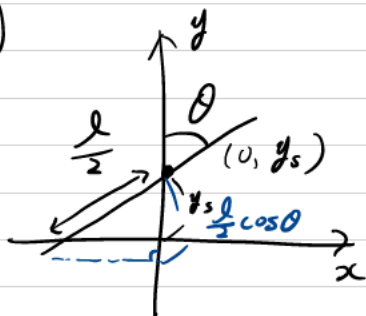


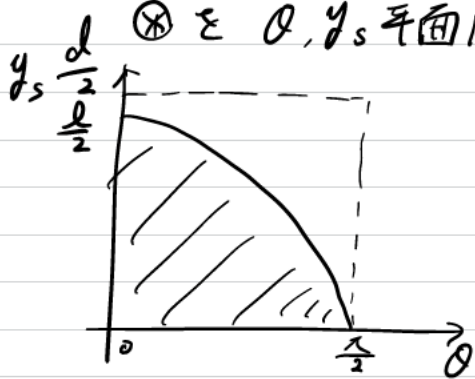
第1問  
(1)



棒が直線に交わるパラメータ  $y_s, \theta$  の条件は

$$y_s \leq \frac{l}{2} \cos \theta \quad \cdots \textcircled{*}$$

$\textcircled{*}$  を  $\theta, y_s$  平面に図示すると以下のようになる



$$\left( \begin{array}{l} 0 < \theta < \frac{\pi}{2} \\ 0 < y_s < \frac{d}{2} \end{array} \right)$$

$$\frac{l}{2} < \frac{d}{2}$$

$$f(\theta, y_s) = \begin{cases} 1 & (y_s \leq \frac{l}{2} \cos \theta) \\ 0 & (y_s > \frac{l}{2} \cos \theta) \end{cases}$$

と定義すると棒が直線に交わる確率  $P$  は

$$P = \frac{\int_0^{\pi/2} \int_0^{d/2} f(\theta, y_s) dy_s d\theta}{\int_0^{\pi/2} \int_0^{d/2} dy_s d\theta} = \frac{\int_0^{\pi/2} \frac{l}{2} \cos \theta d\theta}{\frac{\pi}{2} \times \frac{d}{2}}$$

$$= \frac{4}{\pi d} \times \frac{l}{2} = \frac{2l}{\pi d}$$

(2)

$$m\ddot{x}(t) = -\gamma\dot{x}(t) - kx(t) \dots (*)$$

$$x(t) = e^{\lambda t} \text{ とおく}$$

$$(m\lambda^2 + \gamma\lambda + k)e^{\lambda t} = 0$$

特性方程式

$$m\lambda^2 + \gamma\lambda + k = 0 \text{ を解く}$$

これを解いて

$$\lambda = \frac{-\gamma \pm \sqrt{\gamma^2 - 4mk}}{2m}$$

$$\lambda_1 = -\frac{\gamma}{2m} + \frac{1}{2m}\sqrt{\gamma^2 - 4mk}$$

$$\lambda_2 = -\frac{\gamma}{2m} - \frac{1}{2m}\sqrt{\gamma^2 - 4mk} \text{ とおく}$$

(i)  $\gamma^2 - 4mk < 0$  のとき  $\omega = \sqrt{4mk - \gamma^2}$  とおくと

$$x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$$

$$= e^{-\frac{\gamma}{2m}t} \left( C_1 e^{\frac{\omega}{2m}it} + C_2 e^{-\frac{\omega}{2m}it} \right)$$

$$= e^{-\frac{\gamma}{2m}t} \left( A_1 \cos\left(\frac{\omega}{2m}t\right) + A_2 \sin\left(\frac{\omega}{2m}t\right) \right)$$

減衰振動

( $A_1, A_2$  は任意定数)

(ii)  $\gamma^2 - 4mk > 0$  のとき  $\eta = \sqrt{\gamma^2 - 4mk}$  とおくと

$\lambda_1, \lambda_2$  は実数、このとき

$$x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$$

$$= e^{-\frac{\gamma}{2m}t} \left( C_1 e^{\frac{\eta}{2m}t} + C_2 e^{-\frac{\eta}{2m}t} \right)$$

過減衰

( $C_1, C_2$  は任意定数)

$$(ii) \quad \xi^2 - 4mk = 0 \text{ のとき}$$

$$x_1(t) = e^{-\frac{\xi}{2m}t}$$

$$x_2(t) = t e^{-\frac{\xi}{2m}t} \quad \text{が解}$$

一般解は

$$x(t) = (C_1 + C_2 t) e^{-\frac{\xi}{2m}t} \quad (C_1, C_2 \text{ は任意定数})$$

臨界減衰

まとめると

$$(i) \quad \xi^2 - 4mk < 0 \text{ のとき} \quad \text{減衰振動}$$

$$(ii) \quad \xi^2 - 4mk > 0 \text{ のとき} \quad \text{過減衰}$$

$$(iii) \quad \xi^2 - 4mk = 0 \text{ のとき} \quad \text{臨界減衰}$$

(2)

$$m\ddot{x}(t) = -\gamma\dot{x}(t) - kx(t)$$

$$\begin{cases} \cdot x = a\tilde{x} \\ \cdot t = t_0\tilde{t} \\ \cdot \dot{x} = \frac{a}{t_0}\tilde{v} \end{cases} \quad \text{とおく}$$

$$m \frac{\frac{a}{t_0}\tilde{v}(\tilde{t}+\Delta\tilde{t}) - \frac{a}{t_0}\tilde{v}(\tilde{t})}{t_0\Delta\tilde{t}} = -\gamma \frac{a}{t_0}\tilde{v}(\tilde{t}) - k a\tilde{x}(\tilde{t})$$

$$\frac{m}{t_0\Delta\tilde{t}} (\tilde{v}(\tilde{t}+\Delta\tilde{t}) - \tilde{v}(\tilde{t})) = -\gamma\tilde{v}(\tilde{t}) - k t_0\tilde{x}(\tilde{t})$$

$$\tilde{v}(\tilde{t}+\Delta\tilde{t}) = \tilde{v}(\tilde{t}) - \frac{\gamma}{m} t_0\Delta\tilde{t} \tilde{v}(\tilde{t}) - \frac{k}{m} t_0^2\Delta\tilde{t} \tilde{x}(\tilde{t})$$

$$= \left(1 - \frac{\gamma}{m} t_0\Delta\tilde{t}\right) \tilde{v}(\tilde{t}) - \frac{k}{m} t_0^2\Delta\tilde{t} \tilde{x}(\tilde{t})$$

①

位置に関しては

$$\tilde{x}(\tilde{t} + \Delta\tilde{t}) = \tilde{x}(\tilde{t}) + \tilde{v}(\tilde{t} + \Delta\tilde{t})\Delta\tilde{t} \dots (2)$$

①, ② をまとめて

$$\tilde{v}(\tilde{t} + \Delta\tilde{t}) = (1 - \frac{g}{k} t_0 \Delta\tilde{t}) \tilde{v}(\tilde{t}) - \frac{g}{k} t_0^2 \Delta\tilde{t} \tilde{x}(\tilde{t})$$

$$\tilde{x}(\tilde{t} + \Delta\tilde{t}) = \tilde{x}(\tilde{t}) + \tilde{v}(\tilde{t} + \Delta\tilde{t})\Delta\tilde{t}$$

(3) 式①について  $t_d = \frac{m}{g}$ ,  $t_s = \sqrt{\frac{m}{k}}$  とおくと

$$\tilde{v}(\tilde{t} + \Delta\tilde{t}) = (1 - \frac{1}{t_d} \cdot t_0 \Delta\tilde{t}) \tilde{v}(\tilde{t}) - \frac{1}{t_s^2} t_0^2 \Delta\tilde{t} \tilde{x}(\tilde{t})$$

$$= (1 - \frac{t_0}{t_d} \Delta\tilde{t}) \tilde{v}(\tilde{t}) - \left(\frac{t_0}{t_s}\right)^2 \Delta\tilde{t} \tilde{x}(\tilde{t})$$

$$(4) \quad g = \frac{m}{t_d}, \quad k = \frac{m}{t_s^2}$$

これを代入し,

$$g^2 - 4mk = m^2 \left( \frac{1}{t_d^2} - 4 \frac{1}{t_s^2} \right)$$

(i) 減衰振動の条件は

$$g^2 - 4mk = m^2 \left( \frac{1}{t_d^2} - 4 \frac{1}{t_s^2} \right) < 0$$

$$\left( \frac{t_0}{t_d} \right)^2 < 4 \left( \frac{t_0}{t_s} \right)^2$$

$$\frac{t_0}{t_d} > 0, \quad \frac{t_0}{t_s} > 0 \text{ より}$$

$$\frac{t_0}{t_d} < 2 \frac{t_0}{t_s} \text{ であればよい}$$

$$(< 2)$$

(ii) 過減衰の条件は

$$\frac{t_o}{t_d} > 2 \frac{t_o}{t_s} (=2)$$

(iii) 臨界減衰の条件は

$$\frac{t_o}{t_d} = 2 \frac{t_o}{t_s} (=2)$$