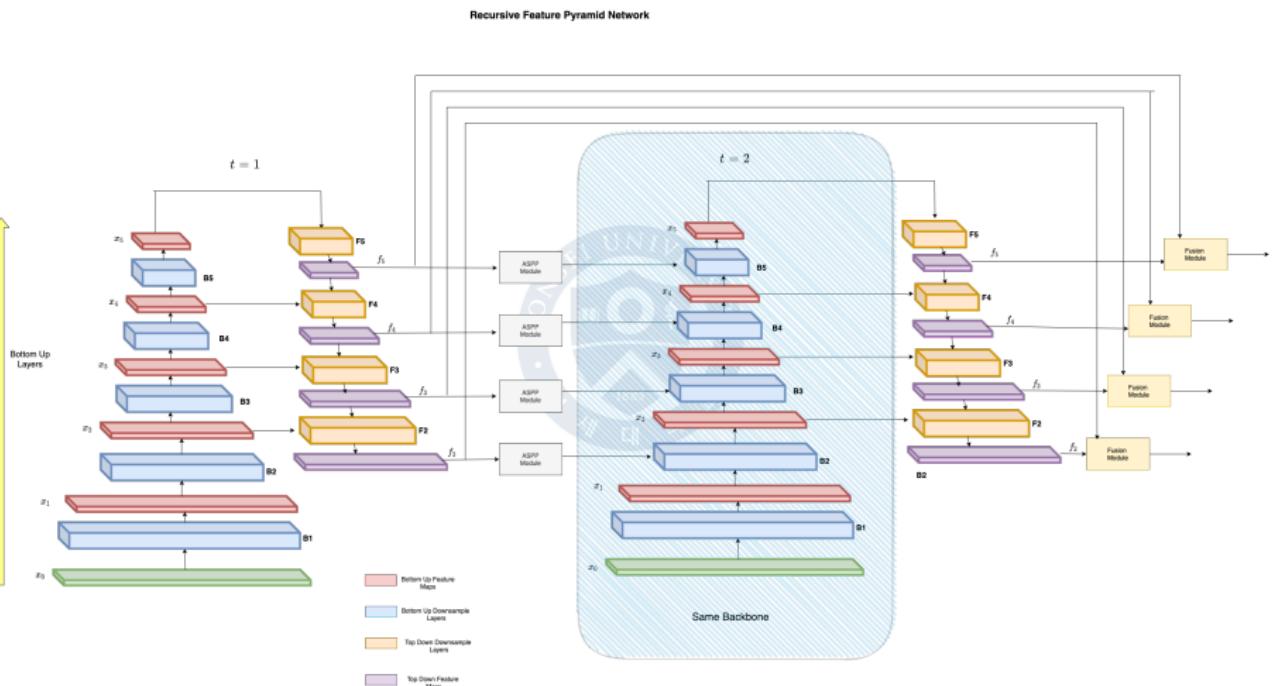


Figure: Recursive feature pyramid unrolled to a 2-step sequential network (detail).

ASPP as the Connecting Module

Connecting Module

- Authors make changes to the ResNet backbone **B** to allow it to take both \mathbf{x} and $\mathbf{R}(\mathbf{f})$ as its input.
- They only make changes to the first block of each ResNet stage by combining RFP features.

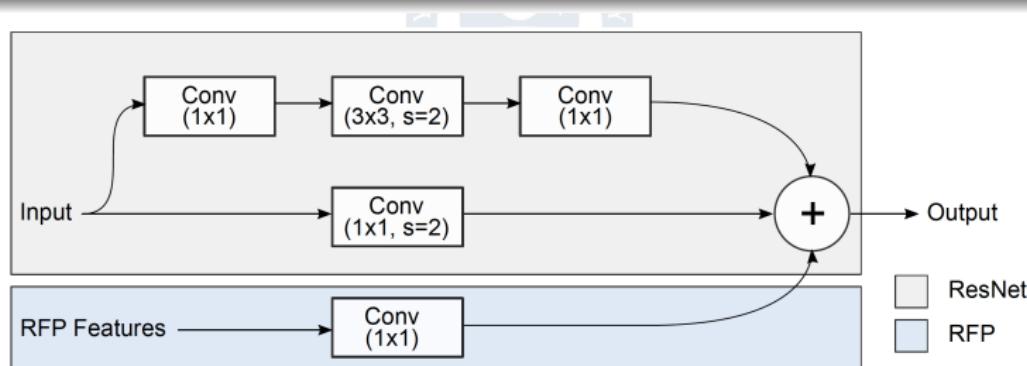


Figure: ASPP as the connecting module.

ASPP as the Connecting Module

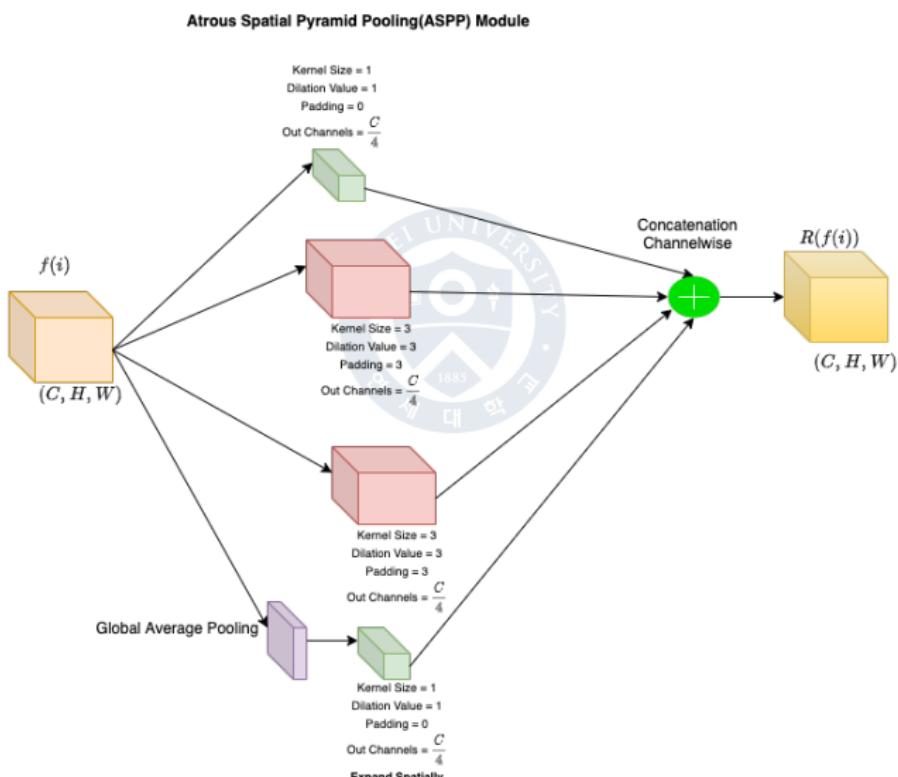
Connecting Module

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layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer
conv1	112×112			7×7, 64, stride 2		
conv2_x	56×56	$\left[\begin{array}{l} 3 \times 3, 64 \\ 3 \times 3, 64 \end{array} \right] \times 2$	$\left[\begin{array}{l} 3 \times 3, 64 \\ 3 \times 3, 64 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{array} \right] \times 3$
conv3_x	28×28	$\left[\begin{array}{l} 3 \times 3, 128 \\ 3 \times 3, 128 \end{array} \right] \times 2$	$\left[\begin{array}{l} 3 \times 3, 128 \\ 3 \times 3, 128 \end{array} \right] \times 4$	$\left[\begin{array}{l} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{array} \right] \times 4$	$\left[\begin{array}{l} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{array} \right] \times 4$	$\left[\begin{array}{l} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{array} \right] \times 8$
conv4_x	14×14	$\left[\begin{array}{l} 3 \times 3, 256 \\ 3 \times 3, 256 \end{array} \right] \times 2$	$\left[\begin{array}{l} 3 \times 3, 256 \\ 3 \times 3, 256 \end{array} \right] \times 6$	$\left[\begin{array}{l} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{array} \right] \times 6$	$\left[\begin{array}{l} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{array} \right] \times 23$	$\left[\begin{array}{l} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{array} \right] \times 36$
conv5_x	7×7	$\left[\begin{array}{l} 3 \times 3, 512 \\ 3 \times 3, 512 \end{array} \right] \times 2$	$\left[\begin{array}{l} 3 \times 3, 512 \\ 3 \times 3, 512 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{array} \right] \times 3$	$\left[\begin{array}{l} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{array} \right] \times 3$
	1×1	average pool, 1000-d fc, softmax				
FLOPs		1.8×10^9	3.6×10^9	3.8×10^9	7.6×10^9	11.3×10^9

Figure: Structure summary of ResNet [5].

ASPP as the Connecting Module [6]



Fusion Module

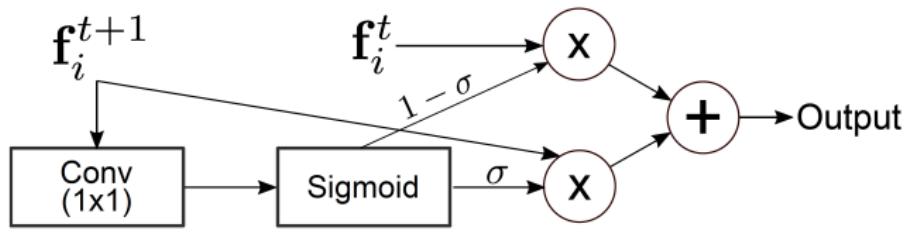
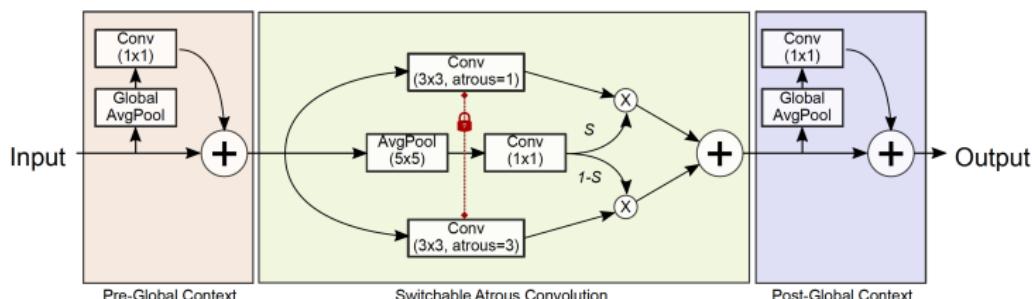


Figure: Fusion module in RFP.

Fusion Module

- FRP uses a fusion module to combine \mathbf{f}_i^t and \mathbf{f}_i^{t+1} to update the values of \mathbf{f}_i at the unrolled stage $t + 1$.
- The fusion module uses the feature \mathbf{f}_i^{t+1} to compute an attention map by a convolutional layer followed by a Sigmoid operation.
- The resulting attention map is used to compute the weighted sum of \mathbf{f}_i^t and \mathbf{f}_i^{t+1} to form an update \mathbf{f}_i .

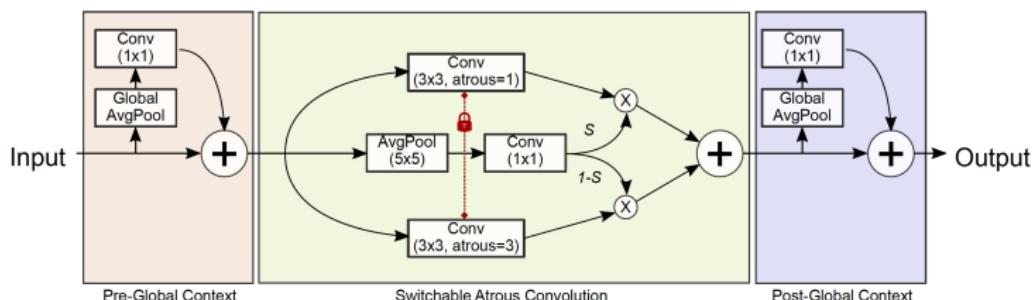
Switchable Atrous Convolution (SAC)



Switchable Atrous Convolution (SAC)

- Authors convert every 3×3 convolutional layer in the backbone to SAC.
- Two global context modules are added before and after the SAC component.

Switchable Atrous Convolution (SAC)

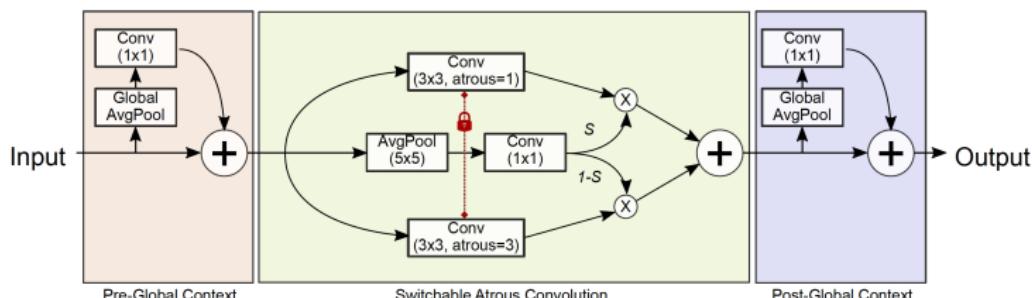


Switchable Atrous Convolution (SAC)

$$\text{Conv}(x, w, 1) \xrightarrow[\text{SAC}]{\text{Convert}} S(x) \cdot \text{Conv}(x, w, 1) + (1 - S(x)) \cdot \text{Conv}(x, w + \Delta w, r),$$

where $\text{Conv}(x, w, 1)$ be the convolutional operation with weight w and atrous rate r which takes x as its input and output y .

Switchable Atrous Convolution (SAC)



Switchable Atrous Convolution (SAC)

$$\text{Conv}(x, w, 1) \xrightarrow[\text{SAC}]{\text{Convert}} S(x) \cdot \text{Conv}(x, w, 1) + (1 - S(x)) \cdot \text{Conv}(x, w + \Delta w, r),$$

where r is a hyper-parameter of SAC, Δw is a trainable weight, and the switch function $S(\cdot)$ is implemented as an average pooling layer with a 5×5 kernel followed by a 1×1 convolutional layer.

Conclusions

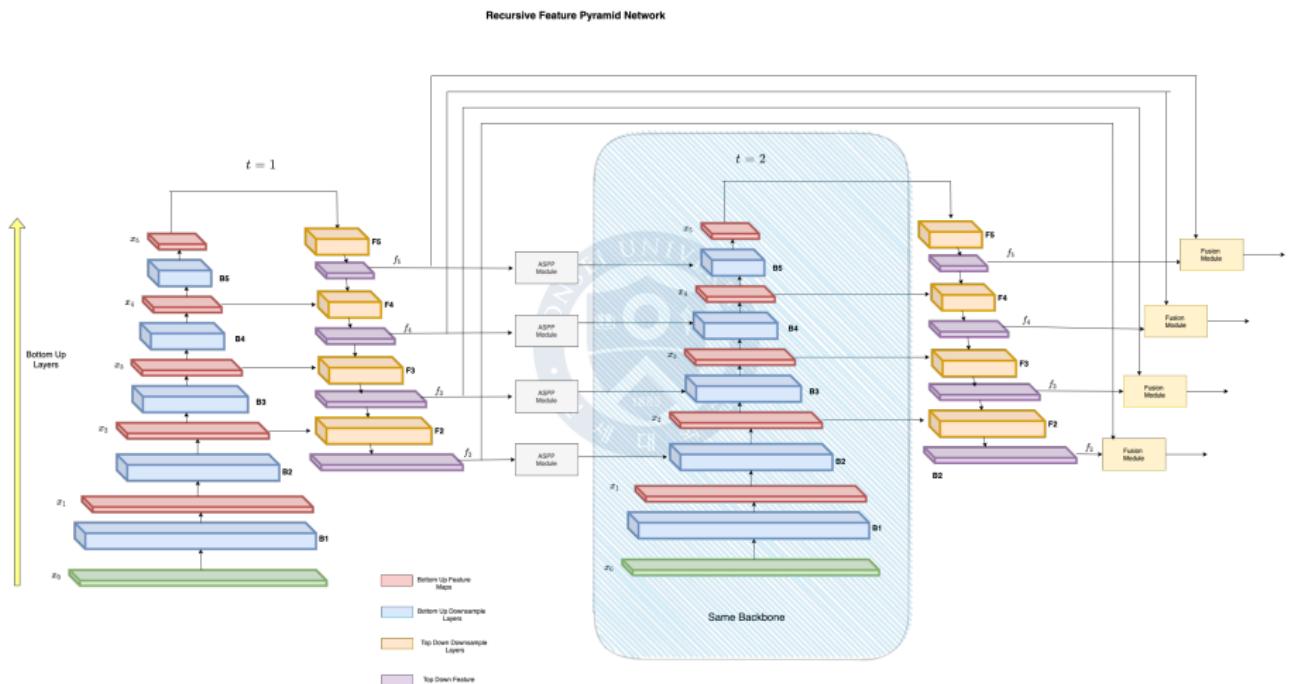


Figure: Recursive feature pyramid unrolled to a 2-step sequential network (detail) [6].

Conclusions

Conclusions

- RFP implements **thinking twice at the macro level**, where the outputs of FPN are brought back to each stage of the bottom-up backbone through feedback connections.
- SAC instantiates **looking twice at the micro level**, where the inputs are convolved with two different atrous rates.

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- [6] <https://medium.com/visionwizard/detectors-state-of-the-art-object-detector-from-google-research-e0b89abdd1fc>