

7/9/23

Deep Learning

- Recap SNE ✓
- Wrap up SNE ✓
- Issue with SNE: Asymmetry, High dim vs low dim distances (Crowding problem) ✓
- t-SNE: (1) Symmetric SNE, (2) t-distributed SNE ✓

◦ ANNs & Back prop

$$P_i = p_{j|i} = \frac{\exp(-\|x_i - x_j\|_2^2 / 2\sigma_i^2)}{\sum_{k \neq i} \exp(-\|x_i - x_k\|_2^2 / 2\sigma_i^2)}$$

$$Q_i = q_{j|i} = \frac{\exp(-\|y_i - y_j\|_2^2 / 2 \cdot \frac{1}{2})}{\sum_{k \neq i} \exp(-\|y_i - y_k\|_2^2 / 2 \cdot \frac{1}{2})}$$

$$C = \sum_i KL(P_i || Q_i)$$

$$y^{(t)} = y^{(t-1)} - \eta \nabla_{y^{(t-1)}} C + \alpha(t) (y^{(t-1)} - y^{(t-2)}) - \textcircled{A}$$

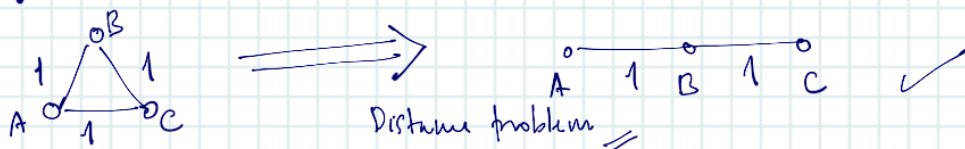
- σ_i is found by doing a search over $\text{Perp}(\cdot | P_i) = 2^{H(P_i)}$ (which is a function of σ_i).

$$H(P_i) = - \sum_j p_{j|i} \log_2 p_{j|i}$$

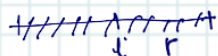
◦ Remarks:

- (i) SNE makes use of distance measure
- (ii) SNE makes use of KL divergence
- (iii) SNE makes use of entropy

- Mapping equidistant points in high dim space to low dim space → Aside



- Area in a norm ball.



Crowding problem:

- Student t-distributed SNE (t-SNE): Two modifications to the original SNE formulations to address the challenges identified above.

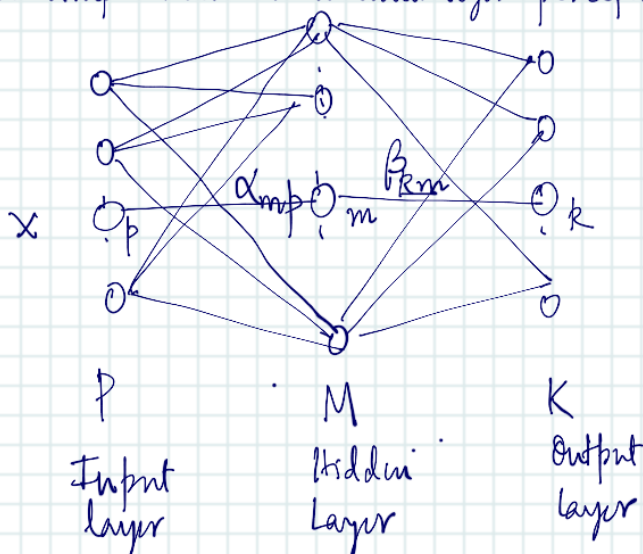
(i) Symmetric SNE:
$$P_i = \frac{p_i |c| + p_i |j|}{2n} \rightarrow n \text{ is \# datapoints}$$

- (ii) Mapping to a heavy tailed distributed - Student-t distribution

$$Q_i = q_{f,i} = \frac{(1 + \|y_i - y_f\|_2^2)^{-1}}{\sum_{k \neq i} (1 + \|y_k - y_f\|_2^2)^{-1}}$$

- Artificial Neural Nets (ANNs): ANNs are popular functions used to model I/O relations in the supervised learning setting: $\hat{y} = f(x; \theta)$

- Let's define a simple ANN or a multilayer perceptron



$$\hat{y} = f(x; \theta)$$