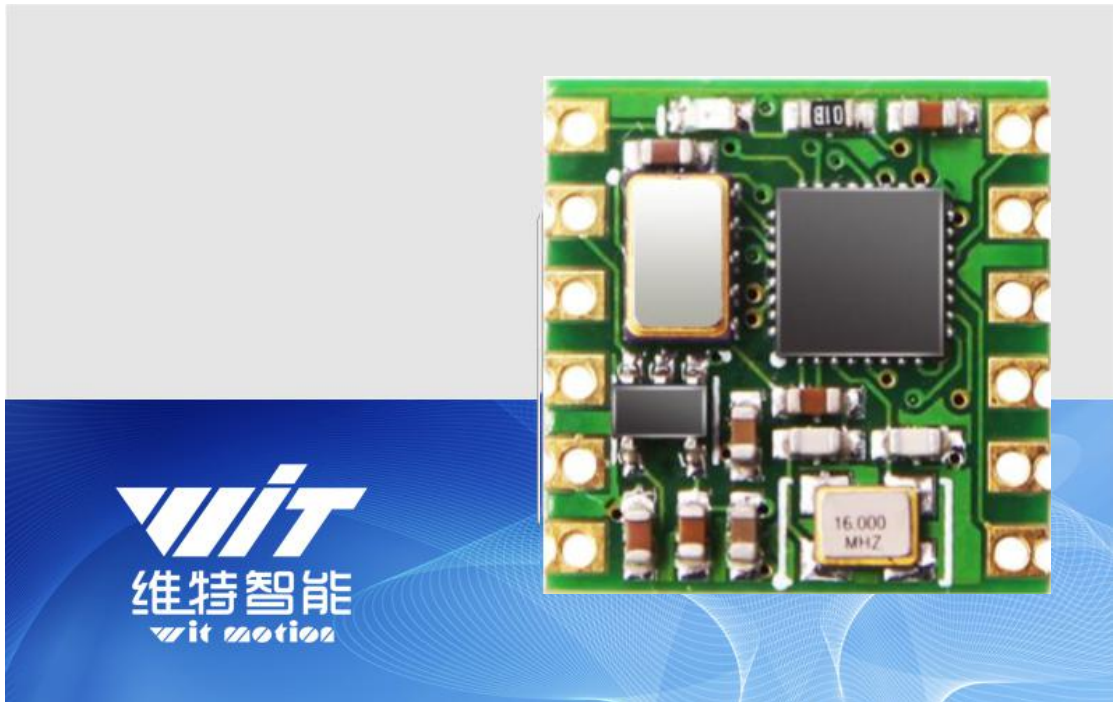




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<https://wiki.wit-motion.com/english>

HWT101 Yaw-axis Angle Sensor



Model : HWT101

Description : HWT101 Single-axis Crystal Gyroscope Sensor

Quality control system standard: ISO9001:2016

Tilt switch production standard: GB/T191SJ 20873-2016

Criterion of detection: GB/T191SJ 20873-2016

Revision date: 2019.09.09



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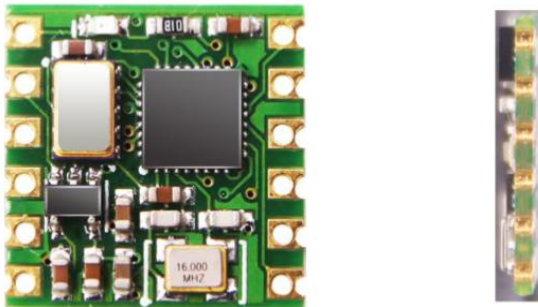
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1 Description

- The module integrates high-precision crystal gyro sensor with high-performance microprocessor and advanced dynamic solution and Kalman dynamic filtering algorithm to quickly solve the current real-time motion attitude of the module.
- Using advanced digital filtering technology, it can effectively reduce measurement noise and improve measurement accuracy.
- The module integrates an attitude solver with dynamic Kalman filter algorithm to accurately output in a dynamic environment.
- The module integrates an attitude solver with dynamic Kalman filter algorithm to accurately output in a dynamic environment.
- The current attitude of the module, the attitude measurement accuracy is static 0.05 degree, the dynamic 0.1 degree, the stability is extremely high, and the performance is even better than some professional inclinometers.
- Stamp hole gold plating PCB design, can be embedded in the user's PCB board.
- The module has its own voltage stabilization circuit, the working voltage is 3.3V~5V, and the pin level is compatible with 3.3V/5V embedded system.
- Support serial port and IIC two digital interfaces. It is convenient for users to choose the best connection method. The serial port rate is adjustable from

2400bps to 921600bps, and the IIC interface supports full speed 400K.

- Up to 500Hz data output rate. Input content can be arbitrarily selected, output rate can be adjusted from 0.1 to 500HZ
- Retain 4 expansion ports, which can be configured as analog input, digital input, digital output, PWM output, etc.
- With GPS connectivity. Accepts serial GPS data in accordance with NMEA-0183 standard to form GPS-IMU integrated navigation unit
- 4-layer PCB board process, thinner, smaller, and more reliable



2 Product parameters

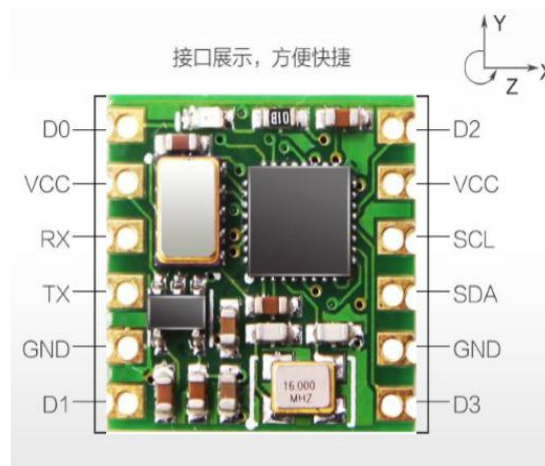
- 1) Voltage: 3.3V-5V
- 2) Current: <25 mA
- 3) Size : 15.24mmx 15.24mm X 2mm
- 4) Pad pitch: up and down 100mil (2.54mm), left and right 600mil(15.24mm).
- 5) Measurement Dimension: Angle: 1 dimension (Z axis)
- 6) Range: Angle: $\pm 180^\circ$

7) Attitude stabilization measurement: 0.01°

8) Data output frequency : 0.1Hz~500Hz.

9) Data interface: serial port (TTL level, baud rate support 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800, 921600), I2C (maximum support high speed IIC rate 400K)

3 Pin description



| Pin | Function |
|-----|-------------------------------|
| VCC | Power supply, 3.3v/5v input |
| RX | UART TTL Receiver |
| TX | UART TTL Transmitter |
| GND | GND |
| SCL | I2C clock line |
| SDA | I2C data line |
| D0 | Expansion port 0 |
| D1 | Hardware Z-axis angle to zero |
| D2 | Expansion port 2 |
| D3 | Expansion port 3 |

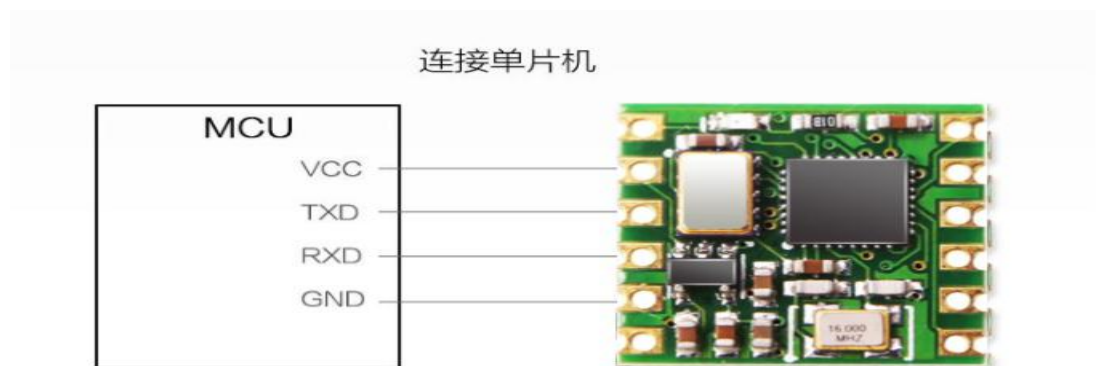
4 Axial direction

As shown in the figure above, the coordinates of the module are indicated, and the right is the X-axis, the upper is Y axis, the Z axis is perpendicular to the surface of the paper to yourself. The direction of rotation is defined by the right hand rule. that is, the thumb of the right hand is pointed to the axial direction, and the four is the direction of the bending of the right hand.

5 Connection

5.1 Serial connection

5.1.1 Connect to MCU

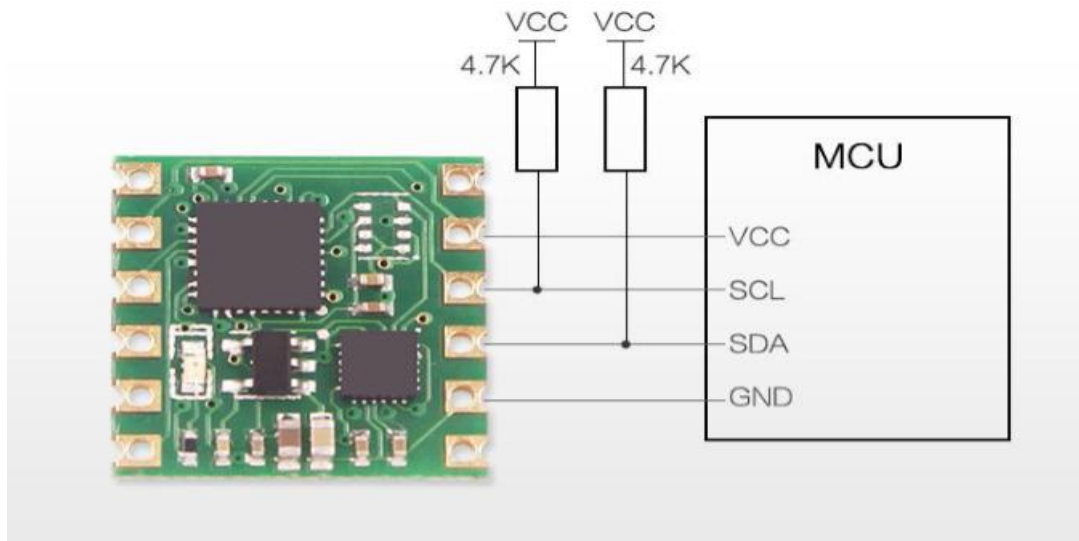


5.1.2 IIC Connection

JY-901 modules can be connected through the IIC interface to MCU, connection method as shown below. Note that, in order to connect several modules on IIC bus, module IIC bus is open-drain output, MCU need a 4.7K resistor pulled to VCC when connecting the module.

Reminder: The power supply VCC is 3.3V which should be powered by other power. The direct use of the power supply of the module may cause voltage drop, so

that the actual voltage of the module can not reach to 3.3-5V.



5.2 Connect with PC software

Note: Please download .net framework4.0 the users who cannot run the PC Software:

<http://www.microsoft.com/zh-cn/download/details.aspx?id=17718>

Hardware connection :

USB - TTL serial module: Firstly connect the module with the USB - TTL and then connect them to the computer. The ways of connecting module with USB -TTL are:
VCC TX RX GND of the module connected to +5V RX TX GND of the serial module respectively. It is noteworthy that TX and RX need to be crossed--- RX connected to TX,TX connected to RX.

Module 6 in 1 Convert:

<https://www.aliexpress.com/item/Free-shipping-usb-converter-cp2102-usb-ttl-48>

[5-232-3-3v-and-5v-output-Six-multifunctional/32607767675.html](https://www.aliexpress.com/item/5-232-3-3v-and-5v-output-Six-multifunctional/32607767675.html)



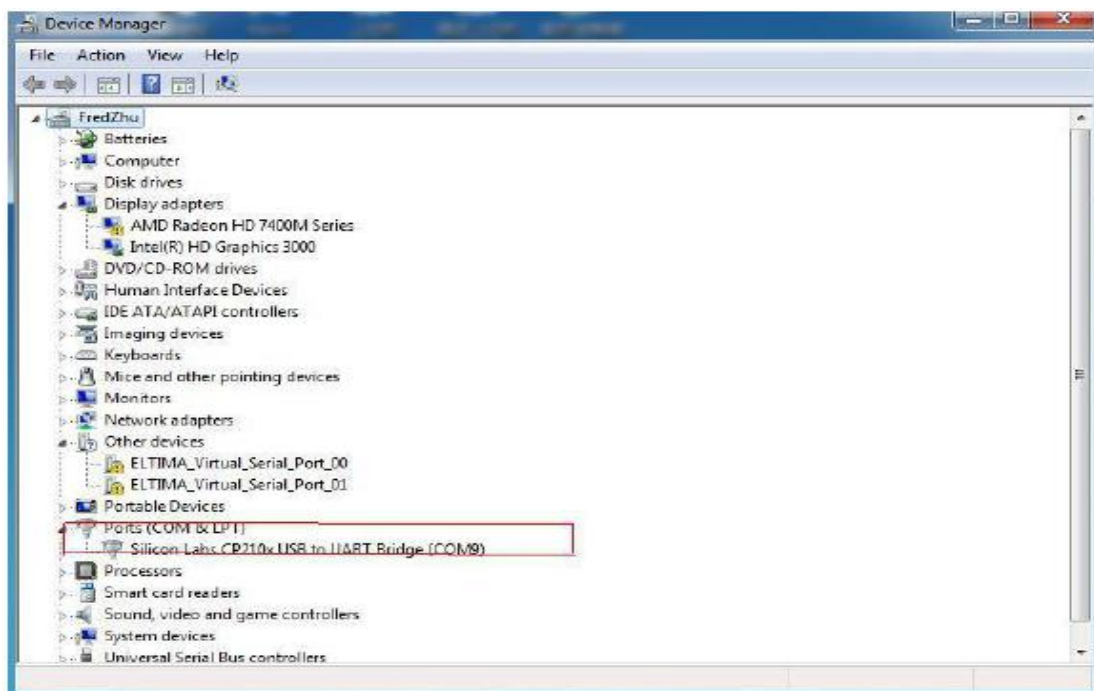
Driver installation:

First, install the driver CP2102 when we used the USB serial module, after installing the driver, then get the corresponding Com number in the device manager. Driver as followed:

https://wiki.wit-motion.com/english/doku.php?id=communication_module

Resource Summary

User Manual and Development Documents : [communication_module document center](#)
Device driver: [serial_port_debugging_assistant](#) [CH340](#) [CP2102](#)





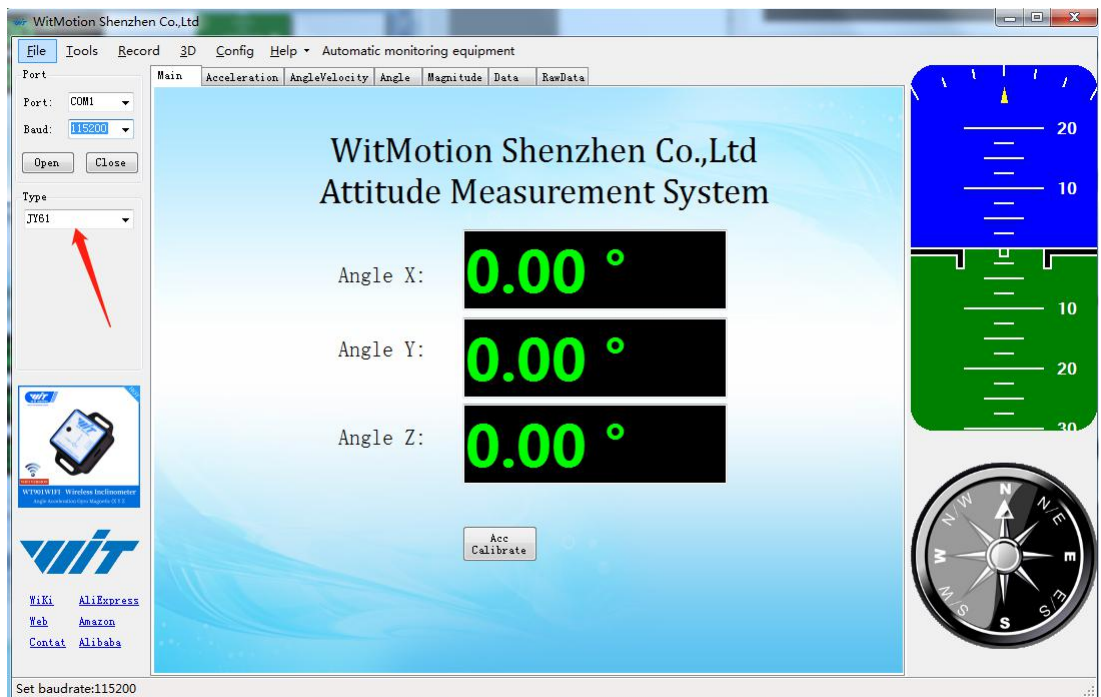
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<https://wiki.wit-motion.com/english>

Then Open the software “MiniIMU.exe” and select the Com number which you have got in the device manager before.



Click the menu “Type” , Select the model as “WT101” in the software.





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Click the menu "Baud " in the software and then select 115200, then the software will show the data.

Note: Please ignore the data output with X and Y Axis angles.

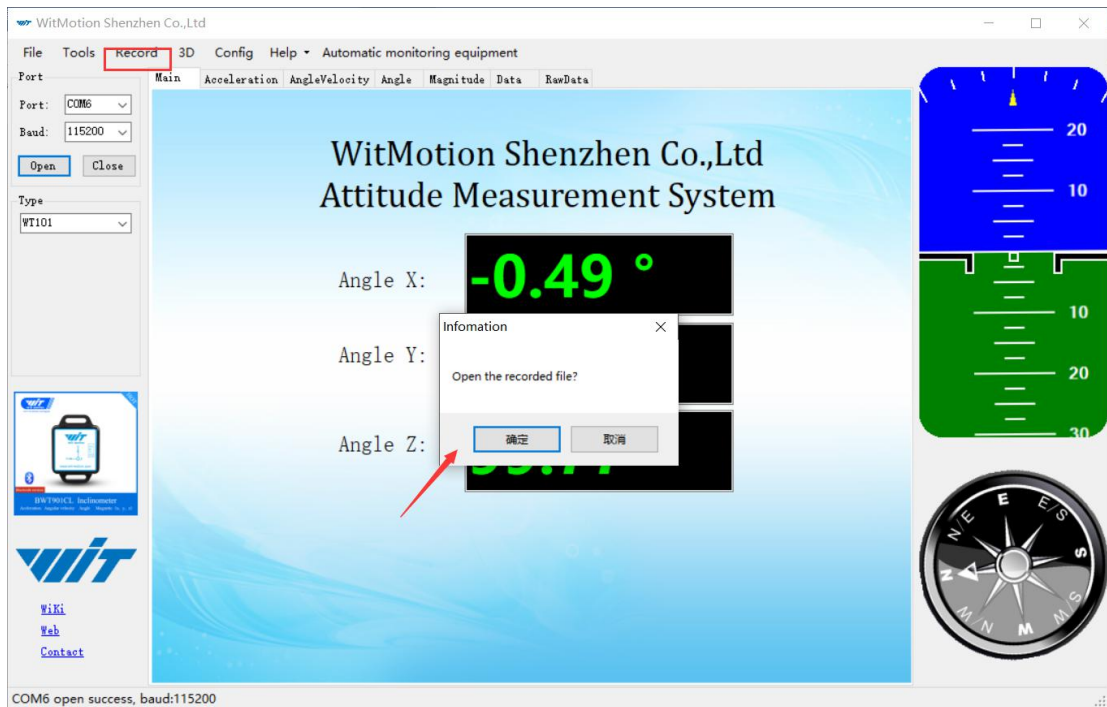


Clicking the button "Record" can save the data as a file.



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The files are saved in the directory Data.tsv: of the software.

| Time(s) | wx(deg/s) | wy(deg/s) | wz(deg/s) | AngleX(deg) | AngleY(deg) | AngleZ(deg) | T(°) |
|--------------|-----------|-----------|-----------|-------------|-------------|-------------|--------|
| 16:05:49.016 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 | |
| 16:05:49.115 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:49.228 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:49.316 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:49.415 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:49.515 | 0.0000 | 0.0000 | 0.0610 | 0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:49.626 | 0.0000 | 0.0000 | 0.1221 | 0.0110 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:49.716 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:49.816 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:49.916 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.020 | 0.0000 | 0.0000 | 0.0610 | 0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.116 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.216 | 0.0000 | 0.0000 | -0.1221 | -0.0110 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.316 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:50.416 | 0.0000 | 0.0000 | 0.1221 | 0.0110 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:50.515 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.616 | 0.0000 | 0.0000 | 0.0610 | 0.0055 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:50.715 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:50.815 | 0.0000 | 0.0000 | -0.1831 | 0.0165 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:50.916 | 0.0000 | 0.0000 | 0.0610 | 0.0055 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:51.015 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:51.116 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:51.216 | 0.0000 | 0.0000 | -0.0610 | -0.0055 | 0.1318 | 99.7668 | 0.0000 |
| 16:05:51.315 | 0.0000 | 0.0000 | 0.3052 | 0.0275 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:51.416 | 0.0000 | 0.0000 | 0.1831 | 0.0165 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:51.516 | 0.0000 | 0.0000 | -0.1831 | -0.0165 | 0.1318 | 99.7614 | 0.0000 |
| 16:05:51.616 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.1318 | 99.7614 | 0.0000 |

5.3 calibration(calibration on PC software)

5.3.1 A-axis to 0

The module should be calibrated before you use it. The module calibrate includes Z-axis to 0 , Accelerometer calibration.

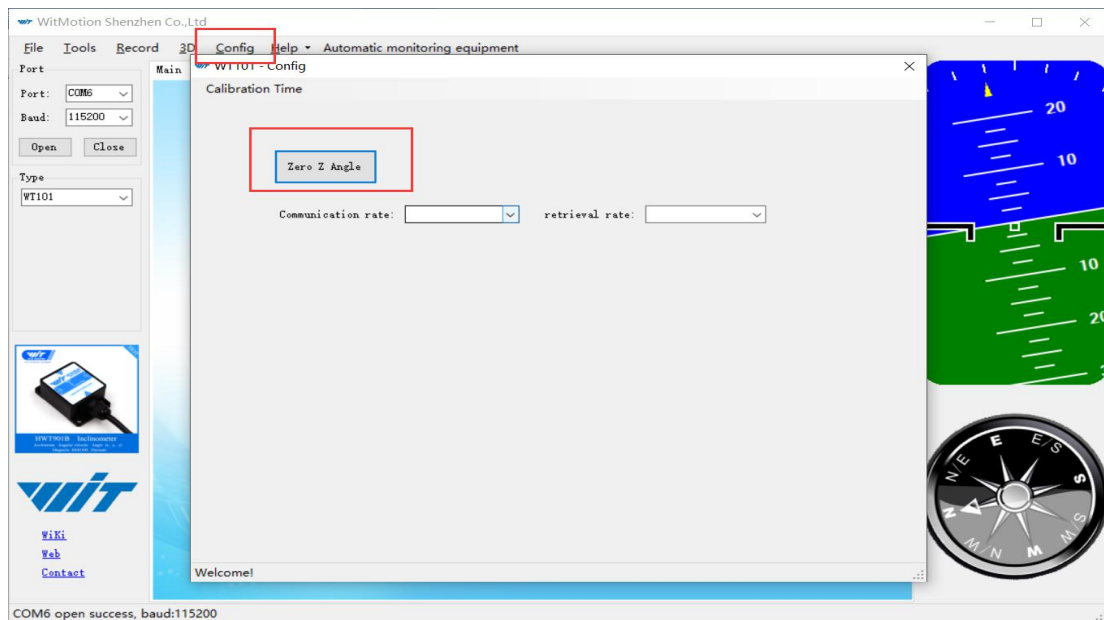
The z axis is 0 is the module z axis angle initial state is relative 0 degree angle



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When the module is used before and z - axis drift is large, the z - axis can be calibrated



Then the data will show



5.4 Dormancy and break dormancy

Dormancy: The module pauses working and enters the standby state, dormancy



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can reduce power consumption.

Break dormancy: The module enters the working state from the standby state.

How to use: The default state of the module is working state, Click "Sleep" in the "config" of the PC software to enter the standby state, click "Sleep" again the module will break the dormancy.

5.5 Set the return rate

Setting method: Click the upper computer configuration option, and select the return rate from 0.1 to 500HZ in the configuration bar.

The default return rate of the module is 10Hz, and the return rate is up to 500Hz.

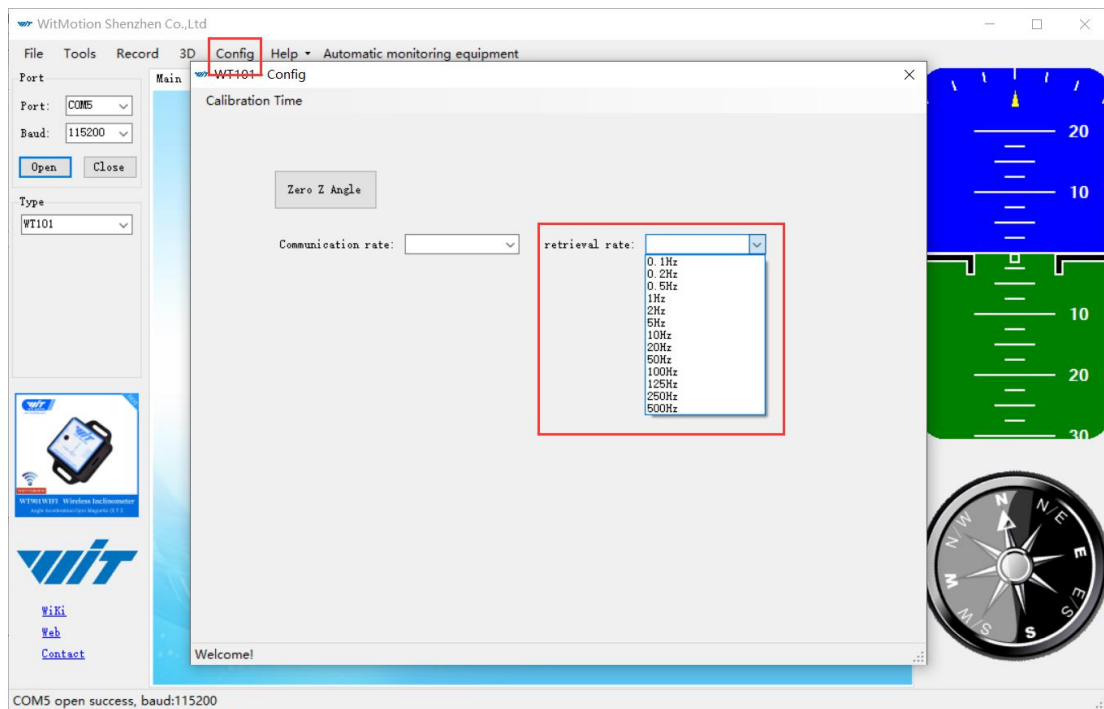
10HZ means that 1S returns 10 packets, and the default is 1 packet is 11 bytes.

Note: If there are more backhaul content and the baud rate of communication is lower, it may not be able to transmit so much data. At this time, the module will automatically down-convert and output at the maximum allowable output rate. To put it simply, if the return rate is high, the baud rate should also be set higher, generally 115200. (Note: 115200 baud for 250hz and 921600 baud for 500hz)



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5.6 Set communication baud rate

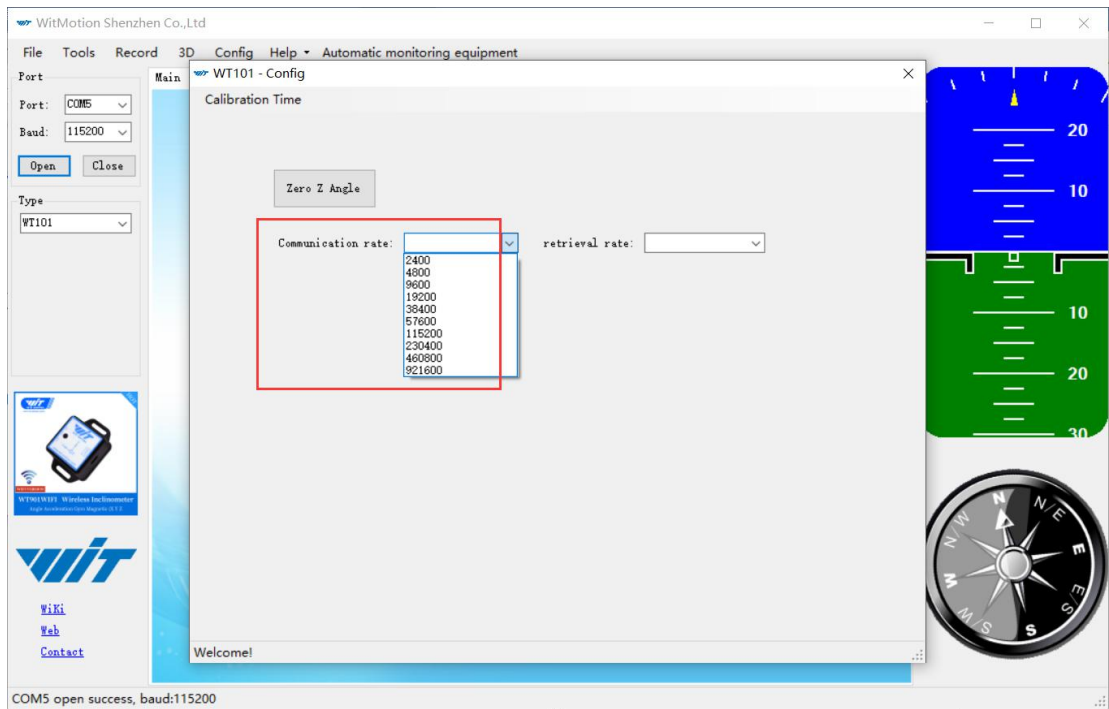
Setting method: The module supports multiple baud rates, and the default baud rate is 9600. To set the baud rate of the module, you need to select the baud rate to be changed in the communication rate drop-down box in the configuration bar (JY9Config) based on the correct connection between the software and the module.

Note: After the change, the module will not output data at the original baud rate. To re-select the baud rate that has been changed in the main interface of the host computer, the data will be output.



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6 Application area

Agricultural machinery



Internet of things



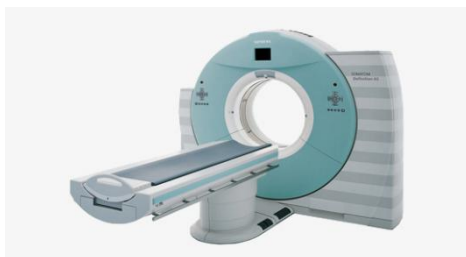
Solar energy



Power monitoring



Medical instruments



Construction machinery



Geological monitoring





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HWT101 Single-axis Crystal Gyroscope Sensor

Contact: Mr. Kyle Tsang

E-mail : support@wit-motion.com

Skype: live:kyle_8394

WhatsApp: +86 136 523 39539

Amazon in USA: www.amazon.com/witmotion

Amazon in Canada: www.amazon.ca/witmotion

Amazon in Japan: www.amazon.co.jp/witmotion

Official Direct Store: www.aliexpress.com/store/4709011

Address : Honghai building 1405 Songgang town Baoan District

Shenzhen Guangdong Province China