

- [Getting Started with Vivado](#)

Introduction

The goal of this guide is to familiarize the reader with the Vivado tools.

Prerequisites

Hardware

- **Digilent FPGA System Board**
- **MicroUSB Programming Cable**

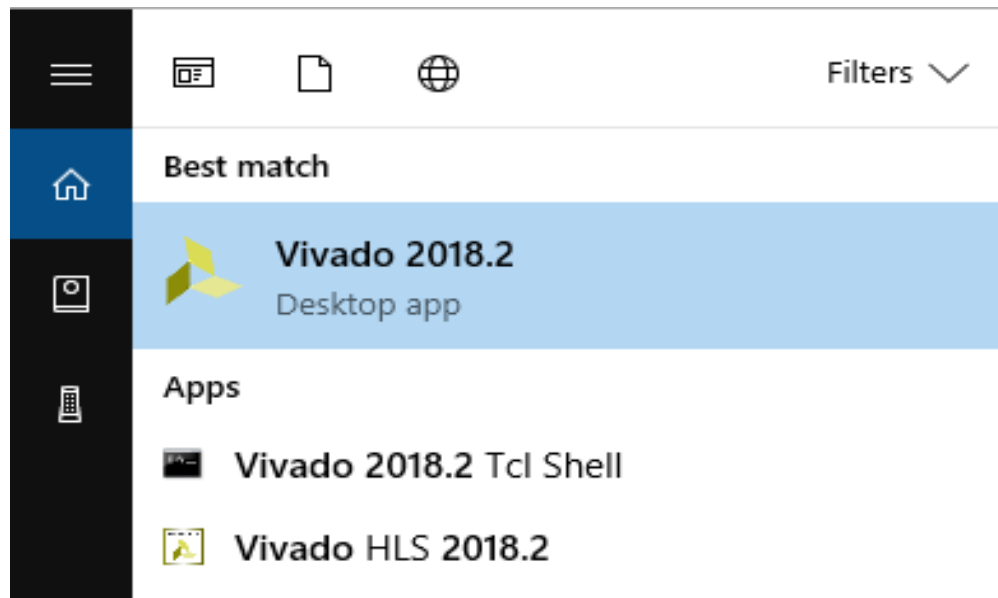
Software

- **Xilinx Vivado 2018.2 and Digilent Board Files**
 - *Other versions of Vivado may work, but functionality is not guaranteed*
-

1. [Starting Vivado](#)

Windows

Open Vivado via the start menu or desktop shortcut created during the installation process.



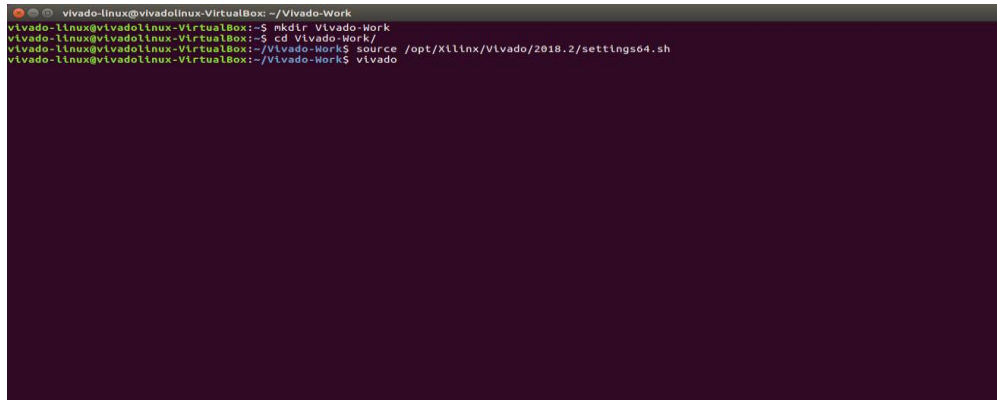
Linux

Open a terminal, **cd** into a working directory that can be cluttered with temporary Vivado files and logs, then run the following two commands:

```
source <install_path>/Vivado/<version>/settings64.sh
```

```
vivado
```

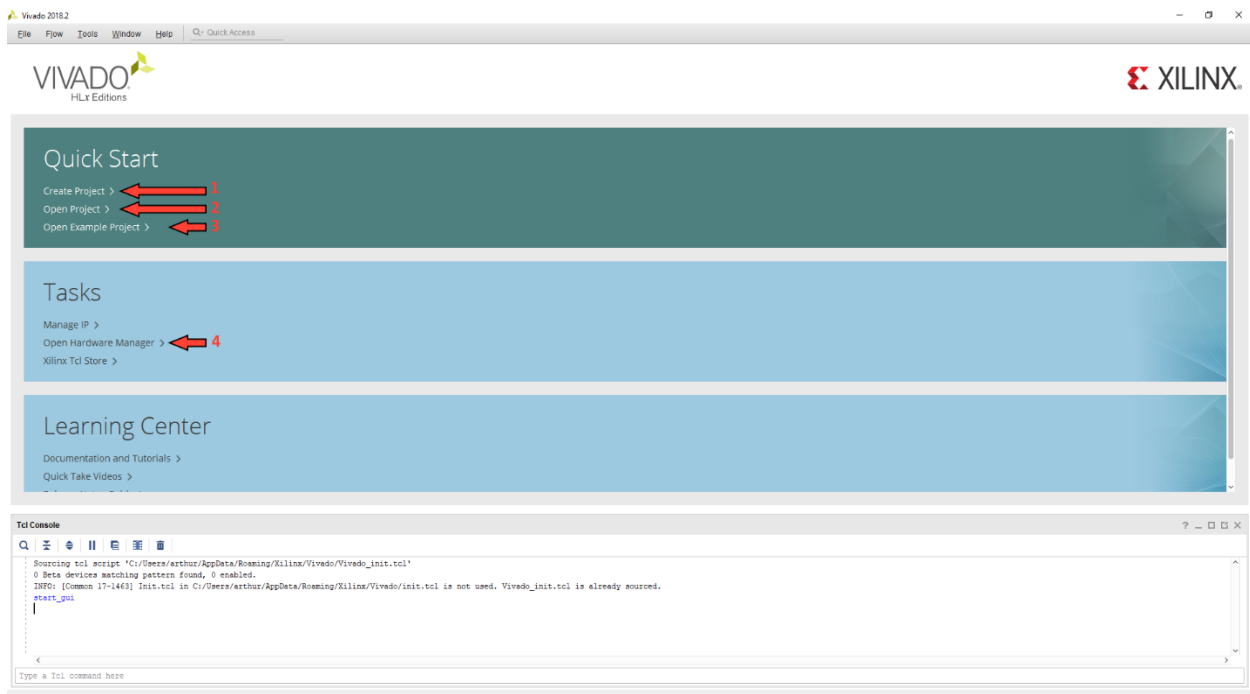
For a default installation of Vivado, the install path will be “C:/Xilinx/” on Windows, and “/opt/Xilinx/” on Linux.



```
vivado-linux@vivadolinux-VirtualBox: ~/Vivado-Work
vivado-linux@vivadolinux-VirtualBox:~$ mkdir Vivado-Work
vivado-linux@vivadolinux-VirtualBox:~$ cd Vivado-Work/
vivado-linux@vivadolinux-VirtualBox:~/Vivado-Work$ source /opt/Xilinx/Vivado/2018.2/settings64.sh
vivado-linux@vivadolinux-VirtualBox:~/Vivado-Work$ vivado
```

2. [The Start Page](#)

This is the Vivado's start-up screen. The different options available are described below using the image as a guide.

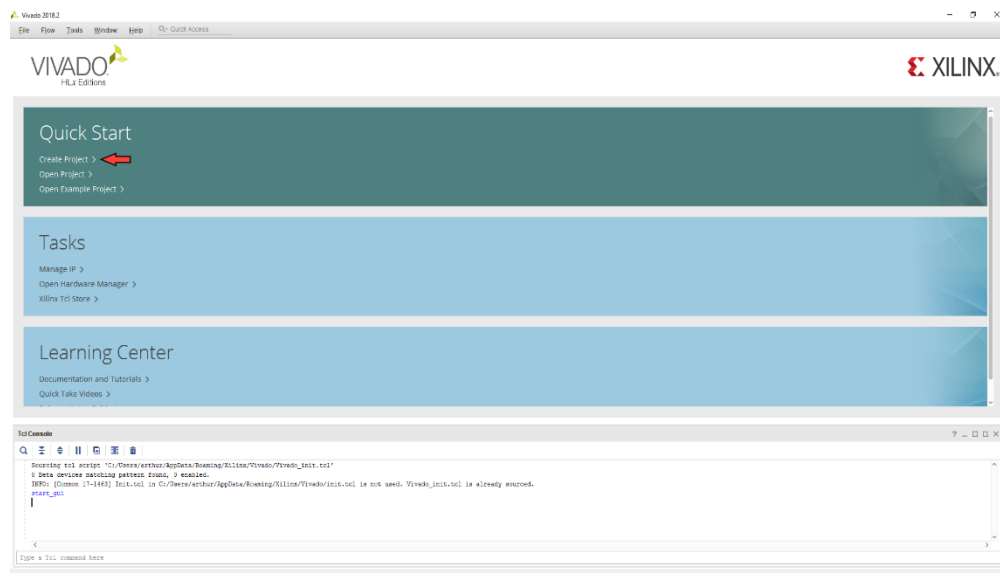


- **Create New Project:** This button will open the New Project wizard. This wizard steps the user through creating a new project. The wizard is stepped through in section 3.
- **Open Project:** This button will open a file browser. Navigate to the desired Xilinx Project (.xpr) file and click **Open** to open the project in Vivado.
- **Open Example Project:** This will guide the user through creating a new project based on an example project. These projects will not work on all devices. Many Digilent example projects are instead released on Github, and linked to through the target FPGA System Board's Resource Center, which can be found through the list of [List of Digilent FPGA System Boards](#).
- **Open Hardware Manager:** This will open the Hardware Manager without an associated project. If connecting to and programming a device is all that the user wants to do, then this is the button to use.

3. Creating a New Project

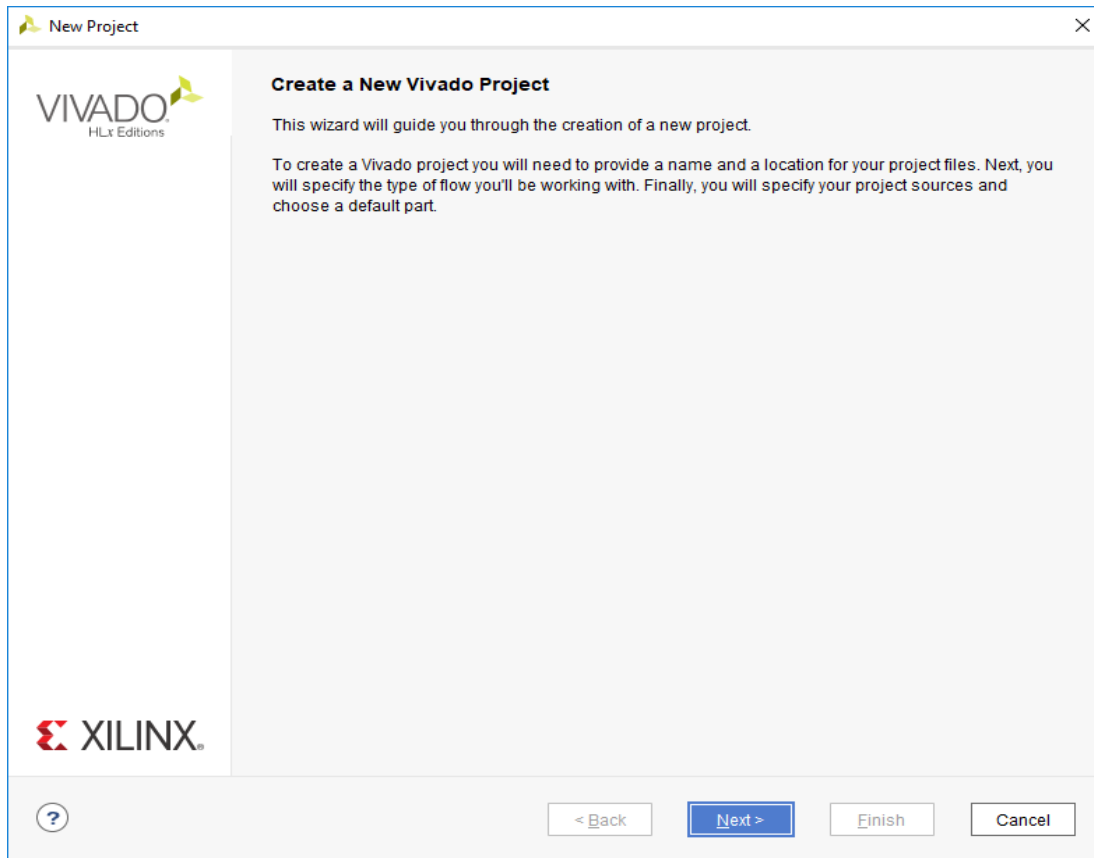
3.1

From the start page, click the **Create New Project** button to start the New Project Wizard.



3.2

The text in this dialog describes the steps that will be taken to create a project. Click **Next** to continue.



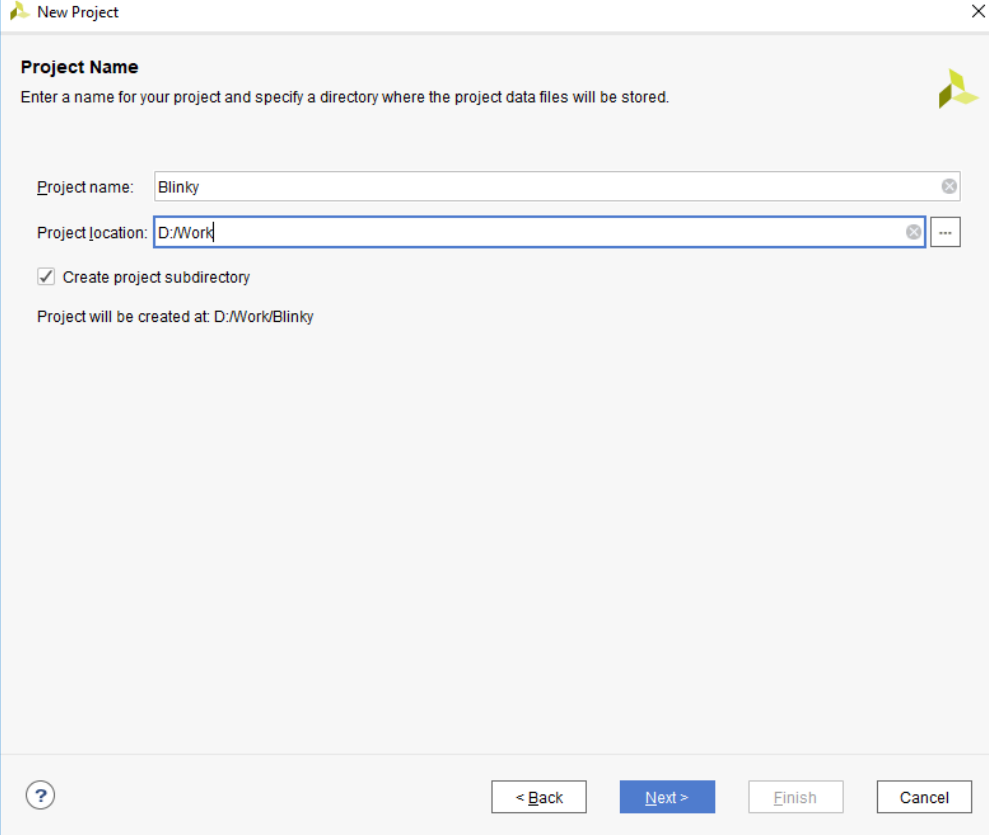
3.3

The first page is used to set the name of the project. Vivado will use this name when generating its folder structure.

Important

Do NOT use spaces in the project name or location path. This will cause problems with Vivado. Instead use an underscore, a dash

Click **Next** to continue.



The image shows a 'New Project' dialog box with a title bar containing a yellow logo and a close button. The main area is titled 'Project Name' and contains the instruction 'Enter a name for your project and specify a directory where the project data files will be stored.' Below this, there are two input fields: 'Project name:' with the text 'Blinky' and 'Project location:' with the text 'D:/Work'. To the right of the 'Project location:' field is a button with three dots. Below the input fields, there is a checked checkbox labeled 'Create project subdirectory' and the text 'Project will be created at: D:/Work/Blinky'. At the bottom of the dialog, there is a help icon (a question mark in a circle) and four buttons: '< Back', 'Next >' (highlighted in blue), 'Finish', and 'Cancel'.

New Project

Project Name
Enter a name for your project and specify a directory where the project data files will be stored.

Project name: Blinky

Project location: D:/Work

☒ Create project subdirectory

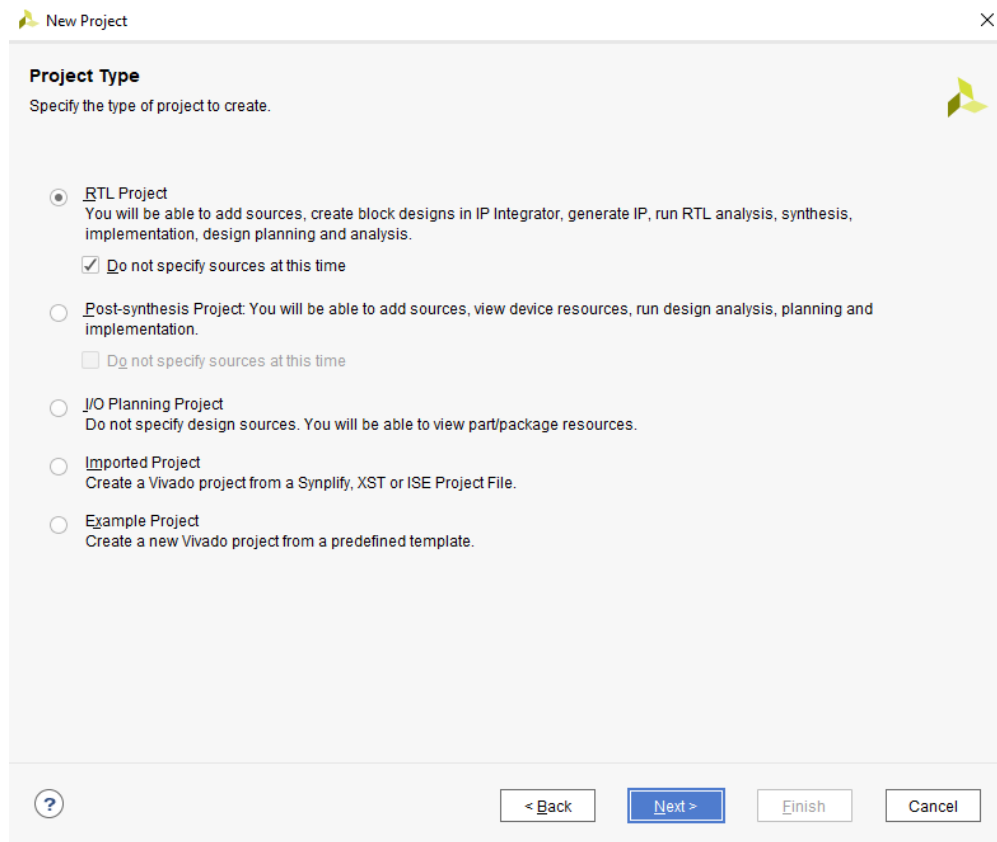
Project will be created at: D:/Work/Blinky

? < Back Next > Finish Cancel

3.4

Now that the project has a name and a place to save its files we need to select the type of project we will be creating. Select *RTL Project* and make sure to check the *Do not specify sources at this time* box. Source files will be added and created after the project has been created. Advanced users may use the other options on this screen, but they will not be covered in this guide.

Click **Next** to continue.



3.5

Important

If the target board does not appear in this list, then Digilent's board files haven't yet been installed. If this is the case, revisit the prerequisites section of this guide, then close Vivado and start again from the beginning.

Now it is time to choose the target device. Click the **Boards** tab at the top of the dialog, then select the target board from the list.

Click **Next** to continue.

New Project

Default Part

Choose a default Xilinx part or board for your project. This can be changed later.

Parts | **Boards**

[Reset All Filters](#)

Vendor: All Name: All

Search: arty a7 (2 matches)

Display Name	Preview	Vendor	File V
Arty A7-100		digilentinc.com	1.0
Arty A7-35		digilentinc.com	1.0

?

< Back

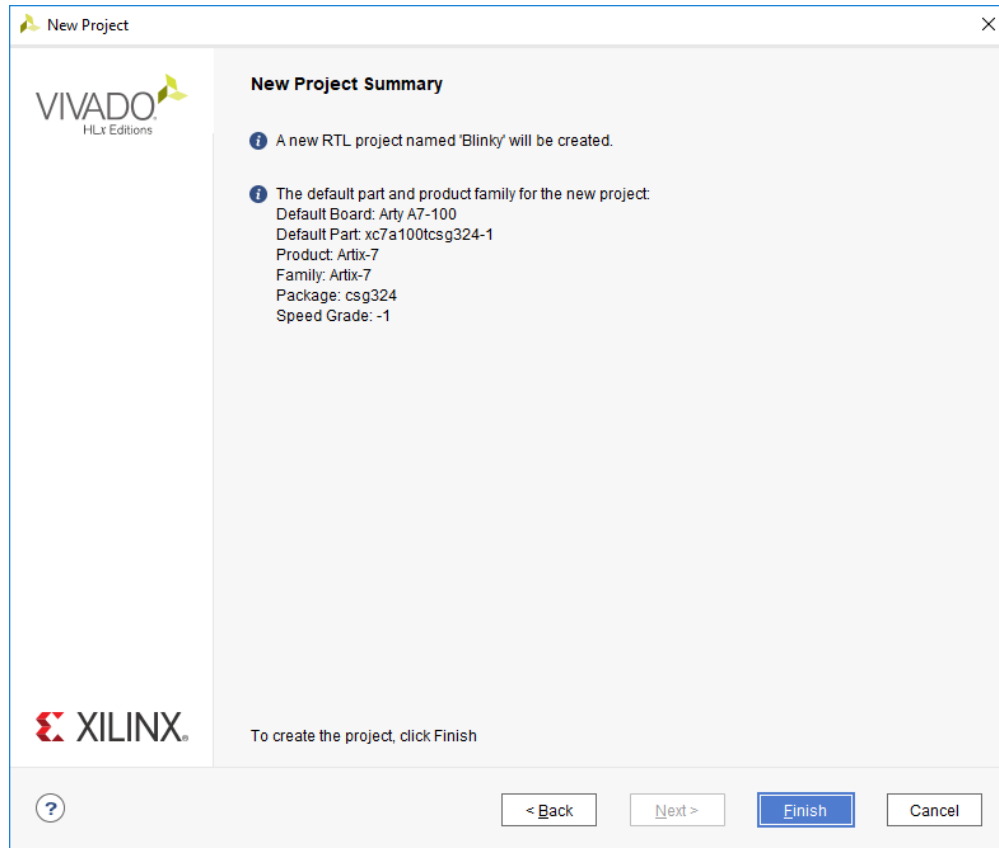
Next >

Finish

Cancel

3.6

The next section gives a summary of the options selected throughout the wizard. Verify that the information looks correct and click **Finish**.



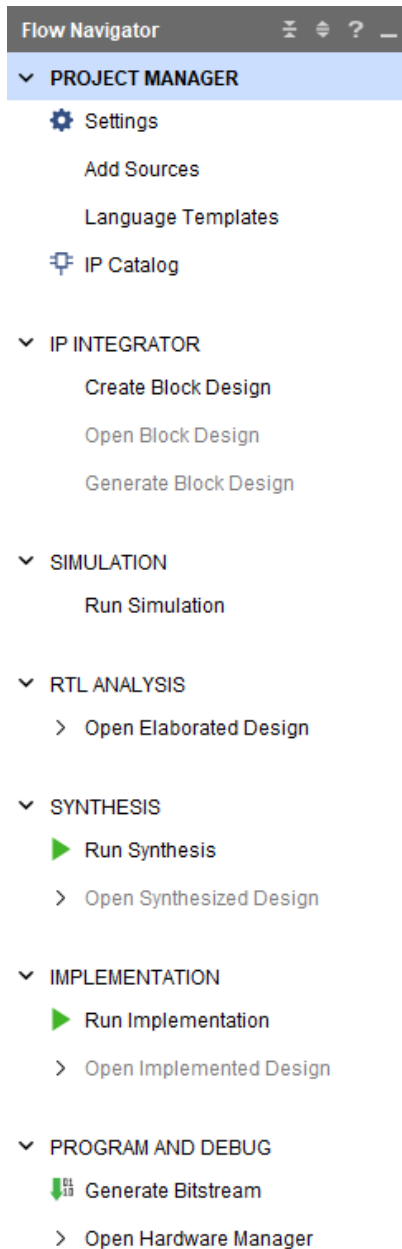
4. The Flow Navigator

The *Flow Navigator* is the most important pane of the main Vivado window to know. It is how a user navigates between different Vivado tools.

The Navigator is broken into seven sections:

- **Project Manager:** Allows for quick access to project settings, adding sources, language templates, and the IP catalog.
- **IP Integrator:** Tools for creating complex designs in a graphical user interface, rather than by writing large source files.
- **Simulation:** Allows a developer to verify the output of their design prior to programming the target device.
- **RTL Analysis:** Lets the developer see how the tools are interpreting their code.
- **Synthesis:** Gives access to Synthesis settings and post-synthesis reports.
- **Implementation:** Gives access to Implementation settings and post-implementation reports.

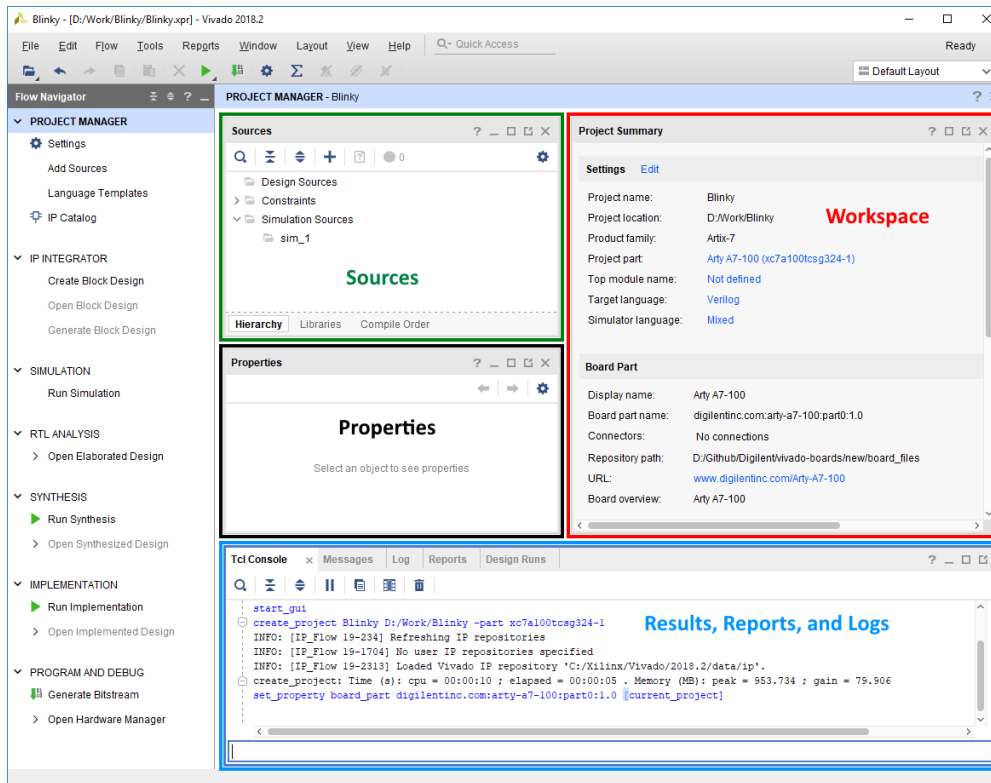
- **Program and Debug:** Gives access to settings for bitstream generation and tools to program FPGAs.



5. The Project Manager

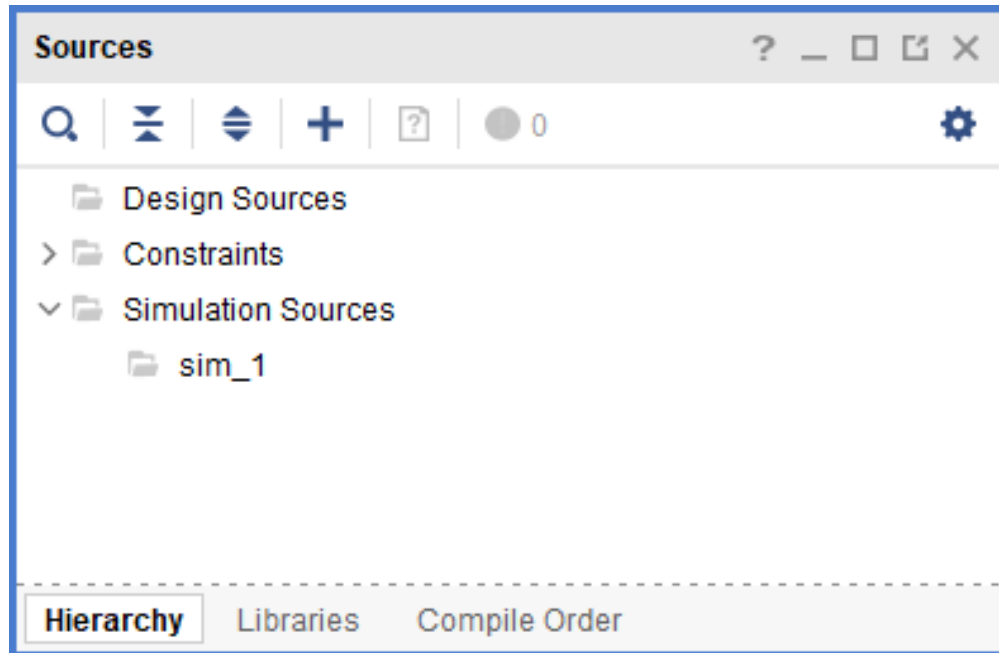
This tool is where most development will occur and is the initial tool open after creating a new project.

The *Project Manager* consists of four panes, *Sources*, *Properties*, *Results*, and the *Workspace*, described below.



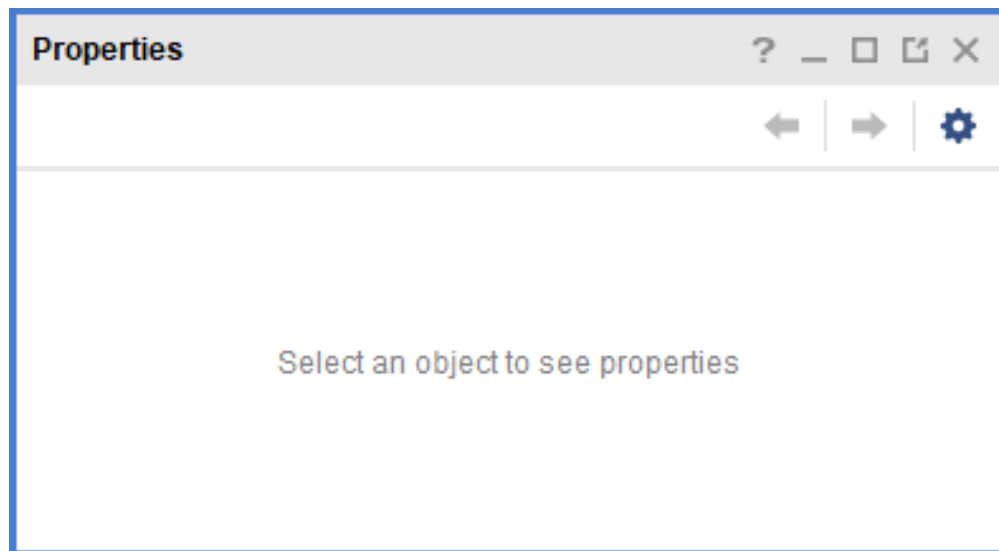
Sources Pane

The *Sources* pane contains project hierarchy and is used for opening up files. The folder structure is organized such that the HDL files are kept under the *Design Sources* folder, constraints are kept under the *Constraints* folder, and simulation files are kept under the *Simulation Sources* folder. Files can be opened in the *Workspace* by double-clicking on the corresponding entry in the *Sources* pane. Sources can also be added by either clicking the folder to add the file to and selecting *Add Sources* or by clicking the *Add Sources* button



Properties Pane

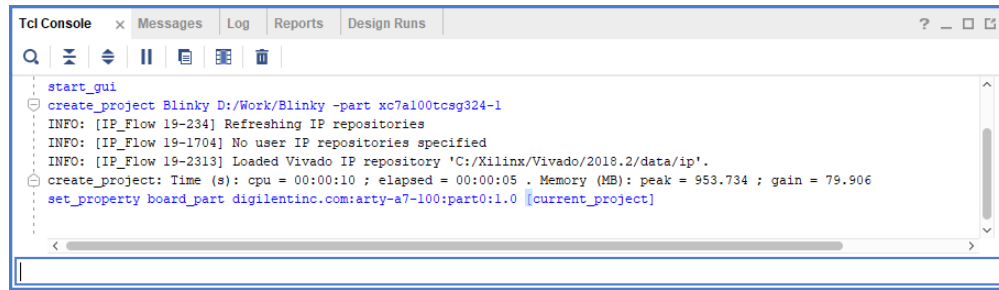
The *Properties* pane allows for viewing and editing of file properties. When a file is selected in the Sources pane its properties are shown here. This pane can usually be ignored.



Results, Reports, and Logs

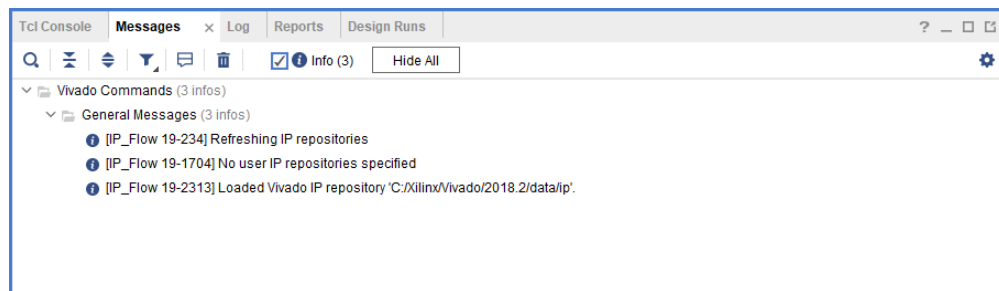
TCL Console Tab

The *Tcl Console* is a tool that allows running commands directly without the use of the main graphical user interface.



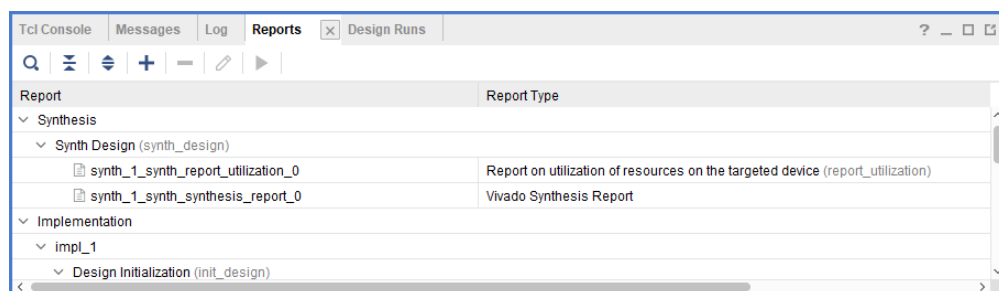
Messages Tab

The *Messages* tab displays warnings (critical or otherwise) and errors that may occur during the process of building a project. If anything goes wrong while designing and building a project, check the Messages first. Solutions for many errors and warning can be found by right clicking on the message and selecting “Search for Answer Record”.



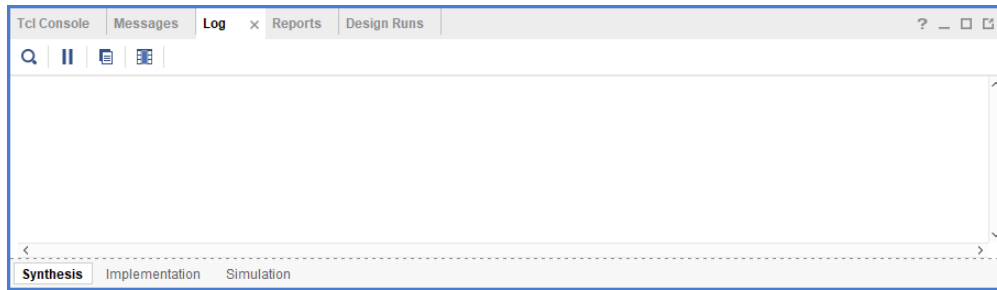
Reports Tab

The *Reports* tool is useful for quickly jumping to any one of the many reports that Vivado generates on a design. These include power, timing, and utilization reports just to name a few.



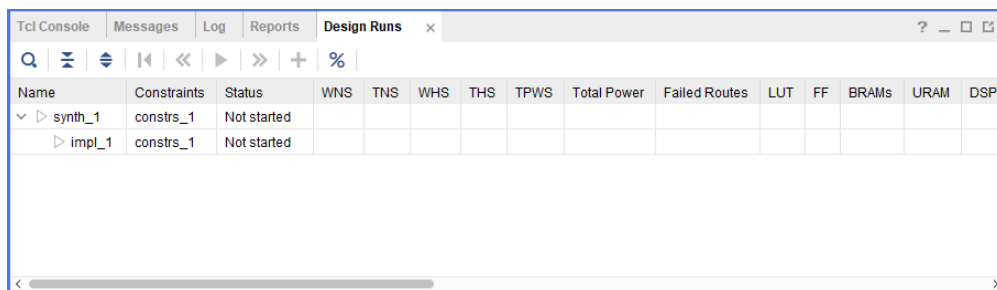
Log Tab

The *Log* displays the output from the latest Synthesis, Implementation, and Simulation runs. Digging into this is usually not necessary as the reports and message’s view store the information in the log in a more readable format.



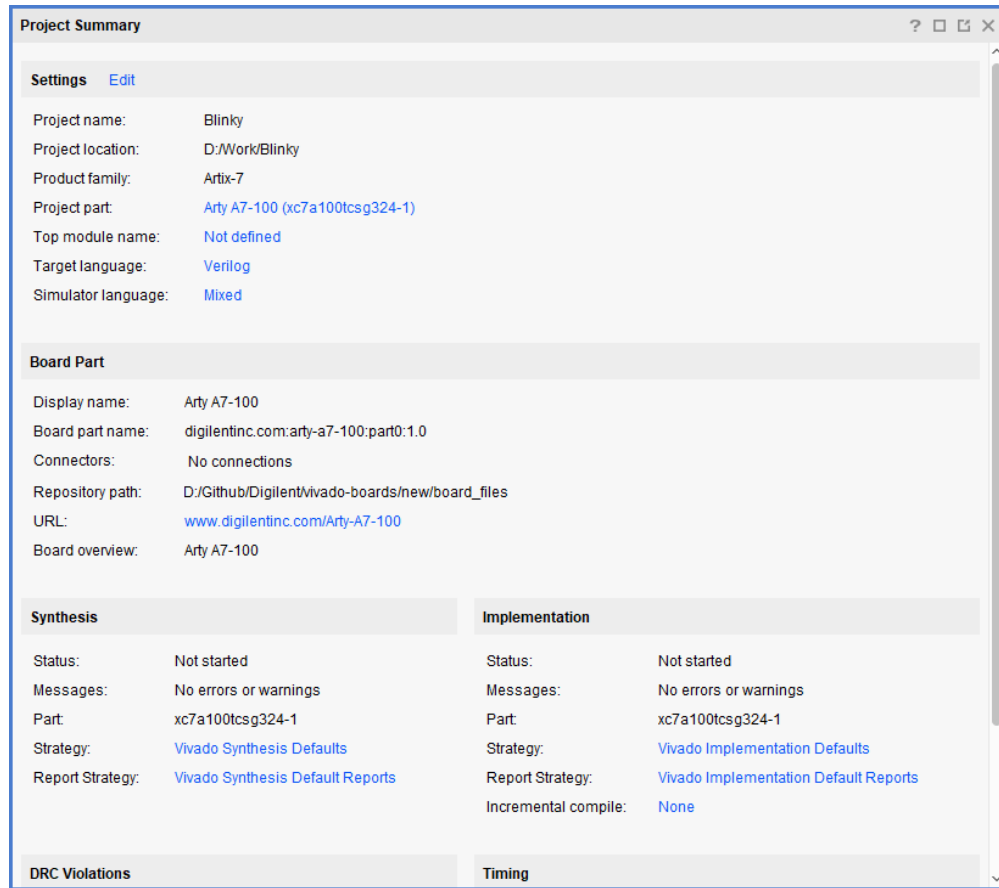
Design Runs Tab

The last tool is the *Design Runs*. Using this tool, run settings can be edited and new runs can be created. This tool is useful when targeting multiple devices with the same design.



Workspace Pane


The most important pane in the Project Manager is the *Workspace*. The *Workspace* is where reports are opened for viewing and source files are opened for editing. Initially the *Workspace* displays the *Project Summary* which show some basic information from some of the reports.

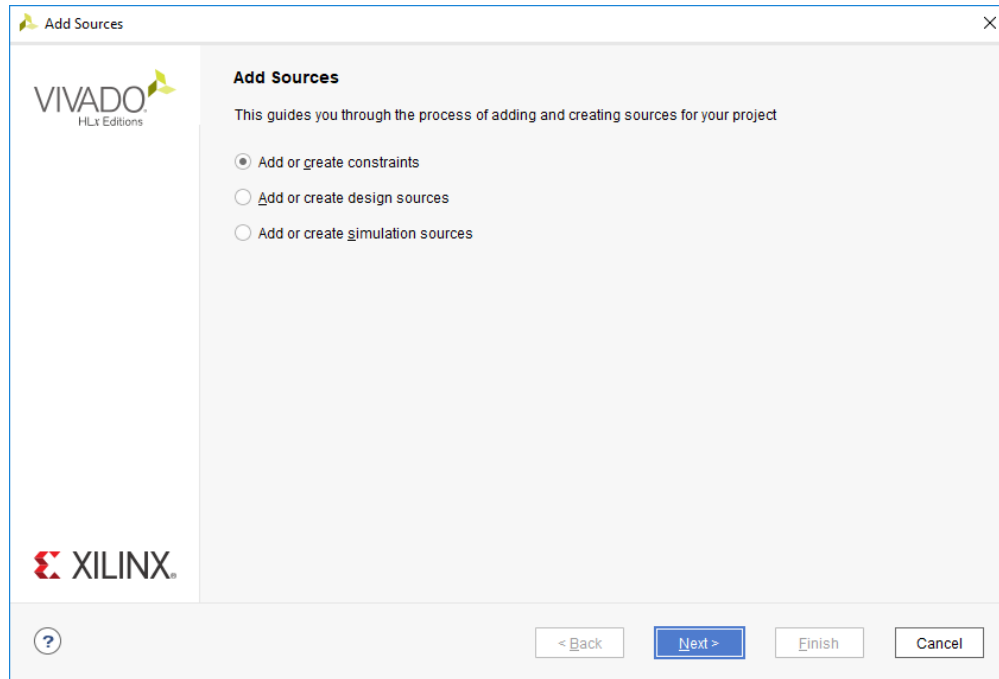


6. Adding a Constraint File

In order to connect the inputs and outputs of an HDL design with the physical pins of the FPGA, a constraint file needs to be added or created. Digilent has produced a Xilinx Design Constraint (XDC) file for each board.

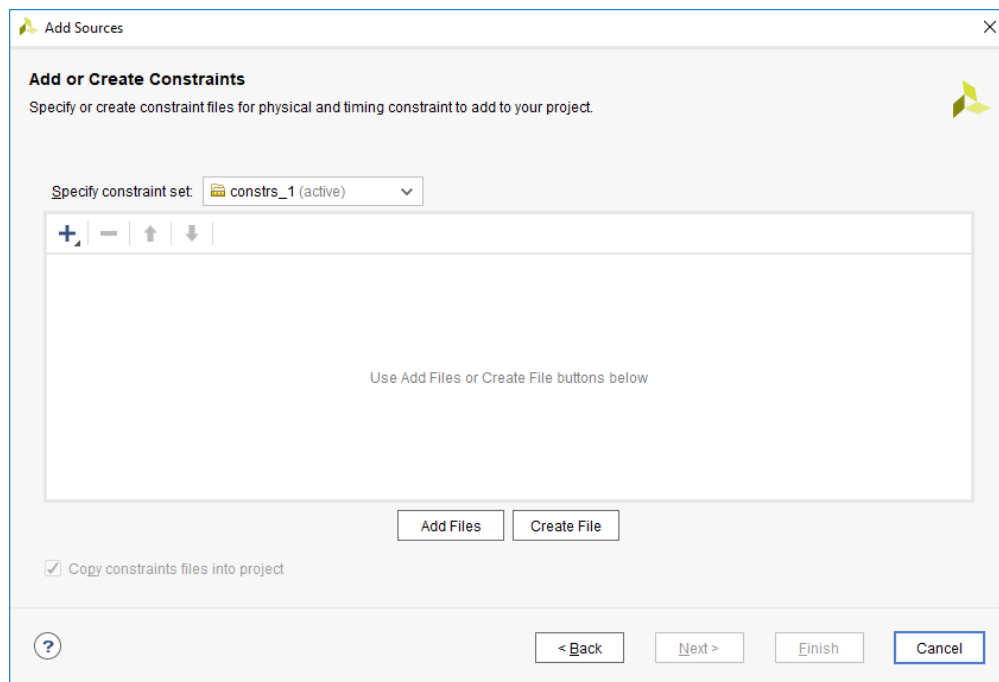
6.1

In the *Project Manager* section of the *Flow Navigator*, click the  **Add Sources** button. In the wizard that pops up, select *Add or create constraints* then click **Next**.



6.2

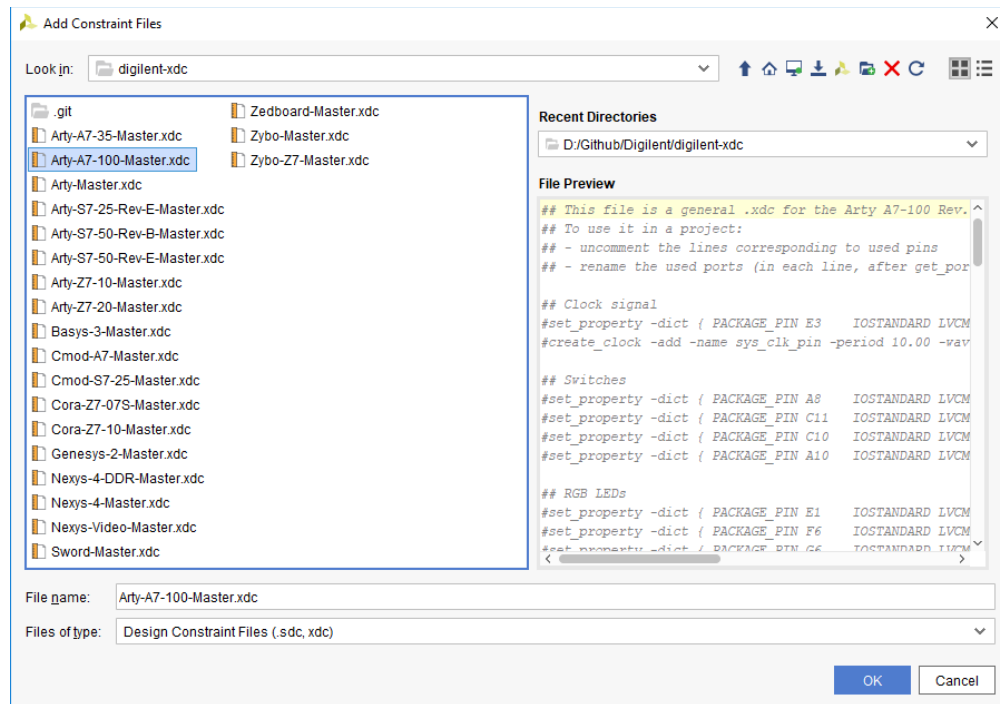
At this stage, Vivado provides a list of all of the constraint files that will be added or created when we click Finish. Currently this list is empty, this will change when files have been added or created. A constraint file will not be created from scratch in this guide, so click **Add Files**.



6.3

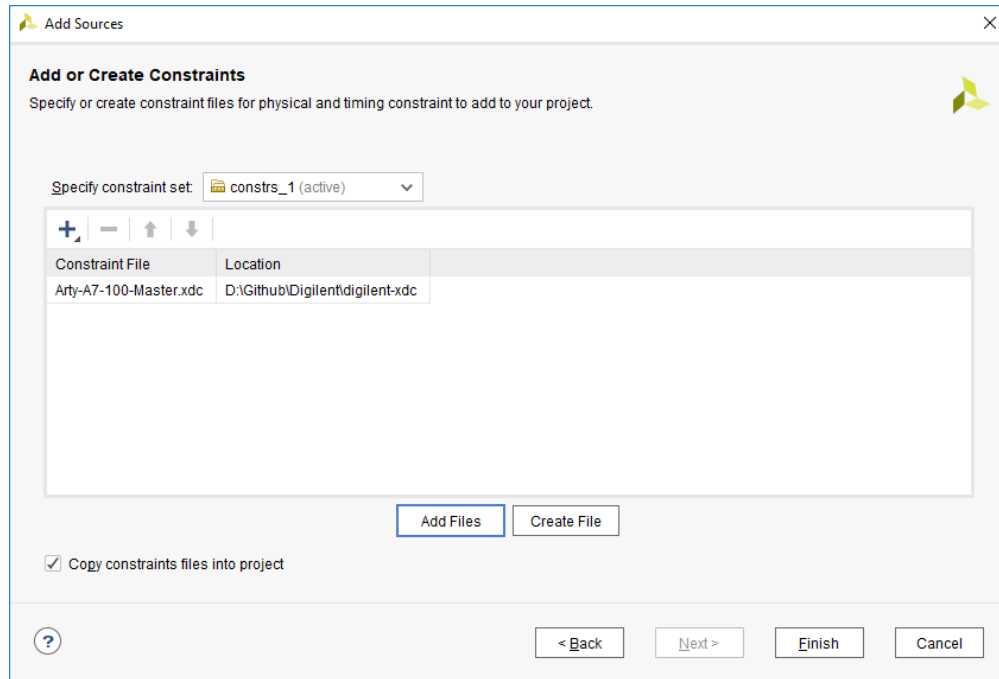
Find the directory the “diligent-xdc-master.zip” archive was extracted into, then click on the file for the target FPGA system board.

Click **OK** to continue.



6.4

Make sure that the selected XDC file has been added into the list of sources. Make sure that the “Copy constraint files into project” box is checked, so that the original file will be left alone so that it can be used in other projects. Click **Finish**.



6.5

In the *Sources* pane of the *Project Manager*, expand the *Constraints* folder, then double click on the XDC file that was just added. Each of Digilent's XDC files contains constraints for each of the commonly used peripherals on their respective boards. For this demo, constraining the default system clock and a single led is required.

Find and uncomment the lines that call *get_ports* on the names *led[0]* and *clk* by removing the '#' symbol at the beginning of the line. On some boards the clock port will consist of two different ports, *clk_p* and *clk_n*. The clock port is occasionally named something like *sysclk*, but should appear at the top of the XDC file. Uncomment the *create_clock* line that follows the clock port/s definition as well.

Tip

A board using *clk_p/clk_n* pins means that the input clock that uses differential logic. Check out the Wikipedia article on [low-voltage differential signalling](#) for more information.

Change the name inside of the *get_ports* call to 'led' from 'led[0]'. Do the same for the clock if it is something other than 'clk' or 'clk_p' and 'clk_n'.

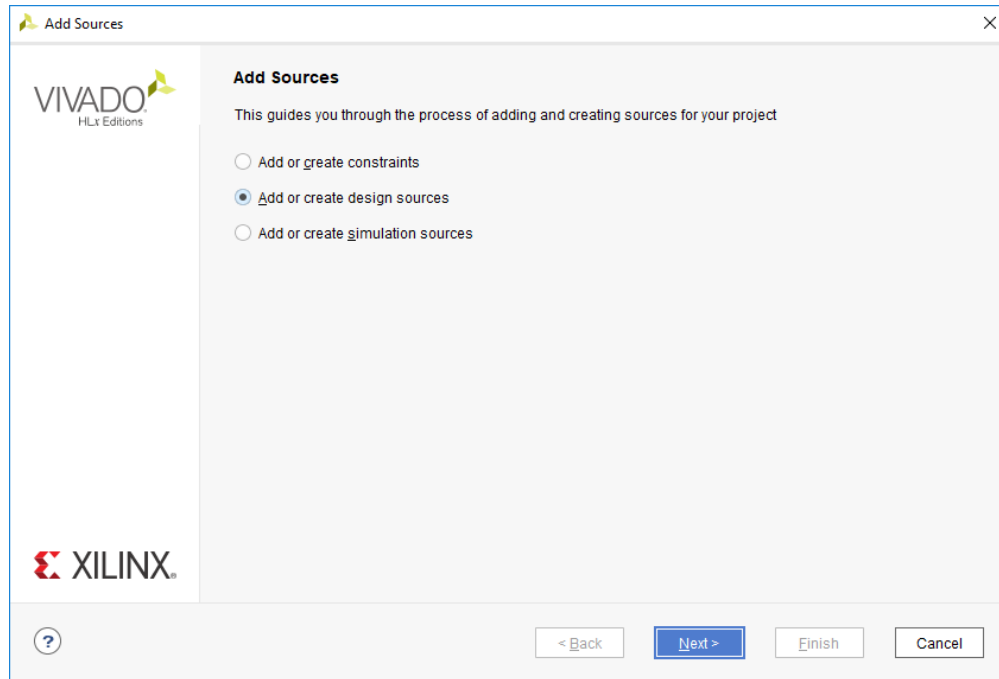
```
Project Summary x Arty-A7-100-Master.xdc x ? □ ⌵
D:/Work/Blinky/Blinky.srcs/constrs_1/imports/digilent-xdc/Arty-A7-100-Master.xdc

1  ## This file is a general .xdc for the Arty A7-100 Rev. D
2  ## To use it in a project:
3  ## - uncomment the lines corresponding to used pins
4  ## - rename the used ports (in each line, after get_ports) according to the top level signal names in the project
5
6  # Clock signal
7  set_property -dict { PACKAGE_PIN E3      IOSTANDARD LVCMOS33 } [get_ports { clk }]; #IO_L12P_T1_MRCC_35 Sch=clk[100]
8  create_clock -add -name sys_clk_pin -period 10.00 -waveform { 0 5 } [get_ports { clk }];
9
10 ## Switches
11 set_property -dict { PACKAGE_PIN A8      IOSTANDARD LVCMOS33 } [get_ports { sw[0] }]; #IO_L12N_T1_MRCC_16 Sch=sw[0]
12 set_property -dict { PACKAGE_PIN C11    IOSTANDARD LVCMOS33 } [get_ports { sw[1] }]; #IO_L13P_T2_MRCC_16 Sch=sw[1]
13 set_property -dict { PACKAGE_PIN C10    IOSTANDARD LVCMOS33 } [get_ports { sw[2] }]; #IO_L13N_T2_MRCC_16 Sch=sw[2]
14 set_property -dict { PACKAGE_PIN A10    IOSTANDARD LVCMOS33 } [get_ports { sw[3] }]; #IO_L14P_T2_MRCC_16 Sch=sw[3]
15
16 ## RGB LEDs
17 set_property -dict { PACKAGE_PIN E1      IOSTANDARD LVCMOS33 } [get_ports { led0_b }]; #IO_L18N_T2_35 Sch=led0_b
18 set_property -dict { PACKAGE_PIN F6      IOSTANDARD LVCMOS33 } [get_ports { led0_g }]; #IO_L18N_T3_VREF_35 Sch=led0_g
19 set_property -dict { PACKAGE_PIN G6      IOSTANDARD LVCMOS33 } [get_ports { led0_r }]; #IO_L19P_T3_35 Sch=led0_r
20 set_property -dict { PACKAGE_PIN J4      IOSTANDARD LVCMOS33 } [get_ports { led1_b }]; #IO_L20P_T3_35 Sch=led1_b
21 set_property -dict { PACKAGE_PIN J4      IOSTANDARD LVCMOS33 } [get_ports { led1_g }]; #IO_L21P_T3_DQS_35 Sch=led1_g
22 set_property -dict { PACKAGE_PIN G3      IOSTANDARD LVCMOS33 } [get_ports { led1_r }]; #IO_L20N_T3_35 Sch=led1_r
23 set_property -dict { PACKAGE_PIN H4      IOSTANDARD LVCMOS33 } [get_ports { led2_b }]; #IO_L21N_T3_DQS_35 Sch=led2_b
24 set_property -dict { PACKAGE_PIN J2      IOSTANDARD LVCMOS33 } [get_ports { led2_g }]; #IO_L22N_T3_35 Sch=led2_g
25 set_property -dict { PACKAGE_PIN J3      IOSTANDARD LVCMOS33 } [get_ports { led2_r }]; #IO_L22P_T3_35 Sch=led2_r
26 set_property -dict { PACKAGE_PIN K2      IOSTANDARD LVCMOS33 } [get_ports { led3_b }]; #IO_L23P_T3_35 Sch=led3_b
27 set_property -dict { PACKAGE_PIN H6      IOSTANDARD LVCMOS33 } [get_ports { led3_g }]; #IO_L24P_T3_35 Sch=led3_g
28 set_property -dict { PACKAGE_PIN K1      IOSTANDARD LVCMOS33 } [get_ports { led3_r }]; #IO_L23N_T3_35 Sch=led3_r
29
30 ## LEDs
31 set_property -dict { PACKAGE_PIN H5      IOSTANDARD LVCMOS33 } [get_ports { led }]; #IO_L24N_T3_35 Sch=led[4]
32 set_property -dict { PACKAGE_PIN J5      IOSTANDARD LVCMOS33 } [get_ports { led[1] }]; #IO_25_35 Sch=led[5]
33 set_property -dict { PACKAGE_PIN T9      IOSTANDARD LVCMOS33 } [get_ports { led[2] }]; #IO_L24P_T3_A01_D17_14 Sch=led[6]
34 set_property -dict { PACKAGE_PIN T10     IOSTANDARD LVCMOS33 } [get_ports { led[3] }]; #IO_L24N_T3_A00_D16_14 Sch=led[7]
35
36 ## Buttons
```

7. Creating a Verilog Source File

7.1

In the *Project Manager* section of the *Flow Navigator*, click the  **Add Sources** button again. Select *Add or create design sources* then click **Next**.

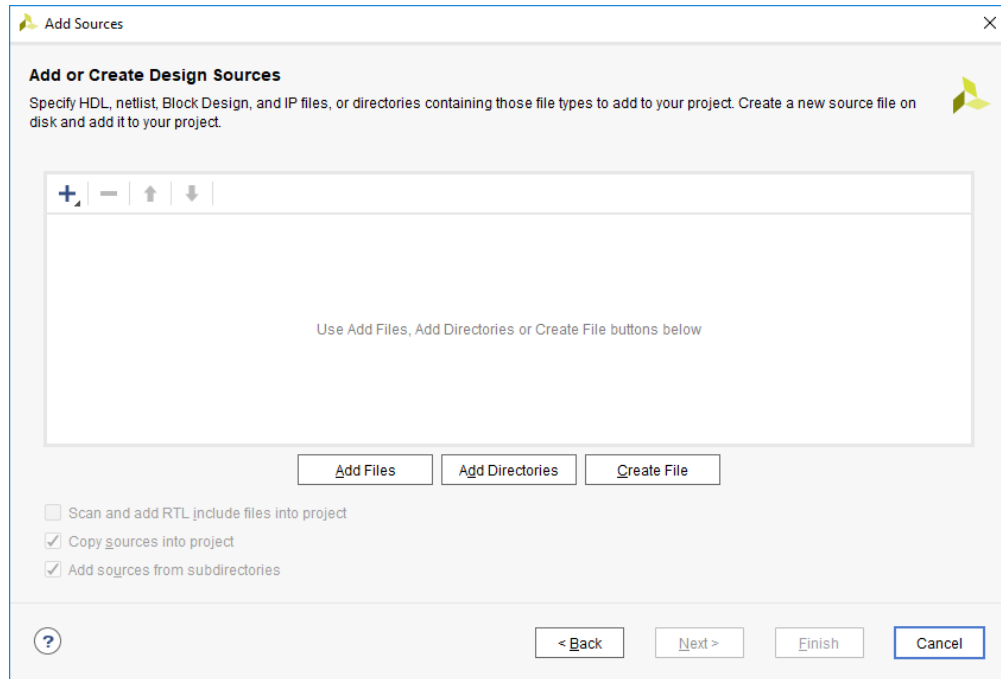


7.2

As before, at this stage, a list is provided of all of the source files that will be added or created when Finish is clicked. Instead of clicking Add Files, click **Create File**.

Tip

It is also possible to add existing source files in the same way as the the constraint file was added above.



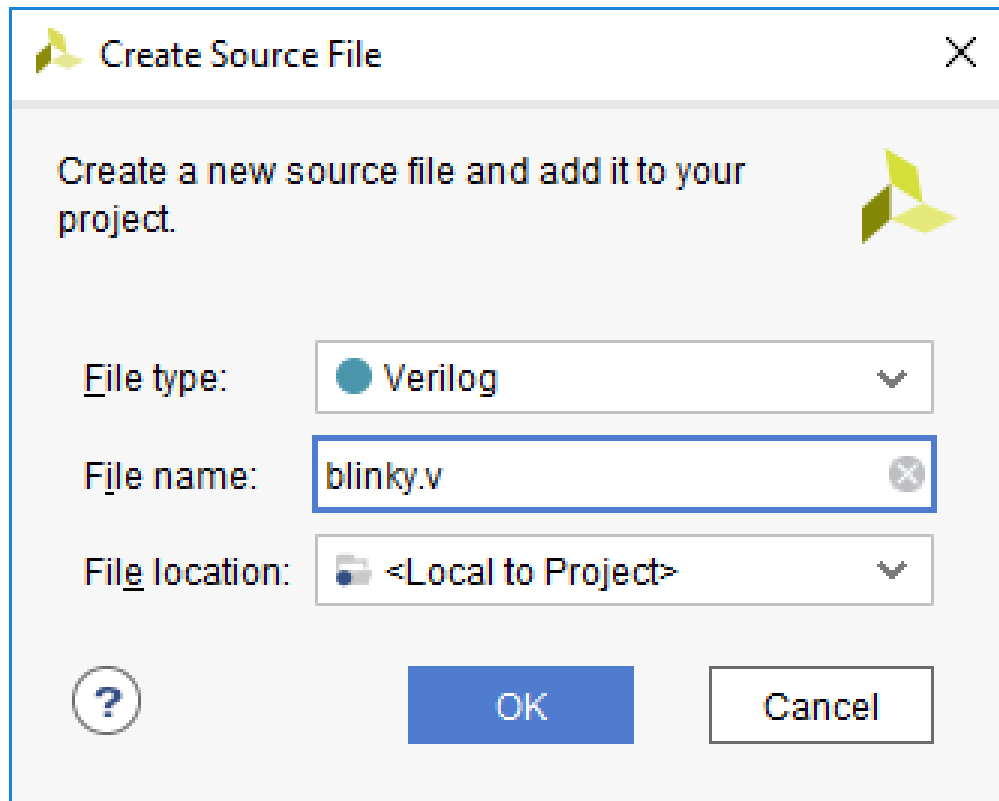
7.3

When prompted to select a *File type*, *File name*, and *File location*, make sure to pick *Verilog* and *<Local to project>* for the type and location. Give the file a name ending in '.v'.

Important

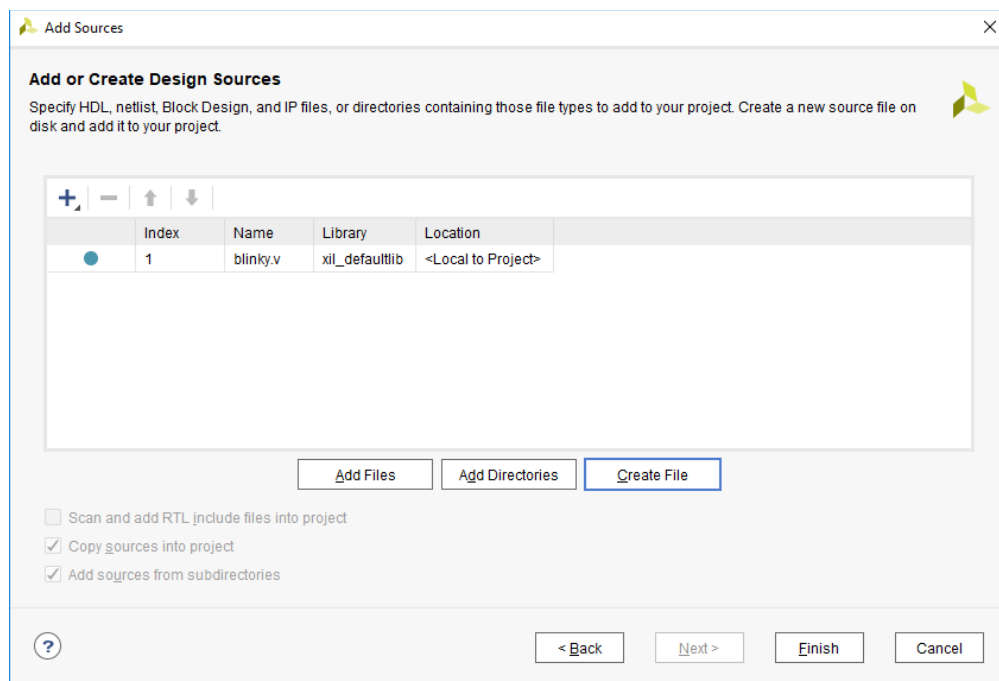
Do NOT use spaces in file names. This will cause problems with Vivado. Instead use an underscore, or a dash

Click **OK** to continue.




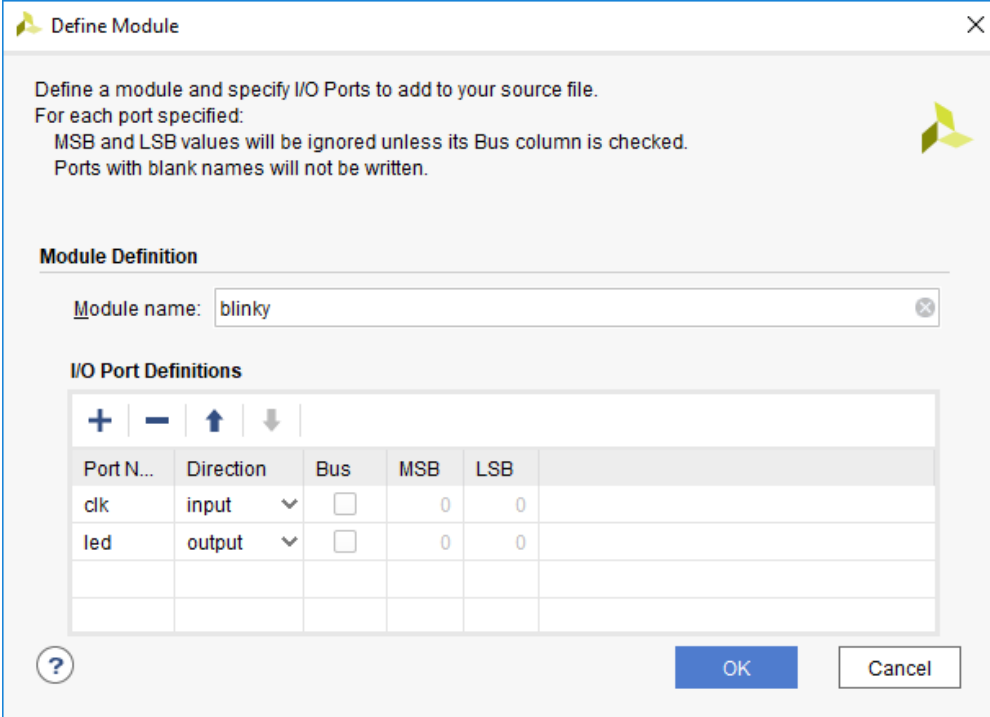
7.4

Make sure that the new Verilog source file has been added into the list of sources, then click **Finish**.



7.5

Unlike when the constraint file was added, at this point a *Define Module* dialog will pop up. The Verilog module can be renamed using the *Module name* field, but this is unnecessary in this instance. The Verilog module's clock and led ports need to be defined. Clicking the **Add** () button will add an empty slot for a port to the *I/O Port Definitions* list.



The dialog box is titled "Define Module" and contains instructions: "Define a module and specify I/O Ports to add to your source file. For each port specified: MSB and LSB values will be ignored unless its Bus column is checked. Ports with blank names will not be written." Below this is the "Module Definition" section with a text field for "Module name:" containing the value "blinky". The "I/O Port Definitions" section features a table with columns: "Port N...", "Direction", "Bus", "MSB", and "LSB". There are two rows defined: "clk" with direction "input" and "led" with direction "output". Both have "Bus" unchecked and "MSB" and "LSB" set to 0. Above the table are buttons for adding (+), removing (-), and moving up/down. At the bottom are "OK" and "Cancel" buttons.

Port N...	Direction	Bus	MSB	LSB
clk	input	<input type="checkbox"/>	0	0
led	output	<input type="checkbox"/>	0	0

There are five fields to define for each of the module's I/O ports:

- **Port Name:** This field defines the name of the port and needs to match one of the names used in the XDC file.
- **Direction:** This drop-down menu can be set to *input*, *output*, or *inout*, defining the direction that signals propagate through the port, with respect to the Verilog module. Outputs are the signals that the module will control.
- **Bus:** This box can be checked or not; when checked, the port will consist of multiple single bit signals, grouped into a single bus.
- **MSB:** This field sets the index of the most significant bit of the port, if it is a bus. This option is grayed out for single-bit ports.
- **LSB:** This field sets the index of the least significant bit of the port, if it is a bus. This option is grayed out for single-bit ports.

Tip

When defining a module which will be instantiated in another module, which is beyond the scope of this guide, be aware that the port names should not be declared in the XDC, this is only done for the 'top' module.

If the target board uses differential clocking, add two single-bit input ports with the same names as the positive and negative clock ports that were uncommented in the XDC file. Otherwise, add a single single-bit input port with the same name as the clock port that was uncommented in the XDC file.

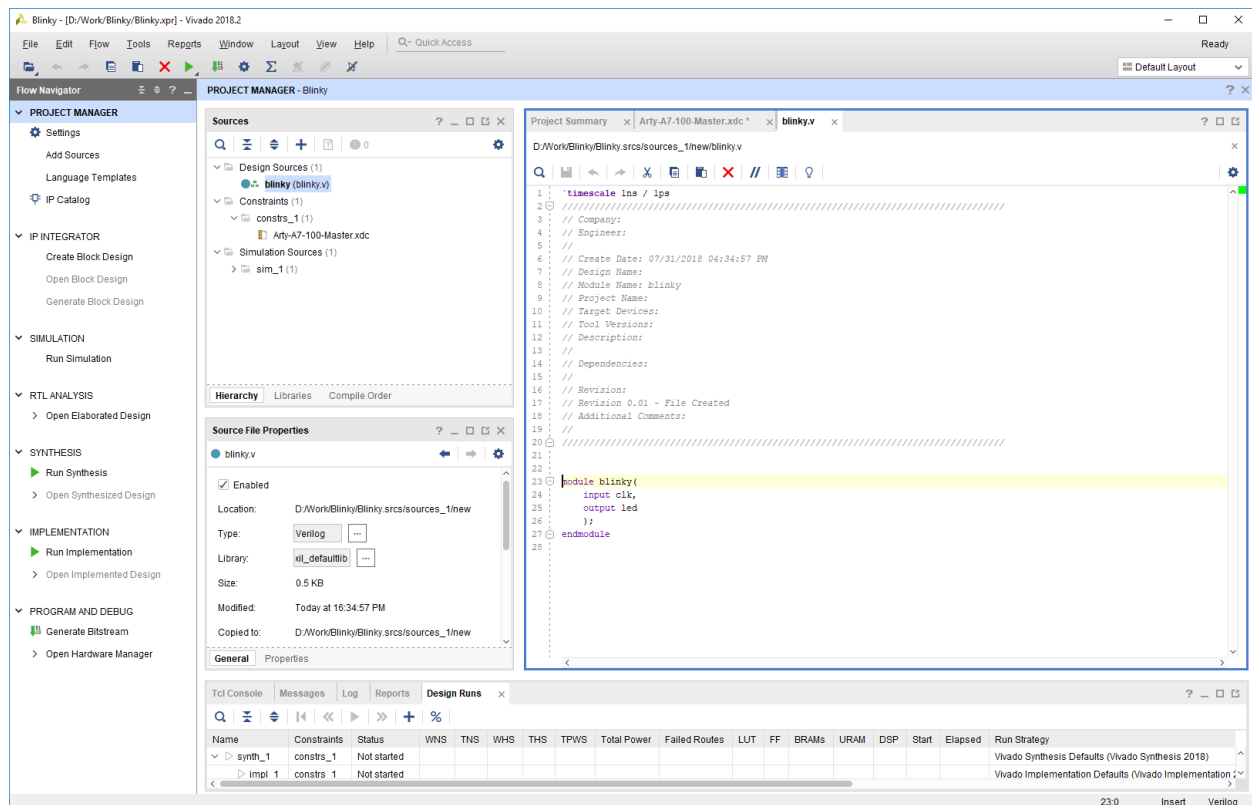
Add a single-bit output port with the same name as the LED port that was uncommented in the XDC file.

Once these two or three ports have been added, click **OK** to continue.

7.6

At this point, the new source file will be added to the *Design Sources* folder in the *Sources* pane of the *Project Manager*. Expand this folder and double click on the file to open it.

Next, some Verilog code needs to be written to define how the design will actually behave.



Between the ');' that comes after the module's port list and the 'endmodule' statement, add the following code:

```
reg [24:0] count = 0;
```

```
assign led = count[24];
```

```
always @ (posedge(clk)) count <= count + 1;
```

If the target board is differentially clocked, add the following lines of code after ');' and before the 'reg [24:0] count = 0;' line:

```
wire clk;
```

```
IBUFGDS clk_inst (
```

```
    .O(clk),
```

```
    .I(clk_p),
```


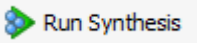



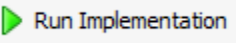
```
.IB(clk_n)  
);
```


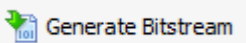
It should be noted that the rate at which the clock will blink will differ depending on the board used. System clocks on different Digilent boards run at a number of different rates, depending on the needs of the board. The system clock period in nanoseconds can be found on the *create_clock* line of the XDC file.

8. Synthesis, Implementation, and Bitstream Generation

In order to create a file that can be used to program the target board, each stage of the “compilation pipeline” needs to be run.

This starts with *Synthesis*. Synthesis turns HDL files into a transistor level description based on timing and I/O constraints. To run Synthesis click either  in the toolbar or  in the *Flow Navigator*. The output of Synthesis is then passed to Implementation.

Implementation has several steps. The steps that are always run are *Opt Design* (Optimize the design to fit on the target FPGA), *Place Design* (Lay out the design in the target FPGA fabric), and *Route Design* (Route signals through the fabric). To run Implementation click either  in the toolbar or  in the *Flow Navigator*. This output is then passed on to the Bitstream Generator.

The *Bitstream Generator* generates the final outputs needed for programming the FPGA. To run Bitstream Generation click either  in the toolbar or  in the *Flow Navigator*. With no settings changed, the generator will create a '.bit' file, which can be used to program the design onto the target FPGA system board.

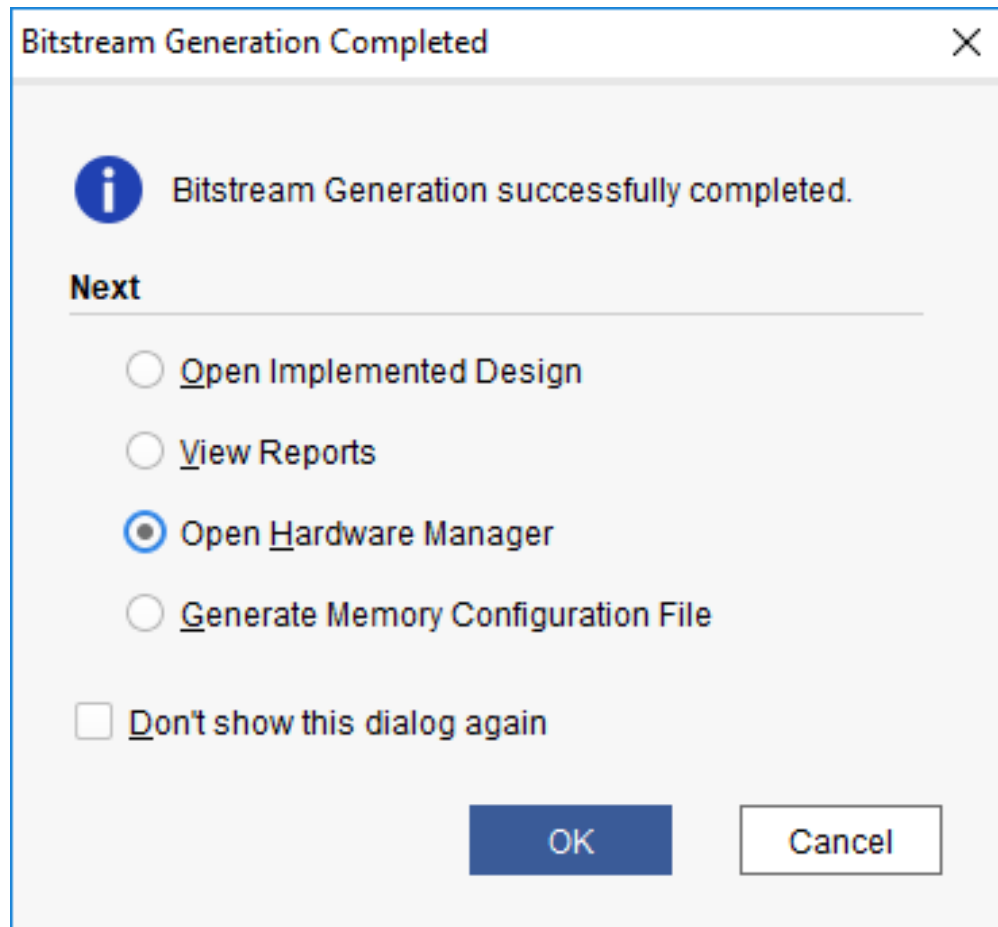
Bitstream Generation Completed Pop-Up

Once the bitstream has been generated, a pop-up will appear asking what Vivado should do next. The options in this pop-up allow the user to do several different things:

- **Open Implemented Design** takes the user to a tool where they can view how the project will be programmed into the fabric of the target FPGA chip.
- **View Reports** takes the user to a list of many different reports and statistics about how the project was laid out, including information about how fast the design can potentially be run, and how much of the FPGA will be used to run the design.

- **Open Hardware Manager** takes the user to a tool that can be used to program the generated bitstream onto a connected FPGA board.
- **Generate Memory Configuration File** lets the user create a file that can be used to program a non-volatile memory part on an FPGA system board, so that the FPGA can be automatically programmed each time that the board is powered on.

For the purposes of this guide, select *Open Hardware Manager*, then click **OK**.





9. The Hardware Manager


First, plug the target FPGA system board into the computer running Vivado using a MicroUSB cable capable of transferring data. With the board plugged in, it needs to be connected to the Vivado Hardware Server. There are two ways to do this through the Vivado Hardware Manager:

9.1(A) Open New Hardware Target

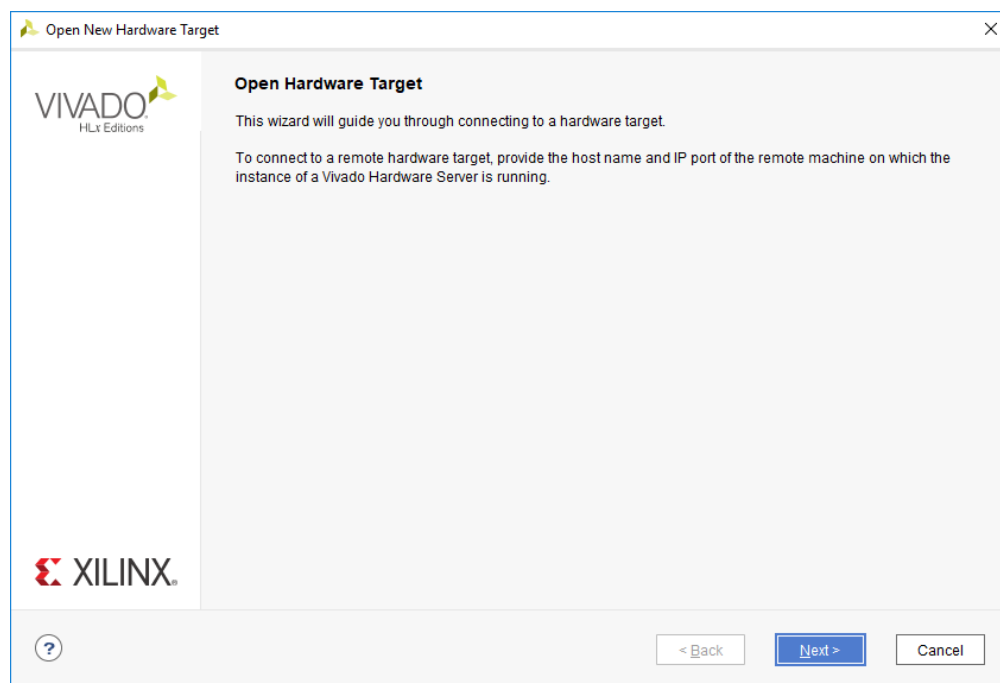
9.1(A).1

The first method is to manually open the target. This is required if the hardware is connected to a computer other than the one running Vivado (outside of the scope of this guide). To get to the *Open Hardware Target* wizard either:

- Open the *Hardware Manager* and click the [Open target](#) link in the green banner at the top of the screen.
- Or click the  **Open Target** button in the *Flow Navigator* under  **Hardware Manager**.

From the drop-down that opens from either button, click  **Open New Target...**.


Once the wizard opens, click **Next**.



9.1(A).2

The next screen asks if the hardware server is local or remote. If the board is connected to the host computer choose local, if it is connected to another machine choose remote and fill in the *Host Name* and *Port* fields.

Click **Next** to continue.

 Open New Hardware Target
 ✕

Hardware Server Settings

Select local or remote hardware server, then configure the host name and port settings. Use Local server if the target is attached to the local machine; otherwise, use Remote server.

Connect to: Local server (target is on local machine) ▼


Click Next to launch and/or connect to the hw_server (port 3121) application on the local machine.

?
< Back
Next >
Finish
Cancel

9.1(A).3

This screen gives a list of devices connected to the hardware server. If there is only one connected it should be the only device shown. If there are multiple connected devices, determine the serial number of the device to connect to and find it in the list.


Click **Next** to continue.

 Open New Hardware Target
 ✕

Select Hardware Target


Select a hardware target from the list of available targets, then set the appropriate JTAG clock (TCK) frequency. If you do not see the expected devices, decrease the frequency or select a different target.

Hardware Targets

Type	Name	JTAG Clock Frequency
 xilinx_tcf	Digilent/210319000001A	15000000 ▼

Add Xilinx Virtual Cable (XVC)

Hardware Devices (for unknown devices, specify the Instruction Register (IR) length)

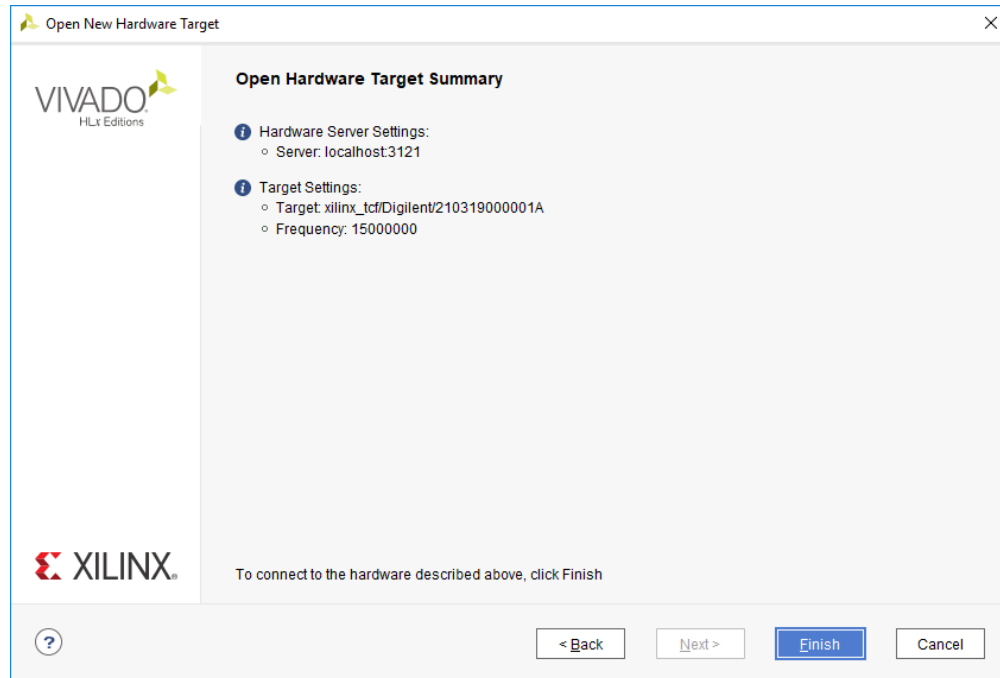
Name	ID Code	IR Length
 xc7a100t_0	13631093	6

Hardware server: localhost:3121


?
< Back
Next >
Finish
Cancel



9.1(A).4


The final screen shows a summary of the options selected in the wizard. Verify the information and click **Finish**. The board is now connected to the hardware manager.




9.1(B) Auto-Connect



The second method is to automatically open the target. To get to the  **Auto Connect** button either:

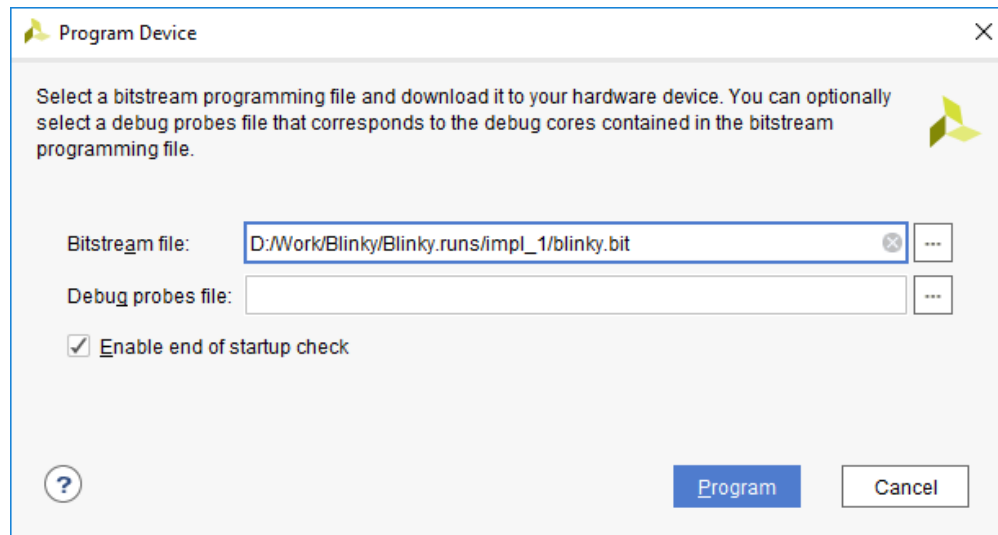
- Open the Hardware Manager and click the [Open target](#) link in the *green banner* at the top of the window
- Or click the  **Open Target** button in the *Flow Navigator* under  **Hardware Manager**.



From the drop-down that opens from either button click  **Auto Connect**. Vivado will attempt to find a hardware server running on the local machine and will connect to the device from the server.

9.2 Programming

To program the device with the bit file generated earlier, either click the [Program device](#) link in the *green banner* at the top of the window or click the  **Program Device** button in the *Flow*

Navigator under  Hardware Manager . From the drop-down that opens, select the device to program (Example:  xc7a35t_0) and the following window will open:



The *Bitstream File* field should be automatically filled in with the bit file generated earlier. If not, click the  button at the right end of the field and navigate to `<Project Directory>/<Project Name>.runs/impl_1/` and select the bit file (Example:  top.bit). Now click **Program**. This will connect to the board, clear the current configuration, and program using the new bit file.

10. Finished!

One of the LEDs on the programmed board will now be blinking! The rate at which the LED blinks depend on the speed of the clock used by the FPGA. Given that the counter created in the Verilog source file takes 2^{25} clock cycles to roll over, for a 100MHz clock, the LED will blink three times per second. One possible next step to learn some more about verilog would be to try to modify the Verilog source file so that the LED blinks only once per second. There are many good resources online to learn more about Verilog and other hardware description languages, far more than could be listed here.