# dog\_app

September 19, 2020

# 1 Convolutional Neural Networks

# 1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

**Note**: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

**Note:** Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

## Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog\_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human\_files and dog\_files.

## Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [4]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face\_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

#### 1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face\_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [5]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

#### 1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

**Question 1:** Use the code cell below to test the performance of the face\_detector function.

- What percentage of the first 100 images in human\_files have a detected human face?
- What percentage of the first 100 images in dog\_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human\_files\_short and dog\_files\_short.

**Answer:** (You can print out your results and/or write your percentages in this cell)

```
In [6]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        detected_count_human = 0
        detected_count_dog = 0
        for file in human_files_short:
            if face_detector(file):
                detected_count_human += 1
        for file in dog_files_short:
            if face_detector(file):
                detected_count_dog += 1
        print("{}% faces detected in human_files".format(detected_count_human))
        print("{}% faces detected in dog_files".format(detected_count_dog))
98% faces detected in human_files
17% faces detected in dog_files
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

## Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

# 1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [8]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

# 1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher\_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
In [9]: device = 'cuda' if use_cuda else 'cpu'
```

```
In [10]: from PIL import Image
         # From https://knowledge.udacity.com/questions/32899
         from PIL import ImageFile
         import torchvision.transforms as transforms
         ImageFile.LOAD_TRUNCATED_IMAGES = True
         def im_convert(tensor):
             image = tensor.to("cpu").clone().detach()
             image = image.numpy().squeeze()
             image = image.transpose(1,2,0)
             image = image * np.array((0.229, 0.224, 0.225)) + np.array((0.485, 0.456, 0.406))
             image = image.clip(0, 1)
             return image
In [11]: def VGG16_predict(img_path):
             Use pre-trained VGG-16 model to obtain index corresponding to
             predicted\ \textit{ImageNet class for image at specified path}
             Args:
                 img_path: path to an image
             Returns:
                 Index corresponding to VGG-16 model's prediction
             ## TODO: Complete the function.
             ## Load and pre-process an image from the given img_path
             ## Return the *index* of the predicted class for that image
             image = Image.open(img_path).convert('RGB')
             in_transform = transforms.Compose([
                                 transforms.RandomResizedCrop(224),
                                 transforms.ToTensor(),
                                 transforms.Normalize((0.485, 0.456, 0.406),
                                                       (0.229, 0.224, 0.225))])
             image = in_transform(image)[:3,:,:].unsqueeze(0)
             image = image.to(device)
             output = VGG16(image)
             accuracy, class_index = output.topk(1)
             return class_index.item() # predicted class index
         # VGG16_predict('/data/dog_images/train/001.Affenpinscher/Affenpinscher_00001.jpg')
```

## 1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog\_detector function below, which returns True if a dog is detected in an image (and False if not).

## 1.1.6 (IMPLEMENTATION) Assess the Dog Detector

**Question 2:** Use the code cell below to test the performance of your dog\_detector function.

- What percentage of the images in human\_files\_short have a detected dog?
- What percentage of the images in dog\_files\_short have a detected dog?

#### **Answer:**

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

```
In [14]: ### (Optional)
     ### TODO: Report the performance of another pre-trained network.
     ### Feel free to use as many code cells as needed.
```

## Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

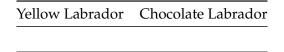
We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

Curly-Coated Retriever	American Water Spaniel

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.



We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

## 1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog\_images/train, dog\_images/valid, and dog\_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [15]: def img_show(img):
             img = img.transpose((1, 2, 0))
             img = img*np.array([0.229, 0.224, 0.225]) + np.array([0.485, 0.456, 0.406])
             img = img.clip(0,1)
             plt.imshow(img)
             plt.show()
In [16]: import os
         from torchvision import datasets
         from torch.utils.data.sampler import SubsetRandomSampler
         ### TODO: Write data loaders for training, validation, and test sets
         ## Specify appropriate transforms, and batch_sizes
         data_transform = transforms.Compose([transforms.Resize((256, 256)),
                                              transforms.CenterCrop(224),
                                              transforms.RandomRotation(10),
                                              transforms RandomHorizontalFlip(),
                                              transforms.ToTensor(),
                                              transforms.Normalize((0.485, 0.456, 0.406),
                                                       (0.229, 0.224, 0.225))])
         test_transform = transforms.Compose([transforms.Resize((256, 256)),
                                              transforms.CenterCrop(224),
                                              transforms.ToTensor(),
                                              transforms.Normalize((0.485, 0.456, 0.406),
                                                       (0.229, 0.224, 0.225))])
         train_data = datasets.ImageFolder('/data/dog_images/train', transform=data_transform)
         test_data = datasets.ImageFolder('/data/dog_images/test', transform=test_transform)
         batch_size = 20
         valid_size = 0.2
         num_train = len(train_data)
         indices = list(range(num_train))
         np.random.shuffle(indices)
         split = int(np.floor(valid_size * num_train))
         train_idx, valid_idx = indices[split:], indices[:split]
         train_sampler = SubsetRandomSampler(train_idx)
         valid_sampler = SubsetRandomSampler(valid_idx)
         train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size, sampler=t
         valid_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size, sampler=w
         test_loader = torch.utils.data.DataLoader(test_data, batch_size=batch_size)
         loaders_scratch = {'train': train_loader, 'valid': valid_loader, 'test': test_loader}
         # images, label = next(iter(train_loader))
```

```
# img = images.numpy()[0]
# img_show(img)
# print(label[0].item())
```

**Question 3:** Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

#### Answer:

I used transforms. Resize for resizing images. Following VGG, I set image size as 224. I decided to use RandomRotation, RandomHorizontalFlip and RandomVerticalFlip to reduce the risk of overfitting.

#### 1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
In [17]: import torch.nn as nn
         import torch.nn.functional as F
         # define the CNN architecture
         class Net(nn.Module):
             ### TODO: choose an architecture, and complete the class
             def __init__(self):
                 super(Net, self).__init__()
                 ## Define layers of a CNN
                 self.conv1 = nn.Conv2d(3, 16, 3, padding=1, stride=1)
                 self.conv2 = nn.Conv2d(16, 32, 3, padding=1, stride=1)
                 self.pool = nn.MaxPool2d(2, 2)
                 \# (WF+2P)/S+1
                 self.fc1 = nn.Linear(56*56*32, 160) # Number of breed
                 self.fc2 = nn.Linear(160, 133)
                 self.dropout = nn.Dropout(0.3)
                 self.batch_norm = nn.BatchNorm1d(160)
             def forward(self, x):
                 ## Define forward behavior
                 x = self.pool(F.relu(self.conv1(x)))
                 x = self.pool(F.relu(self.conv2(x)))
                 \# (WF+2P)/S+1
                 x = self.dropout(F.relu(self.batch_norm(self.fc1(x.view(-1, 56*56*32)))))
                 x = self.fc2(x)
                 return x
         #-#-# You so NOT have to modify the code below this line. #-#-#
         # instantiate the CNN
```

**Question 4:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

## **Answer:**

First, I created 3 convolutional layer and 3 FC layer.

Although I tried to change some parameters, it didn't decrease loss at all.

Then I found this post and got a clue. https://knowledge.udacity.com/questions/106988

I reduced number of layers of my network. Tried with some learning rate and I decided to set it 0.001. Reduced kernel layer and Increased dropout rate to avoid overfitting. But I couldn't reduce validation loss enough. Then, I added batch normarization. Finally I works.

## 1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_scratch, and the optimizer as optimizer\_scratch below.

#### 1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_scratch.pt'.

```
"""returns trained model"""
# initialize tracker for minimum validation loss
valid_loss_min = np.Inf
for epoch in range(1, n_epochs+1):
    # initialize variables to monitor training and validation loss
    train_loss = 0.0
    valid_loss = 0.0
    ###################
    # train the model #
    ###################
    model.train()
    for batch_idx, (data, target) in enumerate(loaders['train']):
        # move to GPU
        if use cuda:
            data, target = data.cuda(), target.cuda()
        ## find the loss and update the model parameters accordingly
        ## record the average training loss, using something like
        optimizer.zero_grad()
        output = model(data)
        loss = criterion(output, target)
        if batch_idx\%20 == 0:
            print("")
        train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
        sys.stdout.write("\rBatch: {} loss: {}".format(batch_idx, train_loss))
        sys.stdout.flush()
        loss.backward()
        optimizer.step()
    ########################
    # validate the model #
    ########################
    model.eval()
    for batch_idx, (data, target) in enumerate(loaders['valid']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
        ## update the average validation loss
        output = model(data)
        loss = criterion(output, target)
        valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss)
    # print training/validation statistics
    print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
        epoch,
```

```
train_loss,
                     valid_loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss < valid_loss_min:</pre>
                     torch.save(model.state_dict(), save_path)
                     print("valid_loss decreased {} -> {}".format(valid_loss_min, valid_loss))
                     print("saving the model...")
                     valid_loss_min = valid_loss
             # return trained model
             return model
In [79]: # train the model
         model_scratch = train(25, loaders_scratch, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, 'model_scratch.pt')
Batch: 19 loss: 3.3440642356872565
Batch: 31 loss: 3.3261678218841553
                                                  Traceback (most recent call last)
        KeyboardInterrupt
        <ipython-input-79-7dafa179598a> in <module>()
          1 # train the model
          2 model_scratch = train(25, loaders_scratch, model_scratch, optimizer_scratch,
                                  criterion_scratch, use_cuda, 'model_scratch.pt')
    ---> 3
        <ipython-input-78-a8a93fabfc3d> in train(n_epochs, loaders, model, optimizer, criterion,
         15
                    ####################
         16
                    model.train()
    ---> 17
                    for batch_idx, (data, target) in enumerate(loaders['train']):
         18
                        # move to GPU
         19
                        if use_cuda:
        /opt/conda/lib/python3.6/site-packages/torch/utils/data/dataloader.py in __next__(self)
                    if self.num_workers == 0: # same-process loading
        262
                        indices = next(self.sample_iter) # may raise StopIteration
        263
    --> 264
                        batch = self.collate_fn([self.dataset[i] for i in indices])
                        if self.pin_memory:
        265
        266
                            batch = pin_memory_batch(batch)
```

```
/opt/conda/lib/python3.6/site-packages/torch/utils/data/dataloader.py in <listcomp>(.0)
                if self.num_workers == 0: # same-process loading
   262
   263
                    indices = next(self.sample_iter) # may raise StopIteration
                    batch = self.collate_fn([self.dataset[i] for i in indices])
--> 264
                    if self.pin_memory:
    265
   266
                        batch = pin_memory_batch(batch)
   /opt/conda/lib/python3.6/site-packages/torchvision-0.2.1-py3.6.egg/torchvision/datasets/
    99
   100
                path, target = self.samples[index]
--> 101
                sample = self.loader(path)
                if self.transform is not None:
    102
   103
                    sample = self.transform(sample)
   /opt/conda/lib/python3.6/site-packages/torchvision-0.2.1-py3.6.egg/torchvision/datasets/
    145
                return accimage_loader(path)
   146
            else:
--> 147
                return pil_loader(path)
   148
   149
    /opt/conda/lib/python3.6/site-packages/torchvision-0.2.1-py3.6.egg/torchvision/datasets/
            with open(path, 'rb') as f:
   128
                img = Image.open(f)
   129
--> 130
                return img.convert('RGB')
   131
   132
    /opt/conda/lib/python3.6/site-packages/PIL/Image.py in convert(self, mode, matrix, dithe
   890
   891
--> 892
                self.load()
   893
                if not mode and self.mode == "P":
   894
   /opt/conda/lib/python3.6/site-packages/PIL/ImageFile.py in load(self)
   233
   234
                                    b = b + s
--> 235
                                    n, err_code = decoder.decode(b)
    236
                                    if n < 0:
    237
                                         break
```

## KeyboardInterrupt:

## 1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [54]: def test(loaders, model, criterion, use_cuda):
             # monitor test loss and accuracy
             test_loss = 0.
             correct = 0.
             total = 0.
             model.eval()
             for batch_idx, (data, target) in enumerate(loaders['test']):
                 # move to GPU
                 if use_cuda:
                     data, target = data.cuda(), target.cuda()
                 # forward pass: compute predicted outputs by passing inputs to the model
                 output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
             print('Test Loss: {:.6f}\n'.format(test_loss))
             print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                 100. * correct / total, correct, total))
         # call test function
         test(loaders_scratch, model_scratch, criterion_scratch, use_cuda)
Test Loss: 3.854539
Test Accuracy: 11% (92/836)
```

## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

# 1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, you are welcome to use the same data loaders from the previous step, when you created a CNN from scratch.

```
In [24]: ## TODO: Specify data loaders
         loaders_transfer = {'train': train_loader, 'valid': valid_loader, 'test': test_loader}
```

#### 1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model\_transfer.

```
In [48]: import torchvision.models as models
         import torch.nn as nn
         ## TODO: Specify model architecture
         model_transfer = models.vgg11(pretrained=True)
         # print(model_transfer)
         for param in model_transfer.features.parameters():
             param.requires_grad = False
         model_transfer.classifier = nn.Sequential(nn.Linear(25088, 200),
                                                    nn.BatchNorm1d(200),
                                                    nn.ReLU(),
                                                    nn.Dropout(0.5),
                                                    nn.Linear(200, 133))
         # print(model_transfer)
         # model_transfer = models.resnet18()
         # for param in model_transfer.parameters():
              param.requires_grad = False
         \# model_transfer.fc = nn.Sequential(nn.Linear(512, 133))
         if use_cuda:
             model_transfer = model_transfer.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg11-bbd30ac9.pth" to /root/.torch/models/vgg 100%|| 531456000/531456000 [00:06<00:00, 87034551.49it/s]

**Question 5:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

#### **Answer:**

I chose VGG11 as a CNN architecture as I thought it is light enough to detect dog's breed. I created a classifier that consists of 2 FC layer with batch normalization and dropout.

# 1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_transfer, and the optimizer as optimizer\_transfer below.

### 1.1.15 (IMPLEMENTATION) Train and Validate the Model

Batch: 79 loss: 1.8027678728103638 Batch: 99 loss: 1.7892137765884456 Batch: 119 loss: 1.7798607349395752 Batch: 139 loss: 1.7610698938369757

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_transfer.pt'.

```
In [50]: # train the model
         n_{epochs} = 25
         model_transfer = train(n_epochs, loaders_transfer, model_transfer, optimizer_transfer,
Batch: 19 loss: 4.869855880737305
Batch: 39 loss: 4.7691631317138675
Batch: 59 loss: 4.6484236717224125
Batch: 79 loss: 4.4679303169250495
Batch: 99 loss: 4.276965141296387
Batch: 119 loss: 4.0997052192687995
Batch: 139 loss: 3.9547371864318848
Batch: 159 loss: 3.8148279190063477
Batch: 179 loss: 3.6835761070251465
Batch: 199 loss: 3.5776028633117676
Batch: 219 loss: 3.4702033996582037
Batch: 239 loss: 3.3792843818664553
Batch: 259 loss: 3.2916359901428223
Batch: 267 loss: 3.2581989765167236Epoch: 1
                                                     Training Loss: 3.258199
                                                                                     Validation I
valid_loss decreased inf -> 1.596474289894104
saving the model...
Batch: 19 loss: 1.8296840190887451
Batch: 39 loss: 1.8629436492919922
Batch: 59 loss: 1.8248488903045654
```

```
Batch: 159 loss: 1.7408064603805542
Batch: 179 loss: 1.7235656976699835
Batch: 199 loss: 1.7146859169006348
Batch: 219 loss: 1.7116057872772217
Batch: 239 loss: 1.6965441703796387
Batch: 259 loss: 1.6869935989379883
Batch: 267 loss: 1.6932039260864258Epoch: 2
                                             Training Loss: 1.693204
                                                                                     Validation I
valid_loss decreased 1.596474289894104 -> 1.181237816810608
saving the model...
Batch: 18 loss: 1.2877017259597778
        KeyboardInterrupt
                                                  Traceback (most recent call last)
        <ipython-input-50-3e2bdaf5671d> in <module>()
          1 # train the model
          2 \text{ n\_epochs} = 25
    ----> 3 model_transfer = train(n_epochs, loaders_transfer, model_transfer, optimizer_transfe
          5 # load the model that got the best validation accuracy (uncomment the line below)
        <ipython-input-19-a8a93fabfc3d> in train(n_epochs, loaders, model, optimizer, criterion,
                            print("")
         28
         29
                        train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
    ---> 30
                        sys.stdout.write("\rBatch: {} loss: {}".format(batch_idx, train_loss))
                        sys.stdout.flush()
         31
                        loss.backward()
         32
        /opt/conda/lib/python3.6/site-packages/torch/tensor.py in __format__(self, format_spec)
                def __format__(self, format_spec):
        326
        327
                    if self.dim() == 0:
    --> 328
                        return self.item().__format__(format_spec)
        329
                    return object.__format__(self, format_spec)
        330
        KeyboardInterrupt:
In [52]: # load the model that got the best validation accuracy (uncomment the line below)
```

model\_transfer.load\_state\_dict(torch.load('model\_transfer.pt'))

#### 1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [55]: test(loaders_transfer, model_transfer, criterion_transfer, use_cuda)
Test Loss: 1.141974
Test Accuracy: 64% (536/836)
```

### 1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

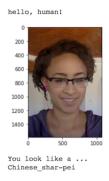
```
In [103]: ### TODO: Write a function that takes a path to an image as input
          ### and returns the dog breed that is predicted by the model.
          # list of class names by index, i.e. a name can be accessed like class_names[0]
          class_names = [item[4:].replace("_", " ") for item in train_data.classes]
          # print(class_names)
          def predict_breed_transfer(img_path):
              # load the image and return the predicted breed
              image = Image.open(img_path).convert('RGB')
              in_transform = transforms.Compose([transforms.Resize((256, 256)),
                                  transforms.CenterCrop(224),
                                  transforms.ToTensor(),
                                  transforms.Normalize((0.485, 0.456, 0.406),
                                                        (0.229, 0.224, 0.225))])
              image = in_transform(image)[:3,:,:].unsqueeze(0)
              image = image.to(device)
              output = model_transfer(image)
              _, class_index = output.topk(1)
              class_index.cpu()
              return class_names[class_index]
```

## Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face\_detector and human\_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!



Sample Human Output

# 1.1.18 (IMPLEMENTATION) Write your Algorithm

```
In [110]: ### TODO: Write your algorithm.
    ### Feel free to use as many code cells as needed.

def run_app(img_path):
    ## handle cases for a human face, dog, and neither
    image = Image.open(img_path).convert('RGB')
    im_list = np.asarray(image)
    plt.imshow(im_list)
    title = """

    if face_detector(img_path):
        title = "This is human!"
    if dog_detector(img_path):
        title = "This is dog!"

    dogname = predict_breed_transfer(img_path)
    plt.title(title + "\nYou look like a {}".format(dogname))
    plt.show()
```

## Step 6: Test Your Algorithm

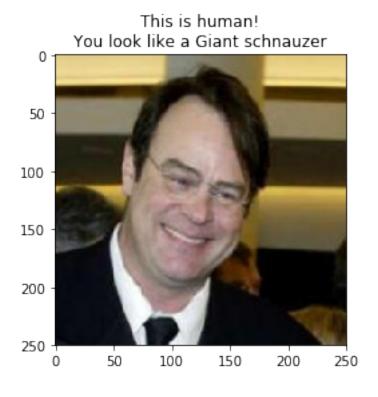
In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

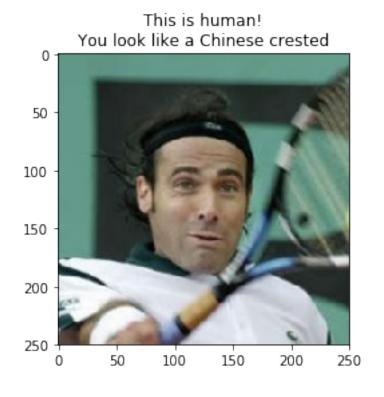
## 1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

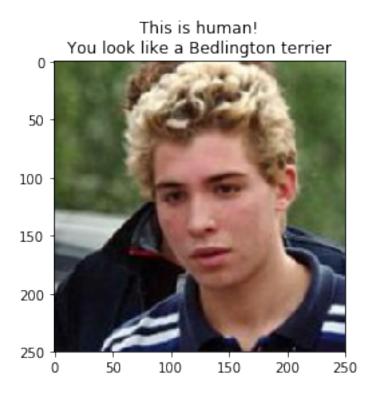
Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

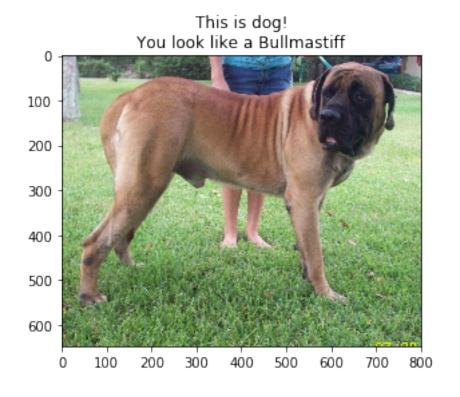
**Question 6:** Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

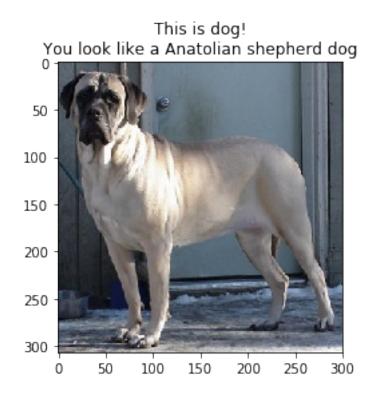
**Answer:** (Three possible points for improvement)

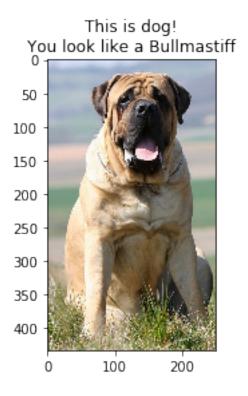












In []: