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/*AVLTree.h
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 *This file taken from Joshua Brody's CS31 Class
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 */
#ifndef AVLTREE_H_
#define AVLTREE_H_
#include "BST.h"
#include "pair.h"
#include "library/queue.h"
// Forward declaration of the AVLTreeNode class
template <typename K, typename V> class AVLTreeNode;
   A AVLTree is a templated binary search tree, implementing the
   BST interface (see BST.h). This implementation is similar
   to LinkedBST except:
      (1) Each AVLTreeNode stores the height of its sub-tree
      (2) An AVLTree is balanced according to the AVL property:
           the difference between the height of two child nodes is at most 1
 */
template <typename K, typename V>
class AVLTree : public BST<K,V> {
  private:
                        // Current number of items in the tree.
   AVLTreeNode<K,V>* root; // Pointer to the root node (possibly NULL).
  public:
   AVLTree();
   ~AVLTree();
    /* All public functions declared/detailed in BST.h*/
    /* These methods are defined in AVLTree-inl.h*/
    /* sizing operations */
    int getSize();
    bool isEmpty();
    int getHeight();
    /* test operations */
   bool isBalanced();
    /* Key operations */
         getMax();
   K
         getMin();
    /* dictionary operations */
   void insert (K key, V value);
    void update (K key, V value);
   bool contains(K key);
   void remove (K key);
         find
                 (K key);
    /* traversal operations */
    Queue< Pair<K, V> >* getPreOrder();
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Queue< Pair<K, V> >* getInOrder();
 Queue < Pair < K, V > * getPostOrder();
 Queue< Pair<K, V> >* getLevelOrder();
private:
 /* Private recursive internal methods that
  * correspond to the public methods defined above.
  * These methods are defined in AVLTree-private-inl.h
    isBalancedInSubtree - Recursive function that tests whether a
                           a subtree is balanced
  * Note: all AVLTrees _should_ be balanced, so if this tree is not,
     there's something wrong with the implementation.
  * @param current : a pointer to the root of the subtree
  * @return bool: true iff the AVL subtree is indeed balanced.
 bool isBalancedInSubtree(AVLTreeNode<K,V>* current);
  /* insertInSubtree - Recursive function that inserts a new node into
                       a sub-tree pointed to by current
  * @param current : a pointer to the root of the sub-tree
  * @param key : the key for the new node being inserted
  * @param value : the value for the new node being inserted
  * @error runtime_error if the key already exists
  * @return AVLTreeNode<K, V>*: the root of the sub-tree.
 AVLTreeNode<K,V>* insertInSubtree(AVLTreeNode<K,V>* current, K key, V value);
  /* updateInSubtree - Recursive function that updates a key-value pair
                       in the tree
  ^{\star} @param current : pointer to root node of the sub-tree
  * @param key : the key being searched for
  * @param value : the new value to associate with the given key
  * @error runtime_error if key not found
 void updateInSubtree(AVLTreeNode<K,V>* current, K key, V value);
 /* removeFromSubtree - Recursive function that searches for and removes
                       the element associated with the given key in the
                       sub-tree pointed to by current
  * @param current : a pointer to the root of the sub-tree
  * @param key : the key for the node to be removed
  * @error runtime_error if the key does not exist
  * @return AVLTreeNode<K,V>*: the root of the sub-tree.
 AVLTreeNode<K,V>* removeFromSubtree (AVLTreeNode<K,V>* current, K key);
  /* containsInSubtree - Recursive function that checks if the sub-tree
                     pointed by current contains the given key
  * @param current : pointer to root node of the sub-tree
  * @param key : the key being searched for
   * @return bool : true if the key was found
 bool containsInSubtree (AVLTreeNode<K, V>* current, K key);
 /* findInSubtree - Recursive function that returns the value associated
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with the given key in the sub-tree
                    pointed by current
 *@param current : pointer to root node of the sub-tree
 *@param key : the key being searched for
 *@error runtime_error if the key is not in the sub-tree
 *@return V : the value associated with the search key
V findInSubtree(AVLTreeNode<K, V>* current, K key);
/* getMaxInSubtree - Recursive function that retrieves the maximal key
                      in the sub-tree pointed to by current
 * @param current: pointer to root node of the sub-tree
 * @return K : the maximal key in the subtree
K getMaxInSubtree(AVLTreeNode<K, V>* current);
/* getMinInSubtree - Recursive function that retrieves the minimal key
                      in the sub-tree pointed to by current
 * @param current: pointer to root node of the sub-tree
 ^{\star} @return K : the minimal key in the subtree
K getMinInSubtree(AVLTreeNode<K, V>* current);
/* build{Pre,In,Post} - Recursive helper functions for building
                         iterators for the data structure.
                         Each enqueues all key-value pairs for the
                         sub-tree pointed to by current
 * @param current : pointer to root node of the sub-tree
 * @param it : a pointer to the Queue to fill with the key-value
                                pairs based on the traversal order
 */
void buildPreOrder (AVLTreeNode<K,V>* current, Queue< Pair<K,V> >* it);
void buildInOrder (AVLTreeNode<K,V>* current, Queue< Pair<K,V> >* it);
void buildPostOrder(AVLTreeNode<K,V>* current, Queue< Pair<K,V> >* it);
/* traverseAndDelete - Recursive helper function for the destructor
                        Performs a post-order traversal of the sub-tree
                        freeing memory for all nodes in the sub-tree
                        pointed to by current
 * @param current : pointer to root node of the sub-tree to be deleted
void traverseAndDelete (AVLTreeNode<K, V>* current);
/*These methods are unique to the AVLTree relative to LinkedBST. Each
 * maintains/ensures a balanced tree according to the AVL property
/* computeHeightFromChildren - updates height for a node by checking
        child nodes
 * @param current - root of sub-tree whose height needs to be
                     updated
void computeHeightFromChildren(AVLTreeNode<K,V>* current);
/* balance - updates heights after insert/remove, detects imbalances,
             and invokes rotation to fix an imbalance
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* @param current : pointer to the root node of sub-tree to be balanced
     * @return AVLTreeNode<K,V>* pointer to root of sub-tree (current if
               no rotations are made)
     */
    AVLTreeNode<K, V>* balance(AVLTreeNode<K, V>* current);
    /* The four rotations needed to fix each of the four possible imbalances
         in an AVLTree
         (1) Right rotation for a left-left imbalance
         (2) Left rotation for a right-right imbalance
         (3) LeftRight rotation for left-right imbalance
         (4) RightLeft rotation for a right-left imbalance
     * @param current : pointer to root of sub-tree to be balanced
     * @return AVLTreeNode<K,V>* pointer to root of updated sub-tree
    AVLTreeNode<K,V>* rightRotate(AVLTreeNode<K,V>* current);
AVLTreeNode<K,V>* leftRightRotate(AVLTreeNode<K,V>* current);
    AVLTreeNode<K, V>* leftRotate(AVLTreeNode<K, V>* current);
    AVLTreeNode<K, V>* rightLeftRotate(AVLTreeNode<K, V>* current);
};
/**
 * The AVLTreeNode is a templated class that stores data for each node
 * in the AVLTree.
template <typename K, typename V>
class AVLTreeNode {
  private:
                               // The key stored in this node.
    K key;
                                // The value stored in this node.
    V value;
   V value; // The value stored in this node.

AVLTreeNode<K, V>* left; // Pointer to this node's left subtree.

AVLTreeNode<K, V>* right; // Pointer to this node's right subtree.
    int height;
    /* default constructor */
    AVLTreeNode();
    /* preferred constructor to initialize key and value to given
     * parameters; left and right are set to NULL
    AVLTreeNode(K k, V v);
    /* getHeight checks for NULL for you, returning -1*/
    int getHeight();
  /* indicates that AVLTree is a friend class so that it can directly
   * access private aspects of this class.
 friend class AVLTree<K, V>;
};
//all the public methods are defined here as well as the AVLTreeNode class
#include "AVLTree-inl.h"
//all the private methods are defined here
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#include "AVLTree-private-inl.h"
#endif // AVLTREE_H_