One parameter code

```
clear; clc; close all;
prob name='CAPSO';
delete(strcat('data\',prob name,'\*.mat'));
Mm=1.8e-3;Mc=1.67e-3;k=62;
Om0=sqrt(k/Mm);
muG= (Mm+Mc) *9.81*0.2293;
p0N(1,1) = { 'om' }
                   ;p0(1,1)=(1/Om0)*2*pi*45;
p0N(2,1)={'al'}
                   ;p0(2,1)=(1/muG)*0.208;
p0N(3,1) = \{ 'qa' \}
                   ;p0(3,1) = Mm/Mc;
p0N(4,1) = \{ 'k1' \}
                   ;p0 (4,1) = (1/k) *27900;
p0N(5,1)=\{'k2'\} ; p0(5,1)=(1/k)*53500;
p0N(6,1) = { 'xi' }
                   ;p0(6,1)=(1/(2*Mm*Om0))*0.0156;
p0N(7,1) = { 'void' } ; p0(7,1) = 0;
p0N(8,1) = \{ g1' \}; p0(8,1) = (k/muG) *1.6e-3;
                   ;p0(9,1)=(k/muG)*0;
p0N(9,1) = \{ 'g2' \}
p0N(10,1) = { 'gb' }; p0(10,1) = (k/muG) *7.6e-3; % (k/muG) *8.31e-3
                   ;p0(11,1)=(k/muG)*1.033e-3;
p0N(11,1) = { 'lb' }
p0N(12,1) = {'B0'}
                   ;p0(12,1)=(1/k)*(-9.111e-2);
p0N(13,1) = { 'B1' }
                    ;p0(13,1) = (muG/k^2) * (3.918e4);
```

- declare the name of the continuation problem "CAPS0" in this case.
- define the parameters

```
p0N(14,1)={'B2'} ;p0(14,1)=(muG^2/k^3)*(-1.925e7);

modes={ 'Ck2-Vcp-NCb' 'Ck2-Vcn-NCb' 'NCk-Vcn-NCb' 'NCk-Vcp-NCb' 'Ck2-Vcp-NCb' 'Ck2-Vcn-NCb' 'NCk-Vcn-NCb' 'Ck1-Vcn-NCb' 'Ck1-Vcn-NCb
```

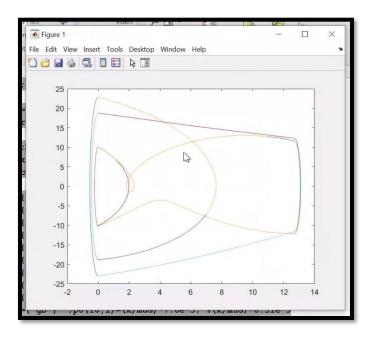
- define modes involved, events and reset functions
- efine initial points for every mode
- very starting point and ending point should be defined
- simulate each mode as a first guess of the solution

```
-1.59778560923237
                     2.81001656133719
                                          12.7089343197156
                                                                -11.6145548462513
                                                                                     0.410496313818697
-1.47821466643057
                                                                                        -0.644631254317500
                    -4.38926554961059
                                         -2.15449098177941e-15
                                                                   -23.0002793960055
[t1,x1] = 0de45(@(t,x) \ vec_fields(x,p0,modes{1}),[0 \ MAT(2,end)-MAT(1,end)],MAT(1,1:end-1)');
[t2,x2] = ode45(@(t,x) vec fields(x,p0,modes{2})), [0 MAT(3,end)-MAT(2,end)], MAT(2,1:end-1)');
[t3,x3]=ode45(@(t,x) vec fields(x,p0,modes{3}),[0 MAT(4,end)-MAT(3,end)],MAT(3,1:end-1)');
[t4,x4] = ode45(@(t,x) \text{ vec fields}(x,p0,modes{4}),[0 MAT(5,end)-MAT(4,end)],MAT(4,1:end-1)');
[t5,x5] = ode45(@(t,x) vec fields(x,p0,modes{5})), [0 MAT(6,end)-MAT(5,end)], MAT(5,1:end-1)');
[t6,x6] = ode45(@(t,x) \text{ vec fields}(x,p0,modes{6}),[0 MAT(7,end)-MAT(6,end)],MAT(6,1:end-1)');
[t7,x7] = ode45(@(t,x) vec fields(x,p0,modes{7}),[0 MAT(8,end)-MAT(7,end)],MAT(7,1:end-1)');
[t8,x8] = ode45(@(t,x) \text{ vec fields}(x,p0,modes{8})), [0 MAT(9,end) - MAT(8,end)], MAT(8,1:end-1)');
[t9,x9] = 0de45(@(t,x) \text{ vec fields}(x,p0,modes}{9}),[0 MAT(10,end)-MAT(9,end)],MAT(9,1:end-1)');
 [t10,x10] = ode 45 (@(t,x) \ vec \ fields(x,p0,modes\{10\}), [0 \ MAT(11,end) - MAT(10,end)], MAT(10,1:end-1)'); 
[t11,x11] = ode 45 (@(t,x) \ vec_fields(x,p0,modes\{11\}), [0 \ MAT(12,end) - MAT(11,end)], MAT(11,1:end-1)');
[t12,x12] = ode45(@(t,x) \ vec_fields(x,p0,modes\{12\}), [0 \ MAT(13,end)-MAT(12,end)], MAT(12,1:end-1)');
[t13,x13]=ode45(@(t,x) vec_fields(x,p0,modes{13}),[0 MAT(14,end)-MAT(13,end)],MAT(13,1:end-1)');
[t14,x14]=ode45(@(t,x) vec fields(x,p0,modes{14}),[0 MAT(15,end)-MAT(14,end)],MAT(14,1:end-1)');
[t15,x15]=ode45(@(t,x) vec fields(x,p0,modes{15}),[0 MAT(16,end)-MAT(15,end)],MAT(15,1:end-1)');
[t16,x16] = ode45(@(t,x) vec_fields(x,p0,modes{16}),[0 MAT(17,end)-MAT(16,end)],MAT(16,1:end-1)');
```

```
[t17,x17]=ode45(@(t,x) vec_fields(x,p0,modes{17}),[0 MAT(18,end)-MAT(17,end)],MAT(17,1:end-1)');
[t18,x18]=ode45(@(t,x) vec_fields(x,p0,modes{18}),[0 MAT(19,end)-MAT(18,end)],MAT(18,1:end-1)');
[t19,x19]=ode45(@(t,x) vec_fields(x,p0,modes{19}),[0 MAT(20,end)-MAT(19,end)],MAT(19,1:end-1)');
[t20,x20]=ode45(@(t,x) vec_fields(x,p0,modes{20}),[0 2*2*pi/p0(1,1)-MAT(20,end)],MAT(20,1:end-1)');

t0={t1 t2 t3 t4 t5 t6 t7 t8 t9 t10 t11 t12 t13 t14 t15 t16 t17 t18 t19 t20);
x0={x1 x2 x3 x4 x5 x6 x7 x8 x9 x10 x11 x12 x13 x14 x15 x16 x17 x18 x19 x20};

%plot(x1(:,3),x1(:,4),x2(:,3),x2(:,4),x3(:,3),x3(:,4),x4(:,3),x4(:,4),x5(:,3),x5(:,4),x6(:,3),x6(:,4)
```



- this is the initial guess for the solution, every color refers to each mode.

- enter vector fields, event functions, reset functions and derivatives (derivatives improve the accuracy of the program)
- define parameters, (5000 is the number of points on the curve, 0.01 is the step size), 0.01 and 3 are the minimum and maximum step size (range), the initial step size is 0.1.

```
[data1,uidx1]=coco_get_func_data(prob,'hspo.orb.bvp.seg1.coll','data','uidx');
maps1=data1.coll_seg.maps;
prob=coco_add_pars(prob,'pars1',uidx1(maps1.T_idx),'T1','active');

[data2,uidx2]=coco_get_func_data(prob,'hspo.orb.bvp.seg2.coll','data','uidx');
maps2=data2.coll_seg.maps;
prob=coco_add_pars(prob,'pars2',uidx2(maps2.T_idx),'T2','active');

[data3,uidx3]=coco_get_func_data(prob,'hspo.orb.bvp.seg3.coll','data','uidx');
maps3=data3.coll_seg.maps;
prob=coco_add_pars(prob,'pars3',uidx3(maps3.T_idx),'T3','active');

[data4,uidx4]=coco_get_func_data(prob,'hspo.orb.bvp.seg4.coll','data','uidx');
maps4=data4.coll_seg.maps;
prob=coco_add_pars(prob,'pars4',uidx4(maps4.T_idx),'T4','active');
```

- define the data structures for each mode, in this example 20 modes

```
prob=coco_add_func(prob,'P1',@M_Vavg,{data data1 data2 data3 data4 data5 data6 data7 data8 data9 data10 data11 data12 data13 c prob=coco_add_func(prob,'P2',@M_Pavg,{data data1 data2 data3 data4 data5 data6 data7 data8 data9 data10 data11 data12 data13 c prob=coco_add_func(prob,'P3',@M_Fcap,{data data1 data2 data3 data4 data5 data6 data7 data8 data9 data10 data11 data12 data13 c prob=coco_add_event(prob,'UZ','M_Vavg',0); prob=coco_add_event(prob,'UZ','M_Vavg',0); prob=coco_add_event(prob,'UZ','al',(1/mug)*[0.2084 0.2095 0.2098]); coco(prob,prob_name,[],1,{'al' 'hspo.test.USTAB' 'M_Vavg' 'M_Fcap' 'M_Pavg' 'T1' 'T2' 'T3' 'T4' 'T5' 'T6' 'T7' 'T8' 'T9' 'T10'
```

- define the measures that you designed for this program, for example "M_Vavg" refers to the average velocity of the device, "M_Pavg" is the power, and "M Fcap" is the force. Define what you want to measure.
- the 1st "UZ" point showed when the average became zero, and the 2nd shows the value for a different variable.
- the "coco" line is the final definition of the problem.

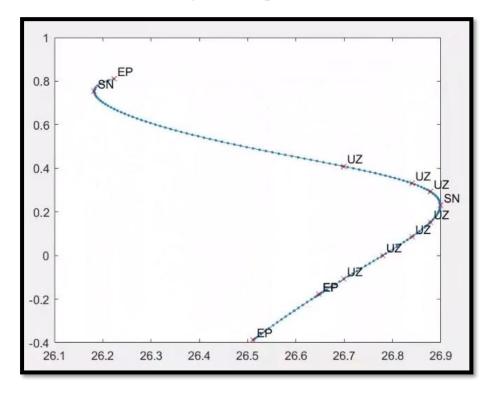
```
Run='CAPSO': Continue family of multi-segment periodic orbits.
  STEP DAMPING
                          NORMS
                                          COMPUTATION TIMES
                         ||f|| ||U|| F(x) DE(x) SOLVE
IT SIT GAMMA ||d||
                     3.93e-01 4.43e+03 0.0
                                                0.0
                                                      0.0
    1 1.00e+00 1.52e-01 9.16e-07 4.43e+03 0.0
                                                0.1
                                                      0.1
                                         0.0
    1 1.00e+00 3.85e-03 2.51e-10 4.43e+03
                                                0.1
                                                      0.1
    1 1.00e+00 3.63e-08 2.77e-13 4.43e+03
                                          0.1
                                                0.1
                 ||U|| LABEL TYPE
STEP
        TIME
                                           al hspo.test.USTAB
                                                                M Vavg
                                                                           M Fcap
  0 00:00:02 4.4312e+03 1 EP 2.6648e+01 0.0000e+00 -1.7920e-01
                                                                        4.7612e+02
```

- every point corresponds to one periodic solution of the model along a family of solutions generated by by the alpha (al).

STEP	TIME	וומון	LABEL	TYPE	al	hspo.test.USTAB	M_Vavg	M_Fcap
0	00:00:02	4.4312e+03	1	EP	2.6648e+01	0.0000e+00	-1.7920e-01	4.7612e+02
20	00:00:18	4.4329e+03	2		2.6515e+01	0.0000e+00	-3.8129e-01	4.8127e+02
24	00:00:24	4.4330e+03	3	EP	2.6511e+01	0.0000e+00	-3.8797e-01	4.8141e+02
STEP	TIME	ווטוו	LABEL	TYPE	al	hspo.test.USTAB	M_Vavg	M_Fcap
0	00:00:25	4.4312e+03	4	EP	2.6648e+01	0.0000e+00	-1.7920e-01	4.7612e+02
10	00:00:32	4.4306e+03	5	UZ	2.6699e+01	0.0000e+00	-1.0841e-01	4.7363e+02
20	00:00:43	4.4296e+03	6	UZ	2.6780e+01	0.0000e+00	1.4124e-09	4.6890e+02
20	00:00:43	4.4295e+03	7		2.6786e+01	0.0000e+00	8.5430e-03	4.6845e+02
28	00:00:50	4.4287e+03	8	UZ	2.6840e+01	0.0000e+00	8.5598e-02	4.6382e+02
35	00:00:57	4.4279e+03	9	UZ	2.6878e+01	0.0000e+00	1.5250e-01	4.5857e+02
40	00:01:01	4.4273e+03	10		2.6895e+01	0.0000e+00	1.9736e-01	4.5414e+02
45	00:01:10	4.4268e+03	11	FP	2.6899e+01	0.0000e+00	2.2992e-01	4.5043e+02
45	00:01:10	4.4268e+03	12	SN]2.6899e+01	1.0000e+00	2.2992e-01	4.5043e+02
54	00:01:19	4.4257e+03	13	UZ	2.6878e+01	1.0000e+00	2.9262e-01	4.4159e+02
60	00:01:25	4.4249e+03	14	UZ	2.6840e+01	1.0000e+00	3.3116e-01	4.3491e+02
60	00:01:25	4.4249e+03	15		2.6839e+01	1.0000e+00	3.3216e-01	4.3472e+02

74	00:01:37	4.4233e+03	16	UZ	2.6699e+01	1.0000e+00	4.0881e-01	4.1953e+02
80	00:01:42	4.4227e+03	17		2.6618e+01	1.0000e+00	4.4433e-01	4.1241e+02
100	00:01:58	4.4212e+03	18		2-6363e+01	1.0000e+00	5.6673e-01	3.9105e+02
120	00:02:15	4.4208e+03	19		2.6196e+01	1.0000e+00	7.0954e-01	3.7205e+02
126	00:02:24	4.4208e+03	20	FP	2.6182e+01	1.0000e+00	7.5320e-01	3.6706e+02
126	00:02:25	4.4208e+03	21	SN	2.6182e+01	1.0000e+00	7.5320e-01	3.6706e+02

- the "EP" refer to the starting and end points, "SN" is saddle node bifurcation.



one-parameter, to detect bifurcations velocity against alpha

Two parameter code

- again, name the continuation process, "CAPS2"
- prob = ode_hspo2SN(prob, ' ', 'CAPS0', 10);
- this line gets point 10 from the 1st run (one parameter), which is the saddle node. If it is period doubling the name would be "ode_hspo2PD"

```
clear;clc;close all;
prob_name='CAPS2[';
delete(strcat('data\',prob_name,'\*.mat'));

Mm=1.8e-3;Mc=1.67e-3;k=62;
Om0=sqrt(k/Mm);
muG=(Mm+Mc)*9.81*0.2293;

prob=coco_prob();
prob=coco_set(prob,'cont','ItMX',5000,'h_min',0.01,'h_max',100,'h0',0.1,'NPR',10);
prob=coco_set(prob,'coll','NTST',20,'NCOL',4);

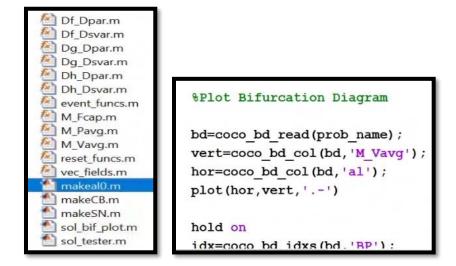
prob=ode_hspo2SN(prob,'','CAPS0',10);

fprintf('\n Run=''%s'': Continue family of multi-segment periodic orbits.\n',prob_name);
[data1,uidx1]=coco_get_func_data(prob,'hspo.orb.bvp.seg1.coll','data','uidx');
maps1=data1.coll_seg.maps;
prob=coco_add_pars(prob,'pars1',uidx1(maps1.T_idx),'T1','active');
[data2,uidx2]=coco_get_func_data(prob,'hspo.orb.bvp.seg2.coll','data','uidx');
```

- define the data structures as before.
- importantly, this time define the two parameters to be varied, in this case "al" and "om".

```
[data20,uidx20]=coco_get_func_data(prob,'hspo.orb.bvp.seg20.coll','data','uidx');
maps20=data20.coll_seg.maps;
prob=coco_add_pars(prob,'pars20',uidx20(maps20.T_idx),'T20','active');
[data,uidx]=coco_get_func_data(prob,'hspo.orb.bvp','data','uidx');
maps=data.bvp_bc;
prob=coco_add_func(prob,'P1',@M_Vavg,{data_data1_data2_data3_data4_data5_data6_data7_daprob=coco_add_func(prob,'P2',@M_Pavg,{data_data1_data2_data3_data4_data5_data6_data7_daprob=coco_add_func(prob,'P3',@M_Fcap,{data_data1_data2_data3_data4_data5_data6_data7_daprob=coco_add_func(prob,'P3',@M_Fcap,{data_data1_data2_data3_data4_data5_data6_data7_daprob=coco_add_func(prob,'P3',@M_Fcap,{data_data1_data2_data3_data4_data5_data6_data7_daprob=coco_add_func(prob_name,[],1,{'al'_om'_M_Vavg'_M_Fcap'_M_Pavg'_T1'_T2'_T3'_T4'_T5'
%Plot_Bifurcation_Diagram
bd=coco_bd_read(prob_name);
vert=coco_bd_col(bd,'om');
hor=coco_bd_col(bd,'al');
plot(hor,vert,'.-')
```

These are all the functions he included for this problem.



Answers

- ➤ hspo hybrid system periodic orbit, msbvp multi segment boundary value problem, msbvp is part of hspo.
- > "atlas" is related to many folds along a curve (this is not so relevant for this type of problem, unless if you are inserting certain algebraic equations).

```
prob=coco_prob();
prob=coco_set(prob,'cont_,'ItMX',5000,'h_min',0.01,'h_max',3,'h0',0.1,'NPR',20);
prob=coco_set(prob,'coll','NTST',20,'NCOL',4);
```

- ➤ Coco_set is used to set parameters, in this case cont problem type is continuation, "cont", ItMX is the maximum number of points (5000), h_min and h_max define the minimum and maximum step size, "h0" 0.1 is the initial step size.
- "NPR" 20 shows a set of results after every 20 steps, shown on the results table as $0 \ 20 \ 40 \ \dots$ (new labels are shown if defined by user, for example "UZ" at al = xxx).
- ➤ (Discretization of the periodic solution). Second line sets number of collocation points to 4 and discretization points 20.
- hspo_iso2segs() and msbvp_iso2segs.

 1st one is for setting up an initial solution, 2nd one is more general (multi boundary), we usually use hspo_iso2segs().