Local Constant Approximation for Dominating Set on Graphs Excluding Large Minors

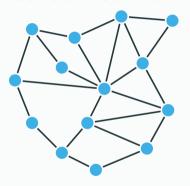
Marthe Bonamy ¹ Cyril Gavoille ¹ <u>Timothé Picavet</u> ¹ Alexandra Wesolek ²

¹LaBRI, U. Bordeaux

²TU Berlin

Distributed algorithms

Centralized view

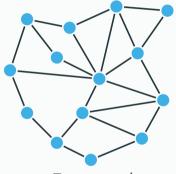


Distributed view



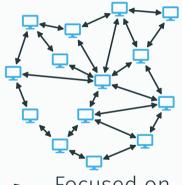
Distributed algorithms

Centralized view



Focused on computing

Distributed view

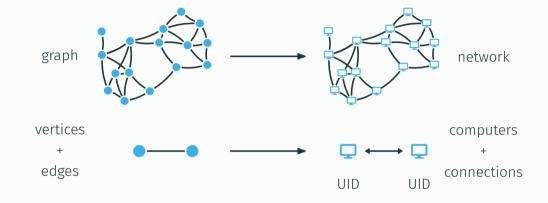




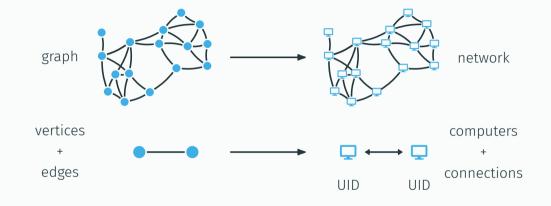
The LOCAL model



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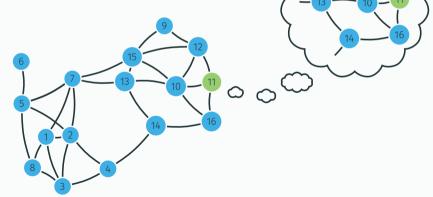
The LOCAL model



The network is also the input graph!

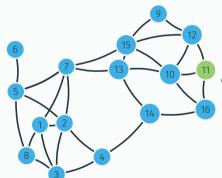
Equivalence with number of rounds T

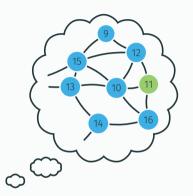
Each vertex sees its distance-*T* neighborhood and decides its return value.



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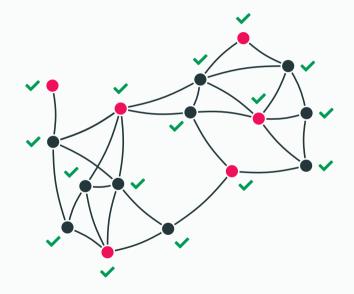
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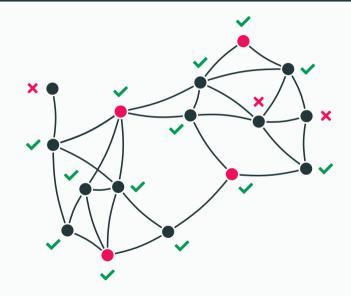


 $\mathsf{Algo} = \mathcal{A} : \underset{\mathsf{neighborhood}}{\mathsf{distance-T}} \mapsto \underset{\mathsf{return}}{\mathsf{local}}$

An example: MINIMUM DOMINATING SET

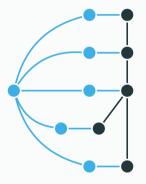


An example: MINIMUM DOMINATING SET



Small diameter allows bruteforcing

MINIMUM DOMINATING SET when ∃ universal vertex



Easy in LOCAL Hard in centralized

Is all hope lost?

Theorem (Kuhn, Moscibroda, and Wattenhofer, 2016)

It is **impossible** to approximate MINIMUM DOMINATING SET with a constant number of rounds and constant approximation ratio on **general graphs**.

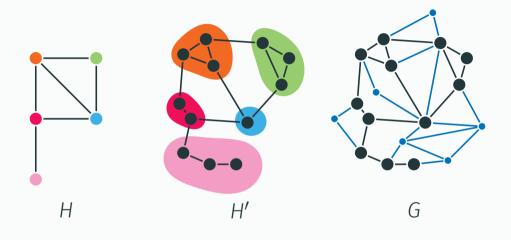
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Graph minors



H is a minor of G

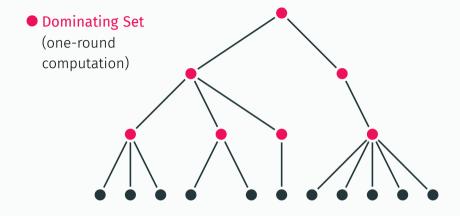
State of the art for MDS with $\mathcal{O}(1)$ LOCAL rounds

MINOR-FREE GRAPHS	lower	PPROX. RATIO upper	#rounds
trees (K ₃)	3 ^[2]	3 ^[2]	2
outerplanar (K_4 , $K_{2,3}$)	5 ^[3]	5 ^[3]	2
planar (<i>K</i> ₅ , <i>K</i> _{3,3})	7 ^[1]	$11 + \varepsilon^{[4]}$	$\mathcal{O}_{arepsilon}(1)$
K _{2,t} -minor-free	5 ^[3]	2t — 1	3
	5 ^[3]	50	\mathcal{O}_t (1)
K _{3,t} -minor-free	7 ^[1]	$(2+\varepsilon)\cdot(t+4)^{[4]}$	$\mathcal{O}_{arepsilon,t}(1)$
K _{s,t} -minor-free	7 ^[1]	$t^{\mathcal{O}(st\sqrt{\log s})}$ [4]	$\mathcal{O}_t(1)$

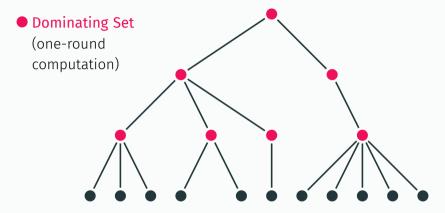


- [1] M. Hilke, C. Lenzen, and J. Suomela. Brief announcement: local approximability of minimum dominating set on planar graphs. PODC 2014. [2] Folklore
- [3] M. Bonamy, L. Cook, C. Groenland, and A. Wesolek. A tight local algorithm for the minimum dominating set problem in outerplanar graphs. DISC 2021.
- [4] O. Heydt, S. Kublenz, P. Ossona de Mendez, S. Siebertz, and A. Vigny. Distributed domination on sparse graph classes. European Journal of Combinatorics, 2025.

Example 1: trees

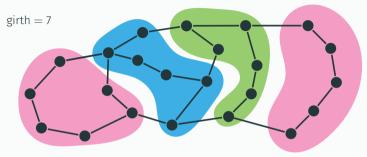


Example 1: trees



Theorem (folklore)

 $\#cutvertices = |\{v \in V(T) \mid deg(v) \ge 2\}| \le 3 \cdot MDS(T)$



Reusing the algorithm of trees?



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 \cdot Every vertex is in a bag (\Longrightarrow covering)



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Reusing the algorithm of trees?

- Every vertex is in a bag (\implies covering)
- Diameter \leq girth/2 (\Longrightarrow to see a tree)
- \cdot Spacing clusters of same color (\Longrightarrow no overcounting for fixed color)
- Few colors (\Longrightarrow to limit overcounting)

Asymptotic dimension of C is d if $\exists f : \mathbb{N} \to \mathbb{N}, \forall G \in C, \forall r \in \mathbb{N}, \exists B_1, B_2, \dots \subseteq V(G)$, such that

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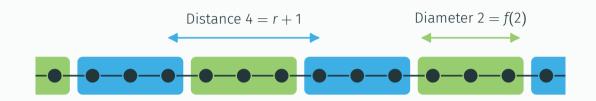
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• Boundedness: $\forall i$, diam_G(B_i) $\leq f(r)$

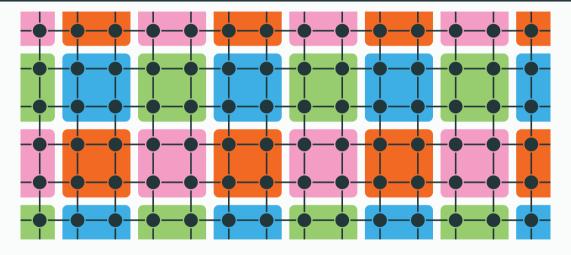


Example 1: the path



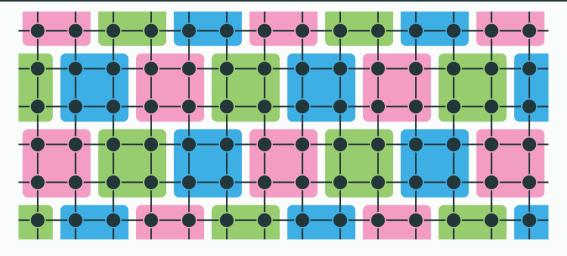
Dimension = 1 (2 colors)
with
$$f(r) = r - 2$$

Example 2: the grid – attempt 1 (r = 2)



Dimension ≤ 3

Example 2: the grid – attempt 2 (r = 2)



Dimension = 2!

Asymptotic dimension and graph minors

Theorem (Bonamy, Bousquet, Esperet, Groenland, Liu, Pirot, Scott, 2020) Every class excluding a fixed minor has asymptotic dimension ≤ 2 .

Application: distributed algorithms

How to use graph theory in distributed algorithms?

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Global concept



Local concept

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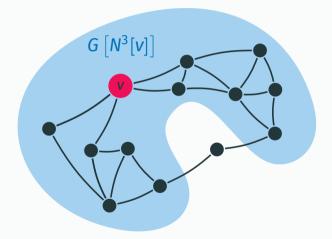
How to use graph theory in distributed algorithms?

Global concept

Local concept

Definition

v is a r-local cutvertex if v is a cutvertex of $G[N^r[v]]$.



Applications: MDS in LOCAL model

Theorem (main)

On graphs excluding $K_{2,t}$ as a minor, there exists a constant-approximation (where the constant is **independent of t**) of MINIMUM DOMINATING SET in the LOCAL model, in f(t) rounds.

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Asymptotic dimension only used in the analysis!

The algorithm

$$Y_t(G) = \bigcup \{18t\text{-local cuts of size } \le 2\} \setminus \{\text{non-interesting vertices}\}\$$

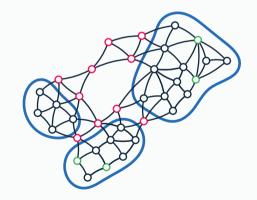
Algorithm = $Y_t(G) \cup [\text{brute-force on } G - Y_t(G)]$

Lemma 1

 $|Y_t(G)| = \mathcal{O}(d) \cdot \mathsf{MDS}(G).$

Lemma 2

If G is $K_{2,t}$ -minor-free, every connected component of $G - Y_t(G)$ has diameter $\mathcal{O}_t(1)$.



Local cutvertices

Lemma 1a (folklore)

For every graph G, #cutvertices $\leq 3 \text{ MDS}(G)$.



Theorem 1

Let C be of asymptotic dimension d.

Then $\forall r \geq r_0, \#r\text{-local}$ cutvertices $\leq 3(d+1) \text{ MDS}(G)$.

Local cutvertices

Lemma 1a (folklore)

For every graph G, #cutvertices $\leq 3 \text{ MDS}(G)$.



Lemma 1b

For every graph G and $S \subseteq V(G)$, #cutvertices $\in S \le 3 \text{ MDS}(G, N[S])$.



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Dimension d, function f: sets B_1, B_2, \ldots for r = 5.

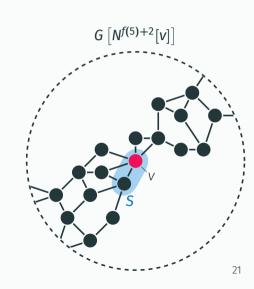
Proof of Lemma 1b \implies Theorem 1

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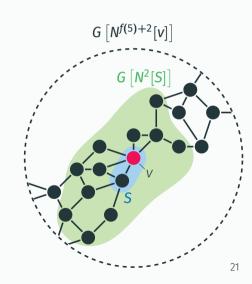


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Claim: $N^2[S] \subseteq N^{f(5)+2}[v]$.



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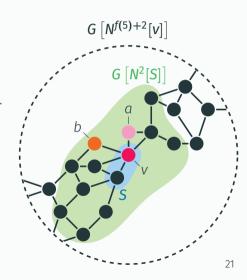
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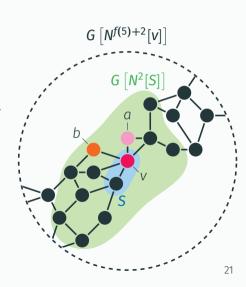
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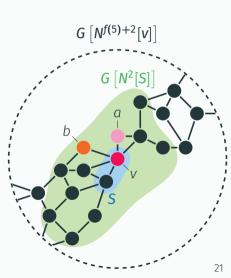
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#(f(5)+2)-local cutvertex $\leq \sum_{c=1}^{d+1} \sum_{\substack{i, \ c(B)=c}} 3 \cdot \mathsf{MDS}(G, N[B_i])$



End of the proof

$$\#(f(5) + 2)$$
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 $(N^2[B_i]$'s are disjoint)

$$\#(f(5) + 2)$$
-local cutvertex $\leq \sum_{i=1}^{G-1} 3 \cdot MDS(G) = 3(d+1) \cdot MDS(G)$.

What about local 2-cuts?

Theorem

Let C of asymptotic dimension d.

Then $\forall r \geq r_0, \# vertices \in r\text{-local 2-cut} \leq 8(d+1) \, \mathsf{MVC}(G)$.

Conclusion and perspectives

Follow-up works:

- H-minor-free graphs admit a 50-approximation if pathwidth(H) = 2.
- · Constant factor approximations in locally-nice graphs, e.g. bounded genus.
- Transform algorithms from a class ${\mathcal C}$ to a locally- {\mathcal C} class.

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