Epsilon NFA - NFA with ε-moves

ε transition is a state transition of NFA without reading any input.

Epsilon Non Deterministic Finite State Automata M is a 5 tuple.

 $M = (Q, \Sigma, \delta, q_o, F)$

Where

Q - is a finite set of states

 Σ – is a finite set of input alphabets

q_o- initial state. It belongs to set Q.

F - set of final states / accept states. It is subset of Q.

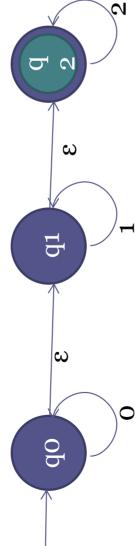
 δ – It is transition function or mapping from set \mathbf{Q} and $\mathbf{\Sigma}$ U $\{\mathbf{\epsilon}\}$ to power set of Q (2 Q).

It maps a given state p and input symbol a to zero or more next state i.e subset of Q. It has e-moves or transitions.

• Symbolically $\delta: Q \times \Sigma \cup \{\epsilon\} -> 2^Q$

e-NFA Example

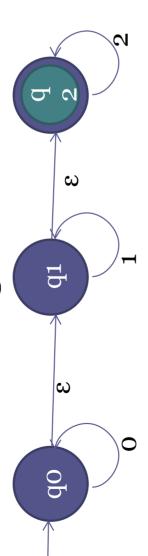
State Transition Diagram



 $L(M)=\{0^n1^m2^k|n,m,k>=0\}$

ε-closure of a state ε*(q)

State Transition Diagram



e -closure of a state q is defines as set of all states reachable from q through ε – moves including itself.

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e-closure(q0)={q0,q1,q2}
e-closure(q1)={q1,q2}
e-closure(q2)={q2}
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Equivalence of ϵ -NFA and NFA

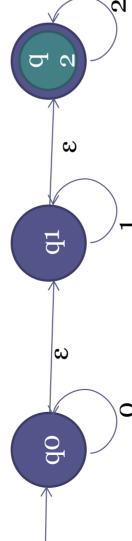
- e-NFA is equivalent to NFA
- Both e-NFA and NFA accepts regular language
- Language accepting power/computation power of e-NFA and NFA is same
- How?
- Convert e-NFA to NFA

E-NFA to NFA Conversion

- Theorem
- Let $M=(Q, \Sigma, \delta, q_o, F)$ be a NFA with ε -moves then an NFA M' without ϵ -moves can be constructed such that L(M)=L(M').
- Proof by construction –
- Given ϵ -NFA M=(Q, Σ ,6,q_o,F)
- Construct NFA without ε -moves M'=(Q, Σ ,8',q_o,F')
- F'=F, if ϵ -closure of qo does not contain a state from F
- F'=F U {qo}, if \(\epsilon\)-closure of qo contains a state from F
 - δ : δ (q,a)= ϵ -closure(δ (ϵ -closure(q),a)) for all q ϵ Q and

e-NFA to NFA

 $\varepsilon^*(q_0) = \{q_0,q_1,q_2\}, \ \varepsilon^*(q_1) = \{q_1,q_2\}, \ \varepsilon^*(q_2) = \{q_2\}$



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ob	q0 q1 q2	ф q1 Ф	{q1,q2 }
q1	q1 q2	q1 Ф	{q1,q2 }
q2	q 2	Ф	Ф

	* &	0	* &
do	q0 q1 q2	ф Ф	{q0,q1, q2}
	q1 q2	Ф	Ф
q2	q2	Ф	Ф

			:
Š	*ట	2	*ట
do	do	Ф	{ q2 }
	q1	Ф	
	q 2	q 2	
q1	q1	Ф	{ q2 }
	q 2	q 2	
q 2	q 2	{ q2 }	{ q2 }

 δ : δ (q,a)= ϵ -closure(δ (ϵ -closure(q),a))

 $\delta(q,0)$ o-moves

8.	*	0	*బ
do	q0 q1 q2	ф ф 0b	{q0,q1, q2}
q1	q1 q2	ФФ	Ф
q2	q2	Ф	Ф

 $\delta'(q,2)$ 2-moves

* &	{q2}	{d2}	{q2}
			2}
ત	ф ф q2	ф q2	{d2}
*ట	q0 q1 q2	q1 q2	q 2
%	ob	q1	d 2

	1-moves	
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* ယ	1	*ట
ob	Ф	{q1,q2
q1	q 1	<u>~</u>
q2	Ф	
q1	q1	{q1,q2
q 2	Ф	~
q 2	Ф	Ф

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ผ	5 b}	{d ₂	{q2}
	{q1.q2} {q2}	{d1,d2} {q2}	
T		6}	Ф
0	{q0,q1, q2}	Ф	Ф
<u>چ</u>	Ob	q1	(d2)