D7560E Embedded Intelligence – AI-Driven Control and Optimization System of Systems Description (SoS-D)

ricbli-7

October 2025

1. Overview

This document describes the **AI-Driven Control and Optimization System of Systems (SoS)** designed for an ore handling process with three cascaded levels of control and optimization. The SoS integrates multiple subsystems such as the PowerSensor, Conveyor Motor Control, and Ore Feeder through Arrowhead compliant service oriented communication.

The system aims to optimize energy efficiency, process operation, and operational safety by enabling local control at the subsystem level and coordinated optimization at the supervisory and cloud levels.

1.1 Significant Prior Art

The concept of hierarchical and distributed control originates from traditional industrial automation and process optimization systems.

1.2 How This SoS Is Meant to Be Used

The SoS is designed for continuous monitoring and control of ore handling operations, enabling optimal performance under varying conditions.
It consists of three cascaded levels:

- **Level 1 – Local Control:** Each subsystem (PowerSensor, Ore Feeder, Conveyor Motor) executes its own low-level control logic, performs real-time measurements, and runs self-diagnostic routines to ensure stable operation.

- **Level 2 – Supervisory Control:** The supervisory level manages and coordinates the operation of all local subsystems. It optimizes energy consumption, balances material flow between the feeder and conveyor, and performs fault detection and recovery actions when anomalies are detected.

- **Level 3 – Cloud Optimization:** The top layer collects combined process data from the supervisory system and applies AI based optimization. It continuously optimizes control parameters and schedules predictive maintenance tasks to improve system performance and efficiency.

1.3 SoS Functionalities and Properties

1.3.1 Functional Properties of the SoS

- Collect and aggregate sensor data from multiple PowerSensor subsystems.

- Execute AI-based optimization algorithms in the cloud.

- Distribute optimized control parameters back to the local controllers.

- Handle fault detection and system recovery.

1.3.2 Configuration of SoS Properties

System configuration includes:

- Network addresses and Arrowhead registry information.

- Subsystem calibration and scaling constants.

- Data transmission intervals and optimization cycles.

1.3.3 Data Stored by the Individual Microsystem

Each subsystem (PowerSensor, MotorControl etc.) may temporarily buffer measurement data in memory for validation or short term averaging. For long term data storage and trend analysis, the system is intended to integrate with a **historian service**. The historian collects and stores time series process data from all subsystems, enabling analysis of performance trends and energy usage (Didn't exist in my version)

1.3.4 Non-Functional Properties

- **Security:** Arrowhead-compliant TOKEN authentication and TLS encryption.

- **Safety:** Redundant communication channels and error detection.

- **Energy Consumption:** Optimization targets reduced power use during low load periods.

- **Latency:** Real-time responsiveness at the local control level; batch updates for cloud optimization.

- **Scalability:** Modular structure allows new subsystems to be added with minimal reconfiguration.

1.3.5 Stateful or Stateless

The SoS is **stateful**, maintaining operational history, calibration data, and learned optimization parameters across its distributed components.

1.4 Important Delimitations

This SoS focuses solely on ore-handling process optimization and control. It does not include physical actuator design, network infrastructure, or detailed AI model implementation. External systems (e.g., ERP or maintenance scheduling) are considered out of scope.

2. Services

2.1 Produced Services

- **PowerMeasurement_SD**

  - PowerSensor_SysD
  - PowerMeasurement_SD
  - PowerMeasurement_IDD
  - TP-2 Compact Power Sensor SysDD

2.2 Consumed Services

- **MotorControl_SD**

  - MotorControl_SysD
  - MotorControl_SD
  - MotorControl_IDD
  - Conveyor Motor SysDD

- **FeederControl_SD**

  - FeederControl_SysD
  - FeederControl_SD
  - FeederControl_IDD
  - Ore Feeder SysDD

3. Security

3.1 Security Model

The SoS can operate exclusively in **Arrowhead secure mode**. All communication uses mutual authentication and encrypted data exchange.

Property	Value
Protocol Supported	HTTP 1.1
Data Protection Supported	TLS 1.3
System Authentication	Arrowhead TOKEN-based (JWT)
Produced Service Authorization	Managed via Arrowhead Authorization System
Certificates	X.509, ApplicationSystem level

4. Revision History

4.1 Amendments

No.	Date	Version	Subject of Amendments / Author
1	2025-10-16	1.0	Initial version of AI-Driven Control and Optimization SoSD (ricbli-7)

4.2 Quality Assurance

No.	Date	Approved by
1	2025-10-16	Supervisor