Taeyoung **Kim**

Robotics · SLAM Engineer

340, Mokdongseo-ro, Yangcheon-gu, Seoul, 08089, Republic of Korea

(+82) 10-9686-8177 | tyoung96@yonsei.ac.kr | taeyoung96.github.io | Taeyoung96

"Nothing ventured, nothing gained."

Summary

This is Taeyoung Kim, who wants to become robotics SLAM / Navigation engineer. My research interests are Sensor fusion and SLAM. I like to take on challenging tasks and I like to grow up with my colleagues around me. That's why I record and share what I did on my Github or Technical Blog. I'm also interested in contributing open-source projects.

Research Interests

SLAM / Spatial AI Focusing on LiDAR(-inertial) SLAM, Robust Localization, Neural representation

Sensor fusion Spatial-temporal calibration for LiDAR, IMU, and Camera etc.

Education

Yonsei University @CILAB *Seoul, S.Korea*

M.S. in Vehicle Convergence Engineering (Advisor: Prof. Euntai Kim) *Mar. 2022 - Feb. 2024 (Expected)*

- **Total GPA** : 4.05 / 4.3
- **Teaching Assistant** : 2023-1 Research Experience for Undergraduate (REU)
- Focusing on LiDAR (-inertial) SLAM
- Research on LiDAR-IMU extrinsic calibration method

Kwang Woon University *Seoul, S.Korea*

B.S. in School of Robotics *Mar. 2016 - Feb. 2022*

- **Total GPA** : 4.10 / 4.50, **Major GPA** : 4.41 / 4.50
- **Club**: BARAM (Robotics Academic Group) - [2020 Staff] , DAISY (English Conversation Club) - [2019 Spring President]

Work Experience

KIST(Korea Institute of Science and Technology) @Robot Vision Lab *Seoul, S.Korea*

Student Intern (Advisor : Dr. Kanggeon Kim) *Sep. 2020 - Feb. 2021*

- Research on Monocular Depth Estimation
- Participated in KIST disinfect robot (AI Disinfection Robot) project - **[Video]**

Projects

Cooperative mapping, environment recognition, and autonomous driving technology for multiple mobile robots operating in large indoor workspaces *KEIT*

Participant *Apr. 2023 - Dec. 2023*

- Development multi robot navigation systems - **[Certification]**

Development of Core Technology for Mobile Manipulator for 5G Edge-based Transportation and Manipulation *Ministry of Science and ICT*

Participant *May. 2022 - Dec. 2022*

- Development LiDAR-inertial visual SLAM algorithm for mobile manipulator - **[Certification]**

Developing LiDAR-IMU calibration methods for mobile robots *Hyundai NGV*

Participant *May. 2022 - Feb.2024*

- Development LiDAR-IMU extrinsic calibration method focusing on mobile robots - **[Certification]**
- Presented at the Hyundai Motor Group Future Mobility Research Exchange in KSAE 2023 workshop

Publication

International Journal

2021.11 **"Standard for the Quantification of a Sterilization Effect Using an Artificial Intelligence Disinfection Robot",** Heeju Hong, Wonkook Shin, Jieun Oh, Sunwoo Lee, Taeyoung Kim , Woosub Lee, Jongsuk Choi, Seungbeum Suh and Kanggeon Kim, Sensors 21, no. 23: 7776. **https://doi.org/10.3390/s21237776** — *Sensors*

International Conference

2022.7 **"Robust Feature Tracking for Better Visual-Inertial System using Dynamic Mask",** Gyuhyeon Pak, Taeyoung Kim, Euntai Kim - **[Paper]** — *ICCAS 2022*

2021.7 **"Dense Monocular SLAM applied Depth Estimation",** Taeyoung Kim, Omer Faruk Ince, JongBeom Baek, Jun-Sik Kim, KangGeon Kim - **[Paper]**, **[Video]** — *UR 2021 (Work in progress)*

Domestic Conference

2023.6 **"Comparative analysis of LiDAR-inertial odometry/SLAM algorithm performance for ground robots",** Taeyoung Kim, Yechan Park, Euntai Kim - **[Paper]** — *ICROS 2023*

2021.5 **"Recognition of disinfection targets and generation of semantic map for disinfection robot",** TaeHwan Kim, Taeyoung Kim, GiJae Lee, KangGeon Kim - **[Paper]** — *KROS 2021*

Honors & Awards

Awards

2023.10 **4th Place on LiDAR-inertial track,** ICCV 2023 SLAM Challenge - **[Certification]**, **[Video]** — *AirLab, Carnegie Mellon Univ.*

2020.11 **Dean's List,** for Academic Excellence — *KwangWoon Univ.*

2020.9 **5th Place on B-track,** Korea Health Datathon 2020 — *NAVER CLOUD PLATFORM*

2019.10 **Dean's List,** for Academic Excellence — *KwangWoon Univ.*

Honors

2023 / 2022 **Full tuition Scholarship,** for the students who have been based on Recruitment Conditions on Hyundai Motors Group — *Hyundai NGV*

2021 / 2020 **National Science and Engineering Undergraudate Scholarship ,** for the students who have been recommended by the university **(Full tuition Scholarship)** — *Korea Student Aid Foundation*

2019-2 **Full tuition Scholarship,** for Top seat last semester — *KwangWoon Univ.*

Skills

Programming C++ / C, Python, Matlab
DevOps Git, Docker, ROS2 / ROS
Languages Korean, English

Extracurricular Activity

Technical Blogs

Github blog

Writers — *May. 2020 - Present*

- You can easily access the blog using **[this link]**.
- Writing some posts about lecture summary, paper review, some tips for developments.
- To share what I have studied with others and to remember it longer.

Open Source Contribution Academy (2021 - 2022)

Ministry of Science and ICT

2022 Mentor, 2021 Mentee — *Aug. 2021 - Nov. 2022*

- I am in the process of translating a Pytorch tutorial into Korean that I want to contribute to the spread of PyTorch.
- Using Github, I developed the ability to collaborate and contribute to open source.
- The open source repository I've contributed can be found **[tutorials-kr]**.

CLOVA AI RUSH 2021

NAVER AI Lab, NAVER CLOVA

Participant — *May. 2021 - Jun.2021*

- Only 150 students are allowed to participate in this project.
- I developed my own deep learning model related to multi-label classification.
- I ranked 30th on Project 1-3.

2021 Spring Capstone Design

KwangWoon Univ.

Project

Mar. 2021 - Jun.2021

- I made a wireless charging electric vehicle charging robot.
- I designed the control input algorithm, trained deep learning model, and developed the ROS package.
- The source code related to this project is on my **[Github repository]**.

Monocular Depth Estimation with ORB-SLAM2

BARAM (Robotics Academic Group)

Personal Toy Project

Sep. 2020 - Nov. 2020

- I was curious about the performance of the recent depth estimation model.
- I used **'Monocular Depth Estimation with Transfer Learning pretrained MobileNetV2'** model and applied to ORB-SLAM2 also compared with ORB-SLAM2(Monocular mode), ORB-SLAM2(RGB-D mode)
- The source code related to this toy project is on my **[Github repository]**.