

STAT 432: Basics of Statistical Learning

KNN and Bias-Variance Trade-Off

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- The main goal of this lecture is to demonstrate a phenomenon called the bias-variance trade-off.
- We use *k*-nearest neighbors as the tool for this demonstration
- We also introduce two additional important concepts:
 - Tuning parameters
 - Cross-Validation for selecting tuning parameters

k -Nearest Neighbors

- Let's consider a regression model,

$$Y = f(X) + \epsilon,$$

where $E(\epsilon) = 0$ and $\text{Var}(\epsilon) = \sigma^2$.

- Suppose that from a set of training data, we are able to estimate the regression function as \hat{f} (called “*f-hat*”).
- We can then predict the value of Y at a target point x_0 by using $\hat{f}(x_0)$.
- Let's consider a very simple approach for estimating \hat{f} , called *k-nearest neighbors*

k -Nearest Neighbors

- k -Nearest Neighbor (k NN) is a nonparametric method that predicts the target point \mathbf{x} with averages of nearby observations in the training data
- For regression, the prediction at a given target point x_0 is

$$\hat{y} = \frac{1}{k} \sum_{x_i \in N_k(x_0)} y_i,$$

where $N_k(x_0)$ defines the k samples from the training data (in terms of their feature values) that are closest to x_0 .

- How to calculate the distance?
- What k should we use?

More on Distance Measures

- By default, we use Euclidean distance (ℓ_2 norm) for continuous variables

$$d^2(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|_2^2 = \sum_{i=1}^p (u_i - v_i)^2$$

Hence the neighborhood is not invariant to the scaling of the variables.

- Mahalanobis distance is scale-invariant

$$d^2(\mathbf{u}, \mathbf{v}) = (\mathbf{u} - \mathbf{v})^\top \Sigma^{-1} (\mathbf{u} - \mathbf{v}),$$

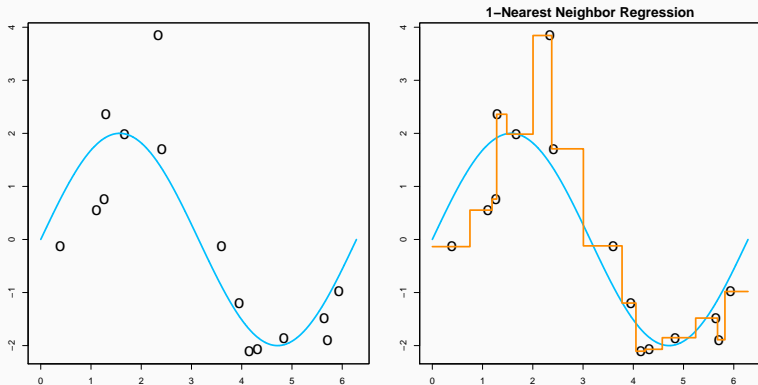
where Σ is a covariance matrix. In practice, we can use the sample covariance matrix of the training data

k -Nearest Neighbors for Regression

- The the following data is observed, with only 1 feature, uniformly from $[0, 2\pi]$. The true model (blue line) is

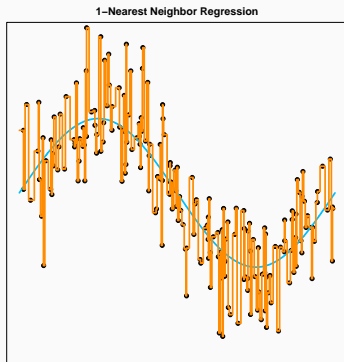
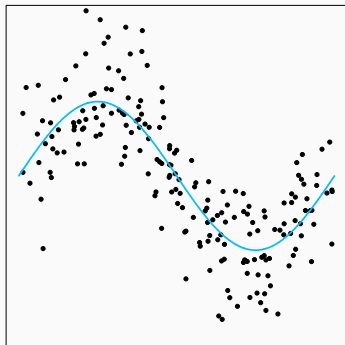
$$Y = 2 \sin(X) + \epsilon,$$

where ϵ is a standard normal error. We fit the data with 1NN.



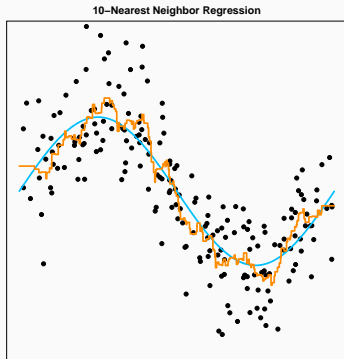
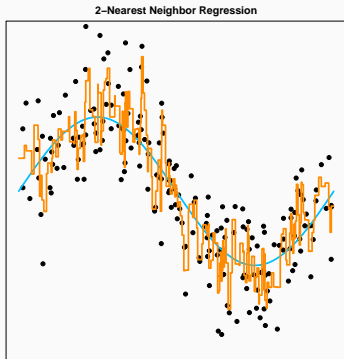
k -Nearest Neighbors for Regression

Now we simulate 200 observations, and see how the model changes over k .



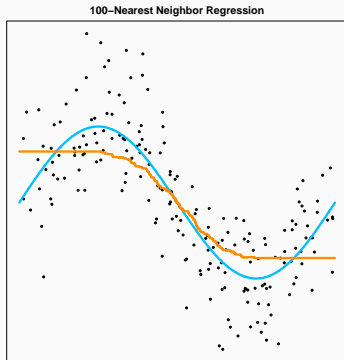
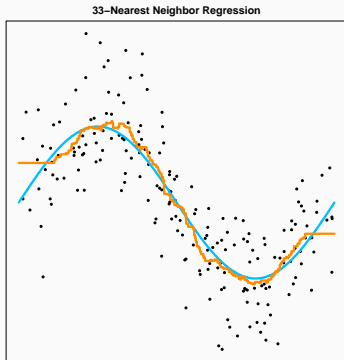
k -Nearest Neighbors for Regression

Now we simulate 200 observations, and see how the model changes over k .



k -Nearest Neighbors for Regression

The model becomes “smoother” as k increases. However, this the model seems to be “off” eventually.



Bias and Variance of a Model

- As k changes, the behaviour of the fitted model also changes.
 - When k is small, the model is “unstable”, but we are using the closest point, which approximate the target well.
 - When k is large, the model is stable, but it can be systematically biased.
- This phenomenon is called the **bias-variance trade-off**
- But we need to formally define what do we mean by bias and variance (of the estimator \hat{f})

- At any target point x_0 , the **bias of an estimator** \hat{f} is defined as

$$f(x_0) - \mathbb{E}[\hat{f}(x_0)]$$

- It can be understood this way:
 - Suppose we have many researchers, and each of them collect independently a set of 200 samples.
 - Then, each of them use KNN to give a predilection at the target point x_0 , i.e., $\hat{f}(x_0)$
 - Overall, does the mean of these predictions (averaged across all researchers) differ from the truth?

Variance

- At any target point x , the **variance of an estimator** \hat{f} is defined as

$$\mathbb{E}[(\hat{f}(x_0) - \mathbb{E}[\hat{f}(x_0)])^2]$$

- It can be understood this way:
 - Suppose we have many researchers, and each of them collect independently a set of 200 samples.
 - Then, each of them use KNN to give a predilection at the target point x , i.e., $\hat{f}(x)$
 - Overall, what is the variance of all these $\hat{f}(x)$ values (regardless of whether they are accurate or not)

Bias-Variance Trade-Off

- To demonstrate the trade-off between these two components, let's consider two extreme cases: $k = 1$ and $k = n$
- When $k = 1$, we have low bias but high variance
- When $k = n$, we have low variance but high bias
- Let's analyze these two cases.

Case 1: $k = n$

- Regardless of what x_0 we are trying to predict, the fitted model is

$$\hat{f} = \bar{y} = \frac{1}{n} \sum_i y_i,$$

since every data point will be in the neighborhood of the target point.

- What is the variance of \bar{y} ?

$$\begin{aligned}\text{Var}(\bar{y}) &= \text{Var}\left(\frac{y_1 + y_2 + \dots + y_n}{n}\right) \\ &= \frac{1}{n^2} \sum_i \text{Var}(y_i)\end{aligned}$$

- Under some conditions, $\text{Var}(y_i)$ should be finite, so the variance for this prediction is in the order of $1/n$, which goes to 0 as we collect more and more samples.

Case 1: $k = n$

- What is the bias of \bar{y} ? That depends on which point we are predicting.
- However, $E[\bar{y}]$ is just the population mean.
- As long as the function $f(x)$ is not a constant, $f(x_0)$ is usually not the population mean.
- So its fair to say that there will be a substantial bias if we use $k = n$.
- **Summary:** for $k = n$, \hat{f} has small variance and large bias

Case 2: $k = 1$

- As the number of samples increases, the closest neighbor of x_0 is getting closer and closer.
 - Suppose we have p independent variables, all follows uniform distribution.
 - As long as x_0 is not a boundary point, let's look at a neighboring cube of x_0 , with fixed width ϵ on each dimension.
 - The volume of this cube is ϵ^p
 - The probability of no sample point located within this cube is

$$\left(1 - \epsilon^p\right)^n \rightarrow 0$$

- Hence, it's fair to say that, as the sample size grows, it is almost guaranteed that there exist a point very close to x_0

Case 2: $k = 1$

- Suppose this closest point is x^*
- As long as x_0 is not a point where $f(x)$ jumps,

$$f(x^*) \rightarrow f(x_0) \quad \text{as} \quad n \rightarrow \infty.$$

- What is our 1NN estimator $\hat{f}(x_0)$? the y value corresponds to this x^* , which is simply

$$\begin{aligned} \hat{f}(x_0) &= y^* = f(x^*) + \epsilon^* \\ \implies \mathbb{E}[\hat{f}(x_0)] &= f(x^*) \end{aligned}$$

- Hence, 1NN is asymptotically unbiased — small bias

Case 2: $k = 1$

- What about the variance of 1NN?
- Since we only use 1 observation, and its almost always at a close neighbor of x_0 , the variance of 1 observation is simply the variance of the error term, i.e.

$$\text{Var}(\hat{f}(x_0)) \rightarrow \text{Var}(\epsilon) = \sigma^2$$

- This is a constant, and is much worse compared with $k = n$.
- **Summary:** for $k = 1$, \hat{f} has large variance and small bias

A General Formula

- The bias-variance trade-off can be formally understood by using this breakdown of the prediction error:

Prediction Error at x_0

$$\begin{aligned} &= \mathbb{E}[(Y - \hat{f}(x_0))^2] \\ &= \mathbb{E}[(Y - f(x_0) + f(x_0) - \mathbb{E}[\hat{f}(x_0)] + \mathbb{E}[\hat{f}(x_0)] - \hat{f}(x_0))^2] \\ &= \underbrace{\mathbb{E}[(Y - f(x_0))^2]}_{\text{Irreducible Error}} + \underbrace{(f(x_0) - \mathbb{E}[\hat{f}(x_0)])^2}_{\text{Bias}^2} + \underbrace{\mathbb{E}[(\hat{f}(x_0) - \mathbb{E}[\hat{f}(x_0)])^2]}_{\text{Variance}} \end{aligned}$$

Take-away

- $E[(Y - f(x_0))^2]$ is the **irreducible error** term that cannot be avoided, because we cannot predict ϵ
- $(f(x_0) - E[\hat{f}(x_0)])^2$ is the **squared bias** term that evaluates how the average of our estimator deviates from the truth
- $E[(\hat{f}(x_0) - E[\hat{f}(x_0)])^2]$ is the **variance** term that reflects the sensitivity of the function estimate $\hat{f}(x)$ to the training sample
- **Important:** no estimator can minimize both Bias² and Variance. We can only attempt to minimize the sum of the two.

Related Concepts

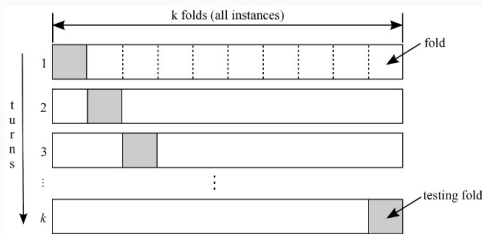
- **bias-variance trade-off** is also related to concepts such as **model complexity**, and **over- and under-fitting**.
- **Over-fitting** happens when the model performs well on the training sample, but not on the testing sample. **Under-fitting** is just the opposite.
- Model complexity can be measured in different ways. In statistics, we often use the **degrees of freedom** (number of parameters in a model)
- The degrees of freedom of a k NN model is roughly n/k
 - intuition: if neighborhoods don't overlap, there would be n/k neighborhoods, with one parameter for each

Balancing the Bias-Variance Trade-off

- Essentially, we need to choose k to minimize the sum of Bias² and Variance
- A common approach is called **cross-validation** (CV).
- The basic idea is to choose k that minimize the prediction error using testing data (since we cannot evaluate Bias² and Variance directly)
- A 10-fold CV is carried out as follows

Cross-Validation

- Randomly split the data into 10 equal sized subsamples
- Fit the model using 9 out of 10 subsamples as training data and calculate the testing error using the remaining one.
- Alternate the testing sample, and average the total of 10 experiments



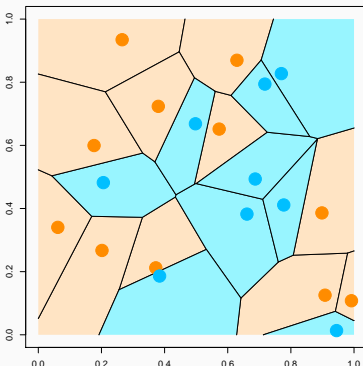
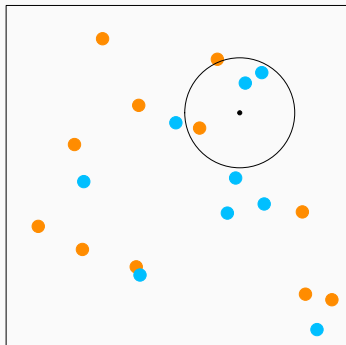
KNN Classification

Classification

- There are usually two types of classification goals:
- Hard Classification predicts the label of the outcome
 - Example: $f : \mathbf{R}^p \rightarrow \{0, 1\}$
- Soft Classification outputs the probability of observing each possible label
 - Example: $f : \mathbf{R}^p \rightarrow [0, 1]$ for the probability of observing “1” in a binary classification
- We will discuss hard classification first.

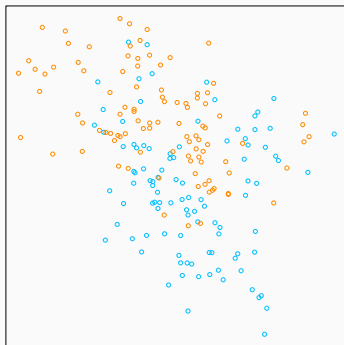
k -Nearest Neighbors in Classification

Similar to the regression case, the k -NN classification model does majority vote (the most prevalent class) within the neighborhood of a target point x . 1NN plot is a Voronoi tessellation



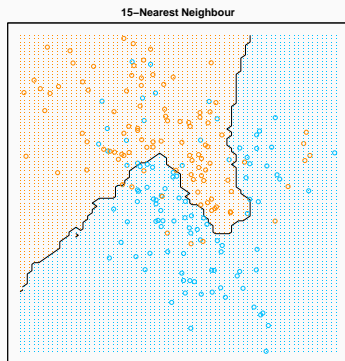
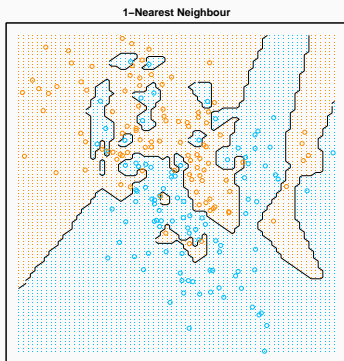
k -Nearest Neighbors in Classification

Let's look at a classification example from the HTF text book.
(BLUE = 0, ORANGE = 1)



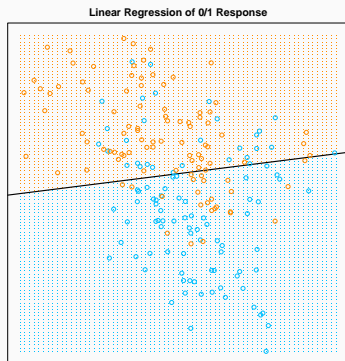
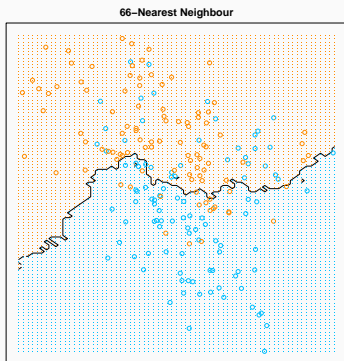
k -Nearest Neighbors in Classification

We fit k -NN classification model to the example. Of course, we would not expect 1NN to perform well...



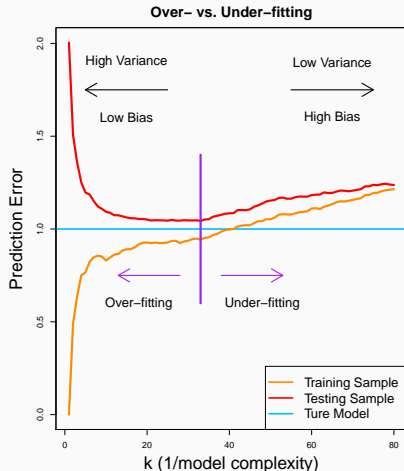
k -Nearest Neighbors in Classification

As we further increase k , the model tends to be less complex.
Compare 66NN with a linear model that uses only 3 parameters.



Model Complexity, over- and under-fitting

- Model complexity \uparrow (small k) \rightarrow Bias² \downarrow and Variance \uparrow
- Model complexity \downarrow (large k) \rightarrow Bias² \uparrow and Variance \downarrow



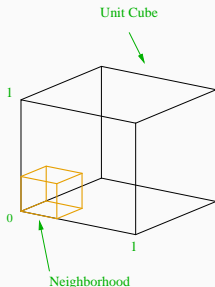
New Challenges

New Challenge

- High-dimension low sample size ($p \gg n$)
 - The resolution of the handwritten digit example is $16 \times 16 = 256$
 - Some common imaging data in medical are 1024×1024 while only a few hundred samples are available
 - Strategy games (Go, StarCraft, DOTA, LOL, etc.) may have a huge number of variables
- Curse of Dimensionality
 - For fixed n , as p increases, the data become sparse
 - As p increases, the number of possible models explodes (computation burden, variable selection necessary)

Curse of Dimensionality

- The curse of dimensionality is well illustrated by a subcubical neighborhood for uniform data in a unit cube.
- Suppose the sample points are evenly spread out on $[0, 1]^p$, and we want to capture 10% of the data by constructing a hypercube neighborhood of x . What is the edge length l of this cube? Since the volume of the cube is $l^p = 10\%$, we need $l = 0.1^{1/p}$,
- Read more in ISL Ch 2.2.2. Check [ESL Video](#).



- When $p = 1$, $l = 0.1$
- When $p = 2$, $l = 0.32$
- When $p = 10$, $l = 0.79$