

Mass properties of Robot v1.7  
Configuration: По умолчанию  
Coordinate system: -- default --

\* Includes the mass properties of one or more hidden components/bodies.

Mass (user-overridden) = 6.45 kilograms

Volume = 0.004 cubic meters

Surface area = 2.012 square meters

Center of mass: ( meters )

X = -0.005

Y = 0

Z = 0.154

Principal axes of inertia and principal moments of inertia: ( kilograms \* square meters )

taken at the center of mass.

Ix = (-0.138, 0.034, 0.99) Px = 0.049

Iy = ( 0.815, 0.572, 0.094) Py = 0.086

Iz = (-0.563, 0.819, -0.106) Pz = 0.096

Moments of inertia: ( kilograms \* square meters )

taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.089 Lxy = 0.004 Lxz = -0.006

Lyx = 0.004 Lyy = 0.093 Lyz = 0.002

Lzx = -0.006 Lzy = 0.002 Lzz = 0.05

Moments of inertia: ( kilograms \* square meters )

taken at the output coordinate system.

Ixx = 0.243 Ixy = 0.004 Ixz = 0.01

Iyx = 0.004 Iyy = 0.247 Iyz = 0.002

Izx = 0.01 Izy = 0.002 Izz = 0.05

Mass Properties have been overridden at the assembly level. Therefore,

any overrides specified at the component level are ignored in

Moment of Inertia calculations. One or more components have

user-overridden mass properties that are being ignored:

Maxon Motor<2><Default>@WheelAssembly v0.3<13><По умолчанию>@Level I v1.7<1><По умолчанию>

Maxon Motor<2><Default>@WheelAssembly v0.3<14><По умолчанию>@Level I v1.7<1><По умолчанию>

Maxon Motor<2><Default>@WheelAssembly v0.3<15><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<1><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<2><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<3><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<7><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<8><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<9><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<19><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<20><По умолчанию>@Level I v1.7<1><По умолчанию>

Proximity Sensor v153l0x<22><По умолчанию>@Level I v1.7<1><По умолчанию>

Battery Check<1><По умолчанию>@Level III v1.6<1><По умолчанию>

Crossboard 2020<1><По умолчанию>@Level III v1.6<1><По умолчанию>