

Interpolation: it is a method used to estimate the value of a function at determined point, while extrapolation compute the value of the function outside the given range.

Many techniques are used to calculate the value of the function at specific point; however, we will talk about only three techniques Newtown General, Newtown Gregory and Lagrange.

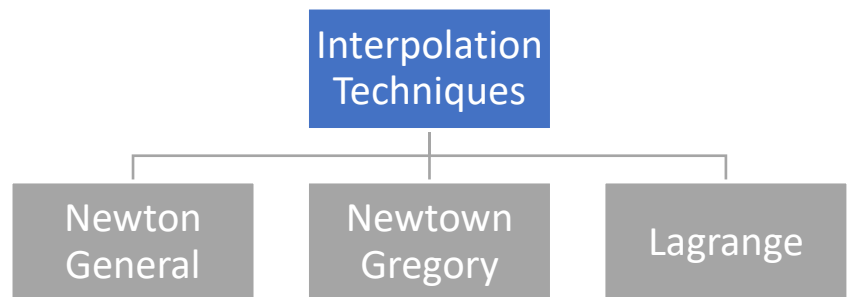


Figure1: Interpolation Techniques

1-**Newton General Interpolation:** is an interpolation technique that used when the step between points is not same.

Divided difference Formula: $\Delta y_i = \frac{y_{i+1} - y_i}{x_{i+1} - x_i}$

Xi	F[xi]	1 st order Differences	2 st order Differences
X1	Y1		
		$\Delta_1 = \frac{y_2 - y_1}{x_2 - x_1}$	
X2	Y2		$\Delta^2_1 = \frac{\Delta_2 - \Delta_1}{x_3 - x_1}$
		$\Delta_2 = \frac{y_3 - y_2}{x_3 - x_2}$	
X3	Y3		

Table1: Divided Difference For 3points

Newton's General Interpolation Formula

$$P_n(x) = y_0 + \frac{\Delta y_0 (x - x_0)}{h} + \frac{\Delta^2 y_0 (x - x_0)(x - x_1)}{2! h^2} + \dots + \frac{\Delta^n y_0 (x - x_0)(x - x_1) \dots (x - x_{n-1})}{n! h^n}$$

Residual Error for Newton's General Interpolation: if we stop at (n-1) term before stopping term then the residual error will be (n) term.

2-Newton Gregory Interpolation: is a special case of newton general that used when the step between points is same for all sequence.

Forward Difference Formula: $\Delta y_i = \frac{y_{i+1} - y_i}{x_{i+1} - x_i}$

x_i	$F[x_i]$	1 st Differences	2 st Differences
x1	Y1		
		$\Delta Y_0 = Y_2 - Y_1$	
x2	Y2		$\Delta^2 Y_0 = \Delta Y_1 - \Delta Y_0$
		$\Delta Y_1 = Y_3 - Y_2$	
x3	Y3		

Table2: Forward Difference For 3points

Newton's Gregory Interpolation Formula

$$Y = Y_0 + \alpha \Delta y_0 + \Delta^2 y_0 \frac{(\alpha)(\alpha-1)}{2!} + \Delta^3 y_0 \frac{(\alpha)(\alpha-1)(\alpha-2)}{3!} + \dots \dots \dots \text{where } \alpha = \frac{x-x_0}{h}$$

- **Newton's Gregory can also used to compute derivatives**

$$\frac{dy}{dx} = \frac{1}{h} \left(\Delta y_0 + \frac{(2\alpha - 1)\Delta^2 y_0}{2!} + \frac{(3\alpha^2 - 6\alpha + 2)\Delta^3 y_0}{3!} \dots \right)$$

- In case this derivative is being evaluated at a point on the table

$$\frac{dy}{dx} = \frac{1}{h} \left(\Delta y_0 + \frac{\Delta^2 y_0}{2!} + \frac{2\Delta^3 y_0}{3!} \dots \right)$$

3-Lagrange polynomial: For a given set of (X_i, Y_i) points with no two X_i values equal it used to get function of power $(n-1)$ from n points.

- **Lagrange Interpolation Formula**

$$P_n(x) = \sum_{i=1}^n \left\{ \left(\prod_{\substack{j=1 \\ j \neq i}}^n \frac{x-x_j}{x_i-x_j} \right) y_i \right\}$$

- An advantage to Lagrange Interpolation to compute $F^{-1}(x)$ easily by for a few numbers of points