

MATH-UA.0148 Honors Linear Algebra

Lecture 29: The Cayley-Hamilton Theorem

I) Characteristic polynomial of an endomorphism

1) Characteristic polynomial of a square matrix

Definition: The characteristic polynomial of an  $n \times n$  matrix  $A$  with real coefficients is the polynomial

$$p_A(x) = \det(A - xI)$$

Proposition 1:  $\lambda$  is an eigenvalue of the  $n \times n$  matrix  $A$  with real coefficients if and only if  $\lambda$  is a root of its characteristic polynomial  $p_A$ .

We already proved this result in Lecture 21

Proposition 2: Two similar matrices  $A$  and  $B$  have the same characteristic polynomial.

Proof: Let  $A$  and  $B$  such that  $B = M^{-1}AM$

$$\begin{aligned} p_B &= p_{M^{-1}AM} = \det(M^{-1}AM - xI) \\ &= \det(M^{-1}(A - xI)M) \\ &= \det(M^{-1}) p_A \det(M) = p_A \quad \blacksquare \end{aligned}$$

Proposition 3: Let  $M$  be an  $n \times n$  matrix with real coefficients which we decompose in the following blocks:

$$M = \begin{bmatrix} A & B \\ 0 & C \end{bmatrix}$$

where  $A$  and  $C$  are square matrices.

We have  $p_M = p_A p_C$

Proof: 
$$p_M = \begin{vmatrix} A-I & B \\ 0 & C-I \end{vmatrix} = |A-I| |C-I| = p_A p_C$$

## 2) Characteristic polynomial of an endomorphism

Definition: An endomorphism of a vector space  $V$  is a linear transformation  $L: V \rightarrow V$

Examples: • Any projection  $P$  is an endomorphism, since  $P(V) \subset V$

• The linear transformation

$$L: P_3 \rightarrow P_3$$

$$p \in P_3 \mapsto q(x) = x \frac{dp}{dx} - 2p$$

which we studied last time, is an endomorphism.

• The linear transformation

$$L: \mathbb{R}^3 \rightarrow P_2$$

$$\vec{a} = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} \in \mathbb{R}^3 \mapsto p(x) = a_2 x^2 + a_1 x + a_0$$

is not an endomorphism.

Since  $L: V \rightarrow V$ , the matrix representation  $A$  of  $L$  in any basis  $B$  is a square matrix.

Now, let  $B$  be the matrix representation of  $L$  in another basis  $B'$ . There exists an invertible matrix  $M$  such that

$$B = M^{-1} A M$$

From proposition 2 of the previous section,  $A$  and  $B$  have the same characteristic polynomial, which can be viewed as the unique characteristic polynomial of the endomorphism  $L$ .

Definition: The characteristic polynomial  $p_L$  of an endomorphism  $L$  is the characteristic polynomial of the matrix representation of  $L$  in any basis of the vector space  $V$ .

$\lambda$  is an eigenvalue of the endomorphism  $L$  if and only if it is a root of the characteristic polynomial  $p_L$ .

If  $\lambda$  is an eigenvalue of the endomorphism  $L$ , then there exists a nonzero vector  $\vec{x}$  such that

$$L\vec{x} = \lambda\vec{x}$$

$$\Leftrightarrow (L - \lambda \text{Id})\vec{x} = \vec{0}_V$$

$$\Leftrightarrow \text{Ker}(L - \lambda \text{Id}) \neq \{\vec{0}_V\}$$

$$\Leftrightarrow L - \lambda \text{Id} \text{ is not injective.}$$

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## II) Polynomials of matrices

### 1) Definition

Let  $A$  be an  $n \times n$  matrix with real coefficients.  
For a given polynomial  $p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$   
in  $P_n$ , we define the matrix

$$p(A) = a_n A^n + a_{n-1} A^{n-1} + \dots + a_1 A + a_0 I$$

Proposition 1: Let  $p_1$  and  $p_2$  be two polynomials  
of  $P_n$ . Then, for any square matrix  $A$ ,

$$i) (p_1 + p_2)(A) = p_1(A) + p_2(A)$$

$$ii) (p_1 p_2)(A) = p_1(A) p_2(A)$$

Proof: Let  $p_1 = \sum_{i=0}^m a_i x^i$   $p_2 = \sum_{i=0}^m b_i x^i$

where some of the  $a_i$  or the  $b_i$  are potentially  
zero. We have,

$$\begin{aligned} (p_1 + p_2)(A) &= \sum_{i=0}^m (a_i + b_i) A^i = \sum_{i=0}^m a_i A^i + \sum_{i=0}^m b_i A^i \\ &= p_1(A) + p_2(A) \end{aligned}$$

$$\begin{aligned} (p_1 p_2)(A) &= \sum_{i=0}^m \sum_{j=0}^m a_i b_j A^{i+j} = \sum_{i=0}^m a_i A^i \sum_{j=0}^m b_j A^j \\ &= p_1(A) p_2(A) \end{aligned}$$

Observe that since any two polynomials  $p_1$  and  $p_2$  commute, the previous result also tell us that the matrices  $p_1(A)$  and  $p_2(A)$  commute.

Proposition 2: Let  $A$  be an  $n \times n$  matrix with real coefficients and  $p_1$  and  $p_2$  be two polynomials in  $P_m$ . Then the matrices  $p_1(A)$  and  $p_2(A)$  commute:  $p_1(A)p_2(A) = p_2(A)p_1(A)$ .

Example: Let  $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ ,  $p_1(x) = x^2 + x + 1$  and  $p_2(x) = x - 1$ .

$$p_1(A) = A^2 + A + I = \begin{bmatrix} 3 & 2 \\ 0 & 1 \end{bmatrix}, \quad p_2(A) = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix}$$

$$p_1(A)p_2(A) = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} = p_2(A)p_1(A)$$

## 2) Matrices as roots of polynomials

Definition: Let  $A$  be an  $n \times n$  matrix with real coefficients. We say that  $A$  is a root of the polynomial  $p \in P_m$  if  $p(A)$  is the zero matrix.

Example: Any  $2 \times 2$  matrix  $A$  with real coefficients is the root of the polynomial

$$p_A(x) = x^2 - \text{Trace}(A)x + \det(A)$$

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Indeed, let  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ ,  $A^2 = \begin{bmatrix} a^2+bc & ab+bd \\ ac+cd & cb+d^2 \end{bmatrix}$

$$A^2 - \text{Trace}(A)A + \det A I = \begin{bmatrix} a^2+bc-a^2-ad+ad-bc & ab+bd-ab-bd \\ ac+cd-ac-cd & cb+d^2-ad-d^2+ad-bc \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Proposition 1: Any  $n \times n$  matrix is the root of at least one polynomial in  $P_m$  with  $m \in \mathbb{N}^*$

Proof: The vector space of  $n \times n$  matrices with real coefficients has dimension  $n^2$ . Therefore, any set of  $n^2+1$   $n \times n$  matrices with real coefficients cannot be linearly independent. This is particularly true for  $(A^{n^2}, A^{n^2-1}, \dots, A^2, A, I)$ . There exists  $c_0, c_1, \dots, c_{n^2}$  such that

$$c_{n^2} A^{n^2} + c_{n^2-1} A^{n^2-1} + \dots + c_2 A^2 + c_1 A + c_0 I = 0$$

$A$  is the root of the polynomial

$$p(x) = c_{n^2} x^{n^2} + \dots + c_2 x^2 + c_1 x + c_0$$

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Proposition 2: Let  $A$  be an  $n \times n$  matrix with real coefficients, and suppose  $A$  is the root of the polynomial  $p \in P_n$ , with  $m \in \mathbb{N}^*$ .

Then any eigenvalue of  $A$  is a root of  $p$ .

Proof: Let  $p = a_m x^m + \dots + a_2 x^2 + a_1 x + a_0$  such that  $p(A) = 0$ . We thus have  $a_m A^m + \dots + a_2 A^2 + a_1 A + a_0 = 0$ .

For any  $\vec{x} \in \mathbb{R}^n$ , we can then write

$$(a_m A^m + \dots + a_2 A^2 + a_1 A + a_0) \vec{x} = \vec{0}$$

If  $\vec{x}$  is an eigenvector of  $A$  with corresponding eigenvalue  $\lambda$ , then

$$a_1 A \vec{x} = a_1 \lambda \vec{x}$$

$$a_2 A^2 \vec{x} = a_2 \lambda A \vec{x} = a_2 \lambda^2 \vec{x}$$

$$\vdots$$

$$a_m A^m \vec{x} = a_m \lambda^m \vec{x}$$

Thus,  $(a_m \lambda^m + \dots + a_2 \lambda^2 + a_1 \lambda + a_0) \vec{x} = \vec{0}$

And since  $\vec{x} \neq \vec{0}$ , this implies  $p(\lambda) = 0$ :  $\lambda$  is a root of  $p$ . ■

△ The converse may not be true:  $p$  can have roots which are not eigenvalues of  $A$ .

Here is an illustration:  $I$ , the identity matrix, is a root of  $p(x) = x(x-1)$ , but  $0$  is not an eigenvalue of  $I$ .

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### III The Cayley-Hamilton Theorem

#### Theorem (Cayley-Hamilton Theorem)

Any  $n \times n$  matrix  $A$  with real coefficients is a root of its characteristic polynomial:  $p_A(A) = 0$ .

Proof: We recall from lecture 25 that  $A$  is similar to a Jordan matrix  $J$ : there exists an invertible matrix  $M$  such that

$$J = M^{-1} A M$$

where  $J = \begin{bmatrix} T_1 & & \\ & \ddots & \\ 0 & & T_k \end{bmatrix}$  where  $T_i = \begin{bmatrix} \lambda_i & & \\ & \ddots & \\ 0 & & \lambda_i \end{bmatrix}$

We have  $p_A(x) = p_J(x) = (x - \lambda_1)^{n_1} (x - \lambda_2)^{n_2} \cdots (x - \lambda_k)^{n_k}$

where the  $n_i$  are the number of rows in  $T_i$ .

Now, for each  $i$ ,  $T_i - \lambda_i I$  is an  $n_i \times n_i$  matrix with zeros on the diagonal. Hence,  $(T_i - \lambda_i I)^{n_i} = 0$ .

Thus,  $(J - \lambda_i I)^{n_i} = \begin{bmatrix} (T_1 - \lambda_i I)^{n_1} & & \\ & \ddots & \\ & & (T_k - \lambda_i I)^{n_k} \end{bmatrix}$

$A$  upper triangular  
zeros on diagonal

$$A \vec{e}_i = \vec{0}$$

$\vec{e}_i = \text{span}\{\vec{e}_1, \dots, \vec{e}_i\}$

contributes to  
 $A^n \vec{e}_i = c A \vec{e}_i = \vec{0}$



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$$= \begin{bmatrix} (T_1 - \lambda_1 I)^{n_1} & & & \\ & \ddots & & \\ & & (T_{i-1} - \lambda_{i-1} I)^{n_{i-1}} & \\ & & & 0 \\ & & & & (T_{i+1} - \lambda_{i+1} I)^{n_{i+1}} \\ & & & & & \ddots \\ & & & & & & (T_2 - \lambda_2 I)^{n_2} \end{bmatrix}$$

$$\text{Thus, } (J - \lambda_1 I)^{n_1} (J - \lambda_2 I)^{n_2} \dots (J - \lambda_k I)^{n_k} = 0$$

$$\Leftrightarrow p_A(J) = 0.$$

$$\begin{aligned} \text{Now, } M^{-1} p_A(A) M &= M^{-1} (A - \lambda_1 I)^{n_1} \dots (A - \lambda_k I)^{n_k} M \\ &= (M^{-1} A M - \lambda_1 I)^{n_1} \dots (M^{-1} A M - \lambda_k I)^{n_k} \\ &= (J - \lambda_1 I)^{n_1} \dots (J - \lambda_k I)^{n_k} \\ &= 0 \end{aligned}$$

$$\text{Thus, } M^{-1} p_A(A) M = 0 \Rightarrow p_A(A) = 0 \text{ since } M \text{ is invertible.} \blacksquare$$

Examples: • Prove the Cayley-Hamilton theorem holds for

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$p(\lambda) = \det(A - \lambda I) = (1 - \lambda)(4 - \lambda) - 6 = \lambda^2 - 5\lambda - 2$$

$$A^2 = \begin{bmatrix} 7 & 10 \\ 15 & 22 \end{bmatrix} \Rightarrow A^2 - 5A - 2I = \begin{bmatrix} 7-5-2 & 10-10 \\ 15-15 & 22-20-2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

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- Use the Cayley-Hamilton Theorem to find the inverse of the matrix

$$A = \begin{bmatrix} 2 & 0 & 1 \\ -2 & 3 & 4 \\ -5 & 5 & 6 \end{bmatrix}$$

$$p(\lambda) = \begin{vmatrix} 2-\lambda & 0 & 1 \\ -2 & 3-\lambda & 4 \\ -5 & 5 & 6-\lambda \end{vmatrix} = (2-\lambda)[(3-\lambda)(6-\lambda)-20] + 5(3-\lambda) - 10$$

$$= -\lambda^3 + 11\lambda^2 - 21\lambda + 1$$

By the Cayley-Hamilton Theorem,

$$A^3 - 11A^2 + 21A - I = 0$$

$$\Rightarrow A^{-1} = A^2 - 11A + 21I$$

$$A^2 = \begin{bmatrix} -1 & 5 & 8 \\ -30 & 29 & 34 \\ -50 & 45 & 51 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -1 & 5 & 8 \\ -30 & 29 & 34 \\ -50 & 45 & 51 \end{bmatrix} - \begin{bmatrix} 22 & 0 & 11 \\ -22 & 33 & 44 \\ -55 & 55 & 66 \end{bmatrix} + \begin{bmatrix} 21 & 0 & 0 \\ 0 & 21 & 0 \\ 0 & 0 & 21 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & 5 & -3 \\ -8 & 17 & -10 \\ 5 & -10 & 6 \end{bmatrix}$$