#86 time=10.001919616 block=GPSSensor type=send\_synchro channel=setPosition params=6

#87 time=10.001256320 block=SpeedSensor type=send\_synchro channel=updateOnSpeed params=10 #88 time=10.003175936 block=ObjectListManagement type=receive\_synchro channel=isObstacleAhead,

#89 time=10.003152512 block=RadarSensor tupe=action

#90 time=10.003460736 block=RadarSensor type=variable\_modification variable=obstacleAhead setTo=1

#91 time=10.003437312 block=RadarSensor blockdestination=ObjectListManagement type=synchro channel=obstacleAhead params=1

#92 time=10.001802496 block=RadarSensor type=send\_synchro channel=obstacleAhead params=1

#93 time=10.000807552 block=CarPositionSimulator type=send\_synchro channel=carPosition params=2,6

#94 time=11.002251264 block=DSRSC\_Management type=send\_synchro channel=setCarPosition params=2,6

#95 time=11.000284800 block=EmergencySimulator blockdestination=DSRSC\_Management type=synchro channel=obstacleDetected params=4,3

#96 time=11.002204416 block=DSRSC\_Management type=receive\_synchro channel=obstacleDetected

#97 time=11.000237952 block=DSRSC\_Management blockdestination=CorrectnessChecking type=synchro channel=forwardEmergencyBrakingMessage params=4,3

#98 time=11.001825920 block=DSRSC\_Management type=send\_synchro channel=forwardEmergencyBrakingMessage params=4,3

#99 time=11.000191104 block=NeighbourhoodTableManagement type=receive\_synchro channel=setPosition

#100 time=11.002418944 block=GPSSensor blockdestination=NeighbourhoodTableManagement type=synchro channel=setPosition params=3

#101 time=12.003222784 block=GPSSensor type=send\_synchro channel=setPosition params=3