#### **Pre-Announcements**

Blockchain event is today 7 - 10 PM at International House at Chevron House.

- Lots of fancy people from fancy places will be there.
- Blockchain is a topical concept.
- Pizza is a topical concept.

Flyers available.

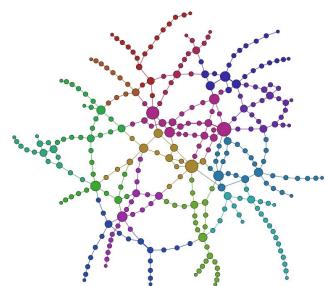
#### **Announcements**

Exam solution exists, not sure why it's not posted, but will be posted soon.

- Exam was really hard, but that's how exams go.
- More later.

Introduction to Network Visualization with GEPHI - Martin Grandjean

#### **Examples**



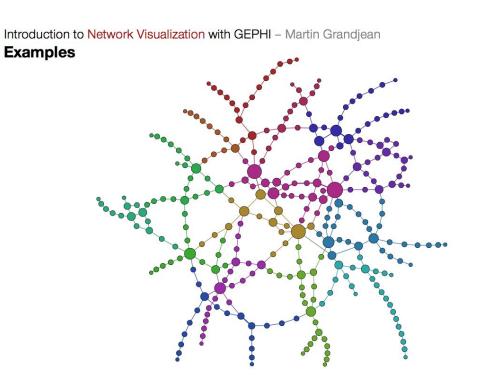
# CS61B

Lecture 26: Graphs

- Intro
- Graph Implementations
- Depth First Traversal

# Graph

Graph: A set of nodes (a.k.a. vertices) connected pairwise by edges.

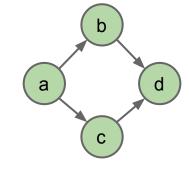


# **Graph Types**

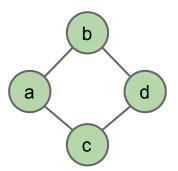
Directed

Undirected

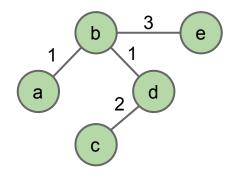
Acyclic:



a d c



With Edge Labels



Cyclic: a

## **Graph Terminology**

- Graph:
  - Set of *vertices*, a.k.a. *nodes*.
  - Set of *edges*: Pairs of vertices.
  - Vertices with an edge between are adjacent.
  - Optional: Vertices or edges may have labels (or weights).
- A path is a sequence of vertices connected by edges.
- A cycle is a path whose first and last vertices are the same.
  - A graph with a cycle is 'cyclic'.
- Two vertices are connected if there is a path between them. If all vertices are connected, we say the graph is connected.

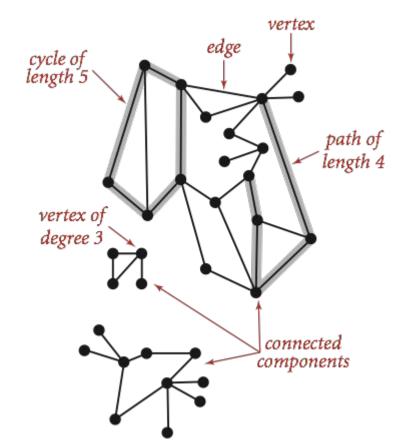


Figure from Algorithms 4th Edition

## **Some Graph-Processing Problems**

**s-t Path**. Is there a path between vertices s and t?

**Shortest s-t Path.** What is the shortest path between vertices s and t?

**Cycle.** Does the graph contain any cycles?

**Euler Tour.** Is there a cycle that uses every edge exactly once?

**Hamilton Tour.** Is there a cycle that uses every vertex exactly once?

**Connectivity.** Is the graph connected, i.e. is there a path between all vertex pairs?

**Biconnectivity.** Is there a vertex whose removal disconnects the graph?

Planarity. Can you draw the graph on a piece of paper with no crossing edges?

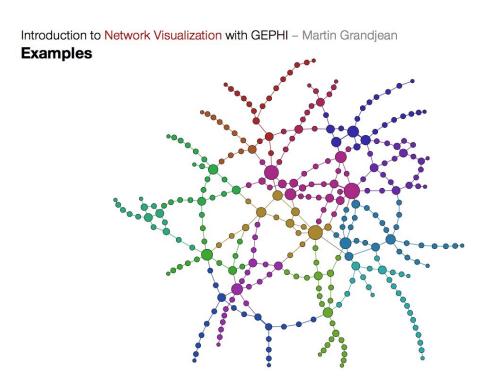
**Isomorphism**. Are two graphs isomorphic (the same graph in disguise)?

Graph problems: Unobvious which are easy, hard, or computationally intractable.

# **Graph Example: The Paris Metro**

#### This subway map of Paris is:

- Undirected
- Connected
- Cyclic (not a tree!)
- Vertex-labeled



### **Graph Example: BART**

Is the BART graph a tree?



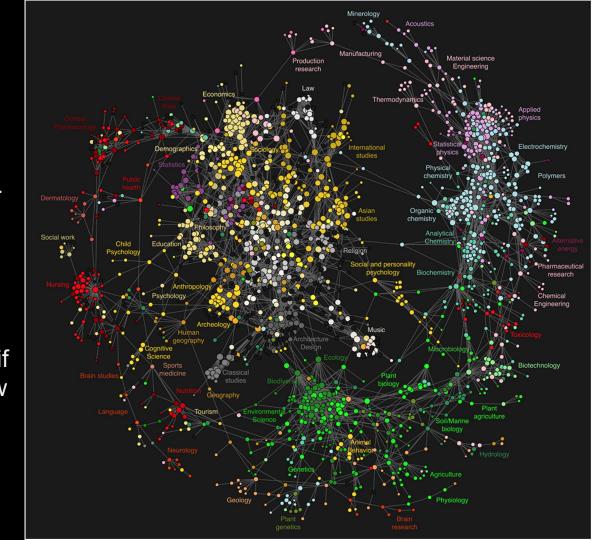


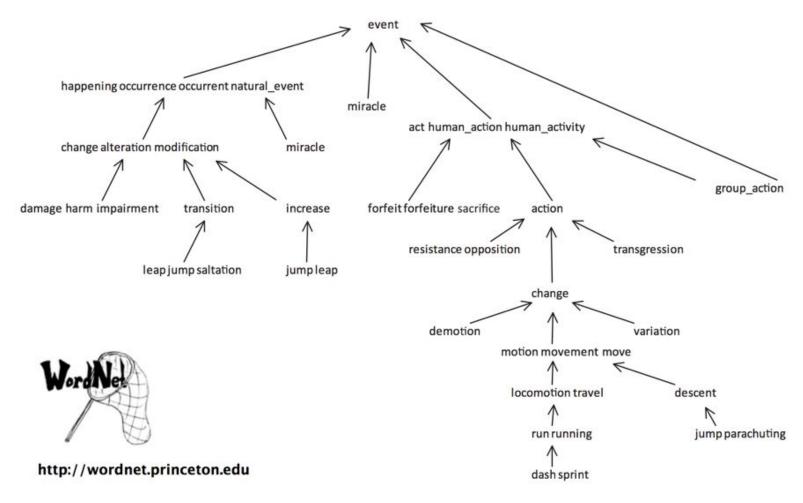
#### Nodes: Scientific Journals.

 Label: AAT classification (the topic that it covers)

#### Edges:

- Based on clickthrough data.
- Clickthrough from v to w means that someone reading an article in journal v clicked on a link to an article in journal w.
- Edge assigned from v to w if clickthrough rate from v to w is above some arbitrary threshold.



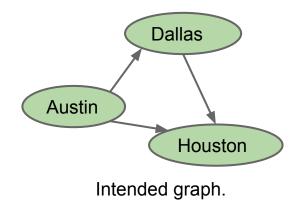


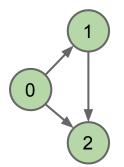
Edge captures 'is-a-type-of' relationship. Example: descent is-a-type-of movement.

# **Graph Representations**

#### **Common Simplification: Integer Vertices**

Common convention: Number nodes irrespective of label, and use number throughout the graph implementation. To lookup a vertex by label, use a Map<Label, Integer>.





Map<String, Integer>

Austin: 0
Dallas: 1
Houston: 2

What you get.

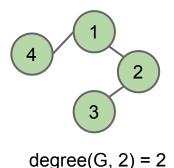
### **Graph API**

#### Using a graph in Java:

## **Graph API**

#### Using a graph in Java:

#### Example client:



```
/** degree of vertex v in graph G */
public static int degree(Graph G, int v) {
   int degree = 0;
   for (int w : G.adj(v)) {
      degree += 1;
   }
   return degree; }
```

(degree = # edges)

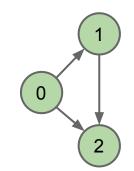
# **Graph Representations**

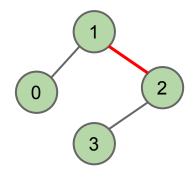
Representation 1: Adjacency Matrix.

s t	0	1	2
0	0	1	1
1	0	0	1
2	0	0	0

For undirected graph:
Each edge is
represented twice in the
matrix. Simplicity at the
expense of space.

v	0	1	2	3
0	0	1	0	0
1	1	0	1	0
2	0	1	0	1
3	0	0	1	0





# **Graph Printing Runtime: http://yellkey.com/paper**

What is the order of growth of the running time of the following code if the graph uses an adjacency-matrix representation, where V is the number of vertices, and E is the total number of edges?

```
A. \Theta(V)
```

- B.  $\Theta(V + E)$
- C.  $\Theta(V^2)$
- D.  $\Theta(V^*E)$

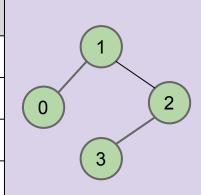
```
for (int v = 0; v < G.V(); v++) {
    for (int w : G.adj(v)) {
        System.out.println(v + "-" + w);
    }
}</pre>
```

What is the runtime of the for-each?

•

How many times is the for-each run?

	0	1	2	3
0	0	1	0	0
1	1	0	1	0
2	0	1	0	1
3	0	0	1	0



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D.  $\Theta(V*E)$ 

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    }
}</pre>
```

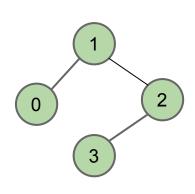
What is the runtime of the for-each?

Θ(V).

How many times is the for-each run?

V times.

	0	1	2	3
0	0	1	0	0
1	1	0	1	0
2	0	1	0	1
3	0	0	1	0



## **Graph Printing Runtime: http://yellkey.com/paper**

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C.  $\Theta(V^2)$ 

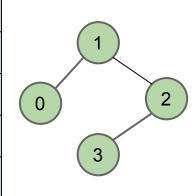
D.  $\Theta(V*E)$ 

```
for (int v = 0; v < G.V(); v++) {
   for (int w : G.adj(v)) {
       System.out.println(v + "-" + w);
   }
}</pre>
```

What does G.adj(1) return?

An iterator with next() = 0, then next() = 2.

	0	1	2	3
0	0	1	0	0
1	1	0	1	0
2	0	1	0	1
3	0	0	1	0

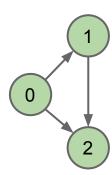


#### **More Graph Representations**

Representation 2: Edge Sets: Collection of all edges.

Example: HashSet<Edge>, where each Edge is a pair of ints.

$$\{(0, 1), (0, 2), (1, 2)\}$$

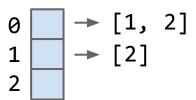


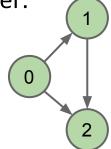
#### **More Graph Representations**

Representation 3: Adjacency lists.

Common approach: Maintain array of lists indexed by vertex number.

Most popular approach for representing graphs.





# **Graph Printing Runtime: http://shoutkey.com/laugh**

What is the order of growth of the running time of the following code if the graph uses an *adjacency-list* representation, where V is the number of vertices, and E is the total number of edges?

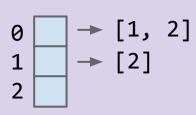
```
A. \Theta(V)
```

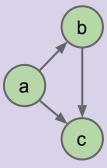
- B.  $\Theta(V + E)$
- C.  $\Theta(V^2)$
- D.  $\Theta(V*E)$

```
for (int v = 0; v < G.V(); v++) {
    for (int w : G.adj(v)) {
        System.out.println(v + "-" + w);
    }
}</pre>
```

What is the runtime of the for-each?

How many times is the for-each run?





## **Graph Printing Runtime: http://shoutkey.com/laugh**

What is the order of growth of the running time of the following code if the graph uses an *adjacency-list* representation, where V is the number of vertices, and E is the total number of edges? Best case:  $\Theta(V)$  Worst case:  $\Theta(V^2)$ 

```
A. \Theta(V)
```

- B.  $\Theta(V + E)$
- C.  $\Theta(V^2)$
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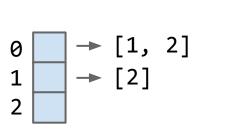
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for (int v = 0; v < G.V(); v++) {
    for (int w : G.adj(v)) {
        System.out.println(v + "-" + w);
    }
}</pre>
```

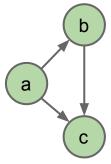
What is the runtime of the for-each? List can be between 1 and V items.

•  $\Omega(1)$ , O(V).

How many times is the for-each run?

• V.





# **Graph Printing Runtime: http://shoutkey.com/ready**

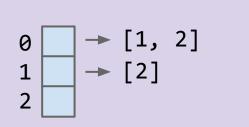
What is the order of growth of the running time of the following code if the graph uses an *adjacency-list* representation, where V is the number of vertices, and E is the total number of edges? Best case:  $\Theta(V)$  Worst case:  $\Theta(V^2)$ 

What is the runtime of the for-each? List can be between 1 and V items.

• Ω(1), O(V).

How many times is the for-each run?

V.



# **Graph Printing Runtime: http://shoutkey.com/ready**

What is the order of growth of the running time of the following code if the graph uses an *adjacency-list* representation, where V is the number of vertices, and E is the total number of edges?

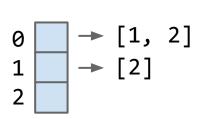
```
A. \Theta(V)
```

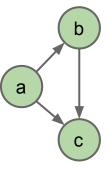
- B.  $\Theta(V + E)$
- C.  $\Theta(V^2)$
- D.  $\Theta(V^*E)$

```
for (int v = 0; v < G.V(); v++) {
    for (int w : G.adj(v)) {
        System.out.println(v + "-" + w);
    }
}</pre>
```

Best case:  $\Theta(V)$  Worst case:  $\Theta(V^2)$ 

All cases:  $\Theta(V + E)$ 





## **Graph Printing Runtime: http://shoutkey.com/ready**

Runtime:  $\Theta(V + E)$ 

V is total number of vertices.

E is total number of edges in the entire graph.

```
for (int v = 0; v < G.V(); v++) {
    for (int w : G.adj(v)) {
        System.out.println(v + "-" + w);
    }
}</pre>
```

How to interpret: No matter what "shape" of increasingly complex graphs we generate, as V and E grow, the runtime will always grow exactly as  $\Theta(V + E)$ .

- Example shape 1: Very sparse graph where E grows very slowly, e.g. every vertex is connected to its square: 2 4, 3 9, 4 16, 5 25, etc.
  - $\circ$  E is  $\Theta(\operatorname{sqrt}(V))$ . Runtime is  $\Theta(V + \operatorname{sqrt}(V))$ , which is just  $\Theta(V)$ .
- Example shape 2: Very dense graph where E grows very quickly, e.g. every vertex connected to every other.
  - $\circ$  E is  $\Theta(V^2)$ . Runtime is  $\Theta(V + V^2)$ , which is just  $\Theta(V^2)$ .

### **Graph Representations**

#### Runtime of some basic operations for each representation:

idea	addEdge(s, t)	for(w : adj(v))	printgraph()	hasEdge(s, t)	space used
adjacency matrix	Θ(1)	Θ(V)	$\Theta(V^2)$	Θ(1)	Θ(V <sup>2</sup> )
list of edges	Θ(1)	Θ(Ε)	Θ(Ε)	Θ(Ε)	Θ(Ε)
adjacency list	Θ(1)	Θ(1) to Θ(V)	Θ(V+E)	Θ(degree(v))	Θ(E+V)

In practice, adjacency lists are most common.

- Many graph algorithms rely heavily on adj(s).
- Most graphs are sparse (not many edges in each bucket).

Note: These operations are not part of the Graph class's API.

## **Bare-Bones Undirected Graph Implementation**

```
public class Graph {
    private final int V; private List<Integer>[] adj;
    public Graph(int V) {
        this.V = V;
        adj = (List<Integer>[]) new ArrayList[V]; 	←
        for (int v = 0; v < V; v++) {
             adj[v] = new ArrayList<Integer>();
    public void addEdge(int v, int w) {
         adj[v].add(w); adj[w].add(v);
    public Iterable<Integer> adj(int v) {
        return adj[v];
```

Cannot create array of anything involving generics, so have to use weird cast as with project 1A.

# **Depth-First Traversal**

#### Maze Traversal / s-t Path

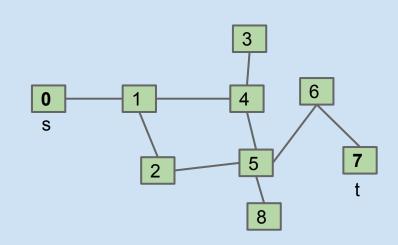
Suppose we want to know if there exists a path from vertex s=0 to vertex t=7. What is wrong with the following recursive algorithm for connected(s, t)?

- Does s == t? If so, return true.
- Otherwise, check all of s's children for connectivity to t.

#### Example:

- connected(0, 7):
  - Does 0 == 7? No, so...
  - if (connected(1, 7)) return true;
  - return false;

connected(1, 7): ...

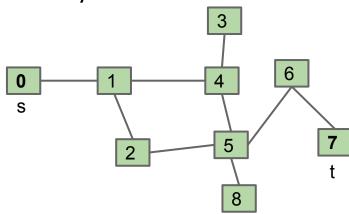


## **Improving Our Connectivity Algorithm**

Goal: Search for a path from s to t, but visit each vertex at most once. To do this, we can mark each vertex as we search. Resulting algorithm for connected(s, t) is as follows:

- Mark s.
- Does s == t? If so, return true.
- Check all of s's unmarked neighbors for connectivity to t.

Recursive connectivity demo.

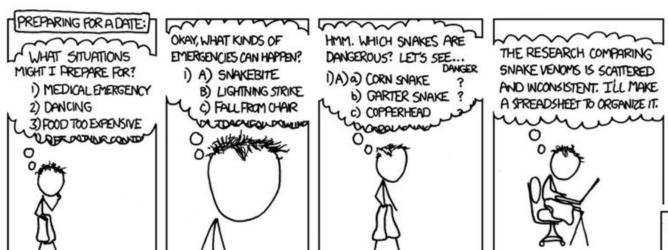


## **Depth First Traversal**

This idea of exploring the entire subgraph for each child is known as Depth First Traversal.

• Ex. Visit all of 1's children before we visit any of 3's.

1
3
4
7



Or a more visceral example: <a href="https://xkcd.com/761/">https://xkcd.com/761/</a>



I REALLY NEED TO STOP USING DEPTH-FIRST SEARCHES.

### **Depth First Search Implementation**

Common design pattern in graph algorithms: Decouple type from processing algorithm.

- Create a graph object.
- Pass the graph to a graph-processing method (or constructor) in a client class.
- Query the client class for information.

```
public class Paths {
    public Paths(Graph G, int s): Find all paths from G
    boolean hasPathTo(int v): is there a path from s to v?
    Iterable<Integer> pathTo(int v): path from s to v (if any)
}
```

#### **Example Usage**

```
Start by calling: Paths P = new Paths(G, 0);

• P.hasPathTo(3); //returns true
• P.pathTo(3); //returns {0, 1, 4, 3}
```

```
public class Paths {
    public Paths(Graph G, int s): Find all paths from G
    boolean hasPathTo(int v): is there a path from s to v?
    Iterable<Integer> pathTo(int v): path from s to v (if any)
}
```

Paths.java

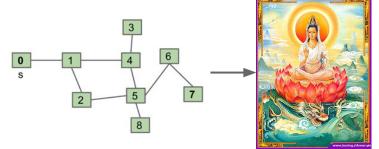
### **Implementing Paths With Depth First Search**

#### To visit a vertex v:

- Mark vertex v.
- Recursively visit all unmarked vertices adjacent to v.

#### **Data Structures:**

- boolean[] marked
- int[] edgeTo
  - $\circ$  edgeTo[4] = 1, means we went from 1 to 4.



Paths.java

```
public class Paths {
    public Paths(Graph G, int s): Find all paths from G
    boolean hasPathTo(int v): is there a path from s to v?
    Iterable<Integer> pathTo(int v): path from s to v (if any)
}
```

# **DepthFirstPaths**

Demo: <u>DepthFirstPaths</u>

# **DepthFirstPaths, Recursive Implementation**

```
public class DepthFirstPaths {
    private boolean[] marked; 
                                                    marked[v] is true iff v connected to s
    private int[] edgeTo; 
                                                    edgeTo[v] is previous vertex on path from s to v
    private int s;
    public DepthFirstPaths(Graph G, int s) {
                                                     not shown: data structure initialization
        dfs(G, s); \longleftarrow
                                                    find vertices connected to s.
                                                     recursive routine does the work and stores results
    private void dfs(Graph G, int v) {
                                                     in an easy to guery manner!
        marked[v] = true;
        for (int w : G.adj(v)) {
         if (!marked[w]) {
             edgeTo[w] = v;
             dfs(G, w);
                                                    Question: How would we write hasPathTo(v)?
```

## **DepthFirstPaths Summary**

Demo: <u>DepthFirstPaths</u>

#### Properties of Depth First Search:

- Guaranteed to reach every node.
- Runs in O(V + E) time.
  - Analysis next time, but basic idea is that every edge is used at most once, and total number of vertex considerations is equal to number of edges.
  - Runtime may be faster than Θ(V+E) for problems which quit early on some stopping condition (for example connectivity).